# EC 440 – Introduction to Operating Systems

Orran Krieger (BU) Larry Woodman (Red Hat)

# **Today's lecture**

- The real world deadlock and synchronization in Linux
- Review of synchronization and Deadlock
- Fun programming (at least for Orran)

# **Today's lecture**

- Short review of synchronization
- The real world deadlock and synchronization in Linux
- Fun programming (at least for Orran)

#### **Review: Deadlocks**

When processes try to acquire resources concurrently they may end up "stuck"

#### Example:

- 1. Process A needs P, Q
- 2. Process B needs Q, P
- 3. Process A gets P
- 4. Process B gets Q
- 5. Process A tries to get Q and blocks
- 6. Process B tries to get P and blocks

#### **Review: Livelock**

- Sometimes processes can never be deadlocked, but still not make progress
- Consider this algorithm, they keep running... but, it is possible for neither to ever make progress
- Lots of real examples of this in OS, e.g. with two phased locking

```
void process_A(void) {
     acquire_lock(&resource_1);
     while (try_lock(&resource_2) == FAIL) {
         release_lock(&resource_1);
         wait_fixed_time();
         acquire_lock(&resource_1);
     use_both_resources();
     release_lock(&resource_2);
     release_lock(&resource_1);
void process_A(void) {
     acquire_lock(&resource_2);
     while (try_lock(&resource_1) == FAIL) {
         release_lock(&resource_2);
         wait_fixed_time();
         acquire_lock(&resource_2);
     use_both_resources();
     release_lock(&resource_1);
     release_lock(&resource_2);
```

#### **Review: Lock Starvation**

- A process never receives the lock it is waiting for, despite the resource (repeatedly) becoming free, the resource is always allocated to another waiting process or CPU.
- For blocking locks(semaphores and mutexes) scheduler is involved so is usually a priority issue.
  - Solution usually involves scheduling priority adjustment or finer granularity locks.
- For spinlocks non-uniform memory or cache placement is usually the issue.
  - Solution usually involves ticketed spinlocks, MCS locks, per-cpu or per numa node locks.
  - Even better is lockless code/RCU

# **Linux Locking and Synchronization**

## Linux user space deadlocks

- Linux uses the "Ostrich" approach to solving user deadlocks.
  - processes with user code deadlocks and livelocks get penalized by the scheduler.
  - starved processes will get rewarded by the scheduler.
  - Otherwise if user code is "stuck" dont do anything except support SIGKILL.
  - Resources are limited to user code:
    - excessive allocation will fail
    - worse case scenario is process gets killed by kernel.

# Linux kernel approach to deadlocks

- Linux takes prevention approach to kernel deadlocks, lovelocks and starvation.
  - Primary focus is on prevention and lockless algorithms(RCU) in the Linux kernel.
  - Locks have a strict hierarchy and must be taken in correct order.
  - Kernel protects itself by throttling(failure to allocate more) and ultimately by process killing.
    - Resource issues arise on kernel data structures, e.g., task table, inode table.

# Locking In the Linux kernel

- semaphores/counting semaphores
  - multiple count resources blocking
  - example: free objects on a list
- mutexes
  - can be reader/writer
  - single count resources blocking
  - example: file access
- spinlocks
  - can be reader/writer
  - reader: multiple access non-blocking
  - writer: single access non-blocking
  - can not block with spinlock held
- atomic operations
  - incrementing/decrementing counters
- RCU
  - read copy update

# Linux Kernel examples

- spinlocks: non-blocking/busy-wait
  - simple spinlock: spinlock\_t
    - spinlock(), spinlock\_irq(), spin\_trylock(), spin\_unlock
  - nested spinlock: nested\_spinlock\_t
    - spinlock(), spinlock\_irq(), spin\_trylock(), spin\_unlock
  - reader/writer spinlock: rw\_spinlock\_t
    - spin\_readlock(), spin\_writelock(), spinunlock()
- mutex & semaphores: blocking/waiting
  - simple mutex/semaphore: mutex\_t/semaphore\_t
    - down(), down\_try(), up()
  - nested mutex: nested\_mutex\_t
    - down(), down\_try(), up()
  - reader/writer mutex rw\_mutex\_t
    - downread(), downwrite(), up()

#### **Detection in the Linux Kernel**

#### Deadlock

one or more processes permanently stuck on spinlock(set-and-test) without making progress.
default behavior: console message/panic if no reschedule in 30s and PC doesnt change.

#### Livelock

one or more processes permanently stuck in a loop not making any progress.
default behavior: console message/panic if no reschedule in 60s but the PC does change.

#### Starvation

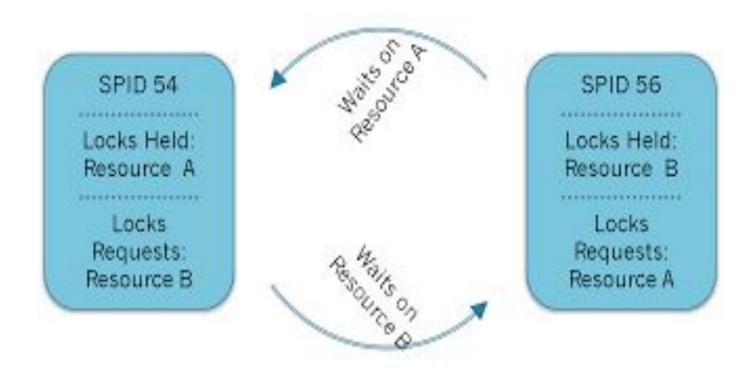
One or more processes never getting CPU time even though they are runnable.

One or more CPUs stuck on a spinlock without ever

acquiring it.
default behavior: SIGKILL if no reschedule in 120s and PC doesnt change but other CPUs get spinlock.

#### Deadlock

• One or more process permanently stuck is a "deadly embrace"



#### deadlocks In the Linux kernel

- Multi thread
  - thread A locks resource X
  - thread B lock resource Y
  - thread A attempts to lock resource Y
  - thread B attempts to lock resource X
- Single thread
  - thread A calls procedure M which locks resource X
  - procedure M calls procedure N which attempts to lock resource X
- Interrupt handling
  - thread A locks resource X
  - interrupt occurs
  - ISR attempts to lock resource X
- livelocks versus deadlocks
  - deadlock: stuck on a single lock
  - livelock: looping down and up a potentially long call chain.

# Linux lock hierarchy

Lock types in Linux kernel are ordered from 1 to N
Low numbered/ordered locks are coarser than high numbered locks and must be acquired first example:

task\_list\_lock protect a list of struct\_tasks
 task\_lock protects an individual struct\_task
 order of task\_list\_lock < order of task\_lock</li>
 a. lock(task\_list\_lock);
 b. lock\_task(&task-being-locked);

- If you need lock A of order 1 and lock B of order 2 you must:
  - lock(A) before lock(B)
  - lock(B) then trylock(A)

- You must unlock in reverse locking order
  lock(A) lock(B) ... unlock(B) unlock(A)
  lock(B) trylock(A) ... unlock(B) unlock(A)
- Well documented in ./GIT/linux/linux/Documentation/locking

#### Multi-thread deadlocks

- Spinlocks are ordered
- X > Y > Z
- kernel locks are ordered in terms of scope
  - X scope is a superset of Y scope
  - Y scope is a superset of Z scope
- X must be locked before Y which must be locked before Z
  - thread A locks resource X
  - thread B attempts to lock resource X
  - thread A locks resource Y
  - thread A releases locks Y then X
  - thread B is granted resource X
  - thread B locks resource Y
  - thread B releades locks Y then X

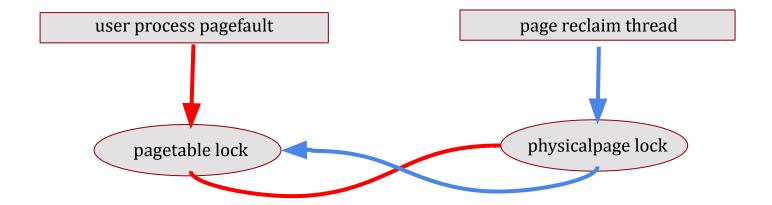
#### Multi-thread deadlocks

- user process 1 simple pagefault:
  - 1. Locate and acquire pagetable\_lock
  - acquire physical pagelock
     multi-threaded deadlock
  - multi-threaded deadlock

- kernel page reclaim thread 2:
  - 1. locate physical page and acquire pagelock
  - 2. acquire owning process pagetable\_lock
  - 3. multi-threaded deadlock

- Solution 1:
  - page reclaim thread does trylock(pagetable\_lock)
- Solution 2:
  - Both processes/threads acquire in correct order
    - 1. pagetable\_lock
    - 2. physical pagelock

#### Multi-thread deadlocks



#### Single threaded deadlocks

Thread A calls procedure M which locks resource X procedure M calls procedure N which attempts to lock resource X

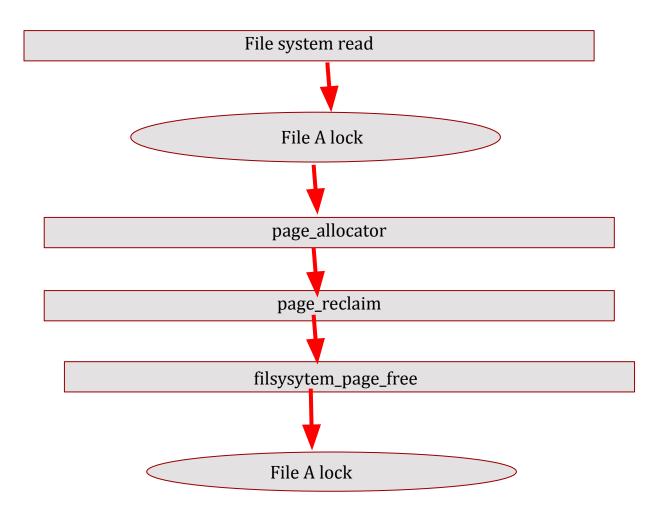
- Solution:
  - recursive locks:
    - Thread A is granted the same lock multiple times in a call chain
      - each lock attempt increments a depth count
      - each unlock decrements a depth count
    - Thread A calls M which locks recursive lock X
      - lock X is acquired, depth count incremented to 1
    - M calls N which locks recursive lock X
      - depth count is incremented to 2
    - N unlocks X
      - depth count is decremented to 1
    - N returns to M
      - depth count is decremented to 0, X is unlocked

# Single threaded deadlock example

- 1. Filesystem read operation locks file A
- 2. Filesystem read needs page, calls page allocator
- 3. Page allocator calls page reclaim code
- 4. Page reclaim code calls filesystem to free a page in file A
- 5. Filesystem freeing routine locks file A
- 6. Single threaded DEADLOCK

Solution: make filelock a recursive/nested lock.

# Single threaded deadlock example



## Interrupt deadlocks

#### Interrupt handling:

thread A locks resource X interrupt occurs ISR attempts to lock resource X

- Solution:
  - spinlock\_IRQ()/spinunlock\_IRQ()
    - disable interrupts before acquiring lock X
    - unlock X then enable interrupts
      - thread A does spinlock\_IRQ(X)disable interrupts then locks X
        - interrupts are blocked
      - thread A runs than does spinunlock\_IRQ(X)unlock X then enables interrupts
      - interrupt occurs» ISR locks X, runs then unlock X

#### Interrupt deadlocks

- Timer routine acquires timer queue lock
- Timer routine inserts task in timer queue
- Clock hardware interrupt occurs
- Clock ISR acquires timer queue lock

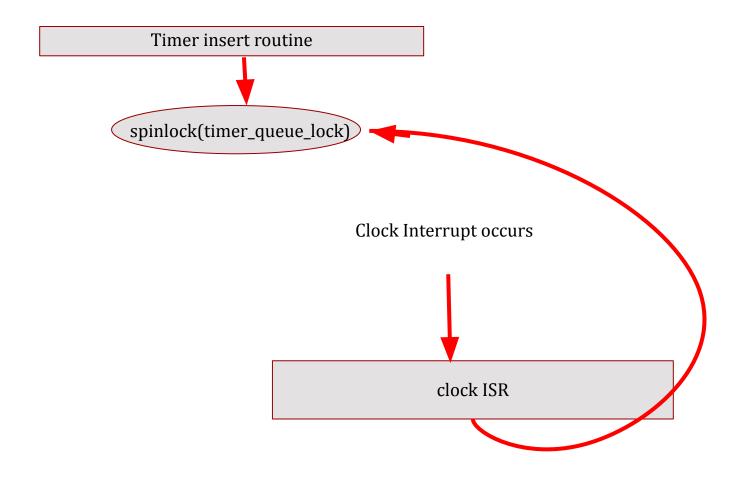
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DEADLOCK

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Solution: use spinlock\_IRQ

# Interrupt deadlocks



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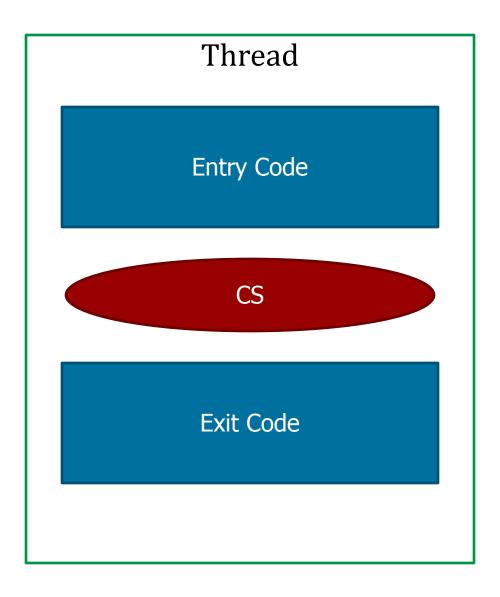
#### Race conditions

- Asynchronous events occur all the time:
  - Interrupt: e.g., timer, device, ...
  - Threads running asynchronously on different cores
- Race is when result depends on order of asynchronous operation
- Race is a bug if result is incorrect.

# Introduced Critical Regions and Mutual Exclusion

- The part of the program where shared memory is accessed is called a *critical region* (or *critical section*)
- Critical regions should be accessed in mutual exclusion
- Solution: Synchronization
  - 1. No two processes may be simultaneously inside the same critical region
  - 2. No process running outside the critical region should block another process
  - 3. No process should wait forever to enter its critical region
  - 4. No assumptions can be made about speed/number of CPUs

# **Introduced Critical Regions**



# Locking

- Busy waiting on variable doesn't work...
   why?
  - if a thread reads lock, then writes, what if asynchronous event happens between
- Peterson's algorithm lets you take turns
- Hardware today supports atomic operations to let you read variable and write it atomically
- Now we can busy wait on lock... what's the problem with that?

# Sleep, wakeup, semaphores

- Sleep and wakeup frees processors, what's the problem?
  - Sleep is not atomic...
- Semaphores:
  - P() or down() decrement counter if > 0, else block atomically
  - V() or up() increment counter and atomically wake process if was 0 and any blocked
- Examples, simple race and producer consumer

#### **Monitors**

- Programing language construct in Concurrent Pascal, Modula-2, Concurrent Euclid and Java:
  - Collection of code where only one thread can be active at a time.
  - Can wait and signal condition variables
- Hugely simplifies code, but:
  - Limits concurrency
  - Requires language level support

# **Examples**

- Consumer producer implemented in semaphores and monitor
- Classic Dining philosophers problem
  - Lock per chopstick can result in deadlock
  - Use trylock can result in starvation
  - Can have one big lock can limit concurrency
  - More complicated example:
    - no deadlock, no starvation, many philosophers can be picking up chopsticks at the same time

#### **Fourth Solution**

```
philosopher(i) {
                        take_chopsticks(i) {
                                                    put_chopsticks(i) {
  think();
                          mutex.down();
                                                      mutex.down();
                                                      state[i] = THINKING;
  take chopsticks(i);
                          state[i] = HUNGRY;
                                                      test((i + 1) % N);
 eat();
                          test(i);
                                                      test((i + N - 1) \% N);
  put_chopsticks(i);
                          mutex.up();
                          philosopher[i].down();
                                                      mutex.up();
test(i) {
  if (state[i] == HUNGRY && state[(i + 1) % N] != EATING &&
                        state[(i + N - 1) % N] != EATING) {
         state[i] = EATING;
         philosopher[i].up();
```

#### The real world

- Processors have caches
- Moving cache lines between the cores expensive
- What we do:
  - Fine grained locks embedded in data
  - Scalable locks: ticketed spin locks, MCS locks
  - Read Copy Update avoid locks all together

## **Deadlock?**

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