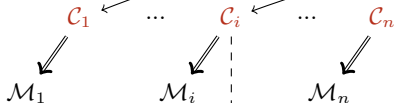


Clusters with parking data

Data sources

GIS + Parking Data
(as RDF)



$$sim_{ij} = C_i \sim C'_j \leftarrow \text{---} C'_j$$

$$pred_{ij} = \mathcal{M}_i(X) * sim_{ij}$$

Clusters without parking data

C'_1

...

C'_j

...

C'_k