

# Computação Gráfica

*Processamento de Imagens*

(Aula 2)

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# Roteiro

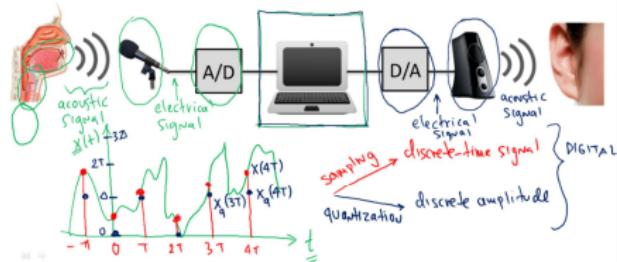
1 Espaço de Cores

2 Práticas

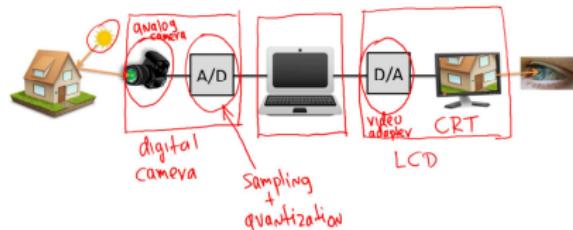
3 Bibliografia



## Analog vs Digital Signals



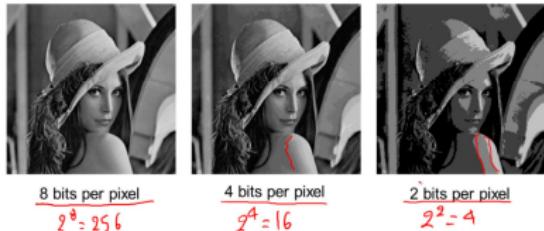
## Analog vs Digital Signals



## Sampling



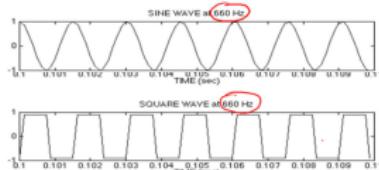
## Quantization



## Images and Videos

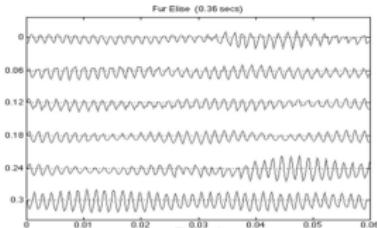
- 1D: tones, speech, audio, biomedical, remote sensing, etc  $s(t)$
- 2D: text, grayscale, color, multispectral, hyperspectral  $s(x, y)$   
images, etc
- 3D: video, 3D volume, etc  $s(x, y, t)$   $s(x, y, z)$
- MD: video of a volume, etc  $s(x, y, z, t)$

## 1D Signals: Tones



J. H. McClellan, R. W. Schafer, and M. A. Yoder, "DSP First: A Multimedia Approach," Prentice Hall, 1998.

## 1D Signal: Piano Piece



J. H. McClellan, R. W. Schafer, and M. A. Yoder, "DSP First: A Multimedia Approach," Prentice Hall, 1998.

## Images

This is a Coursera  
Course on the  
"Fundamentals of  
Digital  
Image and Video  
Processing"

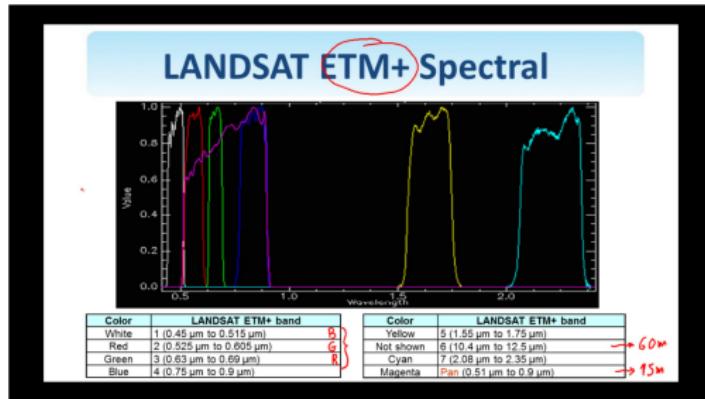
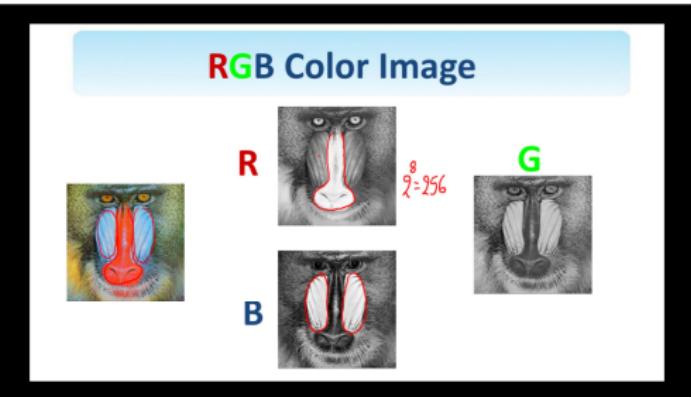
1 bit per pixel



8 bits per pixel

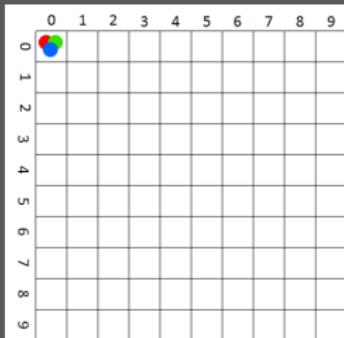


24 bits per pixel



# How do Computers store images?

- OpenCV uses **RGB** color space by default.

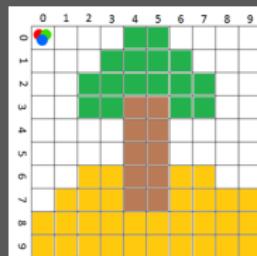


Each pixel coordinate **(x, y)** contains **3** values ranging for intensities of 0 to 255 (8-bit).

- Red
- Green
- Blue

Mixing different intensities of each color gives us the full color spectrum, example **Yellow**:

- Red – 255
- Green – 255
- Blue - 0



How does it look when stored on a computer?

# Images are stored in multi-dimensional arrays

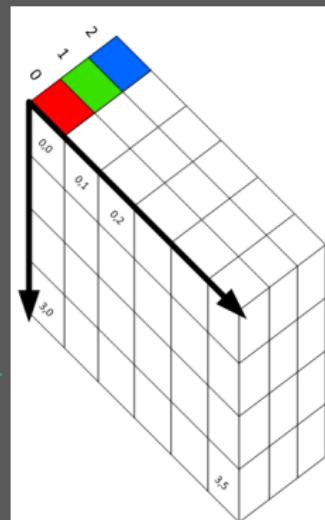
- Think of an array as table. A **1-dimensional** arrays looks like this:

0	1	2	3	4	5	6	7

- A **2-dimensional** array looks like this:

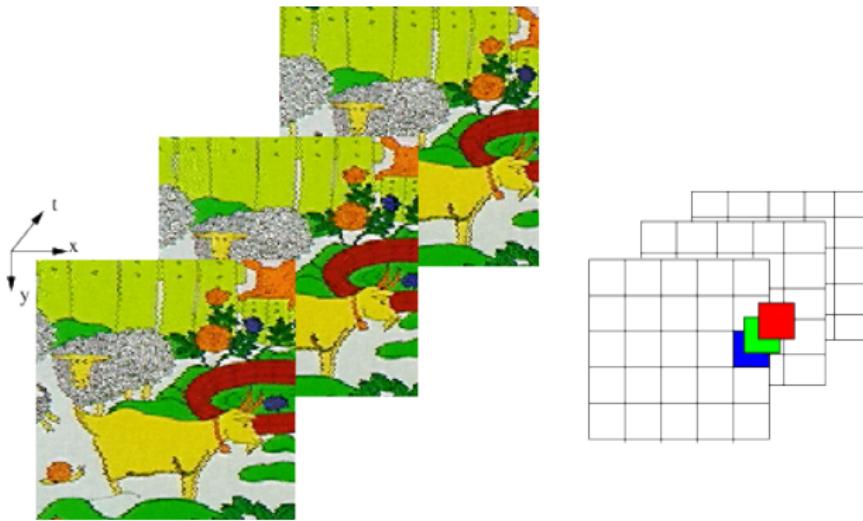
0	1	2	3	4	5	6	7

- **3-dimensional** array



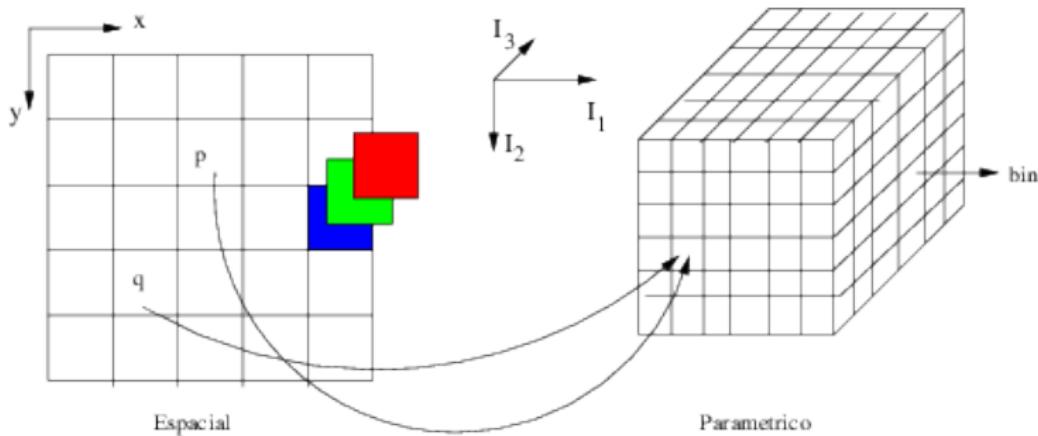
# Formação de uma imagem colorida

No caso de imagens coloridas (fotografia, vídeo), cada pixel  $p$  terá associado um vetor  $\vec{I}(p) = (I_1(p), I_2(p), I_3(p))$  com as medidas de reflexão de luz nos comprimentos de onda do vermelho, verde, e azul, respectivamente. A amostragem da função  $f(x, y, t)$  ao longo do tempo gera spels  $p = (x, y, t)$  (*space elements*).



# Espaços imagem e paramétrico

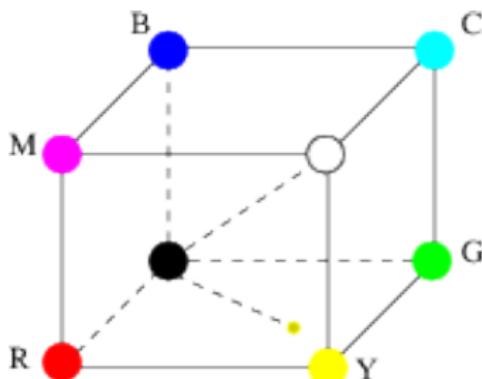
Os três componentes de cor de um pixel são vistos como características (atributos, parâmetros), mapeando cada pixel em um ponto do espaço paramétrico correspondente.



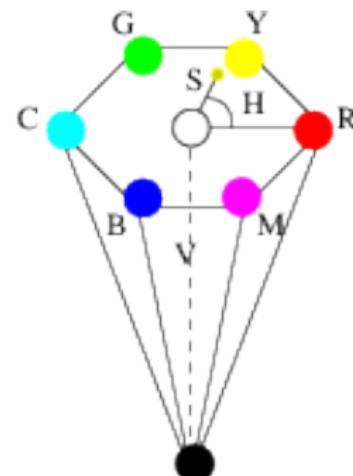
\* Para  $b=24$ bits (8 bits por componente de cor), o número de bins (cores) é  $2^{24} - 1$ .

# Espaços de cor

- Uma imagem colorida pode ser armazenada em diferentes espaços de cor (RGB, YCbCr, CMY, HSV, Lab,etc.).
- A conversão da imagem de um espaço de cor para outro é uma operação matemática pixel a pixel (e.g., multiplicação matricial envolvendo  $\vec{I}(p)$ ).



RGB and CMY

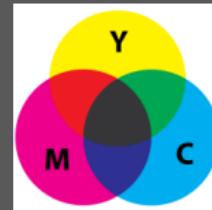
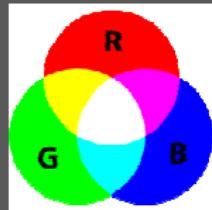


HSV

# Color Spaces

Ever heard of the terms **RGB**, **HSV** or **CMYK**?

These are color spaces, **which is simply a way to represent color.**



# RGB....wait BGR Color Space

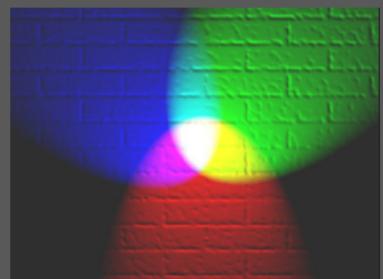
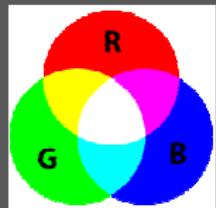
OpenCV's default color space is **RGB**.

RGB is an **additive color** model that generates colors by combining blue, green and red and different intensities/brightness. In OpenCV we 8-bit color depths

- Red
- Green
- Blue

However, OpenCV actually stores color in the **BGR** format.

**COOL FACT** - We use BGR order on computers due to how unsigned 32-bit integers are stored in memory, it still ends up being stored as RGB. The integer representing a color e.g. 0x00BBGGRR will be stored as 0xRRGGBB00.



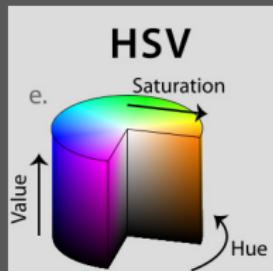
# HSV Color Space

**HSV** (Hue, Saturation & Value/Brightness) is a color space that attempts to represent colors the way humans perceive it. It stores color information in a cylindrical representation of RGB color points.

**Hue** – Color Value (0 – 179)

**Saturation** – Vibrancy of color (0-255)

**Value** – Brightness or intensity (0-255)



It's useful in computer vision for color segmentation. In RGB, filtering specific colors isn't easy, however, HSV makes it much easier to set color ranges to filter specific colors as we perceive them.

Visit these links to learn more:

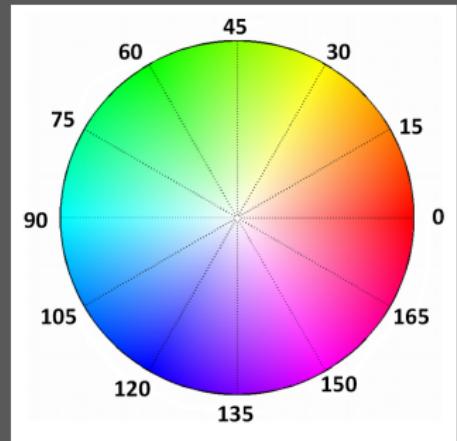
- [wikipedia.org/wiki/HSL\\_and\\_HSV](https://en.wikipedia.org/wiki/HSL_and_HSV)
- [http://coecsl.ece.illinois.edu/ge423/spring05/group8/FinalProject/HSV\\_writeup.pdf](http://coecsl.ece.illinois.edu/ge423/spring05/group8/FinalProject/HSV_writeup.pdf)

# Color Filtering

The Hue (Hue color range, goes from 0 to 180, not 360) and is mapped differently than standard

## Color Range Filters:

- Red – 165 to 15
- Green – 45 to 75
- Blue – 90 to 120



# Baixar Imagem no SIGAA

Antes de prosseguirmos, baixem a imagem 'babuino.jpg' do SIGAA e coloquem n subdiretório (**img** superior ao seu código fonte.



# Abrindo e Exibindo a Imagem

```
import cv2
import numpy as np

image = cv2.imread('..../img/babuino.jpg')
cv2.imshow('Figura', image)
cv2.waitKey()
cv2.destroyAllWindows()
```



# Valor BGR e Suas Camadas

```
import cv2
import numpy as np

image = cv2.imread('..../img/babuino.jpg')

# BGR Values for the first 0,0 pixel
B, G, R = image[0, 0]
print B, G, R

#BGR Layers
print image.shape
```

image.shape

A forma (shape) da uma imagem é acessado por **image.shape**. Que retorna uma tupla com número de **linhas, colunas e canais** (camadas) se a imagem for colorida.

## Brincando com a Imagem

Abra a imagem no Paint e identifique uma região vermelha.  
Identifique a coluna e linha e depois extraia os valores BGR desta  
região. Utizando o Paint:

- ① Click na ferramenta Seleção de Cores;
- ② Selecione a Cor identificada;
- ③ Click em Editar Cores.

### **ATENÇÃO: O Paint inverte a ordem para Linha, Coluna.**

Como resultado irá obter os valores para: Vermelho, Verde, Azul.  
Além de Matriz, Saturação e Iluminação (A serem estudados no  
futuro).

# Brincando com a Imagem

Selecionei o ponto 98, 180 (linha, coluna) e recuperei os seguintes valores BGR (Azul = 196, Verde = 162 e Vermelho = 239).

# Brincando com a Imagem

```
import cv2
import numpy as np

image = cv2.imread('..../img/babuino.jpg')

# BGR Values for the first 0,0 pixel
B, G, R = image[98, 180]
print B, G, R

#BGR Layers
print image.shape
```

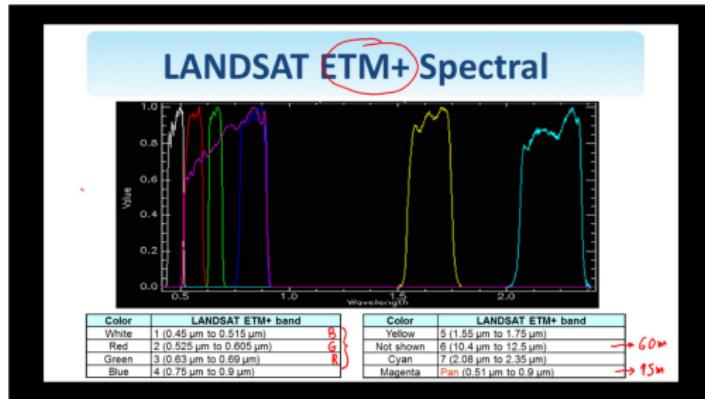
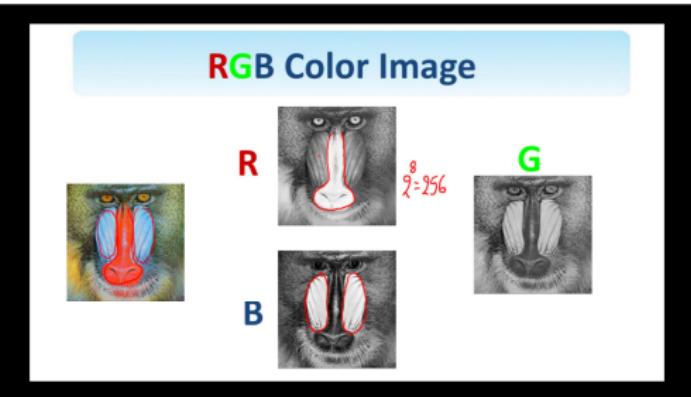
## Resultado

```
>>> 196 162 239
>>> (266L, 400L, 3L)
```

# Baixar Imagem no SIGAA

Antes de prosseguirmos, baixem a imagem 'babuino2.jpg' do SIGAA e coloquem n subdiretório (**img** superior ao seu código fonte.





# Exibindo os 3 Canais (BGR) Separados

```
import cv2
import numpy as np
image = cv2.imread('..../img/babuino2.jpg')

# OpenCV's 'split' function splites the image
#into each color index
B, G, R = cv2.split(image)

cv2.imshow("Original", image)
cv2.imshow("Red", R)
cv2.imshow("Green", G)
cv2.imshow("Blue", B)
cv2.waitKey(0)
cv2.destroyAllWindows()
```

# Mesclando os 3 Canais (BGR) Separados

```
import cv2
import numpy as np
image = cv2.imread('..../img/babuino2.jpg')

# OpenCV's 'split' function splites the image into each
# color index
B, G, R = cv2.split(image)

# Let's re-make the original image,
merged = cv2.merge([B, G, R])
cv2.imshow("Merged", merged)

cv2.waitKey(0)
cv2.destroyAllWindows()
```

# Ampliando o Sinal de Azul

```
import cv2
import numpy as np
image = cv2.imread('..../img/babuino2.jpg')

# OpenCV's 'split' function splites the
#image into each color index
B, G, R = cv2.split(image)

# Let's amplify the blue color
merged = cv2.merge([B+100, G, R])
cv2.imshow("Merged_with_Blue_Amplified", merged)

cv2.waitKey(0)
cv2.destroyAllWindows()
```



## Contraprova

Usando o Gimp ou Photoshop faça a mesma operação.

# Bibliografia

- Solomon C., Breckon T. **Fundamentals of Digital Image Processing.. A Practical Approach with Examples in Matlab** (Wiley-Blackwell, 2011)(ISBN 9780470844724)(en)(355s)
- A. Conci, E. Azevedo e F.R. Leta - **Computação Gráfica: volume 2 (Processamento e Análise de Imagens Digitais)**, Campus/Elsevier. 2008 - ISBN 85-352-1253-3.
- Open CV Tutorials

DÚVIDAS ?

