Construction of DC-DC Converters Fuzzy Models

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Takagi-Sugeno Fuzzy Model

The design procedure begins with representing a given non-linear plant by the Takagi-Sugeno fuzzy model. This model is characterized by fuzzy IF-THEN rules which describe local linear input-output relations of a non-linear system. The TS Fuzzy model expresses the local dynamics of each fuzzy rule using a linear system model, while the global model is achieved by combining these linear system models

The *i*-th fuzzy rules for Continuous Fuzzy Systems (CFS) are of the following forms:

Model Rule i:

IF
$$z_1(t)$$
 is M_{i1} and ... and $z_p(t)$ is M_{ip}
THEN
$$\begin{cases} \dot{x} = A_i x(t) + B_i u(t) \\ y = C_i x, \end{cases}, \quad i = 1, 2, \dots, r.$$

Here, M_{ij} is the fuzzy set and r is the number of model rules; $x(t) \in \mathbb{R}^n$ is the state vector, $u(t) \in \mathbb{R}^m$ is the input vector, $y(y) \in \mathbb{R}^q$ is the output vector, $A_i \in \mathbb{R}^{n \times n}$, $B_i \in \mathbb{R}^{n \times m}$ and $C_i \in \mathbb{R}^{q \times n}$; $z_i(t), \ldots, z_p(t)$ are known premise variables which may be functions of the state variables, external disturbances, and/or time.

Given a pair of (x(t), u(t)), the final outputs of the CFS are inferred as follows:

$$\dot{x} = \frac{\sum_{i=1}^{r} w_i(z(t)) \{A_i x(t) + B_i u(t)\}}{\sum_{i=1}^{r} w_i(z(t))} = \sum_{i=1}^{r} h_i(z(t)) \{A_i x(t) + B_i u(t)\}$$
(1)

$$y(t) = \frac{\sum_{i=1}^{r} w_i(z(t))C_ix(t)}{\sum_{i=1}^{r} w_i(z(t))} = \sum_{i=1}^{r} h_i(z(t))C_ix(t)$$
(2)

where $z(t) = [z_1(t), z_2(t), \dots, z_p(t)],$

$$w_i(z(t)) = \prod_{j=1}^p M_{ij}(z_j(t)), \text{ and}$$
 (3)

$$h_i(z(t)) = \frac{w_i(z(t))}{\sum_{j=1}^r w_i(z(t))},$$
(4)

for all time t. The term $M_{ij}(z(t))$ is the grade of membership of $z_j(t)$ in M_{ij} . Since,

$$\begin{cases} \sum_{i=1}^{r} w_i(z(t)) > 0, \\ w_i(z(t)) \ge 0, \quad i = 1, 2, \dots, r, \end{cases}$$
 (5)

we have,

$$\begin{cases} \sum_{i=1}^{r} h_i(z(t)) > 0, \\ h_i(z(t)) \ge 0, \quad i = 1, 2, \dots, r, \end{cases}$$
 (6)

Buck Converter Fuzzy Model