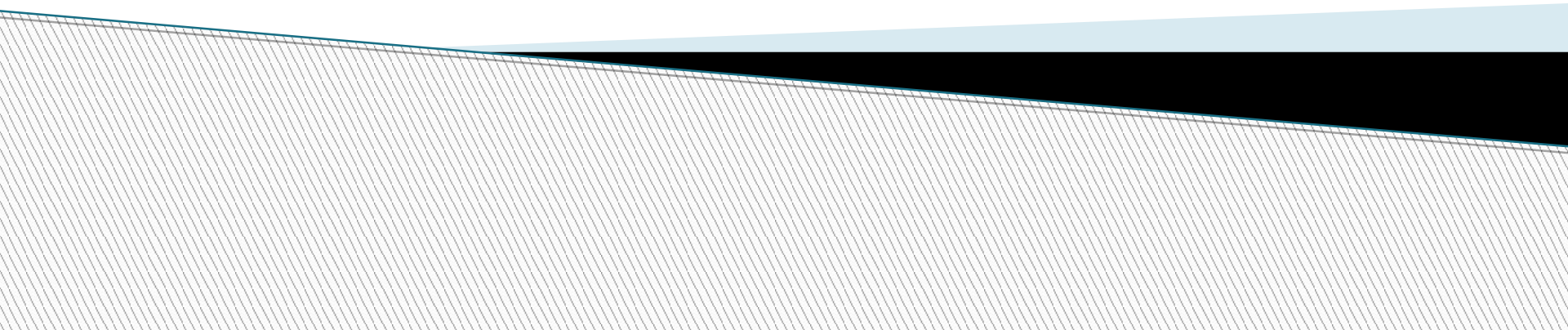


# Digital to Analog Converters and Diodes

Keith Weaver  
James Mulford  
Philip Estrada

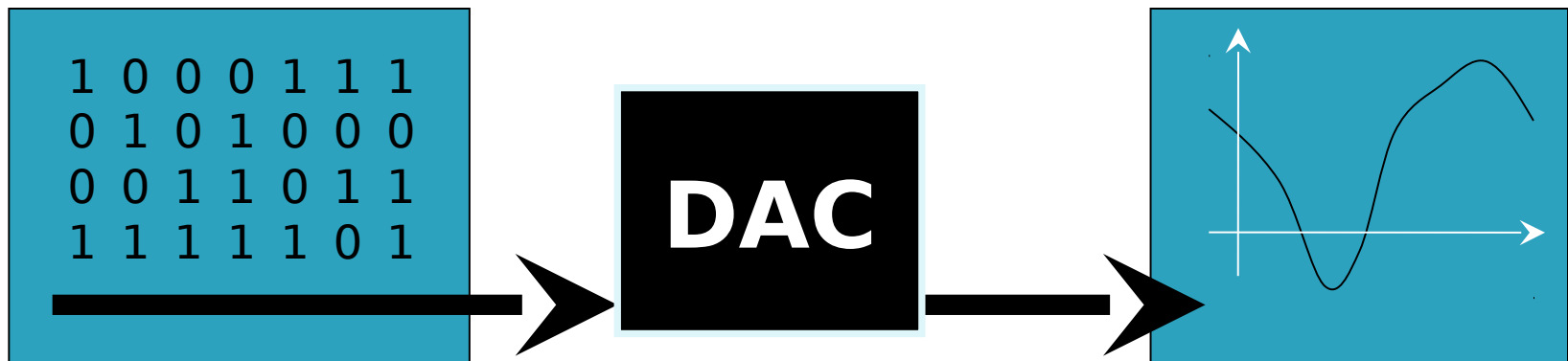


# Outline:

- ▶ What is digital to analog converter (DAC)?
- ▶ Types of DAC
  - Binary Weighted Resistor
  - R-2R Ladder
- ▶ Discuss Specifications:
  - Reference Voltages
  - Resolution
  - Speed
  - Settling Time
  - Linearity
  - Errors
- ▶ Applications
- ▶ Diodes: Theory and applications
  - Ideal vs. real
  - Types: Junction and Zener

# What is Digital-to-Analog Converter (DAC) ?

- ▶ A DAC converts a binary digital signal into an analog representation of the same signal
- ▶ Typically the analog signal is a voltage output, though current output can also be used

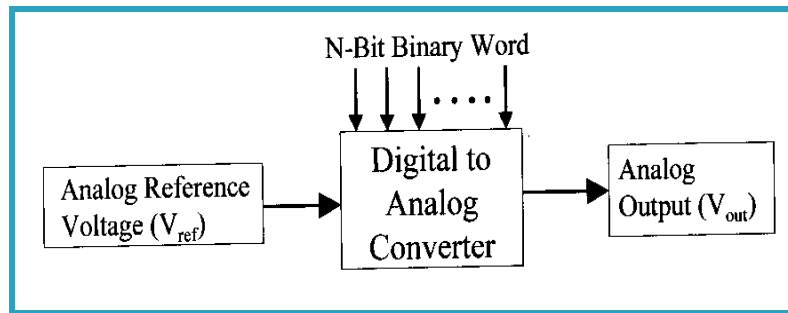


# DAC vs. ADC

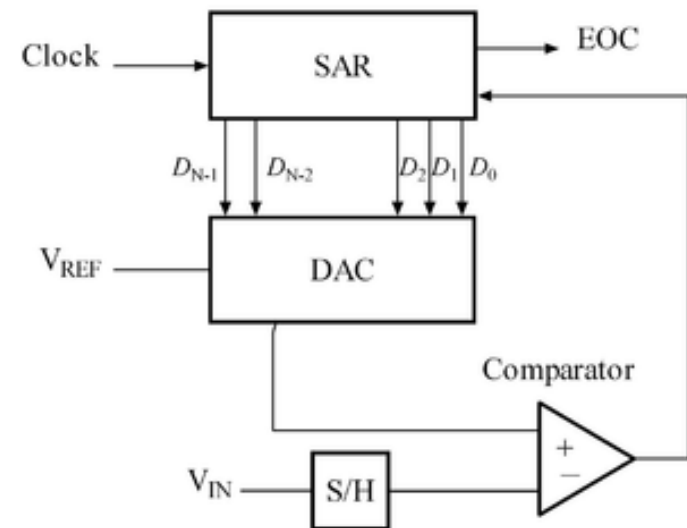
- ▶ ADCs are used in systems to capture “real world” signals and convert them to “digital” signals.
- ▶ DACs are used in systems to capture “digital” signals and convert them to “real world” signals that humans can interpret.

# Significance of Reference Voltage in DACs

- ▶ DACs rely on an input reference voltage to generate analog output from digital signals.



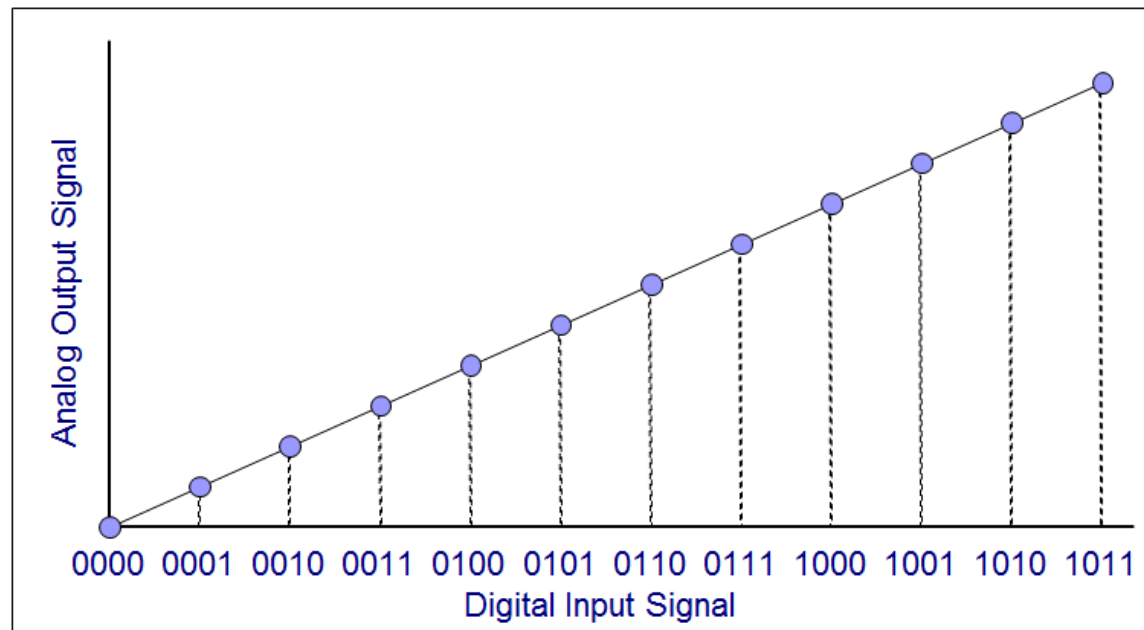
**DAC**



**DAC (using  $V_{ref}$  and bits as input) inside an SAR ADC**  
**As explained in earlier student lecture on ADC**

# Analog Levels For Sampled Digital Values

- ▶ Each binary number sampled by a DAC corresponds to a different output analog level between 0 and  $V_{\text{ref}}$  for **Unipolar** and  $V_{\text{ref}}$  and  $-V_{\text{ref}}$  for **Bipolar**.

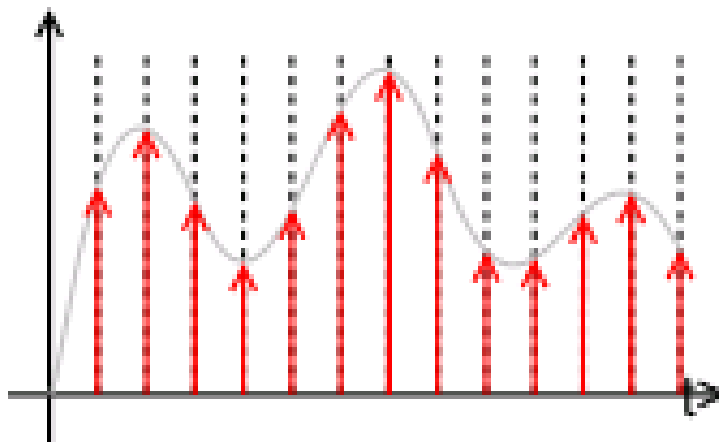


# Sampling Frequency

- ▶ Sampling frequency is the number of data points sampled per unit time
- ▶ Sampling frequency must be twice the frequency of the sampled signal to avoid aliasing, per Nyquist criteria
- ▶ A higher sampling frequency decreases the sampling period, allowing more data to be transmitted in the same amount of time

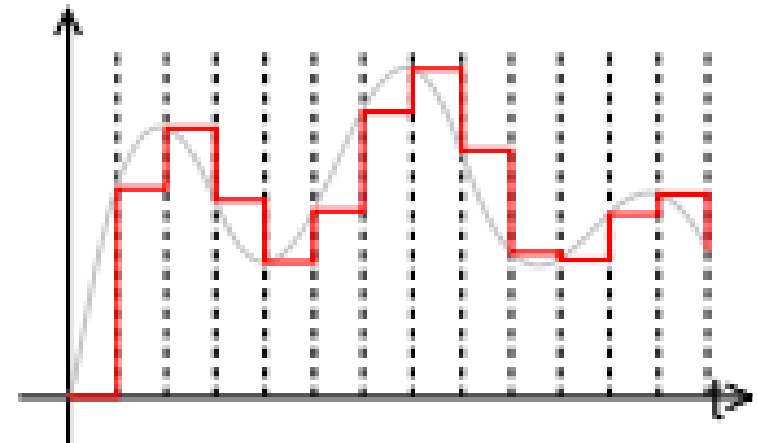

# Output is a Piecewise Function

- ▶ This is due to finite sampling frequency
- ▶ The analog value is calculated and “held” over the sampling period
- ▶ This results in an imperfect reconstruction of the original signal



Ideally Sampled Signal

DAC

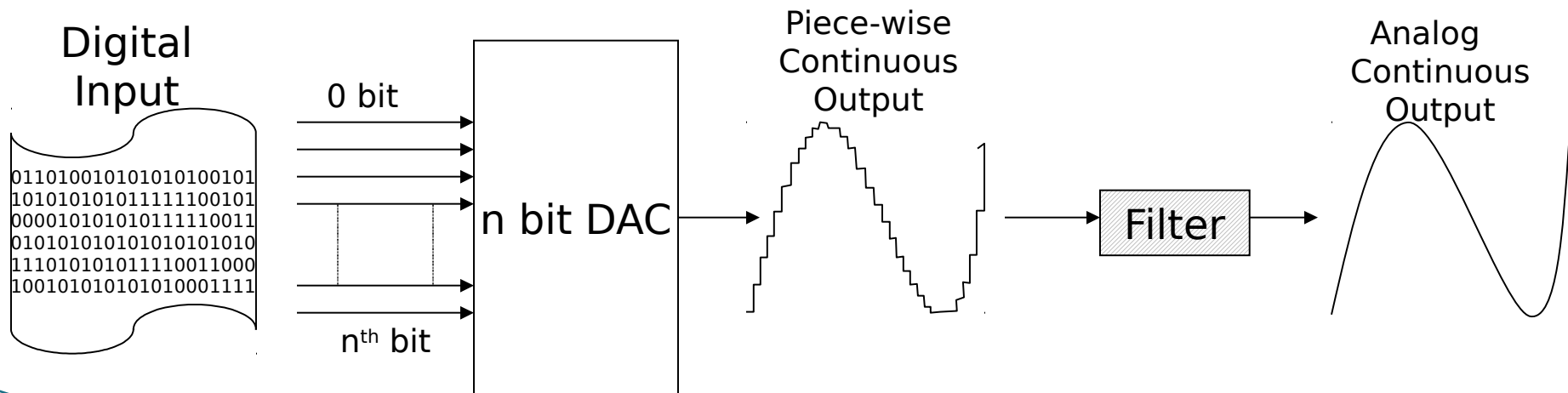


Output typical of a real, practical DAC due to sample & hold



# Filtering

- ▶ The analog signal generated by the DAC can be smoothed using a low pass filter
- ▶ This removes the high frequencies required to sustain the sharp inclines making up the edges

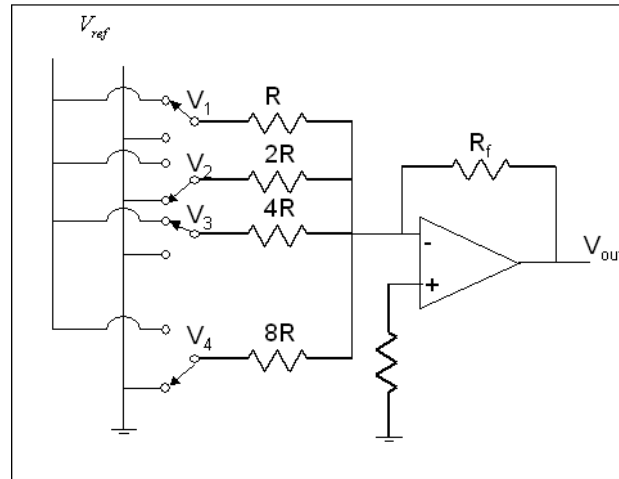


# Types of DAC Implementations

- ▶ There can be several types of DAC implementations. Some of them are:

1. Binary-weighted resistor
2. R-2R ladder
3. Pulse-width modulation
4. Oversampling DAC (in EVB used in lab)
5. Thermometer-coded DAC
6. Hybrid DAC

# 1. Binary-weighted resistor DAC



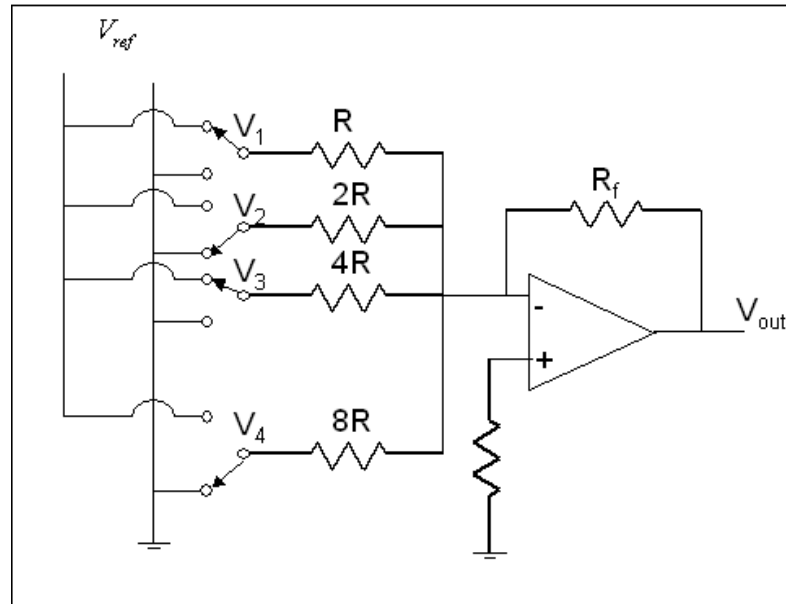
- *Assumptions:*

- Virtual Ground at Inverting Input
- $V_{out} = -IR_f$

- *Details*

- Use  $V_{ref}$  as input voltage
- Use transistors to switch between high and ground
- Use resistors scaled by two to divide voltage on each branch by a power of two
- $V_1$  is MSB,  $V_4$  LSB in this circuit

# 1. Binary-weighted resistor DAC



*For Resistors Parallel*

$$\frac{1}{R_{eq}} = \left( \frac{1}{R_1} + \frac{1}{R_2} \right)$$

$$V_{out} = -\frac{R_f}{R_{eq}} V_{ref} = -R_f V_{ref} \left( \frac{B_{n-1}}{R} + \frac{B_{n-2}}{2R} + \dots + \frac{B_1}{2^{n-2}R} + \frac{B_0}{2^{n-1}R} \right)$$

$$V_{out} = -V_{ref} \frac{R_f}{R} \sum_{i=0}^{n-1} \frac{B_i}{2^{(n-1)-i}}$$

# 1. Binary-weighted resistor DAC

- Example: take a 4-bit converter,
- $R_f / R = a$ ;  $a$  = gain.

$$V_{\text{out}} = -aV_{\text{ref}} \left( \frac{B_3}{2} + \frac{B_2}{4} + \frac{B_1}{8} + \frac{B_0}{16} \right)$$

- Input parameters:
  - Input voltage  $V_{\text{ref}} = -2\text{V}$
  - Binary input = 1011
  - Coefficient  $a = \frac{1}{2}$

$$V_{\text{out}} = -\frac{1}{2}(-2) \left( \frac{1}{2} + \frac{0}{4} + \frac{1}{8} + \frac{1}{16} \right) = 1.375\text{V}$$

# 1. Binary-weighted resistor DAC

- **Resolution:** Making LSB as 1 and all other inputs as 0,

$$|V_{\min}| = \frac{R_f |V_{ref}|}{R 2^{n-1}}$$

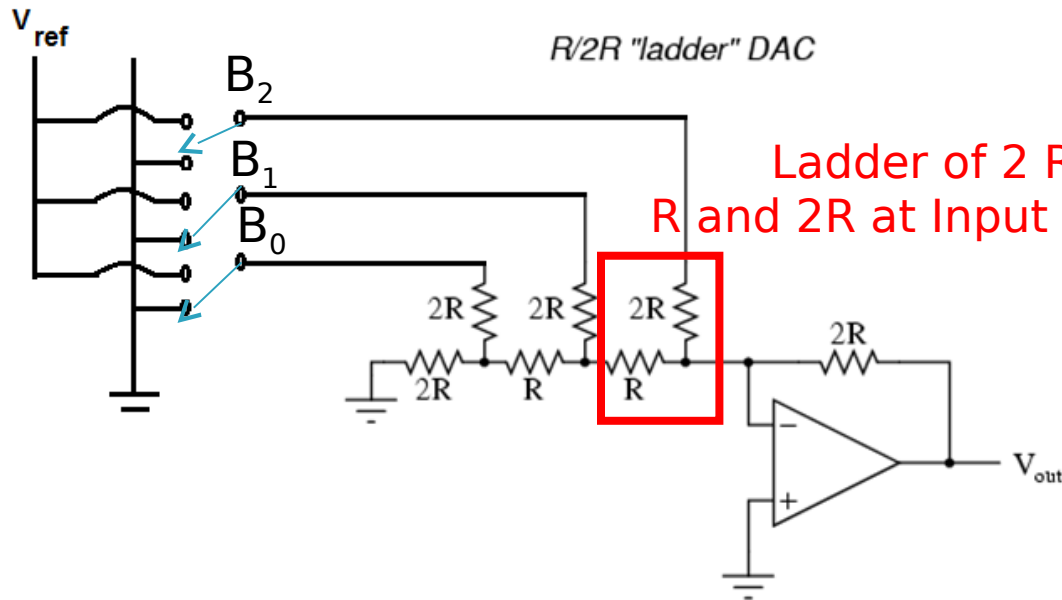
- If  $R_f = R/2$  then resolution is  $\frac{|V_{ref}|}{2^n}$
- **Max  $V_{out}$**  can be obtained making all input bits equal to 1 and it can be obtained solving geometric series in equation (1) as

$$|V_{\max}| = |V_{ref}| \left[ \frac{1}{2} + \frac{1}{2^2} + \frac{1}{2^3} + \dots + \frac{1}{2^n} \right]$$

# 1. Binary-weighted resistor DAC

- Advantages:
  - Simple
  - Fast
- Disadvantages
  - Need large range of resistor values (2048:1 for 12-bit) with high precision in low resistor values.
  - Need very small switch resistances.

## 2. R-2R Ladder DAC

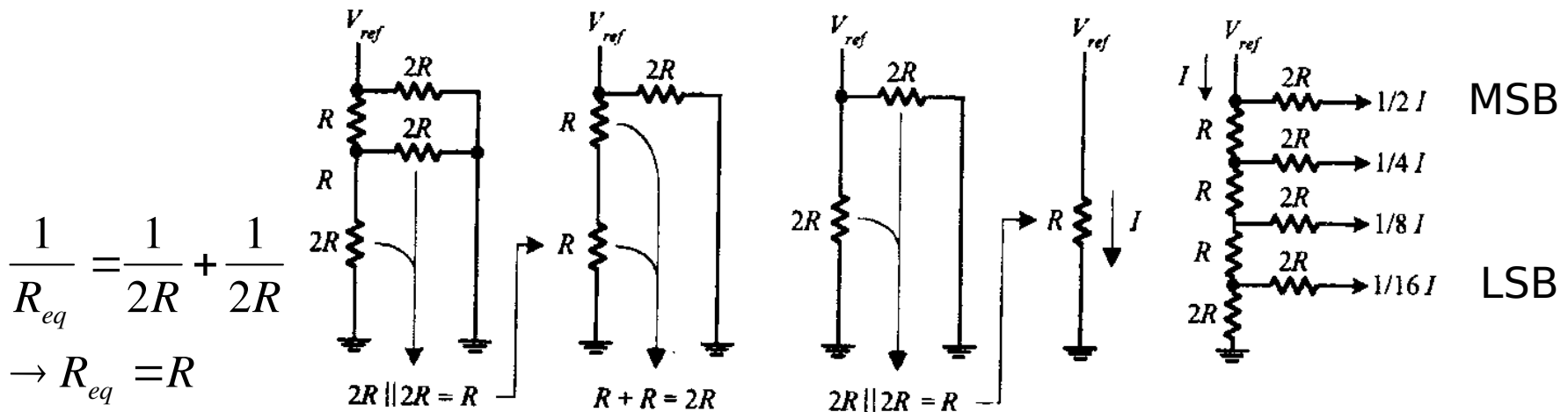


- All the inputs are  $V_{ref}$  followed by switches. Output of switches is  $B_2$ ,  $B_1$  and  $B_0$  in above circuit.
- Similar to binary weighted DAC, status of switches would define if input bits to DAC are  $V_{ref}$  or 0.



## 2. R-2R Ladder DAC

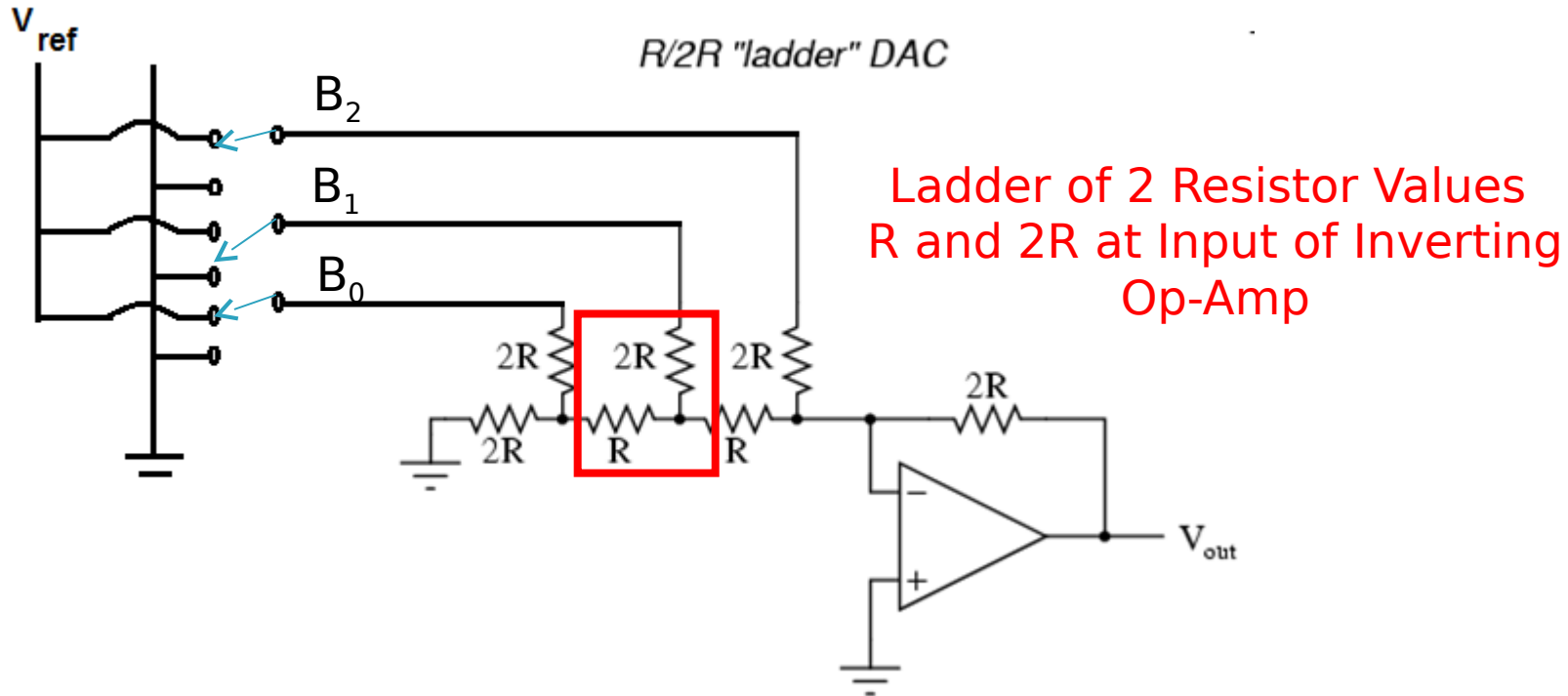
By adding resistance in series and in parallel we can derive an equation for the R-2R ladder.



By knowing how current flows through the ladder we can come up with a general equation for R-2R DACs.

$$V_{out} = -I_{sum} R_f = -I \left[ \frac{B_3}{2} + \frac{B_2}{4} + \frac{B_1}{8} + \frac{B_0}{16} \right] R_f$$

## 2. R-2R Ladder DAC



- Circuit may be analyzed using *Thevenin's theorem* (replace network with equivalent voltage source and resistance).
- Final result is:

$$V_{\text{out}} = -V_{\text{ref}} \frac{R_f}{R} \sum_{i=0}^{n-1} \frac{B_i}{2^{n-i}}$$

$$I = \frac{V}{R}$$

## 2. R-2R Ladder DAC

### ► Example

- Input: 101101
- $V_{\text{ref}} = -5.5$  Volts
- $a = 1$
- $R_f / R = a$ ;  $a = \text{gain}$ .

$$V_{\text{out}} = -V_{\text{ref}} \frac{R_f}{R} \sum_{i=0}^{n-1} \frac{B_i}{2^{n-i}}$$

$$V_{\text{out}} = -(-5.5)(1) \left[ \frac{1}{2^1} + \frac{0}{2^2} + \frac{1}{2^3} + \frac{1}{2^4} + \frac{0}{2^5} + \frac{1}{2^6} \right]$$

$$V_{\text{out}} = 3.867$$

## 2. R-2R Ladder DAC

- **Resolution:** Making LSB as 1 and all other inputs as 0,

$$|V_{\min}| = \frac{R_f |V_{\text{ref}}|}{R 2^n}$$

- If  $R_f = R$  then resolution is  $\frac{|V_{\text{ref}}|}{2^n}$
- **Max  $V_{\text{out}}$**  can be obtained making all input bits equal to 1 and it can be obtained solving geometric series in equation (1) as

$$|V_{\max}| = |V_{\text{ref}}| \left( \frac{1}{2} + \frac{1}{2^2} + \frac{1}{2^3} + \dots + \frac{1}{2^n} \right)$$

## 2. R-2R Ladder DAC

- Advantages:
  - Only 2 resistor values
  - Lower precision resistors acceptable
- Disadvantages
  - Slower conversion rate

# Outline:

- ▶ What is digital to analog converter (DAC)?
- ▶ Types of DAC
  - Binary Weighted Resistor
  - R-2R Ladder
- ▶ Discuss Specifications:
  - Reference Voltages
  - Resolution
  - Speed
  - Settling Time
  - Linearity
  - Errors
- ▶ Applications
- ▶ Diodes: Theory and applications
  - Ideal vs. real
  - Types: Junction and Zener

# Reference Voltage ( $V_{ref}$ )

- ▶ The reference voltage determines the range of outputs from the DAC
- ▶ Non-Multiplying DAC
  - $V_{ref}$  is internally set by the manufacturer and is a constant (fixed) value
  - Sometimes  $V_{ref}$  is external from manufacturer
- ▶ Multiplying DAC
  - $V_{ref}$  is externally set and can be varied during operation
  - Most DACs use this type

# Full Scale Voltage and Resolution

- ▶ Full Scale Voltage ( $V_{fs}$ ) is the output voltage when all bits are set high

$$V_{fs} = V_{ref} \frac{2^N - 1}{2^N} = V_{ref} - V_{LSB}$$

- ▶ The DAC resolution is the amount of variance in output voltage for every change of the LSB in the digital input
  - How closely we can approximate the desired output signal
    - ▢ Higher resolution ▢ Finer Detail ▢ Smaller Voltage Divisions
  - Data sheets list the resolution in bits
  - Typical resolution is 8 - 16 bits

$$* V_{LSB} = \frac{V_{ref}}{2^N} = \text{Resolution} \quad N = \# \text{ of Bits}$$

\*Resolution depends on ratio of  $R_f$  and  $R$  as explained in previous section. This case is similar to R-2R ladder resolution with  $R_f=R$



# Sampling Rate (

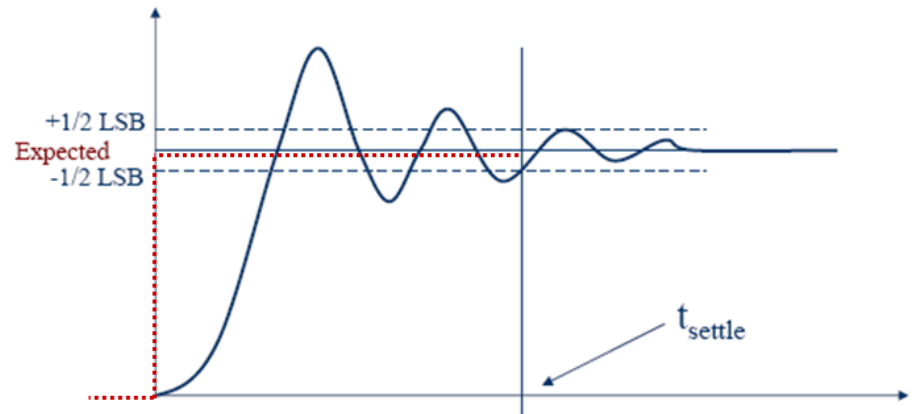
- ▶ The sampling rate is the rate at which the DAC can convert the digital input into an output voltage
- ▶ The Nyquist Criterion is used to ensure the output correctly represents the digital input

$$f_s \geq 2f_{max}$$

- ▶  $f_{max}$  is the max frequency of the analog signal to be reconstructed
- ▶  $f_s$  is limited by the input signal clock speed and DAC settling time

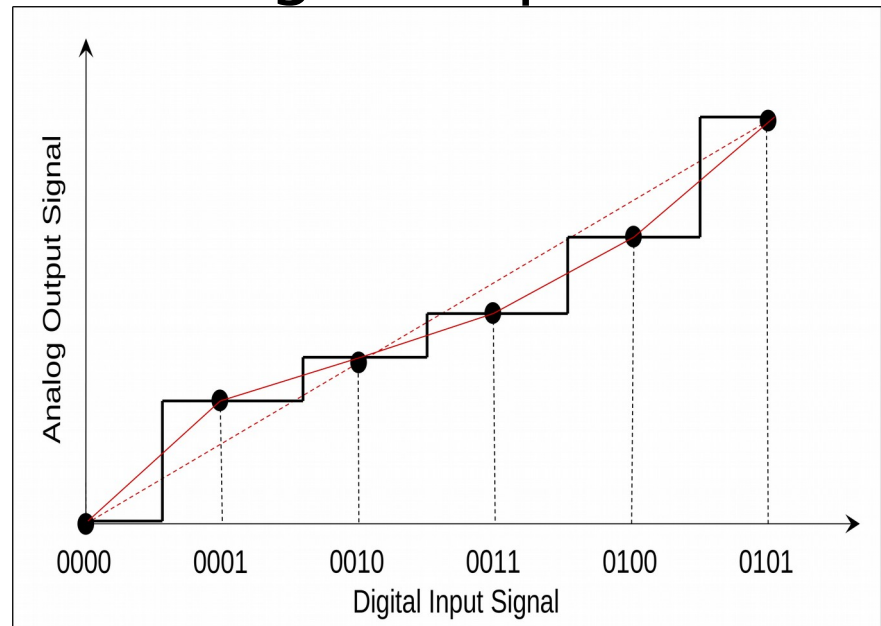
# Settling Time

- ▶ The settling time is the interval between a command to update (change) its output value and the instant it is within a specified percentage of its final value
- ▶ Any change in the input state will not be reflected in the output state immediately. There is a time lag between the two events.



# Linearity

- ▶ The linearity is the difference between the desired analog output and the actual output over the full range of expected values
- ▶ Ideally, a DAC should produce a linear relationship between a digital input and the analog output



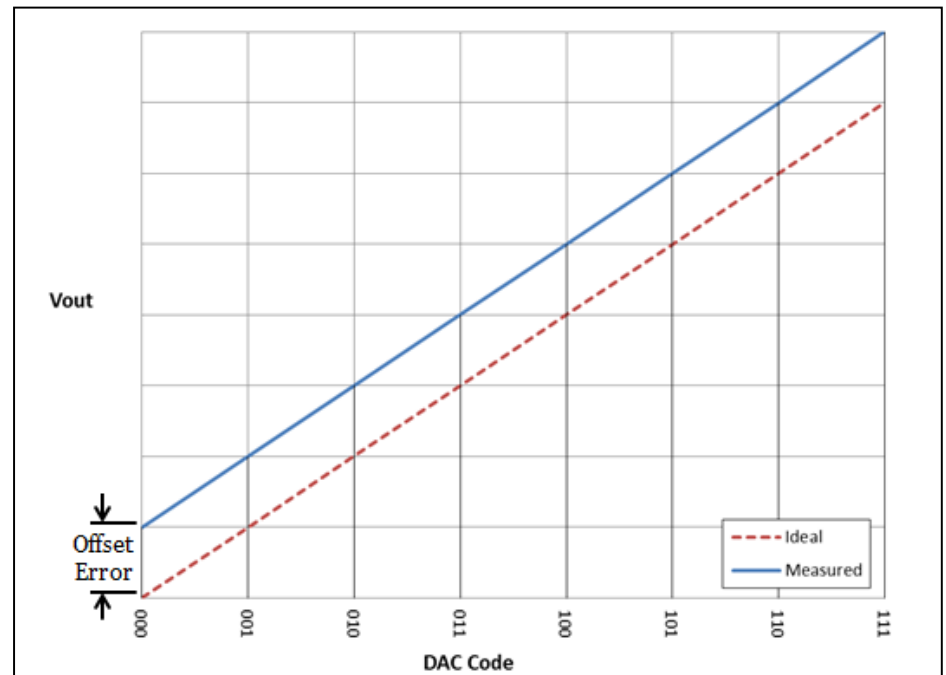
# Errors

## Common DAC Errors:

- ▶ Offset Error
- ▶ Gain Error
- ▶ Full Scale Error
- ▶ Resolution Errors
- ▶ Non Linearity
- ▶ Non-Monotonic
- ▶ Settling Time and Overshoot

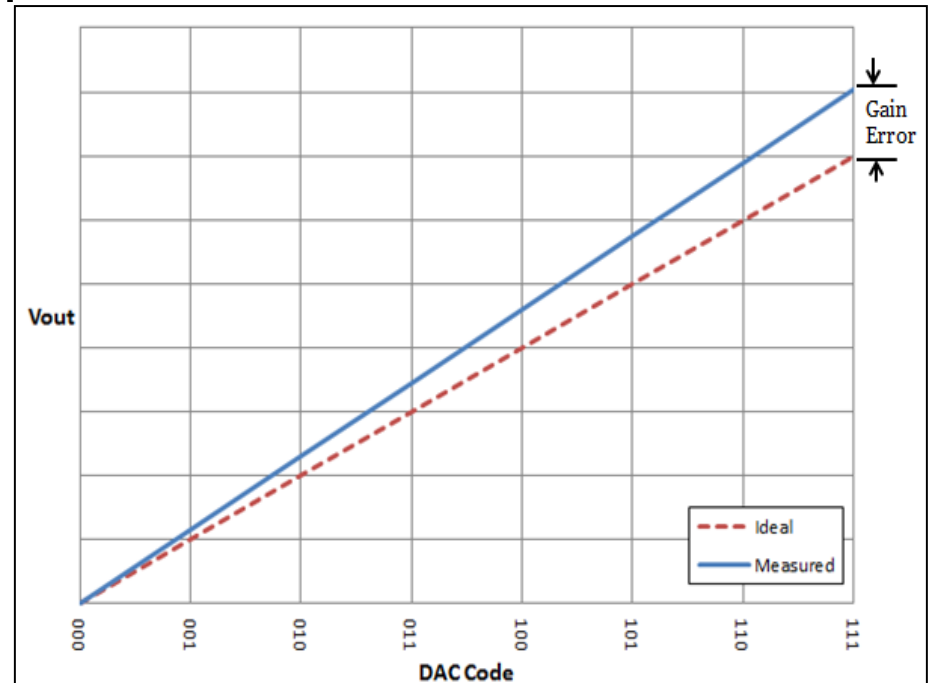
# Offset Error

- ▶ An offset error will cause all the output voltages to be different from the ideal output by the error
  - It can be determined by measuring the output voltage for a digital input of zero.



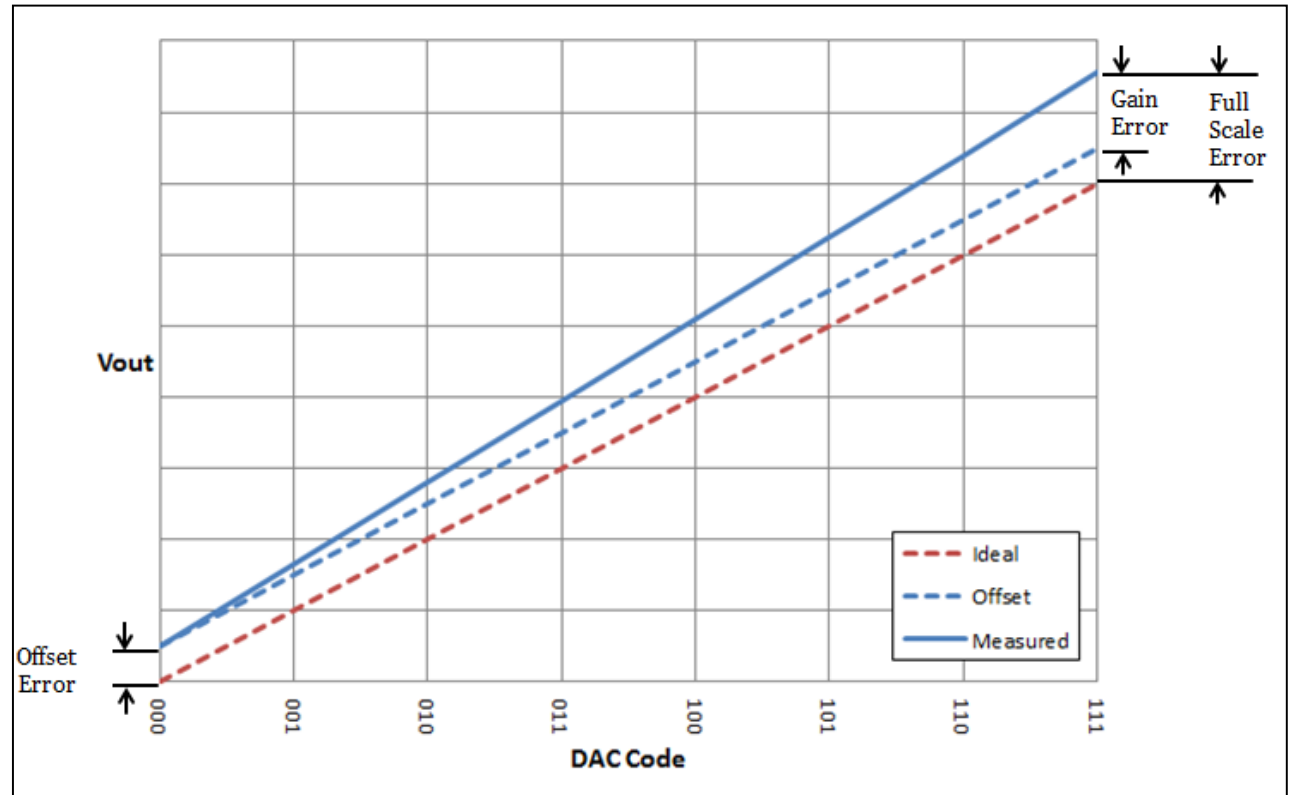
# Gain Error

- ▶ The gain error is how well the slope of the actual transfer function matches the slope of the ideal transfer function
  - It can be determined by measuring the output voltage for a digital input of all 1's



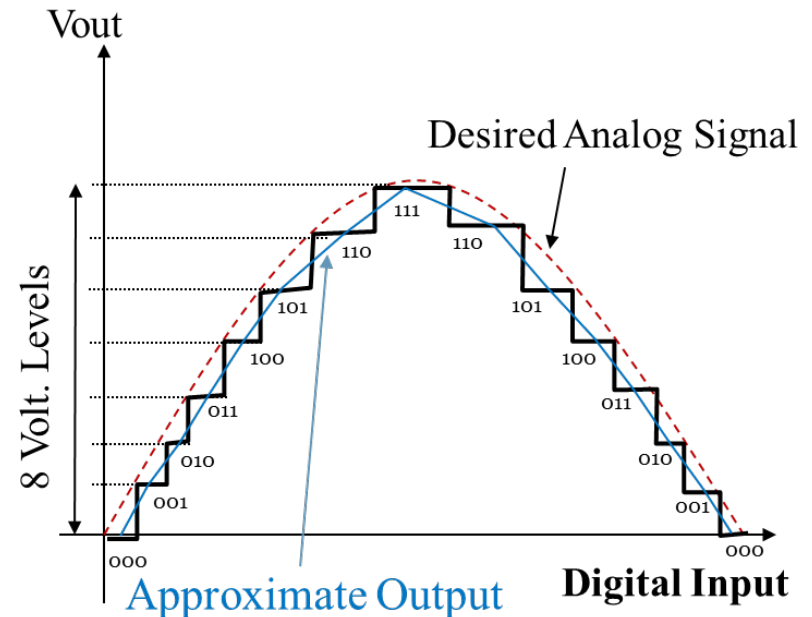
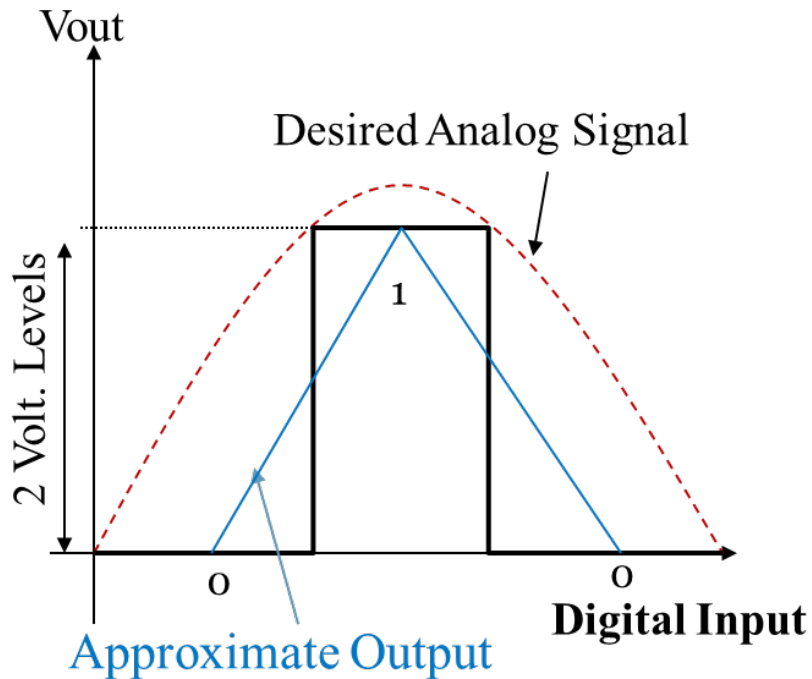
# Full Scale Error

- ▶ Full Scale error is the combination of the Gain Error and the Offset Error



# Resolution Error

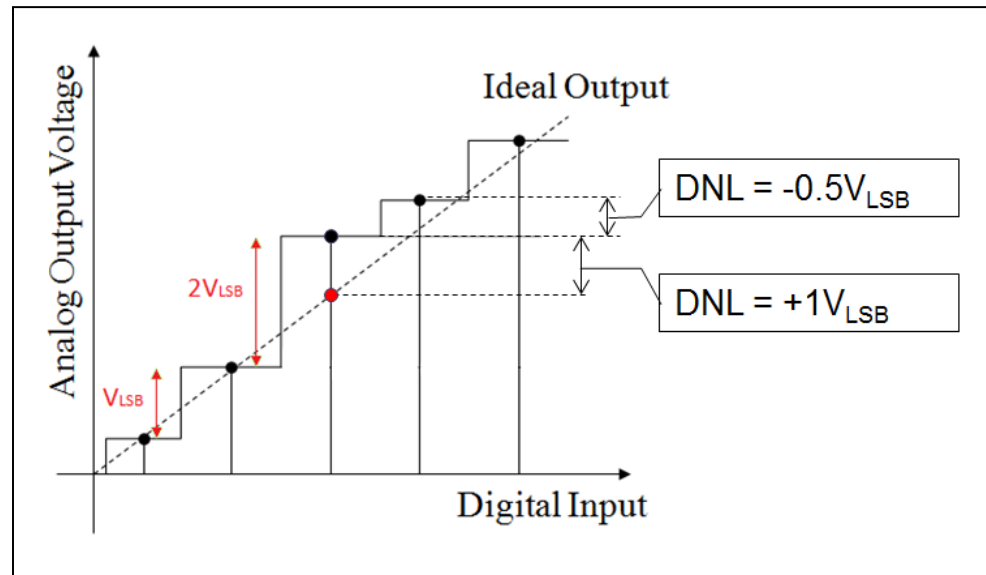
- ▶ The resolution will determine how close your output will match the desired signal





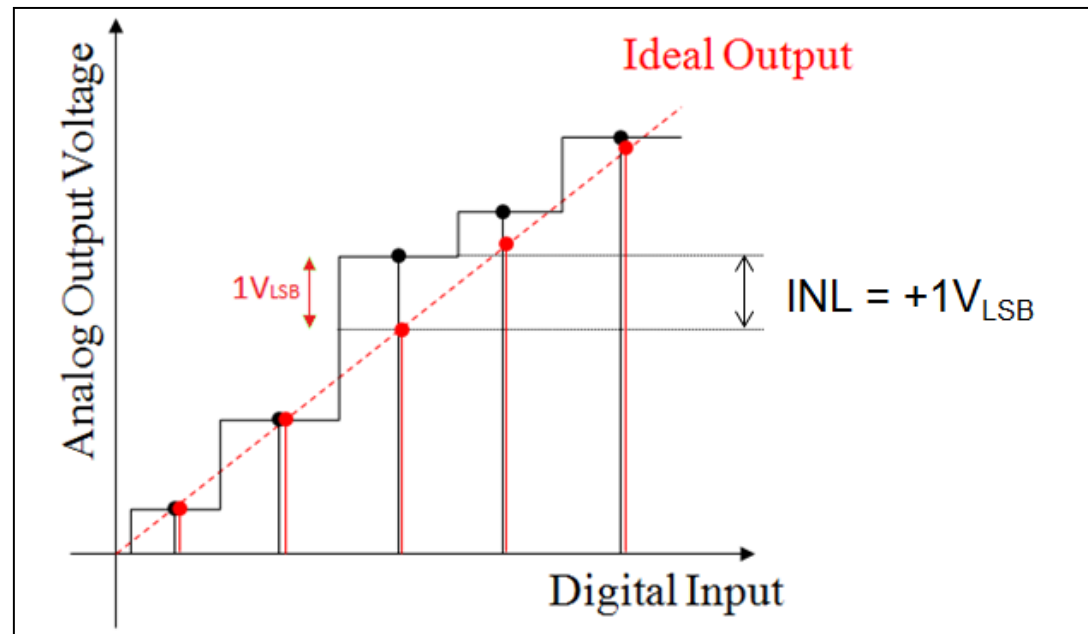
# Differential Nonlinearity Error (DNL)

- ▶ The difference between two successive digital output codes is ideally  $1 V_{\text{LSB}}$
- ▶ The deviation from a step of  $1 V_{\text{LSB}}$  is the DNL error
  - Manufacturers will specify the maximum DNL error



# Integral Linearity Error (INL)

- ▶ The INL is the difference in the ideal linear voltage and the actual output voltage for a given digital code
  - Manufacturers will specify the max INL error



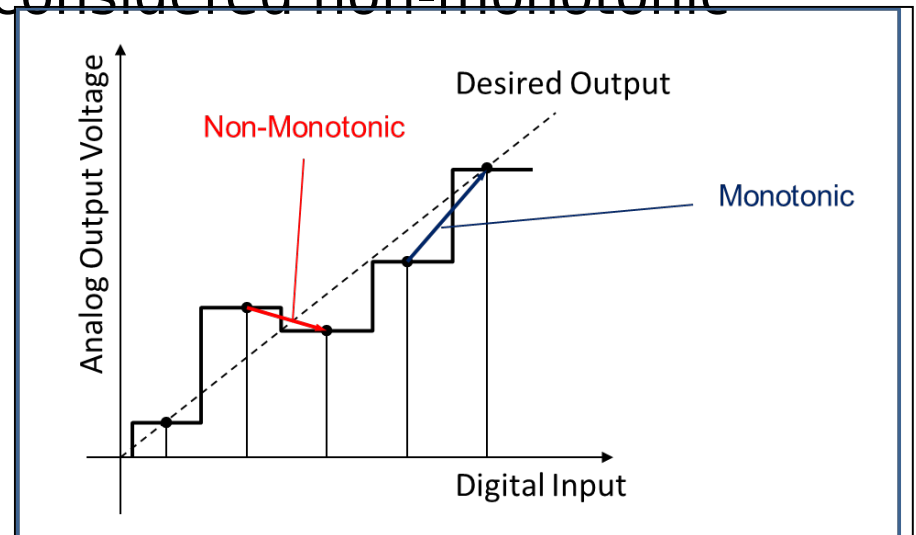
# Non-Monotonic

## ► Monotonic Function

- A monotonically increasing function will always increase or remain constant (non-decreasing)
- A monotonically decreasing function will always decrease or remain constant (non-increasing)

## ► If an increase in the digital input results in a decrease in the output voltage the DAC is considered non-monotonic

- If the DNL error is less than  $\pm 1$  LSB the DAC is guaranteed to be monotonic



# Applications

## ▶ Audio/Video

- MP3 Players
- CD Players
- Cellphones
- USB Speakers
- Analog Monitors



## ▶ Signal Generators

- Sine Wave generation
- Square Wave generation
- Random Noise generation



# Outline:

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  - Speed
  - Settling Time
  - Linearity
  - Errors
- ▶ Applications
- ▶ Diodes: Theory and applications
  - Ideal vs. real
  - Types: Junction and Zener

# Diodes

- ▶ Review of semiconductors
- ▶ Ideal Diode Characteristics
- ▶ Types of Diodes
  - Semiconductor Diodes
    - ▢ P-n Junction Diode
    - ▢ Zener Diode
    - ▢ Light Emitting Diode (LED)
    - ▢ Photodiode

# Semiconductors

## ► Conductors

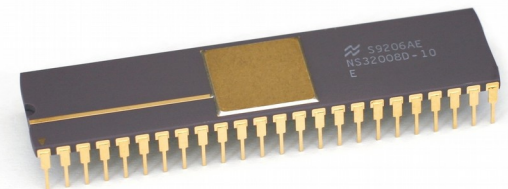
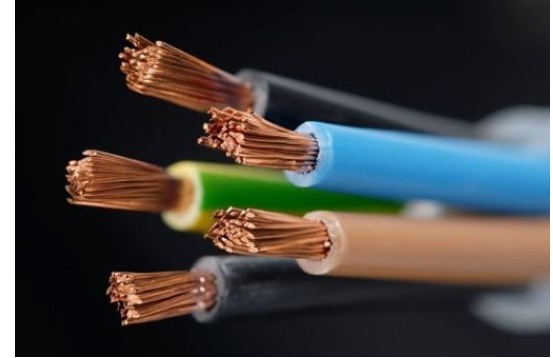
- Material which allows flow of electric charge (current). Ex) Copper wiring, silver (contactor for electric motor)

## ► Insulators

- Material does not allow flow of electric charge (current). In theory have an infinite resistivity. Ex) ceramic, glass, Teflon

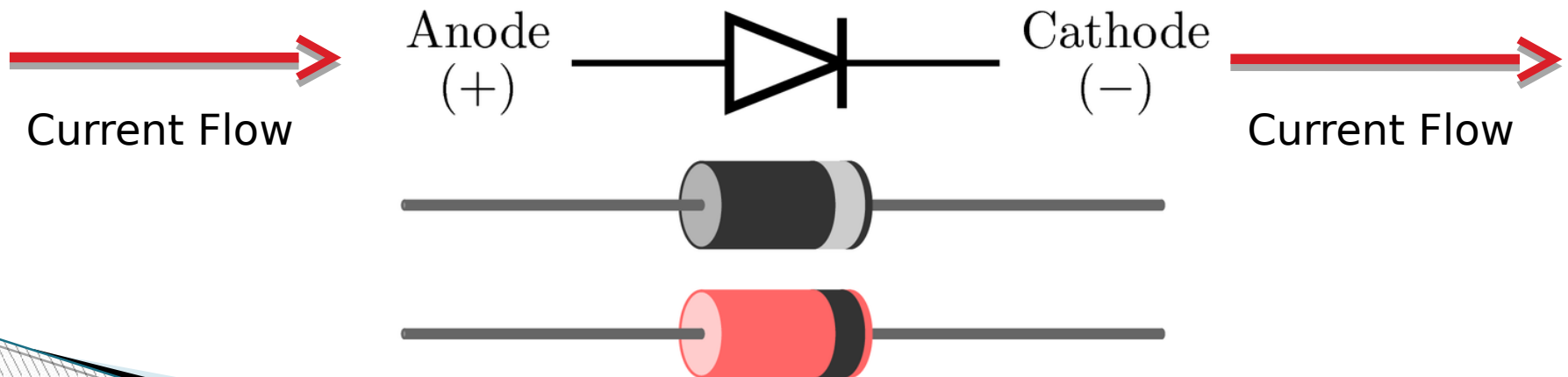
## ► Semiconductors

- A material whose electrical conductivity is poor at low temperatures but is improved by the application of heat, light, or voltage.
- Electrical conductivity can be increased and precisely controlled by adding small impurities in a process called **doping**



# What is a diode?

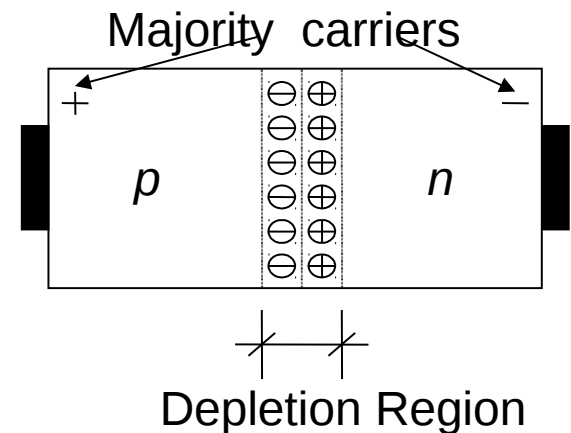
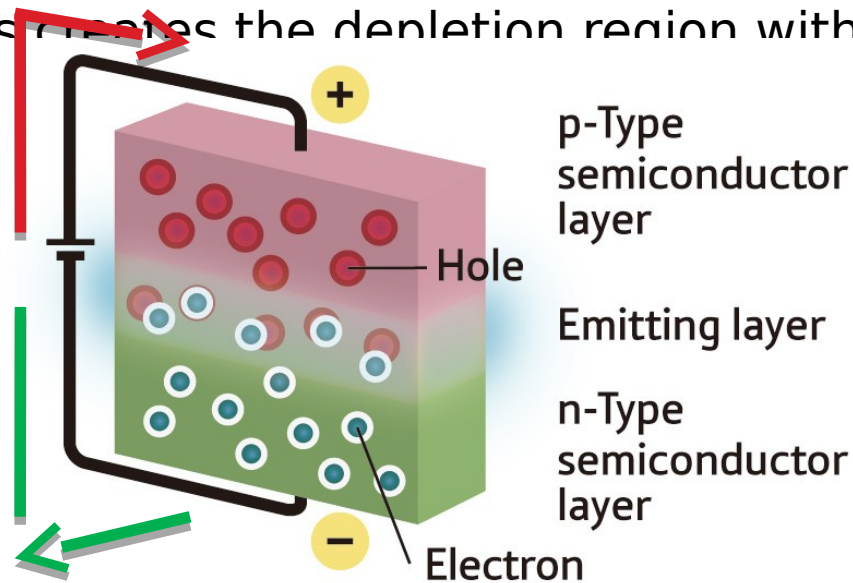
- ▶ A diode is a two-terminal electronic component with asymmetric conductance
- ▶ It has low (ideally zero) resistance to current flow in one direction (**forward**), and high (ideally infinite) resistance in the other (**reverse**)





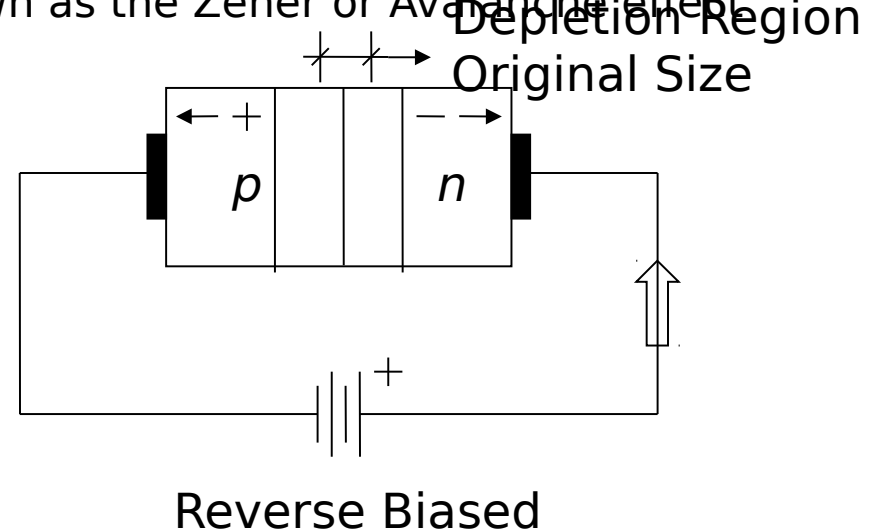
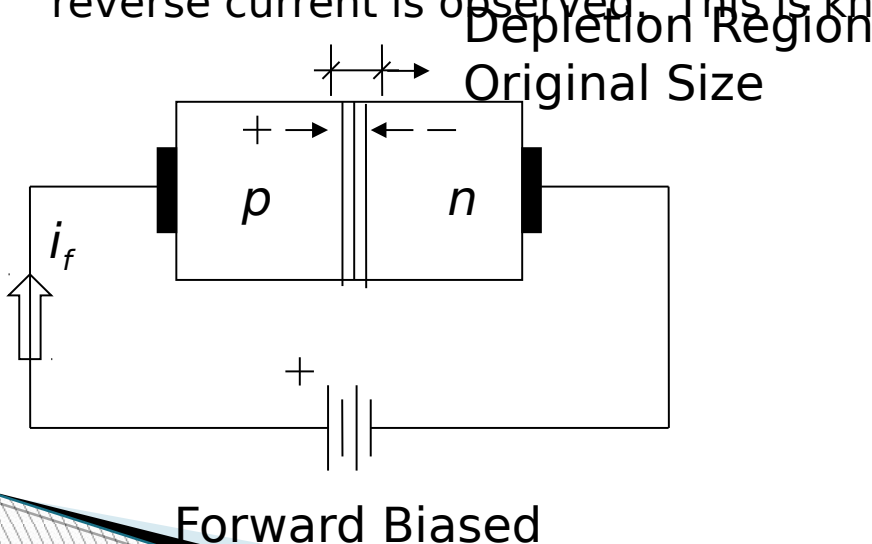
# Solid State Diode

- ▶ A diode is created when a p-type semiconductor is joined with and n-type semiconductor by the addition of thermal energy.
- ▶ When both materials are joined, the thermal energy causes positive carriers in the *p*-type material to diffuse into the *n*-type region and negative carriers in the *n*-type material to diffuse into the *p*-type region.
- ▶ This creates the depletion region within the diode



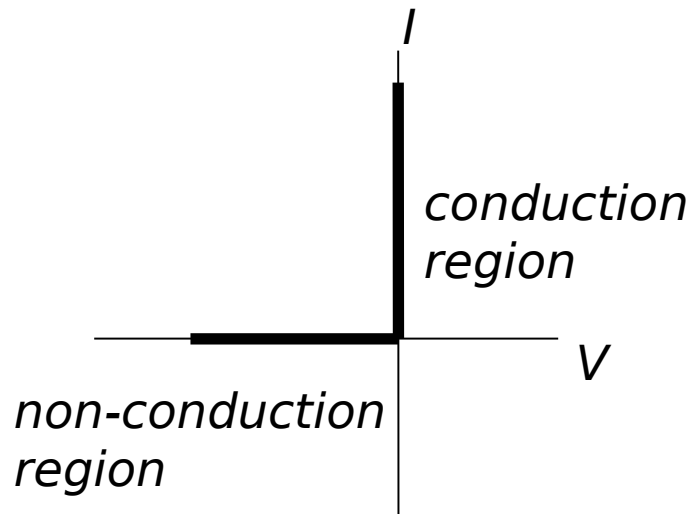
# Forward and Reverse Bias

- ▶ A diode is forward biased if the positive terminal of the battery is connected to the p-type material.
  - Current is sustained by the majority carriers.
- ▶ A diode is reverse biased if the positive terminal of the battery is connected to the n-type material.
  - There is a small reverse current or leakage current sustained by the minority carriers
- ▶ If reverse bias is sufficiently increased, a sudden increase in reverse current is observed. This is known as the Zener or Avalanche effect.

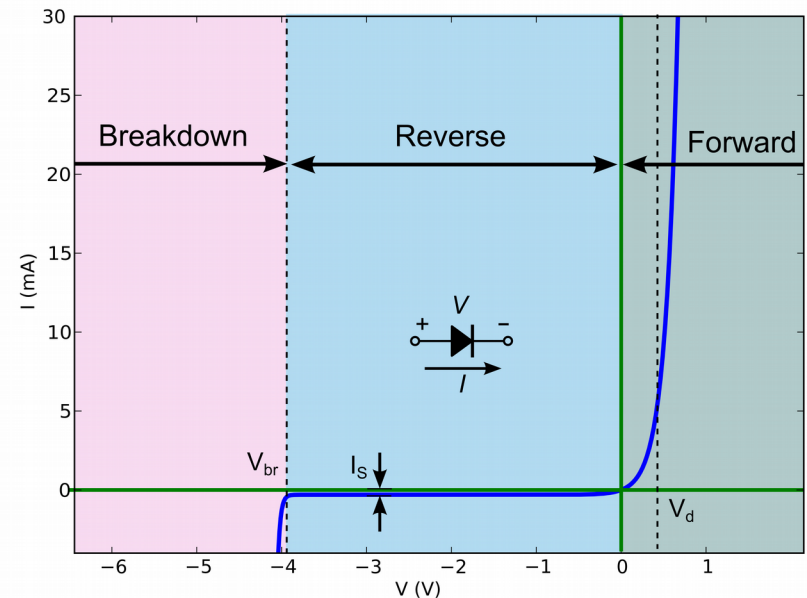


# Diode Characteristic Curve

- ▶ Ideal Diode - no resistance to current flow in the forward direction and infinite resistance in the reverse direction
- ▶ Actual Diode - forward resistance not quite zero and reverse resistance not infinite

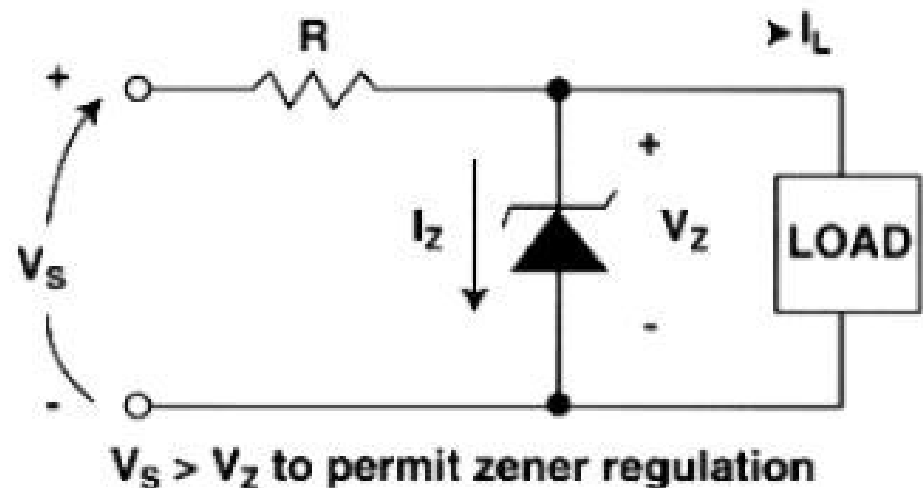


# Ideal Curve



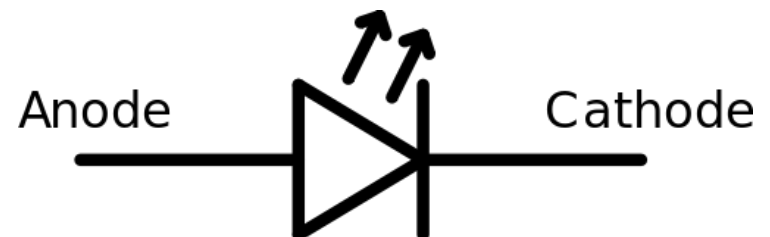
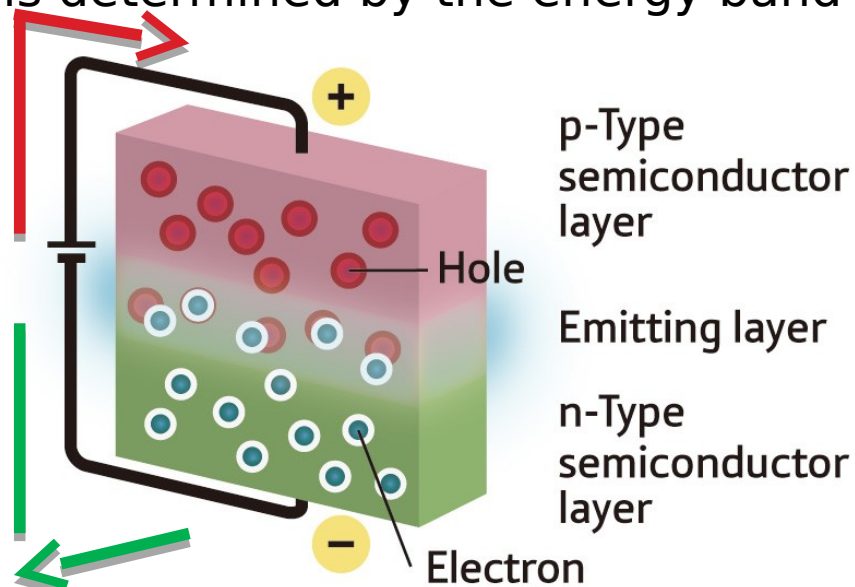
# Zener Diode

- ▶ A diode which allows current to flow in the forward direction in the same manner as an ideal diode
- ▶ But also permits it to flow in the reverse direction when the voltage is above a certain value known as the breakdown voltage
- ▶ Zener diodes have a specified voltage drop when they are used in reverse bias.
- ▶ Every p-n junction (i.e. diode) will break down in reverse bias if enough voltage is applied.
- ▶ Able to maintain a nearly constant voltage under conditions of widely varying current.
- ▶ Zener diodes are operated in reverse bias



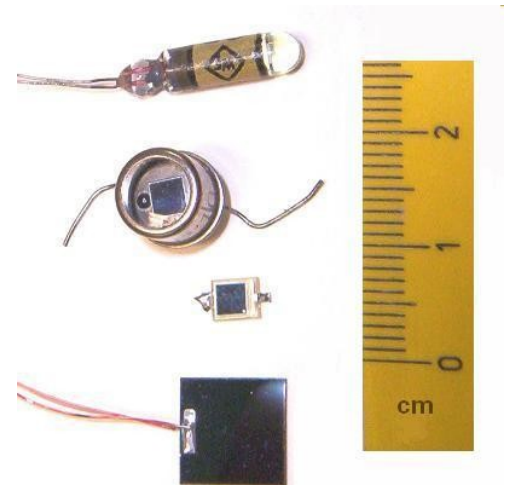
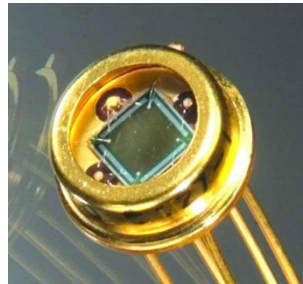
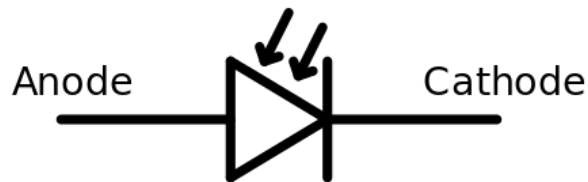
# Light Emitting Diode (LED)

- ▶ Semiconductor device with a p-n junction
- ▶ When a forward bias is applied, electrons are able to recombine with holes within the device, releasing energy in the form of photons (electroluminescence).
- ▶ The color of the light (corresponding to the energy of the photon) is determined by the energy band gap of the semiconductor



# Photodiode

- ▶ Converts light into voltage or current
- ▶ Ex) a solar cell is a large area photodiode operating in zero bias
- ▶ Designed to operate in reverse bias
- ▶ Many use a P-I-N junction rather than a P-N junction
  - PIN diode: a diode with a wide, lightly doped 'near' intrinsic semiconductor region between a p-type semiconductor and an n-type semiconductor region





# References

- ▶ Previous student presentations.
- ▶ [http://en.wikipedia.org/wiki/Digital\\_to\\_analog](http://en.wikipedia.org/wiki/Digital_to_analog)
- ▶ [http://www.allaboutcircuits.com/vol\\_4/chpt\\_13/index.html](http://www.allaboutcircuits.com/vol_4/chpt_13/index.html)
- ▶ Alicatore, David G. and Michael B Histan. *Introduction to Mechatronics and Measurement Systems*, 2<sup>nd</sup> ed. McGraw-Hill, 2003.
- ▶ Walt Kester, “What the Nyquist Criterion Means to Your Sampled Data System Design”, MT 002 Tutorial, Analog Devices.
- ▶ <http://www.maxim-ic.com/app-notes/index.mvp/id/641>