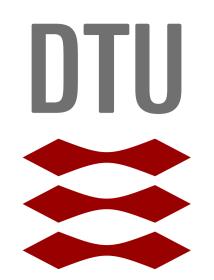
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Methods for image classification

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Case 2 in 02582 Computational Data Analysis

Introduction

Billund images.

Feature extraction approach

The main goal of the hand crafted feature ex-

tractions is to see how well they are to gen-

eralize across locations. The model has been

trained on images from Skive and the test of

generalization are measured on a subset of the

Features: The extracted features were; the

mean value of the Dark channel, the variance

and the squared sum of the Sobel filter values,

the absolute sum and variance of the Laplace

filter and the pct. of overexposed pixels¹. All

features have been adjusted to the size of the

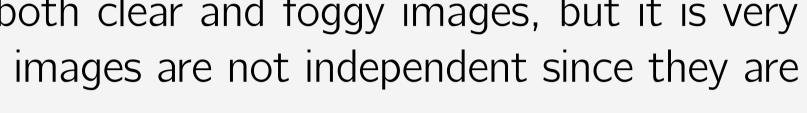
Figure 2 illustrates the properties of the fea-

image to create a standard of reference.

tures by the first and second PCA.

DMI have asked the participants of this course to attempt to classify a number of images of foggy the right is classified as foggy. and clear roads and scenes. Our take on the problem is to test two different methods for classifying the images: A manual extraction of features and a convolutions deep artificial neural network (ANN).

The data sets we have available contains both clear and foggy images, but it is very skewed with about 1.500 foggy images and 150.000 clear images. Additionally there exists duplicates and the images are not independent since they are taken within a short time frame.



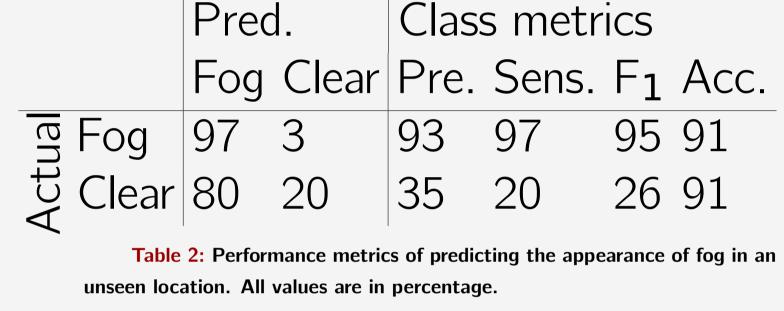
Binary image classification is particularly well *Networks (ConvNets).*

Data preparation: The general concern with this specific data set, was that there was around 100 times more clear images than foggy images. A random subset of the clear images was sampled, equal in size to the foggy.

Network architecture: Considerations were the limited amount of data. Making a



suited for Deep Convolutional Artificial Neural



Feature extraction approach: Table 2 re-

ports the classification metrics from the Billund

Figure f 1: Examples of the data we are working on. The left image is classified as clear and

The RFC does a poor job of detecting the appearance of clear weather in the unseen location. Therefore the generalization of the features is poor and location specific.

too large network prone to over-fitting.

Figures/conv_net_fig-eps-converted-to.pdf

Deep learning approach:

Pred. Class metrics Fog Clear Pre. Sens. F₁ Acc. 87 13 89 89 88 91 89 89

Table 3: Performance metrics of predicting the appearance of fog. All

Clear Fog Figure 2: The first and the second PCA represents 87% of the total

The model: A Random Forrest Classifier (RFC) has been trained on images from Skive. The selection of the hyper-parameters was by a randomized search-grid followed by a thorough search-grid both of which was done by 5-fold CV.

			Class metrics			
	Fog	Clear	Pre.	Sens.	F_1	Acc.
Fog	97	3	93	97	95	91
Actual Clear	0	100	98	100	99	99

Table 1: Performance metrics on the independent test partition. All

The loss function: we are using in the *ConvNet* is *cross-entropy*.

$$C(p,q) = -\sum_{i} p_{i} \log(q_{i}) \qquad (1)$$

Figure 3: Architecture of the convolutional neural network.

$$-y \log(\hat{y}) - (1-y) \log(1-\hat{y})$$
 (2)

Training: was done using a *stochastic gra*dient descent method known as the Adamoptimiser.

Conclusion

Results

images.

The handcrafted features are shown to be location specific and does not generalize to unseen locations. The RFC has an average accuracy of 98.5% on the test set from Skive and an average accuracy of 58.5% on unseen location from Billund.

The ConvNet proved to be quite effective, at an accuracy of 89.0%. It should be mentioned that given the sampling, Billund will very likely be over represented in the training, validation and test data sets.

So In all it seem to be the ANN which is performing best on the data but in order to be certain a bigger dataset and more tests are required.

¹The selected features are inspired by the presented features in "European Study Group with Industry 121" by M. Lyksborg et. al.

