Progettazione avanzata di software di controllo industriale

Elettric80 https://github.com/anatali/lss0

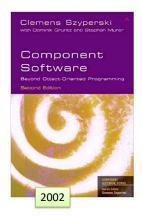
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Sviluppo di sistemi software

PROGETTAZIONE, COMPONENTI, RIUSO, TESTING

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Software components

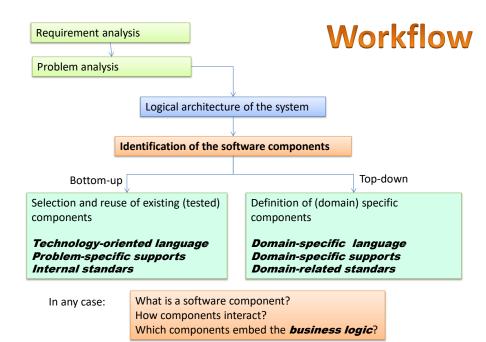


The book gives us an objective survey of the component landscape, blended with unique insights into the market forces that influence deployment and in-depth coverage of real problems and their solutions.

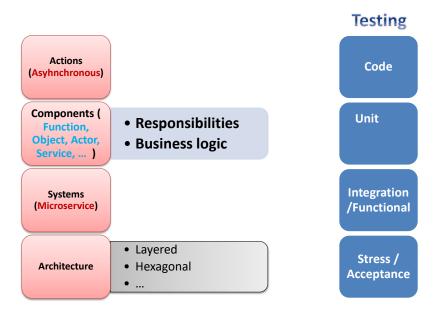
Highlights of the Second Edition include:

- A comprehensive update of market-leading technologies including COM+, CORBA, EJB and J2EE
- New sections evaluating the strengths and weaknesses of emerging technologies like .NET, the CORBA Component Model, XML Web Services, showing how they work together with components and XML-related standards
- New examples in C# in addition to Java and Component Pascal

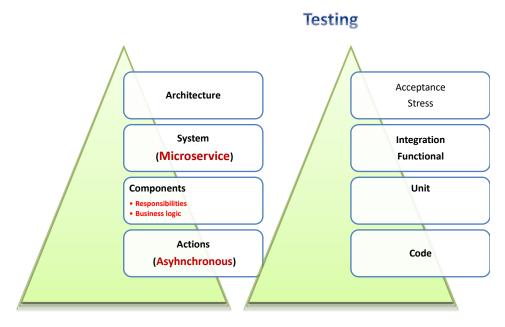
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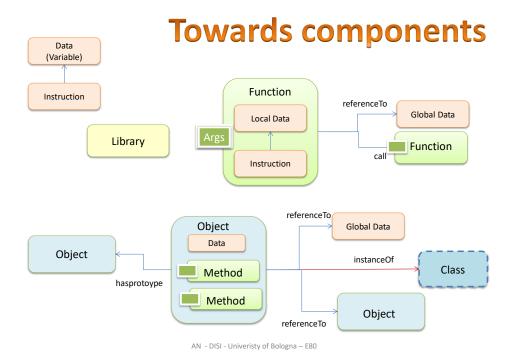
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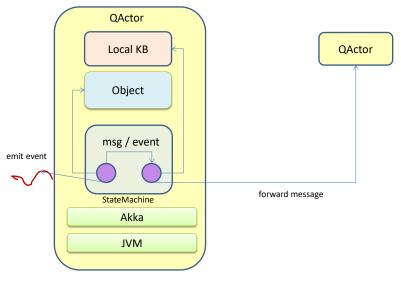
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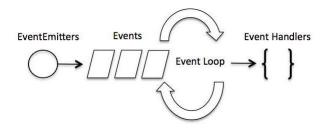


Beyond procedure calls



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Event loop



```
setTimeout( function(){ console.log("1000a1"); console.log("1000a2"); } , 1000 );
setTimeout( function(){ console.log("1000b1"); console.log("1000b2"); } , 1000 );
setTimeout( function(){ console.log("500"); } , 500);
```

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Fact asynch

```
factAsynch = function( n, callback ){ factIterAsynch(n,n,1,callback); }
factIterAsynch = function( n, n0, v, callback ){
                     //ACCUMULATOR
var res = n*v;
      console.log( "factIterAsynch n0=" + n0 + " n=" + n, " v=" + v + " res=" + res);
      if( n == 1 ) callback( "factIterAsynch(" + n0 + ") RESULT="+res );
      else setTimeout( function(){ factIterAsynch( n-1, n0, res, callback ); }, 0);
}
console.log("START");
                                                         START
                                                         factIterAsynch n0=4 n=4 v=1 res=4
console.log("CALL= ", factAsynch(4, console.log) );
                                                         CALL= undefined
factAsynch(6,console.log);
                                                         factIterAsynch n0=6 n=6 v=1 res=6
console.log("END");
                                                         END
                                                         factIterAsynch n0=4 n=3 v=4 res=12
                                                         factIterAsynch n0=6 n=5 v=6 res=30
                                                         factIterAsynch n0=4 n=2 v=12 res=24
                                                         factIterAsynch n0=6 n=4 v=30 res=120
                                                         factIterAsynch n0=4 n=1 v=24 res=24
                                                         factIterAsynch(4) RESULT=24
                                                         factIterAsynch n0=6 n=3 v=120 res=360
                                                         factIterAsynch n0=6 n=2 v=360 res=720
                                                         factIterAsynch n0=6 n=1 v=720 res=720
                                                         factIterAsynch(6) RESULT=720
```

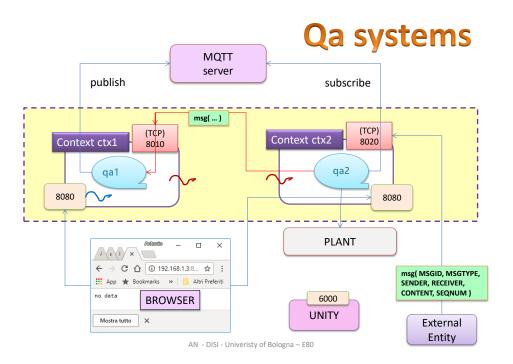
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.0

Fibonacci asynch

```
fibonacciAsync = function( n, callback ){
if( n==1 || n == 2 || n == 3 ) { callback( n ); }
else{
console.log( "fibonacciAsync for " + n );
 process.nextTick(function() {
       fibonacciAsync( n -1 , function(val1){
       process.nextTick(function() {
           fibonacciAsync( n -2, function(val2){
                    callback( val1 + val2 );
           });
         });
      });
    });
  }}
console.log("fibAsynch STARTS");
fibonacciAsync(10, console.log);
console.log("fibAsynch ENDS");
```

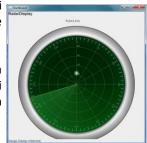
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CaseStudy1

Si vuole realizzare un sistema software capace di presentare su un personal computer convenzionale l'immagine grafica di uno schermo radar (detto *radarGui*)

Il sistema deve fare in modo che su *radarGui* venga visualizzata l'informazione acquisita da una o più sorgenti di diverso tipo, tra cui un sonar HC-SR04 connesso a un RaspberryPi o a un Arduinio.



L'immagine risultante potrebbe essere del tipo mostrato nella figura in cui viene visualizzato un punto a distanza 24 cm in direzione 0.0.

radarGui deve permettere di visualizzare punti a distanza compresa tra cm 0 e cm 80 lungo direzioni comprese tra 0 e 180, utilizzando il quadrante di destra della figura.

PRIMA ANALISI: si tratta di realizzare un sistema software distribuito ed eterogeneo

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ButtonLed system

Project it.unibo.qa.nodeserver https://github.com/anatali/lss0

blsHlCustom: a BLS system on PC /Rasp

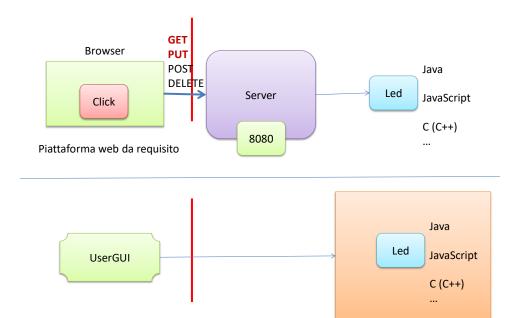
blshlBlink a system that executes reactive actions

blsHlBlinkReactiveWeb

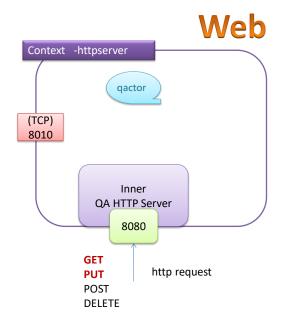
blsHlNode a system that works with Node helloMqtt a system that does publish/subscribe

LED

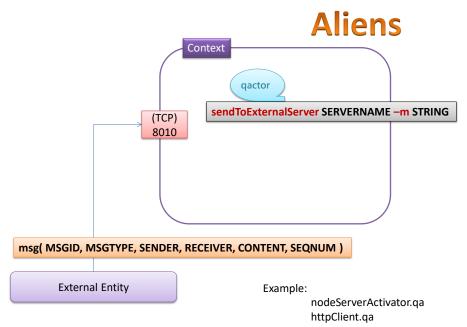
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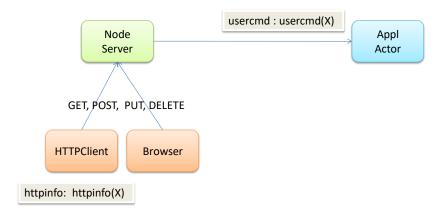
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blsHlCustom

A button-led system working on a PC

- 1. it.unibo.buttonLed.components. DevLed
- 2. it.unibo.buttonLed.components.DeviceLedImpl
- 3. it.unibo.custom.led. LedFactory
- 4. it.unibo.custom.button. ButtonFactory
- 5. blsHLCustom.ga
- 6. -----
- 7. srcMore/it.unibo.ctxBlsHlCustom/QActorWebUI.html
- 8. Context ctxBlsHlCustom ip [host="localhost" port=8029] -httpserver
- 9. -----
- 10. Events and Event-conversion

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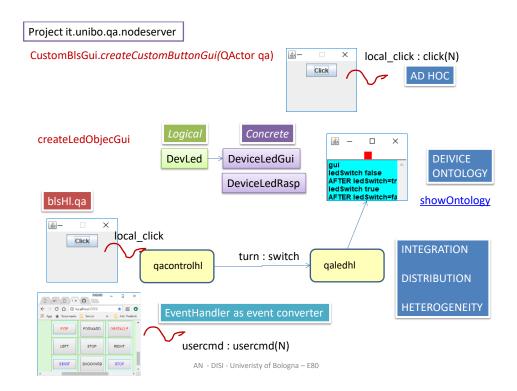
blsHlNode

A button-led system working in Node on a PC and on Raspberry

The Led on PC writes the current value on a file

- 1. it.unibo.qa.nodeserver\node\blsOop\Led.js
- 2. it.unibo.qa.nodeserver\node\blsOop\LedImplPc.js
- 3. it.unibo.qa.nodeserver\node\blsOop\LedHlPc.js
- 4. blsHLNode.qa(a gactor that interacts with a Led implemented in Node)
- 5. -----
- 6. it.unibo.qa.nodeserver\cmd.txt (updated by LedHIPc.js | next: gpio)
- 7. ------
- 8. it.unibo.qa.nodeserver\node\blsOop\LedHlRasp.js
- 9. it.unibo.qa.nodeserver\node\blsOop\LedImplGpiojs

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A ButtonLed system working as a Wot system

blsWot

it.unibo.wot\nodeServerRest\servers\http.js

 it.unibo.wot\nodeServerRest\resources\model.js
 it.unibo.wot\nodeServerRest\resources\resources.json
 it.unibo.wot\nodeServerRest\routes\actuators.js
 it.unibo.wot\nodeServerRest\routes\sensors.js
 it.unibo.wot\nodeServerRest\routes\things.js

 it.unibo.wot\nodeServerRest\servers\coap.js
 it.unibo.wot\nodeServerRest\plugins\internal\ledsPlugin.js

 it.unibo.wot\nodeServerRest\nat\observableFactory.js
 it.unibo.wot\nodeServerRest\nat\TcpClientToQaNode.js

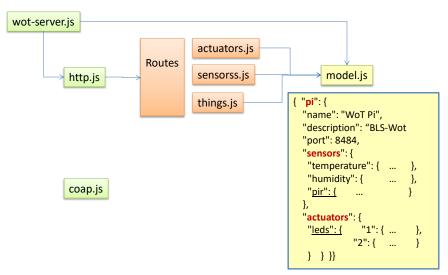
 it.unibo.wot\nodeServerRest\plugins\external\coapPlugin.js
 it.unibo.wot\nodeServerRest\plugins\external\coapPlugin.js
 it.unibo.wot\nodeServerRest\wot-server.js

 wotRestServerNode.qa ()

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 $it.unibo.wot\src\it\unibo\rest\clientHttp.java$

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Applications

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Software Design (and development)

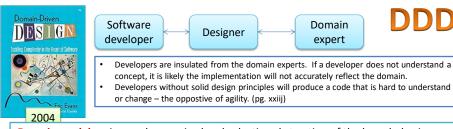
New design

- Domain driven design, Small (autonomous) teams, Continuos integration
- Bounded Contexts,
- · Microservices,

An approach to delivering SOA by building fine-grained services to support business capabilities that are distributed and organized as functional domains

- Communications based on (core) business concepts,
 No more data (anemic CRUD services) but business capabilites
- No more (only) layered architectures but hexagonal architectures
- Communications standards: the REST architecture style Self-descriptive messages / Stateless interactions
- Evolutionary architectures (requirements, componenyts, views)
 (Discoverability, Coonectivity, Reactivity, Safety, Interoperability, Delegation, Scalability, Collaboration, Usability, Marketability)

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Domain model: a rigorously organized and selective abstraction of the knowledge in a domain's expert head (pg. 3).

One model should underlie implementation, design and team communications (pg. 41) The model is the backbone of a language used by all team members (pg. 4, 26).

- iterate a single model to reflect a shared understanding across domain experts, designers and developers
- establisha common language, i.e. a UBIQUITOUS LANGUAGE (pg. 24)

Code as a design document does have its limits (pg. 38). A document should explain the concepts of the model and must be involved in project activities (pg.39)

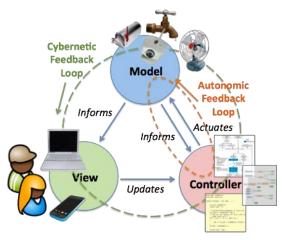
Effective domain modelers are knowledge crunchers. Continuous learning takes place between domain experts, designers and developers (pg. 15) (OO) MODEL-DRIVEN DESIGN pg. 47

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MVC

The Model-View-Controller macro pattern provides a framework for the structured division of responsibility between people and software. It also provides a framework for high level interoperability between data sources, control elements, and UI elements.

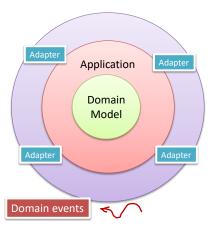


The **Model** is a representation or an abstraction of the physical things and their attributes, which *informs* a Controller.

The **Controller** is software which makes *actuation* decisions based on the information, and sends actuation commands to the thing using it's modeled affordances.

The software goal is to maintain a desired state of the thing through it's model.

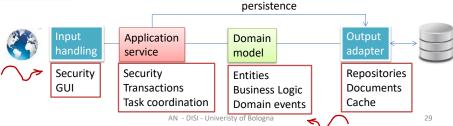
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Architecture

A <u>Ports and Adapters</u> architecture style, or a <u>Hexagonal Architecture</u>, makes a clear separation between the domain model and the devices used for inputs and outputs.

No technology concerns, e.g. HTTP contexts or database calls, are referenced in the domain, allowing changes in technology to be made without affecting the domain.



Microservices (anti)patterns

https://www.infoq.com/articles/seven-uservices-antipatterns

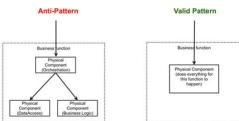
Services must align clearly to a business capability and should not try to do something outside of their boundary.

Functional separation of concern is vital for architecture to govern otherwise it will destroy the agility, performance, and scalability and ended up in establishing a tightly coupled architecture, resulting in delivery entropy and cohesion chaos.

Don't have services separated by technical concerns instead they must be separated based on the business capability.

Try to look at a service as one atomic business entity, which must implement everything to achieve the desired business functionality. The self-contained services are more autonomous and scalable than the layered services.

It's perfect to re-write some common code across multiple services, that's fine and it's a good tradeoff to keep the autonomy level.

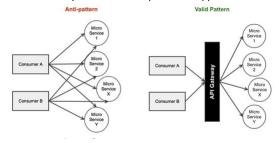


Microservices (anti)patterns

Give independence to your services. Every service that you deliver must have a test suite, which should cover all the service functionality, security, performance, error handling, and consumption driven testing for every current and future consumer.

Continuous deployment, if you have not done so, is a must investment and a cultural change that every enterprise should aim for. At least, if you don't have a way to automatically test and deploy – do not do micro-services.

Invest in API Management solutions to centralize, manage and monitor some of the non-functional concerns and which would also eliminate the burden of consumer's managing several microservices configurations. API gateway can be used orchestrate the cross-functional microservices that may reduce round trips for web applications.



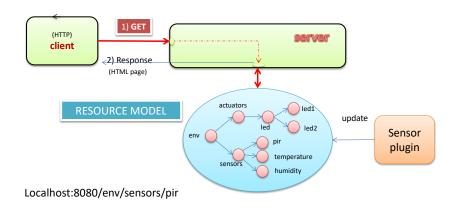
Integration patterns: REST on device, Gateway (CoAP), Cloud (MQTT)

<u>Resource</u> model design: (ontology) tree, knowledge base, .. <u>Representation design</u>: json, prolog, HTML, MessagePack, ...

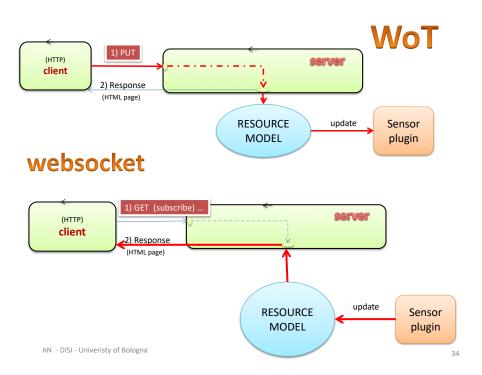
Interface design : GET, PUT, etc

Resourse binding design: HAETOAS (web linking,...), findability, ...





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Challenges

New challenges (Overcorming disruption)

- Service Orchestration vs. service Choreography
- UI fragments and UI composition
- Reporting (event data pump)
- Monitoring (specialized subsystems),
- Distributed transactions,
- Eventual consistency,
- · Compensating transactions,
- Distributed transactions,

Splitting the monolite

- The Strangler Application Pattern
- $\bullet \quad \text{https://www.ibm.com/developerworks/cloud/library/cl-strangler-application-pattern-microservices-apps-trs/index.htm} \\ I = \frac{1}{2} \frac{1}$

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Case study

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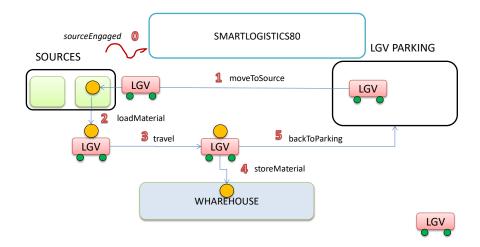
Requirements

Our company must build a software system (named SMARTLOGISTICS80) that must store in automatic way physical material put on one of its material sources into a proper cell of a Warehouse. More specifically the system must:

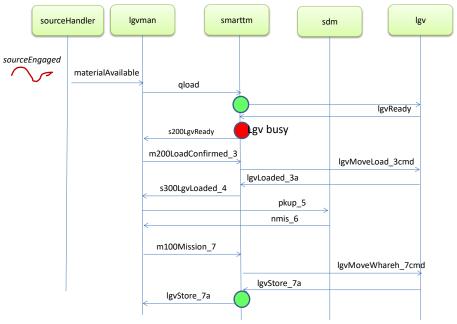
- R0) detect the presence of new material on a source and select a free LGV (LASER GUIDED VEHICLE) in the parking area
- R1) move the selected LGV from the parking area to the source
- R2) check when the material is loaded on the LGV
- R3) select a cell in the Warehouse and drive the LGV from the source to the Warehouse
- R4) check when the material is stored in the selected cell of the Warehouse
- R5) move the LGV from the Warehouse to the parking area

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Requirements



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