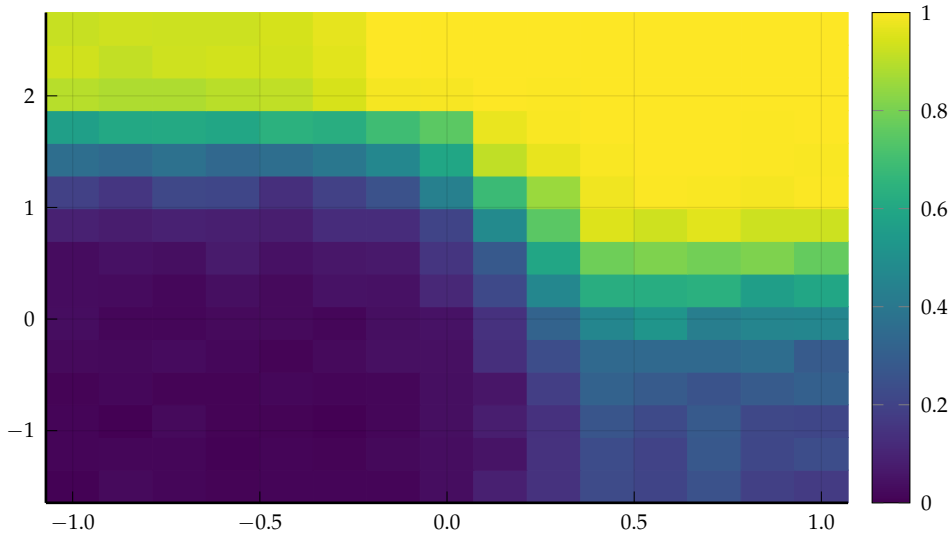


Bound on Longitudinal Acceleration ( $\text{m/s}^2$ )

Failure Rate



Bound on Position Noise (m)