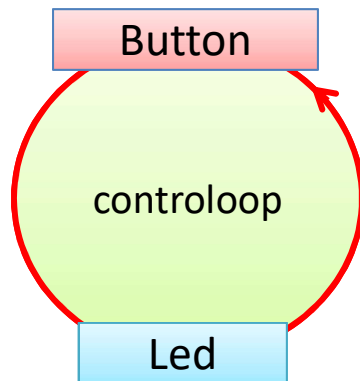


# A qactor based on POJO

The **Button** is a POJO, observable device.  
The **Led** is a POJO, output device.

See project [it.unibo.bls2016.qa](https://github.com/it-unibo/bls2016.qa)



**System blsRaspOop2017**

**Context** ctxBlsOOp

**ip** [host="localhost" port=8030]

**QActor controloop** context ctxBlsOOp {

**Plan** init normal

**println**(" controloop STARTS");

**actorOp** createPi4jButton ( 24 ) ;

**actorOp** createPi4jLed( 25 ) ;

**delay** time(60000);

**println**(" controloop ENDS")

}

	PC	Raspb	Arduino	...
PC				
Raspb				
Arduino				
...				

- Java
- JavaScript
- C / C++
- Python
- ...