






[PO]MDP in practice




The tiger problem



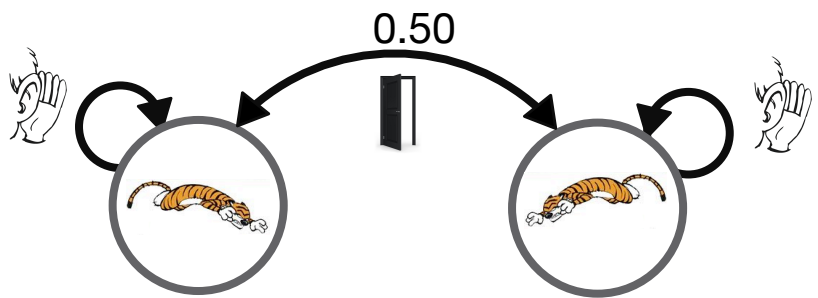
Outcomes

		State	
			
Action		-100	+ 10
		+ 10	-100
		-1	-1

Observations

			
		0.50	0.50
		0.50	0.50
		0.85	0.15
		0.50	0.50
		0.50	0.50
		0.15	0.85

Transitions



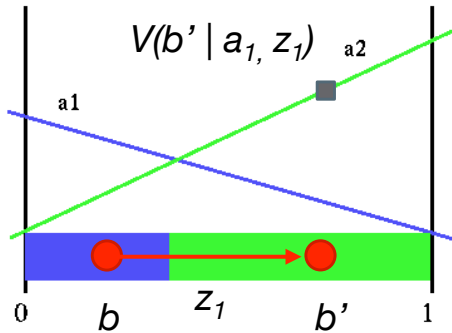
POMDP toolbox

- Download from
Official www.pomp.org <http://cs.brown.edu/research/ai/pomdp/>
Github <https://github.com/lionel-rigoux/CPC-pomdp>
- Compile the C code
- Edit the POMDP description file
- Run the executable or the the helper script

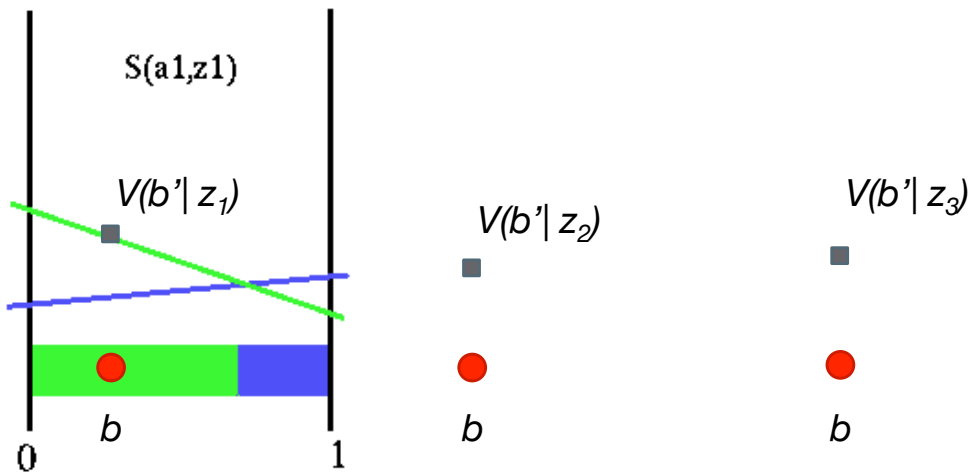


Resolution

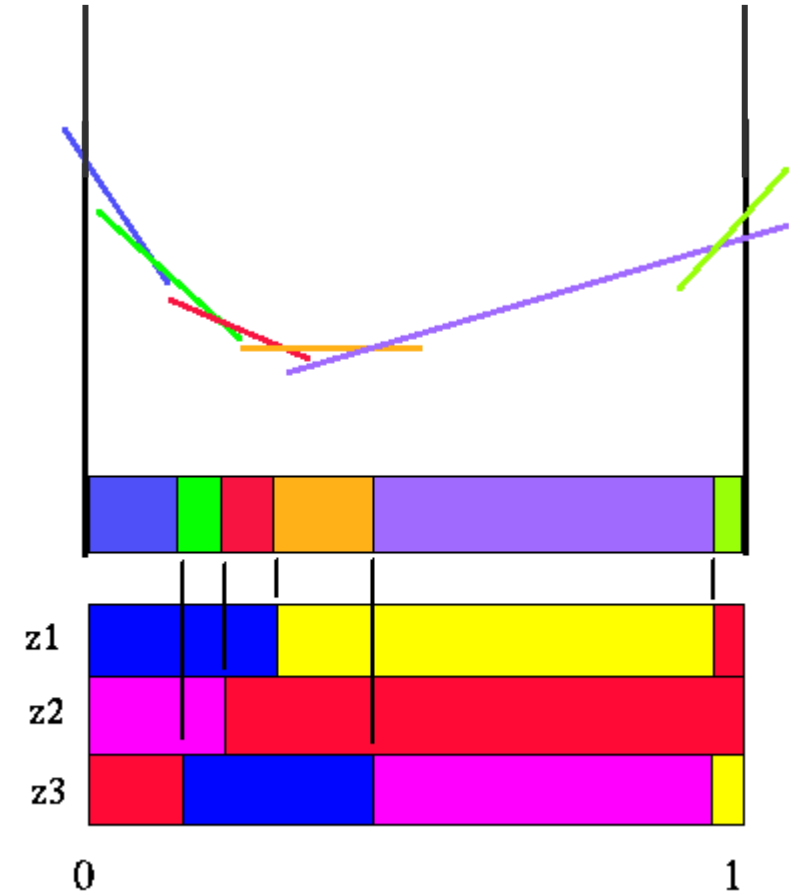
immediate reward



future value $V(b') = \sum V(b'|o)p(o|b)$



belief value $V(b) = r(b) + \gamma V(b')$



POMDP solution

alpha vectors (.alpha file)

```
// action  
// v1 v2 v3 ...  
//  
// ...
```

$b = [p(s=s_1) \ p(s=s_2) \ p(s=s_3) \ \dots]$, sum to 1

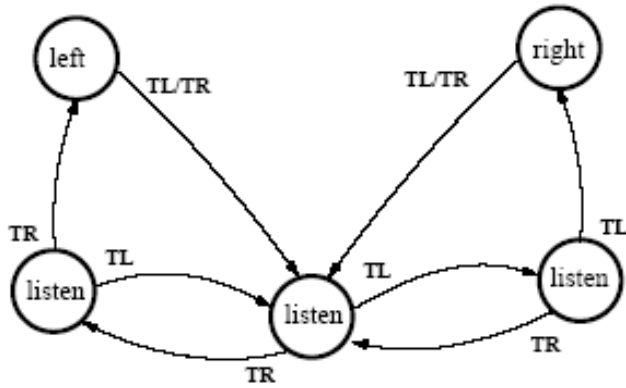
$V(\text{action}, b) = v_1 \ p(s=s_1) + v_2 \ p(s=s_2) + v_3 \ p(s=s_3)$

Some actions can have multiple alpha vectors, some none!

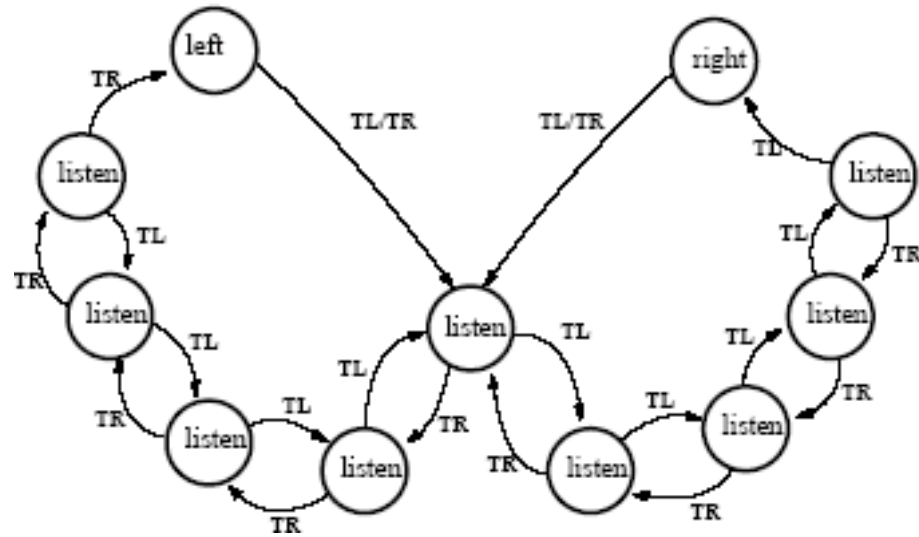


POMDP solution

belief MDP (.pg file)



$$p(o_{TL} \mid \text{listen}, TL) = 0.99$$



$$p(o_{TL} \mid \text{listen}, TL) = 0.75$$





calvin and Hobbes

by BILLY WATSON

drawn by BILL WATSON

10/20

