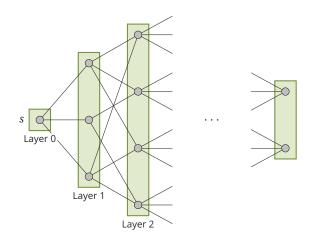


Breadth First Search

Breadth First Search (BFS)

Idea

Explore a graph layer by layer from a start vertex s.



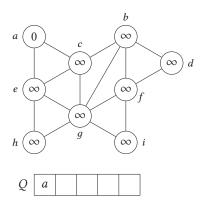
BFS

Applications

- Finding a shortest path.
- Determine distances.
- Garbage collection (checking for connected components)
- Solving Puzzles
- Web crawling
- Base for other algorithms.

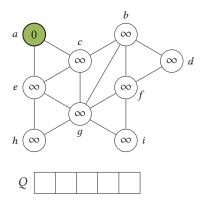
Preparation

- ► For every vertex v, set the distance $\operatorname{dist}(v) := \infty$ and the parent $\operatorname{par}(v) := \operatorname{null}$. For the start vertex a, set $\operatorname{dist}(a) := 0$.
- ▶ Add *a* to an empty queue *Q*.



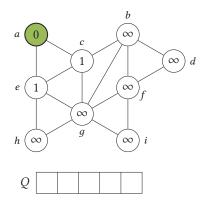
Iteration

• Select and remove first vertex v from Q.



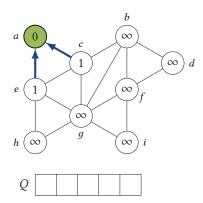
Iteration

- ▶ For each $u \in N(v)$ with $dist(u) = \infty$,
 - set dist(u) := dist(v) + 1,



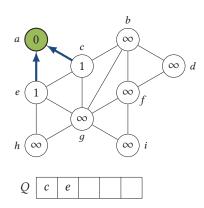
Iteration

- ▶ For each $u \in N(v)$ with $dist(u) = \infty$,
 - set dist(u) := dist(v) + 1,
 - set par(u) := v, and



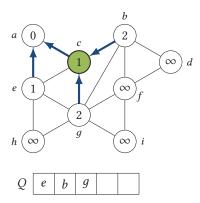
Iteration

- ▶ For each $u \in N(v)$ with $dist(u) = \infty$,
 - set dist(u) := dist(v) + 1,
 - set par(u) := v, and
 - ightharpoonup add u to Q.



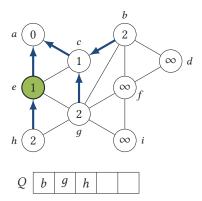
Iteration

ightharpoonup Repeat until Q is empty.



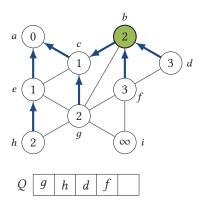
Iteration

► Repeat until *Q* is empty.



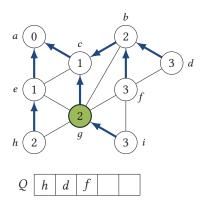
Iteration

ightharpoonup Repeat until Q is empty.



Iteration

ightharpoonup Repeat until Q is empty.



BFS

```
Input: A graph G = (V, E) and a start vertex s \in V.
  For Each v \in V
      Set dist(v) := \infty and par(v) := null.
^{3} Create a new empty queue Q.
  Set dist(s) := 0 and add s to Q.
  While Q is not empty
      v := Q.\mathsf{deque}()
6
      For Each u \in N(v) with dist(u) = \infty
          Set dist(u) := dist(v) + 1 and set par(u) = v.
8
          Add u to Q.
```

BFS - Runtime

Preparation

- Each vertex is accessed once. No edge is accessed.
- ▶ *O*(|*V*|) time

Iteration

- ► Each vertex is added to the queue at most once.
- For each vertex removed from the queue, each neighbour is accessed once.
- ► Thus, runtime is

$$\sum_{v \in V} |N(v)| = 2|E|$$

Total runtime

• O(|V| + |E|)

Depth First Search

Depth First Search

Idea

- Follow path until you get stuck.
- If got stuck, backtrack path until reach unexplored neighbour. Continue on unexplored neighbour.

Applications

- Tree-traversal
- Cycle detection
- Mace generation
- Base for other algorithm

DFS - Algorithm (using recurrence)

Preparation

- For every vertex v, set it as unvisited (vis(v) := False) and set the parent par(v) := null.
- ► Call DFS(s) for the start vertex s.

```
1 Procedure DFS(v)

2 | Set vis(v) = True.

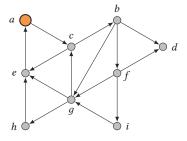
3 | For Each u \in N(v) with vis(u) = False

4 | Set par(u) := v.

5 | Call DFS(u).
```

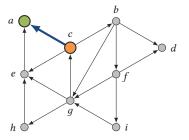
(For large graphs, do not use a recursive implementation.)

Run a DFS with start vertex s.



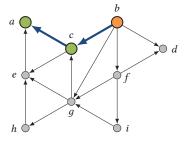
Stack:

Run a DFS with start vertex s.



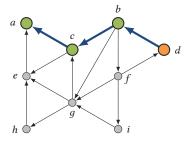
Stack: a

Run a DFS with start vertex s.



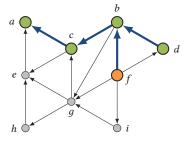
Stack: a c

Run a DFS with start vertex s.



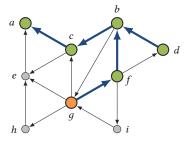
Stack: a c b

Run a DFS with start vertex s.



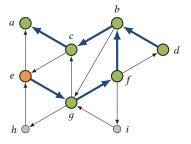
Stack: a c b

Run a DFS with start vertex s.



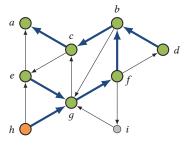
Stack: a c b f

Run a DFS with start vertex s.



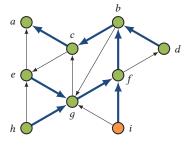
Stack: a c b f g

Run a DFS with start vertex s.



Stack: a c b f g

Run a DFS with start vertex s.



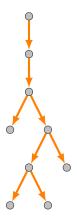
Stack: a c b f

DFS - Runtime

Runtime

- A single DFS(v) call (without recurrence) accesses v and all its neighbours. Thus, runtime is O(|N[v]|) for a single vertex v.
- For each vertex v, DFS(v) is called only once.
- ► Total runtime: O(|V| + |E|)

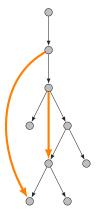
A DFS partitions the edges in four groups.



1. Tree edges.

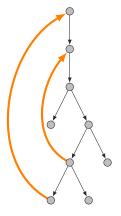
Determined by parent pointers $par(\cdot)$.

A DFS partitions the edges in four groups.



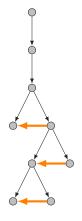
- Tree edges.
 Determined by parent pointers par(·).
- 2. **Forward edges.** From an ancestor to a descented

A DFS partitions the edges in four groups.



- Tree edges.
 Determined by parent pointers par(·).
- 2. **Forward edges.** From an ancestor to a descented
- 3. **Back edges.** From a descented to an ancestor

A DFS partitions the edges in four groups.



- Tree edges.
 Determined by parent pointers par(·).
- 2. **Forward edges.** From an ancestor to a descented
- 3. **Back edges.** From a descented to an ancestor
- 4. **Cross edges.** (only in directed graphs) Remaining edges

DFS – Recognising Edges

On the DFS-tree

- Make a preorder and a postorder traversal.
- ► For each vertex, store a vector (*i*, *j*) where *i* is the index of *v* in the preorder and *j* is the index of *v* in the postorder.

For an edge uv

- Let (i, j) be the indices for u and (x, y) be the indices for v.
- Forward edge: i < x
- ▶ Backward edge: i > x and j < y
- ► Cross edge: i > x and j > y

DFS - Detecting Cycles

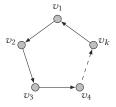
Theorem

A graph ${\cal G}$ has a cycle if and only if any DFS has a back edge.

DFS - Detecting Cycles

$Proof(\Rightarrow)$

Assume G has a cycle $\{v_1, v_2, \dots, v_k\}$. W. l. o. g., let v_1 be the first visited by the DFS.



▶ Then, v_k is an descendent of v_1 in the DFS tree, i. e., v_kv_1 is a back edge.

DFS - Detecting Cycles

$Proof(\Leftarrow)$

Assume a DFS produces a back edge uv.



► Thus, v is an ancestor of u, i. e., the path from v to u using tree edges plus the edge uv form a cycle.