

/home/anderson/my\_ros\_ws/src/rt2\_assignment1/src/position\_service.cpp

```
graph TD; A["/home/anderson/my_ros_ws/src/rt2_assignment1/src/position_service.cpp"] --> B["ros/ros.h"]; A --> C["rt2_assignment1/RandomPosition.h"]
```

ros/ros.h

rt2\_assignment1/RandomPosition.h