

# Byoungkwon An (Kwon An)

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## CONTACT INFORMATION

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## EDUCATION

**Duke University**, Durham, NC, USA  
Ph.D. Student in Computer Science, 2017 - Present

**Massachusetts Institute of Technology**, Cambridge, MA, USA  
S.M. in Computer Science, September 2011

Advisor: Daniela Rus

Thesis: Sticker Controller and Programming for Smart Sheets (Self-Folding Sheets)

**Soongsil University**, Seoul, Korea  
B.A. in Physics, February 2004

Advisor: Jim Min Kim

Thesis: Scaling of Dynamic Surface Growth Model on Fractal Dimension

## PUBLICATIONS

[18] **An, B.**, Miyashita, S., Ong, A., Aukes, D., L., Tolley, M., Demaine, E., Demaine, M., Wood, R., Rus, D., *An End-to-End Approach to Self-Folding Origami Robots by Uniform Heat*, IEEE Transactions on Robotics, Accepted

[17] **An, B.**, Tao, Y., Gu, J., Cheng, T., Chen, X., Zhang, X., Zhao, W., Do, Y., Takahashi S., Wu, H., Zhang, T., Yao, L., *Thermorph: Democratizing 4D Printing of Self-Folding Materials and Interfaces*, ACM Computer-Human Interaction (CHI), Montreal, Canada, 2018, *pdf*

[16] Wang G., Cheng, T., Do, Y., Yang, H., Tao, Y., Gu, J., **An, B.**, Yao, L., *Printed Paper Actuator: A Low-cost Reversible Actuation and Sensing Method for Shape Changing Interfaces*, ACM Computer-Human Interaction (CHI), Montreal, Canada, 2018, *pdf*

[15] **An, B.**, Demaine, E., Demaine, M., Ku, J., *Computing 3SAT on a Fold-and-Cut Machine*, Canadian Conference on Computational Geometry (CCCG), Ottawa, Ontario, Canada, 2017, *pdf*

[14] Han, D.<sup>+</sup>, Qi, X.<sup>+</sup>, Myhrvold, C., Wang, B., Dai, M., Jiang, S., Bates, M., Liu, Y., **An, B.\***, Zhang, F.\*, Yan, H.\*, Yin, P.\* (\* indicates corresponding authors), *Single-Stranded DNA and RNA Origami*, Science, Vol. 358, 2017, *pdf*

[13] **An, B.**, Han, D., Bates, M., Zhao, Wei., Wang, M., Tinnus, M., Zyracki, M., Wang, M., Yin, P., *Computational Design and Self-Assembly for Single Stranded DNA Origami*, Foundations of Nanoscience: Self-Assembled Architectures and Devices (FNANO), 2016, abstract, **selected oral presentation**

[12] Niiyama., R., Sun, X., Sung, C., **An, B.**, Rus, D., Kim, S., *Pouch Motors: Printable Soft Actuators Integrated with Computational Design*, Soft Robotics, 2015, *pdf*

[11] Miyashita, S., DiDio, I., Ananthabhotla, I., **An, B.**, Sung, C., Arabagi, S., Rus D., *Folding Angle Regulation by Curved Crease Design for Self-Assembling Origami Propellers*, Journal of Mechanisms and Robotics (JMR), 2015, *pdf*

[10] Khosla, A., **An, B.**, Lim, J., Torralba, A., *Looking Beyond the Visible Scene*, IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2014, equal contribution, *pdf*

[9] **An, B.**, Miyashita, S., Tolley, M., Aukes, D., Meeker, L., Demaine, E., Demaine, M., Wood, R., Rus, D., *An End-to-End Approach to Making Self-Folded 3D Surface Shapes by Uniform Heating*, IEEE International Conference on Robotics and Automation (ICRA), 2014, *pdf video*

[8] Mehta, A., Bezzoy N., **An, B.**, Gebhardy, P., Lee, I., Kumary, V., Rus, D., *A Design Environment for the Rapid Specification and Fabrication of Printable Robots*, International Symposium on Experimental Robotics (ISER), 2014, *pdf*

[7] **An, B.**, Rus, D., *Designing and Programming Self-Folding Sheets*, Robotics and Autonomous Systems, 2014, *pdf video*

[6] **An, B.**, Rus, D., *Programming and Controlling Self-Folding Robots*, IEEE International Conference on Robotics and Automation (ICRA), 2012, *pdf*

- [5] **An, B.**, Benbernou, N., Demaine, E., Rus, D., *Planning to Fold Multiple Objects from a Single Self-Folding Sheet*, Robotica, 29(1): 87-102, 2011, *pdf*
- [4] Paik, J., **An, B.**, Rus, D., Wood, R., *Robotic Origamis: Self-Morphing Modular Robots*, International Conference on Morphological Computation (ICMC), 2011, *pdf*
- [3] Hawkes, E., **An, B.**, Benbernou, N., Tanaka, H., Kim, S., Demaine, E., Rus, D., Wood, R., *Programmable Matter by Folding*, Proceedings of the National Academy of Sciences (PNAS), 107(28): 12441-12445, 2010, *pdf video*
- [2] **An, B.**, Rus, D., *Making Shapes from Modules by Magnification*, IEEE/RSJ International Conference on Intelligent Robots and System (IROS), 2010, *pdf video*
- [1] **An, B.**, *EM-Cube: Cube-shaped, Self-Reconfigurable Robots Sliding on Structure Surface*, IEEE International Conference on Robotics and Automation (ICRA), 2008, *pdf video1 video2*

RESEARCH EXPERIENCE	<b>Computer Science Department</b> , Duke University <i>Graduate Research Assistant, Advisor John Reif</i>	2017 – Present
	<b>Autodesk Research</b> <i>Principal Research Scientist</i>	2014 – 2017
	<b>Computer Science and Artificial Intelligence Lab</b> , MIT <i>Visiting Alumni Scholar, Advisor Daniela Rus</i>	2011 – 2014
	<i>Graduate Research Assistant, Advisor Daniela Rus</i>	2008 – 2011
	<b>Nanophysics Lab</b> , Korea University <i>Research Engineer, Advisor Se-Jong Kahng</i>	2005 – 2006
	<b>Statistical Physics Lab</b> , Soongsil University <i>Undergrad Research Assistant, Advisor Jin Min Kim</i>	2002 – 2003
	<b>Software Engineering Lab</b> , Soongsil University <i>Undergrad Research Assistant, Advisor Nam-Yong Lee</i>	2001
TEACHING EXPERIENCE	<b>Computational Physics</b> , Physics Department, Soongsil University <i>Teaching Assistant</i>	2003
WORK EXPERIENCE	<b>Co-Founder, Bashan Networks Co.</b>	2001 – 2003
	<ul style="list-style-type: none"> <li>• Founded software engineering consulting company with Professor Nam-Yong Lee</li> <li>• Established partnership with IBM Rational Software to share consulting and education expertise</li> <li>• Consulted and trained on object-oriented analysis and design (OOAD), and software architecture for government institutes and companies, including the Institute of Information Technology Advancement in the Ministry of Information and Communication of Korea, and Hyundai Motor Company</li> </ul>	
	<b>Co-Founder, IFCOM Tec.</b>	1999 – 2001
	<ul style="list-style-type: none"> <li>• Designed and developed a distributed system of information sharing, internet broadcast and communication for investment and securities companies</li> <li>• Designed and developed a distributed system of interactive internet broadcast</li> </ul>	
ART EXHIBITION	<b>An, B.</b> and Rus, D., <i>Self-Folding Sheet</i> , Modern By Design, Atlanta High Museum of Art, GA	2011
	<b>An, B.</b> et al., <i>Programmable Matter Design Pipeline</i> , Programmable Materials, MIT Keller Gallery, MA	2015
HONORS AND AWARDS	2nd Place for <i>1st Planetary Contingency Challenge</i> , IEEE International Conference on Robotics and Automation, Pasadena, CA, USA, 2008	
	<i>Best Undergraduate Thesis</i> , Physics Department, Soongsil University, 2003	
	<i>Four Year Full Tuition Scholarship</i> , Soongsil University, 1999	
PROFESSIONAL ACTIVITY	<b>Reviewer</b> , IEEE International Conference on Robotics and Automation (ICRA)	2010 – 2016
	<b>Reviewer</b> , Robotica, Cambridge Journal,	2014
PATENT	<b>An, B.</b> , <i>FET (Field Effect Transistor) Nerve Electronic Chip</i> , 10-0765960, KR, 2006	

MEDIA  
COVERAGE  
(SELECTED)

MIT News (MIT Main), *Bake Your Own Robot*, May 30, 2014  
NBC News, *Right Out of the Oven: MIT Scientists Bake Self-Building Origami Robots*, May 30, 2014  
Science Daily, *New printable robots could self-assemble when heated*, May 30, 2014  
CNN, *Edge of Discovery, Transformers could be a reality!*, June 1, 2011  
MIT News (MIT Main), *Shape-Shifting Robots*, August 4, 2010  
Discovery News, *Origami Robot Makes Shapes on Demand*, July 7, 2010  
CNET, *Robotics meet origami in self-folding sheets*, June 29, 2010  
Nature News, *Origami that folds itself*, June 28, 2010  
MSNBC, *Programmable matter may shape future tools*, June 28, 2010  
Popular Science, *Video: Smart Sheets Can Self-Assemble Into Airplanes, Boats*, June 28, 2010  
Phys.org, *Shape-shifting sheets automatically fold into multiple shapes*, June 28, 2010  
Harvard Gazette, *Shape-shifting sheets automatically fold into multiple shapes*, June 28, 2010