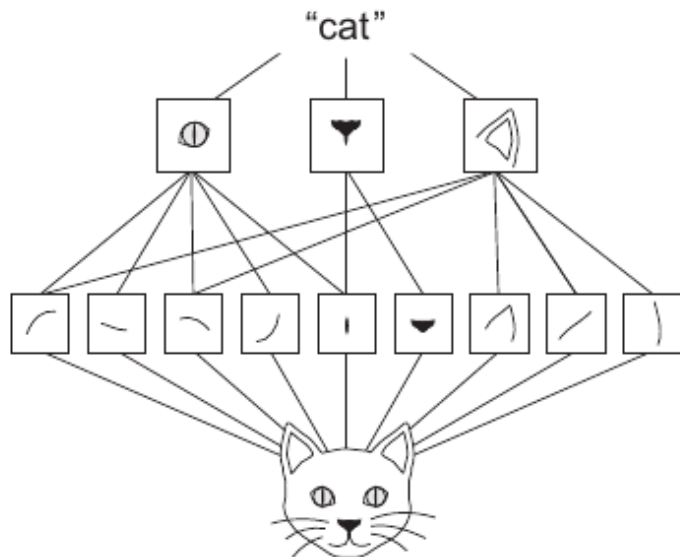


Convolutional neural network

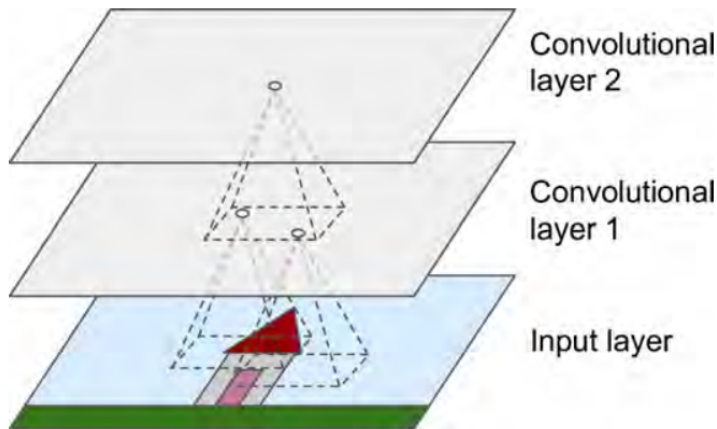
CNN - Hierarchies of patterns



CNN

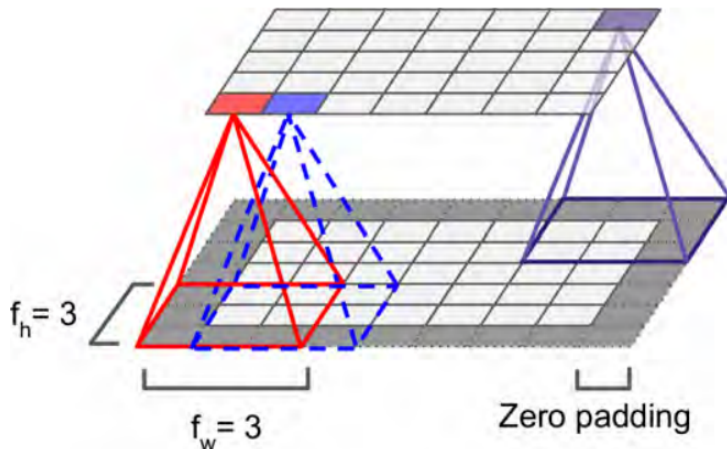
- ▶ Receptive fields
 - ▶ First convolutional layer: neurons are not connected to every single pixel in the input image, but only pixels in their receptive fields
 - ▶ Second convolutional layer: each neuron is connected only to neurons located within a small rectangle
- ▶ the network concentrates on
 - ▶ low-level features in the first hidden layer, then
 - ▶ assemble them into higher-level features in the next hidden layer,
 - ▶ and so on.

CNN layers with rectangular local receptive fields



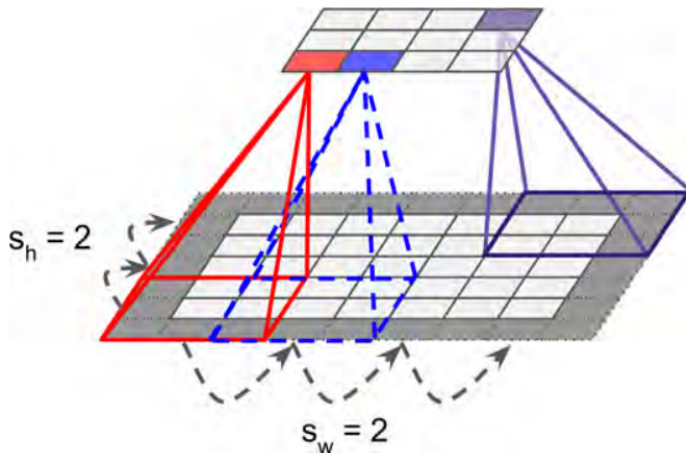
2

Connections between layers (with zero padding)



- ▶ neuron i, j - connected to neurons in previous layer in rows i to $i + f_h - 1$, columns j to $j + f_w - 1$.
- ▶ the layer has the same height and width as the previous layer (with zero padding)

Reduce dimensionality using a stride

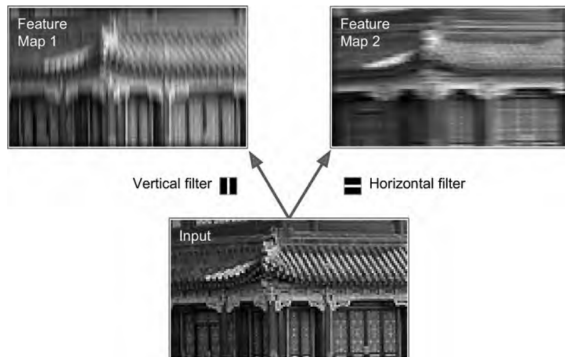


Input

layer : 5x7. Filter: 3x3. Stride: 2.Result: 3x4

Filters

- ▶ a neuron's weight can be seen as a small image the size of the receptive field
- ▶ a layer full of neurons using the same filter gives a = highlights the areas in an image that are most similar to the filter



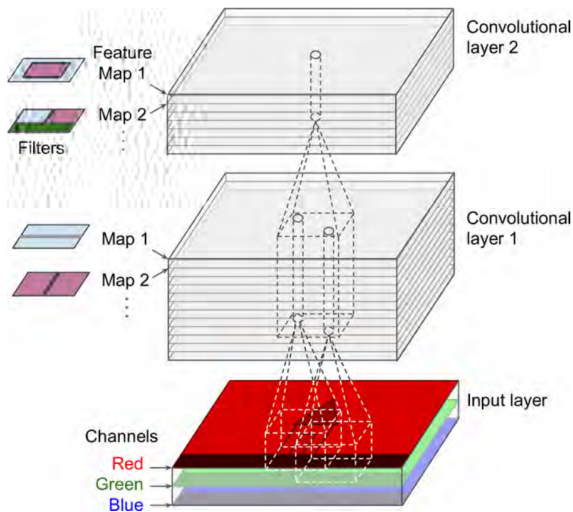
Time for notebook

Stacking multiple feature maps

Obs: All the previous representations were simplifications

- ▶ a convolutional layer is composed of several feature maps of equal sizes
- ▶ within one feature map, all neurons share the same parameters
- ▶ different features maps may have different parameters
- ▶ a neuron's receptive field includes a limited number of neurons but across all the features maps of the previous layer

Convolution layers with multiple feature maps and image with three channels



cont. Feature maps

A neuron located

- ▶ in row i , column j of the feature map k is connected
- ▶ to the outputs of the neurons in the previous layer located in rows ixs_w to $ixs_w + f_w - 1$, columns jxs_h to $jxs_h + f_h - 1$ across all feature maps

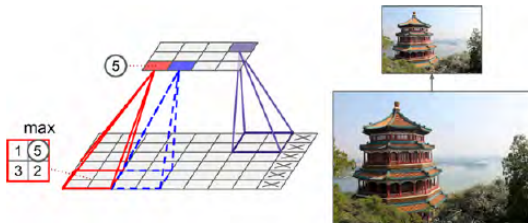
All neurons located in the same row and column but in different feature maps are connected to the outputs of the exact same neurons in the previous layer

Time for notebook

- ▶ Fashion mnist with only dense layers (fully connected)
- ▶ Fashion mnist with convolutional layers
 - ▶ CNN
 - ▶ number of parameters (model.summary)
 - ▶ improvement over fully connected

Pooling layer: max, mean

- ▶ Subsample the input image - reduce number of parameters - reduce overfitting
- ▶ Required info: size, stride, padding type
- ▶ **Has no weights**
- ▶ Works on every input channel independently: output depth is the same as input depth



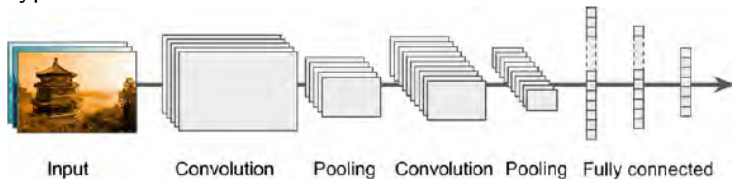
max pooling, 2x2, stride 2, no padding

Why not simply use fully connected layers

- ▶ Image 100x100. First dense layer 1000 neurons (Obs: it restricts the amount of information transmitted to the next layer) $\rightarrow 10^7$ parameters for only one layer!!!
- ▶ the learnt patterns are translation invariants: a certain pattern can be recognized anywhere
- ▶ cnn can learn hierarchies of patterns

Time for notebook

Typical CNN architecture



Pooling effect on FMNIST

Transfer knowledge (ImageNet) - fmnist

Data augmentation - dogs/cats

Covid radiology