

Introduction to Drone Technology (IDT)

Module 11 - Maiden Flights

Class Objectives

Primary

1. Run through checklists and conduct flight operations.
2. Fly manually in Position mode
3. Record GPS coordinates for processing and optimising
4. Fly autonomously using mission mode.

Day Schedule

| | |
|--------------------|---|
| 0900 - 0930 | Presentation with Christian |
| 0930 - 0945 | Safety Briefing |
| 0930 - 1010 | Prepare for flight, Ready to go airside |
| 1030 - 1200 | Flight Slot #1 |
| 1200- 1300 | Lunch Break, prepare to go airside |
| 1300 - 1315 | Prepare at flight line |
| 1315 - 1515 | Flight Slot #2 |
| 1515 - 1545 | Debrief, Flight Log Submission |

* = Estimated Time

Airside Rules.

- Same rules as bigger commercial airports (CPH, BLL)
- Guest Pass Visible at all times.
- No Smoking, No alcohol consumption when airside.
- Must be accompanied by Tutor when airside (no bathroom breaks)
- Give way to aircraft.

Flying Rules

- Listen to DPA (Drone-Pilot Assistant) and Tutors at all times
 - Do not take off until cleared to do so
 - Land in a controlled and safe manner.
- Be aware of your surroundings.
- **Do not pass the flight line** until instructed it is safe to do so.
- **Never** Fly over fellow students or persons.
- Notify Tutors and Other Teams if attempting an autonomous flight
- Have Fun!

Safety Gear & Clothing

- Mandatory Safety Gear
 - High Visibility Jacket
 - Hard Hat
 - Safety Goggles
- Appropriate Clothing
 - Warm Jacket
 - Thick Gloves and Socks
 - Decent Shoes

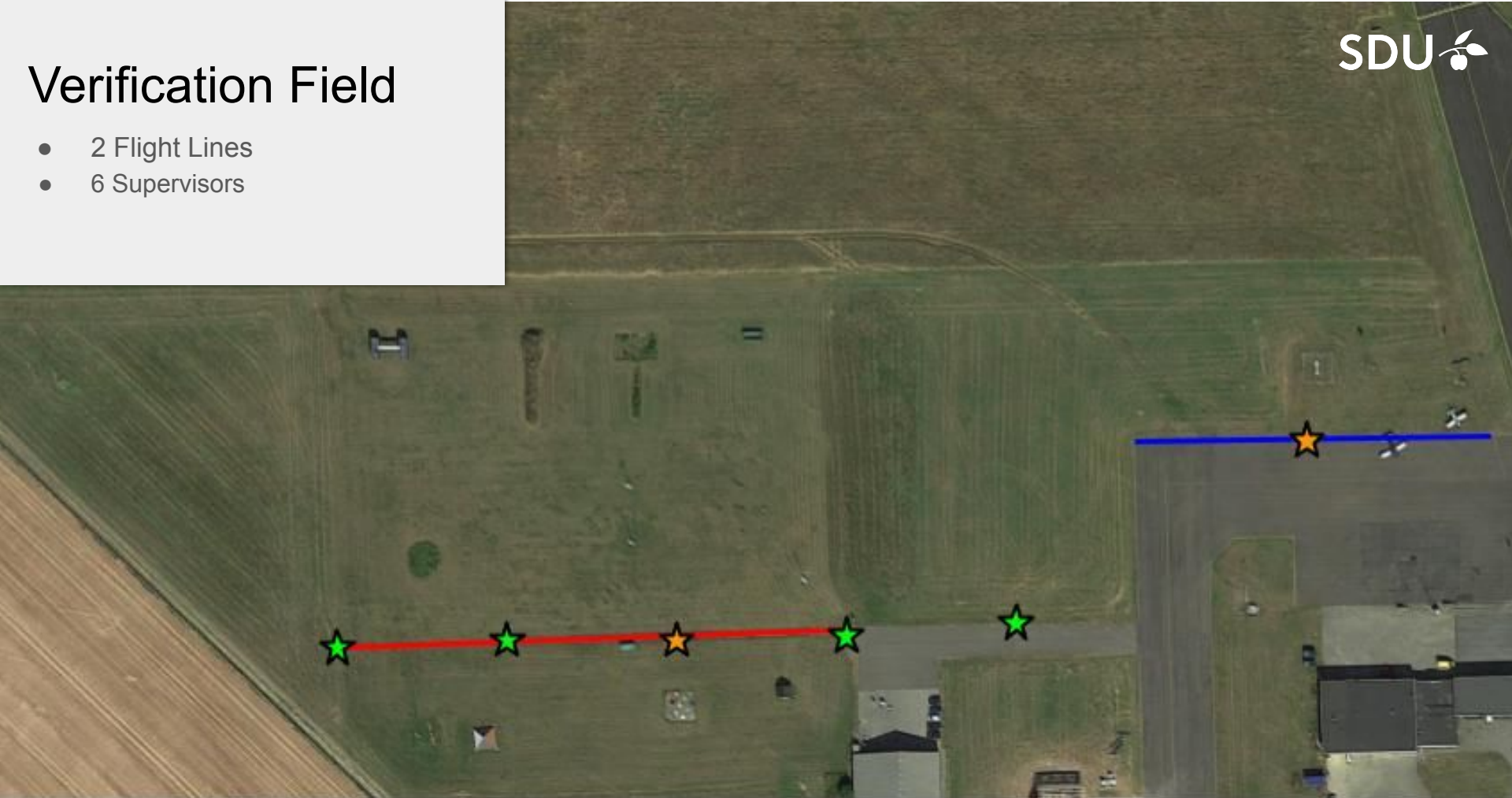
Crashes

- Disarm/ Use Killswitch after crash has occurred.
- Do NOT cross the flight line until safe to do so.
- Take a photo of the crash site before picking up.
- Disconnect battery if possible
- Retrieve all parts before moving from crash site
- Return behind the Flight line before assessing.



Verification Field

- 2 Flight Lines
- 6 Supervisors



Mission Upload

- New node: `idt_mission`
- Requires comma-separated GPS coordinates (Lat, Long, Alt)
- Alternate to use `.plan` files
- Uses current GPS position as takeoff point
- Return to Home behaviour

```
> ros2 run idt upload_mission <path_to_file.txt/.plan>
```

Autonomous Mode

- Notify supervisor before doing auto mode
 - show Supervisor mission plan through QGroundControl
- Arm Drone **manually before** switching to mission mode
- Never arm drone through QGroundControl.

Module 11 Debrief

Group Feedback

How did your flights go?

Did you encounter any problems (or crashes?)

Did you discover anything that is useful for future flights?

Logging

Pilot Log

- Required by law for non-private flights
- Good way to keep track of flight hours

Data

- Date/time
- Weather
- Location
- Drone
- Flight Duration
- Maximum Flight Altitude
- Reason for Flight

| Date | Time (24h) | Drone | Location | Weather | Flight Duration (HH:MM) | Maximum Altititude (m) | Purpose | Remarks |
|------------|------------|-----------------|---------------------------------|--------------------|-------------------------|------------------------|------------------------------|--|
| 06/08/2024 | 10:00 | DJI Mini Pro | Hans Christian Andersen Airport | 20 Degrees | 0:25:00 | 120m | Flight Training | Example Entry |
| 30/08/2024 | 14:00 | Mavic 3 Thermal | Halskenbjerg, Herning | 25 Degrs, No wind | 0:25:00 | 95 | Blueberry Field Inspection | CoffeeDrone Flight |
| 30/08/2024 | 12:30 | Mavic 3 Thermal | Henning Thybo, Arnborg | 25 Degrs, No wind | 0:35:00 | 90 | Potato Field inspection | CoffeeDrone - Flights in proximity to Glider school, avoidance of Tug-planes |
| 30/08/2024 | 11:30 | Mavic 3 Thermal | Halskenbjerg, Herning | 25 Degrs, No wind | 0:30:00 | 95 | Blueberry Field Inspection | CoffeeDrone Flight |
| 03/07/2024 | 13:30 | Mavic 3 Thermal | Dalum Landbrugsskole | 16Degrs, 5m/s Wind | 0:10:00 | 95 | Oats Field Inspection | CoffeeDrone Investigation |
| | | Mavic 3 Thermal | HCA Airport | | 3:00:00 | 50 | Wild Drone sound calibration | |

Logging

Crash Log

- Important for documenting cause of crash
 - Risk mitigation

Data

- Date/time
- Weather
- Location
- Pilot
- Drone
- Cause of crash
- Flight Log
- Pictures

Incident Overview

Incident Date

2024-07-29

Incident Cause

Battery

Review Status

Under Review

Location

HCA Airport (EKOD)

Drone

[12969] - Mavic 2 Pro DJI/Mavic 2 Pro

Project

-

Organization Personnel Involved

Oscar Bowen Schofield

Aircraft Damage

Broken Propeller, Damage to Navigation LEDs (Front Left)

Other Damage

Pilot Pride

Description

(Example)
Drone took off and conducted some aggressive motions to fly to the waypoint. During one of these moves, the battery came loose and ejected from the drone - resulting in a complete loss of power and control of the aircraft

Incursions (people, aircraft...)

Back

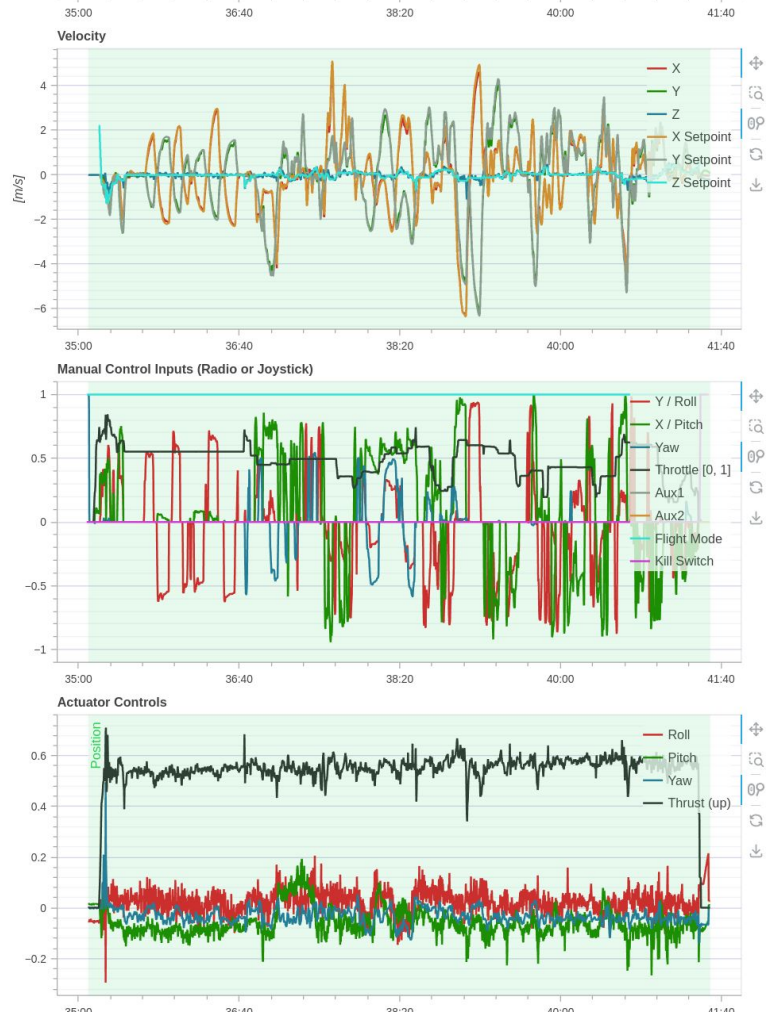
Add

Cancel

Flight Review

During Flight, the Flight Controller saves all information to a ULOG file

- <https://review.px4.io>
- Data can be replayed to look and assess the performance of the drone
- [Example Flight Log](#)



Tasks

1. Download the flight log template and personally fill out piloting
2. Download your flight logs for the day through QGroundControl
 - a. Create a brief text file, outlining pilots for AM/PM sessions, crash event (and who flew)
 - b.
3. Create a zip folder with your group number and upload to itsLearning
4. Visit review.px4.io and upload a flight log from today.
5. Perform any repairs or preparation for next flight.