## CSCI-GA.2560-001, Artificial Intelligence

October 23, 2021

# Solutions to Problem 1 of Homework 1 (3 Points)

Name: Kumar Prasun (kp2692)

Due: September 20

Collaborators:

Show the order of nodes visited using Breadth First Search (BFS), and the final path selected. Is this optimal? Why or why not?

#### **Solution:**

The order of nodes visited is:

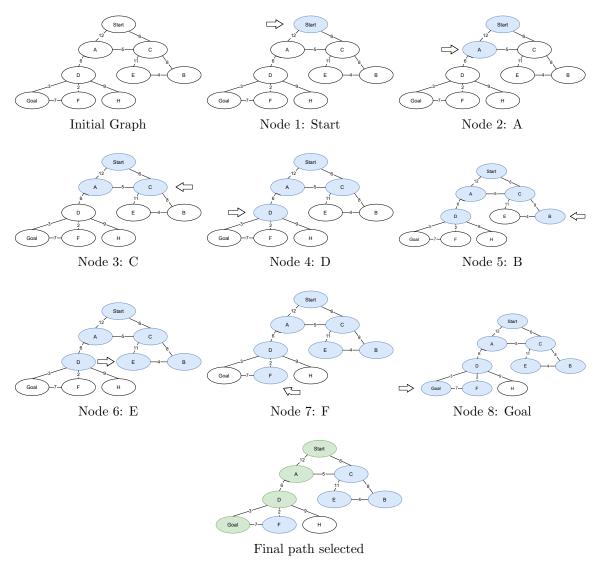


Figure 1: Order of node visits

### EXPLANATION:

Diagram	Current Path	Queue	Visited Nodes	Explanation
Initial Graph	-	{Start}	{}	Since queue has Start, we pop and visit
				that node.
Node 1: Start	Start	{C,A}	{Start}	A is before C in queue due to alphabet-
				ical priority. So visit node A next
Node 2: A	Start->A	{D,C}	{Start,A}	We visit C as it's first in queue.
Node 3: C	Start->C	$\{E,B,D\}$	{Start, A, C}	We visit D as it's first in queue.
Node 4: D	Start->A->D	{H,Goal,F,	{Start, A, C,	We visit B as it's first in queue.
		E,B}	D}	
Node 5: B	Start->C->B	{H,Goal,F,	{Start, A, C,	We visit E as it's first in queue.
Node 5. D	5tart-/0-/D	E}	B}	we visit in as it's first in queue.
Node 6: E	Start->C->E	{H,Goal,F}	{Start, A, C,	We visit F as it's first in queue.
Trode o. E	Start > C > L	(11,00a1,1 )	B, E}	vve visit i as it s inst in queue.
Node 7: F	Start->A->D	>A->D   {H,Goal}	{Start, A, C,	We visit Goal as it's first in queue.
	->F		B, E}	
Node 8: Goal	Start->A->D	{H}	{Start, A, C,	We've visited Goal node. Terminate
110dc o. doar	->Goal	(11)	B, E, F	program.
				program.

The green nodes highlighted in the final graph of Figure 1, are the nodes visited in the final selected path. The path is not optimal as it's path cost is 12+6+3=21. The optimal path among all possible paths is from  $Start \to C \to A \to D \to Goal$  with a path cost of 6+5+6+3=20.  $\square$ 

### CSCI-GA.2560-001, Artificial Intelligence

October 23, 2021

## Solutions to Problem 2 of Homework 1 (3 Points)

Name: Kumar Prasun (kp2692)

Due: September 20

Collaborators:

Show the order of nodes visited using Iterative Deepening (initial depth of 2, increasing depth by 1), and the final path selected. Is this optimal

#### **Solution:**

The order of nodes visited is:

For Depth = 2

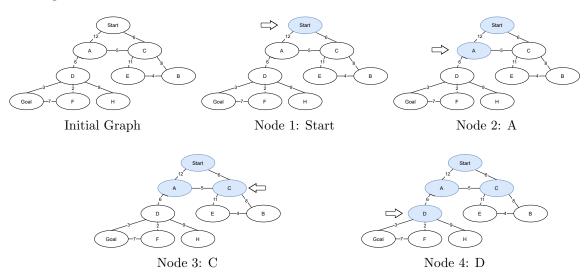


Figure 2: Order of node visits for depth = 2

EXPLANATION: The IDS algorithm tries to go to the deepest level of the tree till it reaches the goal or depth limit. The order in which the children nodes are traversed is based on alphabetical priority.

Nodes E and B will be not be visited since they are can only be reached from path Start - >A - >C, but the depth limit (of 2) has been reached.

They cannot be reached from path Start -> C as Node C has already been visited via path Start -> A -> C and so the former path will be ignored by IDS due to Node C already being in the visited set.

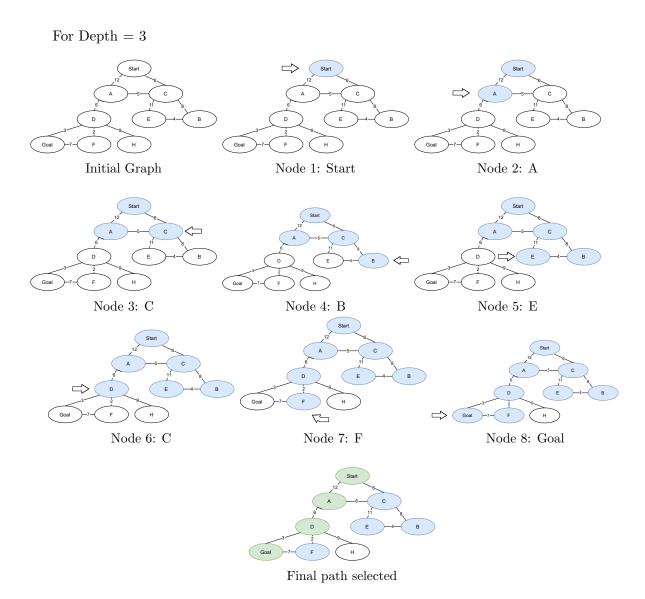


Figure 3: Order of node visits for depth = 3

The green nodes highlighted in the final graph of Figure 3, are the nodes visited in the final selected path. The path is not optimal as it's path cost is 12+6+3=21. The optimal path among all possible paths is from  $Start \to C \to A \to D \to Goal$  with a path cost of 6+5+6+3=20.

## CSCI-GA.2560-001, Artificial Intelligence

October 23, 2021

Solutions to Problem 3 of Homework 1 (4 Points)

Name: Kumar Prasun (kp2692)

Due: September 20

Collaborators:

Using the above h-function, show the order of nodes visited using  $A^*$ ,and the final path selected. Is this optimal? Why or why not?

#### **Solution:**

The order of nodes visited is:

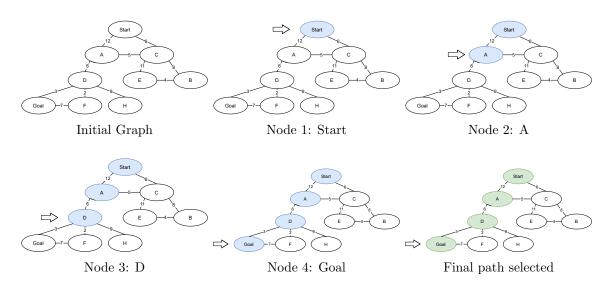


Figure 4: Order of node visits for A\*

Diagram	f(n) Value	Explanation
Node 2:A	= 12 + 9 = 21	This is less than that of Node C, $f(Start->C) = 22$ .
Node 3:D	= 18 + 2 = 20	This is less than that of Node C, $f(Start->C) = 22 \& f(Start->A->C) = 33$ .
Node 4:Goal	= 21 + 0 = 21	This is less than f(n) of all other nodes in the priority queue. Program terminates.

The green nodes highlighted in the final graph of Figure 4, are the nodes visited in the final selected path. The path is not optimal as it's path cost is 12+6+3=21. The optimal path among all possible paths is from  $Start \to C \to A \to D \to Goal$  with a path cost of 6+5+6+3=20.