

Byoungkwon An (Kwon An)

CONTACT INFORMATION	Westwind way McLean, VA USA	Phone: (617) 335-1680 Email: dran@csail.mit.edu Web: www.drancom.com	
EDUCATION	Massachusetts Institute of Technology , Cambridge, MA, USA S.M. in Computer Science, September 2011 Thesis: Sticker Controller and Programming for Smart Sheets (Self-Folding Sheets) Soongsil University , Seoul, Korea B.A. in Physics, February 2004 Thesis: Scaling of Dynamic Surface Growth Model on Fractal Dimension	Advisor: Daniela Rus Advisor: Jim Min Kim	
PUBLICATIONS	<p>[19] Wang, W. , Chen, S., An, B., Huang, K., Bai, T., Xu, M., Bellot, G., Ke, Y., Xiang, Y., and Wei, B., <i>Complex wireframe DNA nanostructures from simple building blocks</i>, Nature Communications, 10:1067, 2019, pdf</p> <p>[18] An, B., Miyashita, S., Ong, A., Aukes, D., L., Tolley, M., Demaine, E., Demaine, M., Wood, R., Rus, D., <i>An End-to-End Approach to Self-Folding Origami Structures</i>, IEEE Transactions on Robotics, 34(6): 1409-1424, 2018, pdf</p> <p>[17] An, B., Tao, Y., Gu, J., Cheng, T., Chen, X., Zhang, X., Zhao, W., Do, Y., Takahashi S., Wu, H., Zhang, T., Yao, L., <i>Thermorph: Democratizing 4D Printing of Self-Folding Materials and Interfaces</i>, ACM CHI Conference on Human Factors in Computing Systems (CHI), Montreal, QC, Canada, 2018, pdf</p> <p>[16] Wang G., Cheng, T., Do, Y., Yang, H., Tao, Y., Gu, J., An, B., Yao, L., <i>Printed Paper Actuator: A Low-cost Reversible Actuation and Sensing Method for Shape Changing Interfaces</i>, ACM CHI Conference on Human Factors in Computing Systems (CHI), Montreal, QC, Canada, 2018, pdf</p> <p>[15] An, B., Demaine, E., Demaine, M., Ku, J., <i>Computing 3SAT on a Fold-and-Cut Machine</i>, Canadian Conference on Computational Geometry (CCCG), Ottawa, Ontario, Canada, 2017, pdf</p> <p>[14] Han, D., Qi, X., Myhrvold, C., Wang, B., Dai, M., Jiang, S., Bates, M., Liu, Y., An, B.*, Zhang, F.*, Yan, H.*, Yin, P.* (* indicates corresponding authors), <i>Single-Stranded DNA and RNA Origami</i>, Science, Vol. 358, 2017, pdf</p> <p>[13] An, B., Han, D., Bates, M., Zhao, Wei., Wang, M., Tinnus, M., Zyracki, M., Wang, M., Yin, P., <i>Computational Design and Self-Assembly for Single Stranded DNA Origami</i>, Foundations of Nanoscience: Self-Assembled Architectures and Devices (FNANO), 2016, abstract, selected oral presentation</p> <p>[12] Miyashita, S., DiDio, I., Ananthabhotla, I., An, B., Sung, C., Arabagi, S., Rus D., <i>Folding Angle Regulation by Curved Crease Design for Self-Assembling Origami Propellers</i>, Journal of Mechanisms and Robotics (JMR), 2015, pdf</p> <p>[11] Niiyama., R., Sun, X., Sung, C., An, B., Rus, D., Kim, S., <i>Pouch Motors: Printable Soft Actuators Integrated with Computational Design</i>, Soft Robotics, 2015, pdf</p> <p>[10] Khosla, A., An, B., Lim, J., Torralba, A., <i>Looking Beyond the Visible Scene</i>, IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2014, equal contribution, pdf</p> <p>[9] An, B., Miyashita, S., Tolley, M., Aukes, D., Meeker, L., Demaine, E., Demaine, M., Wood, R., Rus, D., <i>An End-to-End Approach to Making Self-Folded 3D Surface Shapes by Uniform Heating</i>, IEEE International Conference on Robotics and Automation (ICRA), 2014, pdf video</p> <p>[8] An, B., Rus, D., <i>Designing and Programming Self-Folding Sheets</i>, Robotics and Autonomous Systems, 2014, pdf video</p> <p>[7] Mehta, A., Bezzoy N., An, B., Gebhardy, P., Lee, I., Kumary, V., Rus, D., <i>A Design Environment for the Rapid Specification and Fabrication of Printable Robots</i>, International Symposium on Experimental Robotics (ISER), 2014, pdf</p> <p>[6] An, B., Rus, D., <i>Programming and Controlling Self-Folding Robots</i>, IEEE International Conference on Robotics and Automation (ICRA), 2012, pdf</p>		

- [5] **An, B.**, Benbernou, N., Demaine, E., Rus, D., *Planning to Fold Multiple Objects from a Single Self-Folding Sheet*, Robotica, 29(1): 87-102, 2011, *pdf*
- [4] Paik, J., **An, B.**, Rus, D., Wood, R., *Robotic Origamis: Self-Morphing Modular Robots*, International Conference on Morphological Computation (ICMC), 2011, *pdf*
- [3] Hawkes, E., **An, B.**, Benbernou, N., Tanaka, H., Kim, S., Demaine, E., Rus, D., Wood, R., *Programmable Matter by Folding*, Proceedings of the National Academy of Sciences (PNAS), 107(28): 12441-12445, 2010, *pdf video*
- [2] **An, B.**, Rus, D., *Making Shapes from Modules by Magnification*, IEEE/RSJ International Conference on Intelligent Robots and System (IROS), 2010, *pdf video*
- [1] **An, B.**, *EM-Cube: Cube-shaped, Self-Reconfigurable Robots Sliding on Structure Surface*, IEEE International Conference on Robotics and Automation (ICRA), 2008, *pdf video1 video2*

RESEARCH EXPERIENCE	Computer Science and Artificial Intelligence Lab, MIT	2017
	<i>Visiting Scholar, Advisor Erik Demaine</i>	
	Morphing Matter Lab, CMU	2017
	<i>Research Affiliate, Advisor Lining Yao</i>	
	Autodesk Research	2014 – 2017
	<i>Principal Research Scientist</i>	
	Computer Science and Artificial Intelligence Lab, MIT	
TEACHING EXPERIENCE	<i>Visiting Alumni Scholar, Advisor Daniela Rus</i>	2011 – 2014
	<i>Graduate Research Assistant, Advisor Daniela Rus</i>	2008 – 2011
	Nanophysics Lab, Korea University	2005 – 2006
	<i>Research Engineer, Advisor Se-Jong Kahng</i>	
	Statistical Physics Lab, Soongsil University	2002 – 2003
	<i>Undergrad Research Assistant, Advisor Jin Min Kim</i>	
	Software Engineering Lab, Soongsil University	2001
WORK EXPERIENCE	<i>Undergrad Research Assistant, Advisor Nam-Yong Lee</i>	
	Computational Physics, Physics Department, Soongsil University	2003
	<i>Teaching Assistant</i>	
	Co-Founder, Bashan Networks Co.	2001 – 2003
	<ul style="list-style-type: none"> Founded software engineering consulting company with Professor Nam-Yong Lee Established partnership with IBM Rational Software to share consulting and education expertise Consulted and trained on object-oriented analysis and design (OOAD), and software architecture for government institutes and companies, including the Institute of Information Technology Advancement in the Ministry of Information and Communication of Korea, and Hyundai Motor Company 	
	Co-Founder, IFCOM Tec.	1999 – 2001
	<ul style="list-style-type: none"> Designed and developed a distributed system of information sharing, internet broadcast and communication for investment and securities companies Designed and developed a distributed system of interactive internet broadcast 	
ART EXHIBITION	An, B. and Rus, D., <i>Self-Folding Sheet</i> , Modern By Design, Atlanta High Museum of Art, GA	2011
	An, B. et al., <i>Programmable Matter Design Pipeline</i> , Programmable Materials, MIT Keller Gallery, MA	2015
HONORS AND AWARDS	2nd Place for <i>1st Planetary Contingency Challenge</i> , IEEE International Conference on Robotics and Automation, Pasadena, CA, USA, 2008	
	<i>Best Undergraduate Thesis</i> , Physics Department, Soongsil University, 2003	
	<i>Four Year Full Tuition Scholarship</i> , Soongsil University, 1999	
PROFESSIONAL ACTIVITY	Reviewer , IEEE International Conference on Robotics and Automation (ICRA)	2010 – 2016

PATENT

An, B., *FET (Field Effect Transistor) Nerve Electronic Chip*, 10-0765960, KR, 2006

MEDIA

COVERAGE
(SELECTED)

MIT News (MIT Main), *Bake Your Own Robot*, May 30, 2014

NBC News, *Right Out of the Oven: MIT Scientists Bake Self-Building Origami Robots*, May 30, 2014

Science Daily, *New printable robots could self-assemble when heated*, May 30, 2014

CNN, *Edge of Discovery, Transformers could be a reality!*, June 1, 2011

MIT News (MIT Main), *Shape-Shifting Robots*, August 4, 2010

Discovery News, *Origami Robot Makes Shapes on Demand*, July 7, 2010

CNET, *Robotics meet origami in self-folding sheets*, June 29, 2010

Nature News, *Origami that folds itself*, June 28, 2010

MSNBC, *Programmable matter may shape future tools*, June 28, 2010

Popular Science, *Video: Smart Sheets Can Self-Assemble Into Airplanes, Boats*, June 28, 2010

Phys.org, *Shape-shifting sheets automatically fold into multiple shapes*, June 28, 2010

Harvard Gazette, *Shape-shifting sheets automatically fold into multiple shapes*, June 28, 2010