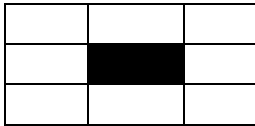


GIS5572 Quiz 2

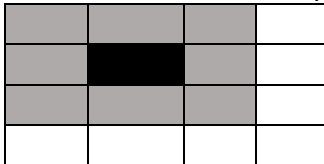
1. What do rasters and spacetime cubes have in common?
 - Both illustrate data values in grid space
2. How are rasters and spacetime cubes different?
 - Rasters can just show coordinates and values
 - Spacetime cubes can show those coordinates and values through time
 - Stacked rasters, essentially
 - So, the dimensionality is higher in cubes.
 - Operations are extended to 3d space
3. What is map algebra?
 - Applying mathematical or Boolean operations to single or multiple map rasters to produce values for analysis
4. Who created map algebra?
 - Dana Tomlin
5. What are local operations in map algebra? (provide a picture)

- Operations on a fixed pixel



6. What are focal operations in map algebra? (provide a picture)

- Operations in a fixed neighborhood of pixel



7. What are zonal operation in map algebra? (provide a picture)

- Operations based on predefined zones



8. What does TIN stand for and what is it?
 - Triangular irregular network. Used to show a continuous elevated surface contours using triangles between data points. Vector
9. What is a terrain?
 - TIN based surface that shows 3D values, can be derived into a TIN and vice versa

10. How is a terrain different from a TIN?

- Data Type: TINs are vectors, Terrains are rasters. Terrains derive Tins on the fly.

11. Describe a basic suitability model (e.g. data flow diagram with operations) to identify a housing location for Jacob. Jacob is terrified of heights or sudden drop offs, but he loves to live Minneapolis and wants to be along the river.

- Define pixels nearer to river as higher values. 1 @ river
- Define pixels higher up as lower values 1 @ river level
- Define pixels with steep slope as lower values. 1 @ zero slope, towards zero as increases up/down
- Pixels in Minneapolis have higher values. 1 in, 0 out
- Standardize to same scale values
- Add rasters together
- Find highest value

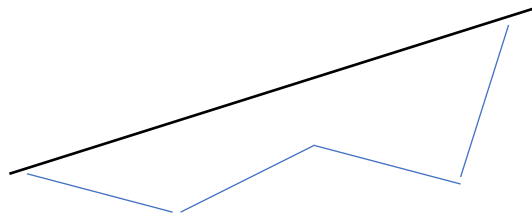
12. What type of suitability model did you choose? Why?

- Rate suitable options
- Weighted rasters are used, not true/false logic. None of the statements seem like complete absolutes, though I suppose they could be defined that way. 'Steep slope' sort of has a range of values inside it.

13. What is a cost surface?

- Raster grid illustrating the cost to move through each cell based on added rasters of each factor

14. How is a cumulative distance different from Euclidean or straight-line distance?



Black line is Euclidian, blue is cumulative. There are many cumulative. Cumulative is distance covered, Euclidean is straight line distance. I.e., you have to go around a lake (cumulative), not straight through (Euclidean)

15. Describe the general data flow model for

calculating a least cost path analysis from a start and end points

- Reclassify all rasters to be included, ie, height and water to common scale to find equivalent costs for each raster.
- Overlay all of these reclassified rasters to build a cost surface
- Define a route origin point and use it with the cost surface in a cost accumulation function, and to create a back raster
- Define a route destination point and use it with both the back raster and cost accumulation output in optimal path function
- Output: final route