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## **Data Structures for Disjoint Set**

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## Union-Find Data Structure

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# Disjoint Set Data Structure

## Disjoint Set Data Structure

- ▶ Storing a family of sets  $\mathcal{S} = \{S_1, S_2, \dots, S_k\}$  with  $i \neq j \rightarrow S_i \cap S_j = \emptyset$ .
- ▶ Each set  $S_i$  is identified by a *representative*  $s_i \in S_i$ .
- ▶ Three operations: *Make-Set*, *Union*, *Find-Set*

## Make-Set( $x$ )

- ▶ Creates a new set  $\{x\}$ . (Clearly,  $x$  is representative of the set.)
- ▶  $x$  cannot be in any other set already.

## Union( $x, y$ )

- ▶ Merges the sets containing  $x$  and  $y$  into one set.

## Find-Set( $x$ )

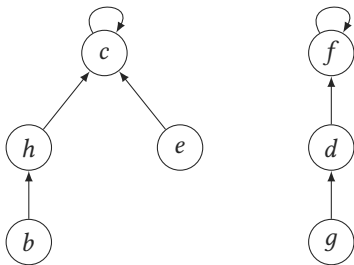
- ▶ Finds the representative of the set containing  $x$ .

# Implementation

## Idea

- ▶ Represent each set  $S_i$  as rooted tree (i. e.,  $\mathcal{S}$  is a forest).
- ▶ Root of tree is representative

Example:  $\mathcal{S} = \{\{b, c, e, h\}, \{d, f, g\}\}$

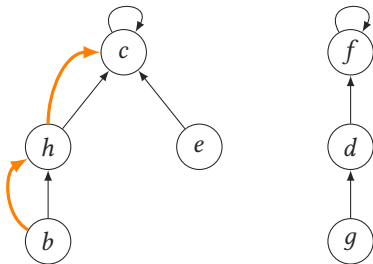


# Implementation — Find-Set

## Find-Set

- ▶ Follow pointers to root.

**Example:**  $\text{Find}(b) = c$



# Implementation — Find-Set

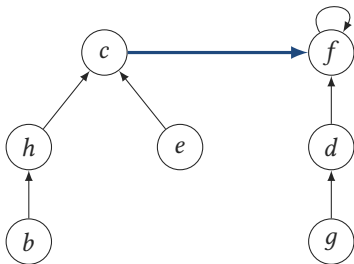
```
1 Procedure Find-Set( $x$ )  
2   While  $\text{par}(x) \neq x$   
3     Let  $x := \text{par}(x)$ .  
4   Return  $x$ 
```

# Implementation — Union

## Union( $x, y$ )

- ▶ Find the representatives  $r_x$  and  $r_y$  of  $x$  and  $y$  (i. e., find roots of trees).
- ▶ Make  $r_x$  parent of  $r_y$

Example: Union( $b, g$ )



# Implementation — Union

```
1 Procedure Union( $x, y$ )  
2   | Set par(Find-Set( $x$ )) := Find-Set( $y$ )
```



# Implementation

## Questions

- ▶ What is the worst-case runtime for these operations?
- ▶ Can we improve the runtime?

# Implementation

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- ▶ Can we improve the runtime?

## Example

- ▶ Assume that we perform  $\text{Union}(1, 2)$ ,  $\text{Union}(1, 3)$ ,  $\text{Union}(1, 4)$ ,  $\dots$ ,  $\text{Union}(1, n)$ .
- ▶ Then, the runtime is in  $O(n^2)$ .

# Improving Find-Set

## Observation

- ▶ If we use Find-Set multiple times on the same element, we have to search for the root each time again.

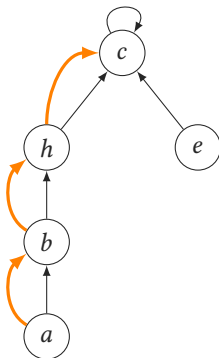
## Idea

- ▶ Update the parent pointer when calling Find-Set such that it points on the root.

```
1 Procedure Find-Set( $x$ )  
2   If  $\text{par}(x) \neq x$  Then  
3     Set  $\text{par}(x) := \text{Find-Set}(\text{par}(x))$   
4   Return  $\text{par}(x)$ 
```

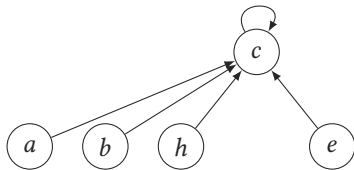
# Improving Find-Set

Example: Find( $a$ )



# Improving Find-Set

**Example:** Find( $a$ )



# Improving Union

## Idea: Union by Rank

- ▶ Keep track of height of a tree.  
Number is denoted as *rank* of a vertex.
- ▶ Make root of smaller tree child of root of larger tree.

1 **Procedure** *Make-Set*( $x$ )

2      $\text{par}(x) := x$

3      $\text{rank}(x) := 0$

## Observation

- ▶ We only need to keep track of the rank of the root.

# Improving Union

```
1 Procedure Union( $x, y$ )  
2   Let  $x := \text{Find-Set}(x)$ .  
3   Let  $y := \text{Find-Set}(y)$ .  
4   If  $\text{rank}(x) > \text{rank}(y)$  Then  
5     | Set  $\text{par}(y) := x$ .  
6   Else  
7     | Set  $\text{par}(x) := y$ .  
8     | If  $\text{rank}(x) = \text{rank}(y)$  Then  
9       | | Set  $\text{rank}(y) := \text{rank}(y) + 1$ .
```

Assume our sets contain  $n$  elements in total.

## Runtime

- ▶ Worst case for single operation:  $O(\log n)$  (Why?)
- ▶ Worst case for  $m$  operations:  $O(m \cdot \alpha(n))$   
Thus,  $O(\alpha(n))$  amortised runtime per operation.

## $\alpha$ -Function

- ▶ Inverse Ackermann function
- ▶  $\alpha(\text{atoms in the universe}) \leq 4$
- ▶ Grows extremely slow. However, it is strictly speaking not constant.



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## Partition Refinement

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# Partition Refinement

## Union-Find

- ▶ Start with a partition  $\mathcal{P} = \{S_1, S_2, \dots, S_k\}$  of a set  $\mathcal{S}$
- ▶ Step by step join two sets  $S_i$  and  $S_j$  together.
- ▶ *Union*( $i, j$ ):  $\mathcal{P} := (\mathcal{P} \setminus \{S_i, S_j\}) \cup \{S_i \cup S_j\}$

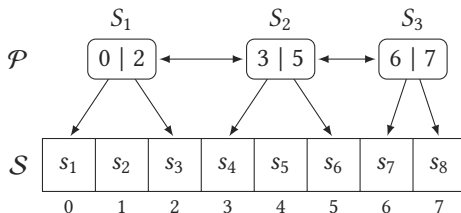
## Partition Refinement

- ▶ Start with a partition  $\mathcal{P} = \{S_1, S_2, \dots, S_k\}$  of a set  $\mathcal{S}$  (often  $\mathcal{P} = \{\mathcal{S}\}$ )
- ▶ Step by step, based on a set  $X \subseteq \mathcal{S}$ , split subsets  $S_i$  into  $S_i \setminus X$  and  $S_i \cap X$ .
- ▶ *Refine*( $X$ ):  $\mathcal{P} := \{S \setminus X, S \cap X \mid S \in \mathcal{P}\}$

# Implementation – Data Structure

## Data Structure

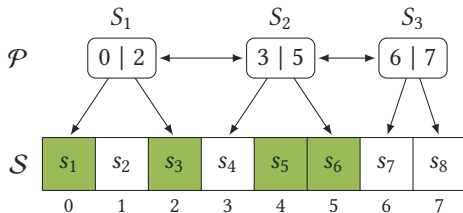
- ▶ Set  $\mathcal{S}$  is an array storing all its elements.
- ▶ Partition  $\mathcal{P}$  is a (doubly-linked) list of subsets  $S_i$
- ▶ Subset  $S_i$  is represented by two integers which describe the interval (i. e., the first and last index) of  $S_i$  in the array  $\mathcal{S}$



# Implementation – Refinement

## Refinement

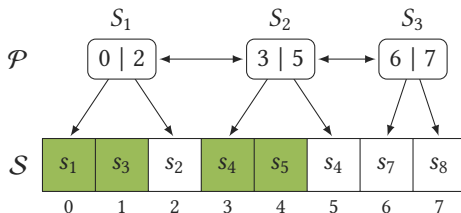
- Flag all elements  $s_i \in X$ .



# Implementation – Refinement

## Refinement

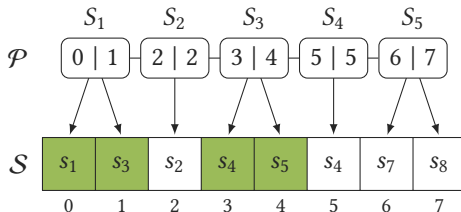
- ▶ Flag all elements  $s_i \in X$ .
- ▶ For each subset  $S_i$ 
  - ▶ Reorder such that flagged elements are in front.



# Implementation – Refinement

## Refinement

- ▶ Flag all elements  $s_i \in X$ .
- ▶ For each subset  $S_i$ 
  - ▶ Reorder such that flagged elements are in front.
  - ▶ Split  $S_i$  into two sets containing only flagged or non-flagged elements.



# Computing Twins

## Twins

In a graph  $G$ , two vertices  $u$  and  $v$  are called *twins* if they have the same neighbourhood. We distinguish between *true twins* where  $N[u] = N[v]$  and *false twins* where  $N(u) = N(v)$ .

## Algorithm Idea

- ▶ Let  $\mathcal{S}$  be a copy of  $V$  and  $\mathcal{P} = \{\mathcal{S}\}$ .
- ▶ For each vertex  $v$  of  $G$ , Refine( $N[v]$ ).

## Observation

- ▶ Two vertices  $u$  and  $v$  are twins if and only if there is no vertex  $w$  such that Refine( $N[w]$ ) separates  $u$  and  $v$ .
- ▶ Therefore, in the resulting partition  $\mathcal{P} = \{S_1, S_2, \dots, S_k\}$ , each subset  $S_i$  is a set of twins.