

[PO]MDP in practice

The tiger problem



The tiger problem



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IF ANYTHING BAD HAPPENS,
IT'S NOT MY FAULT. IT'S FATE.








The tiger problem










Outcomes

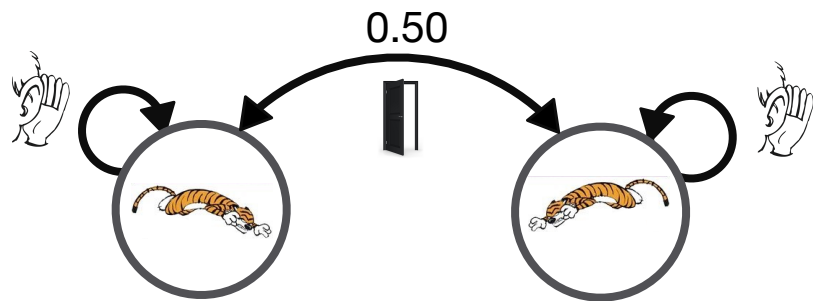
		State	
			
Action		-100	+ 10
		+ 10	-100
		-1	-1








Outcomes

		State	
			
Action		-100	+ 10
		+ 10	-100
		-1	-1







Transitions



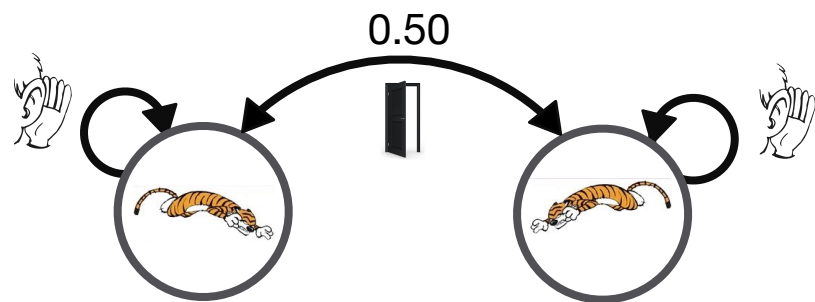
Outcomes





		State	
			
Action		-100	+ 10
		+ 10	-100
		-1	-1

Observations

			
		0.50	0.50
		0.50	0.50
		0.85	0.15

Transitions



		0.50	0.50
		0.50	0.50
		0.15	0.85



POMDP toolbox

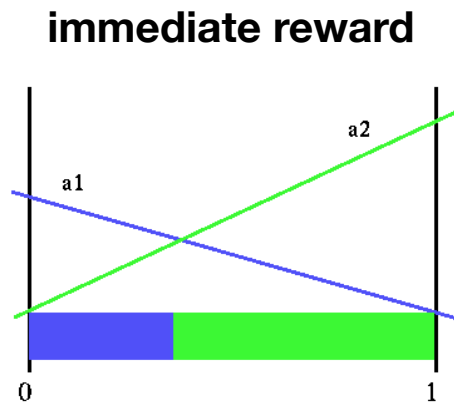
- Download from
Official www.pomp.org <http://cs.brown.edu/research/ai/pomdp/>
Github <https://github.com/lionel-rigoux/CPC-pomdp>
- Compile the C code
- Edit the POMDP description file
- Run the executable or the the helper script



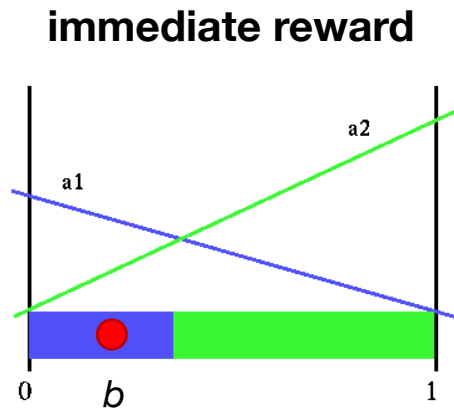
Resolution



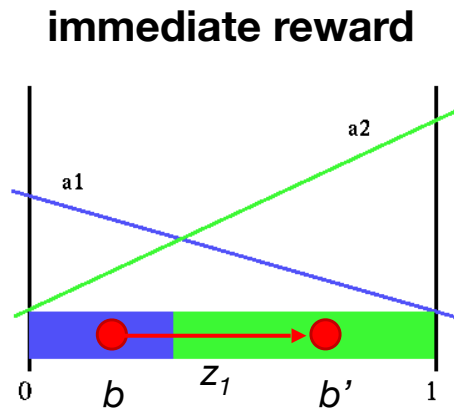
Resolution



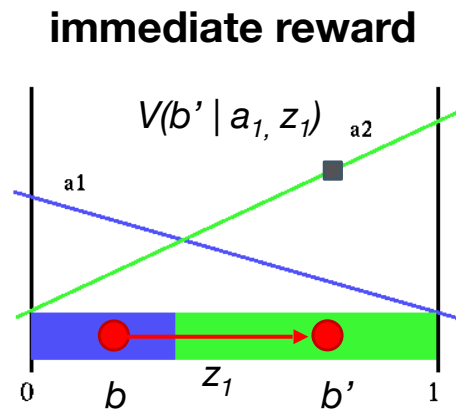
Resolution



Resolution

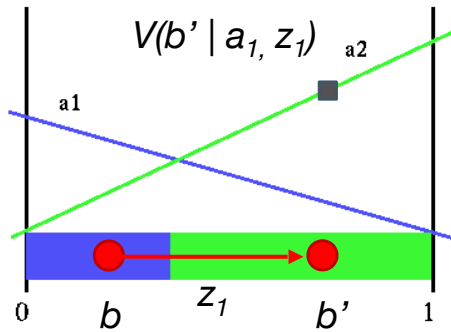


Resolution

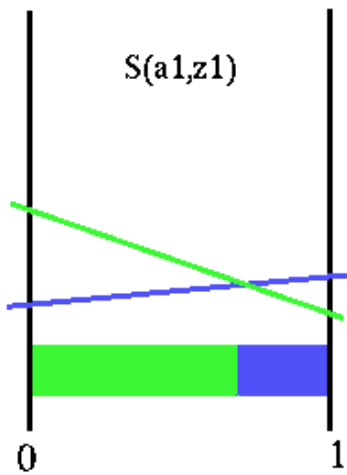


Resolution

immediate reward

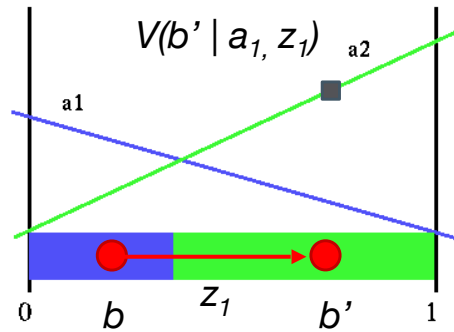


future value

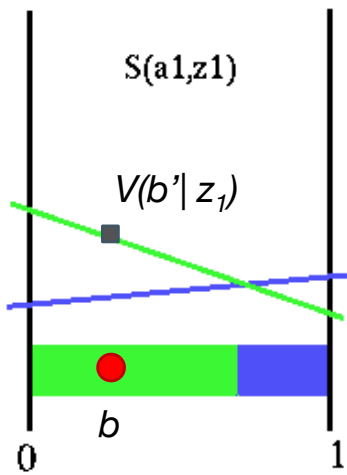


Resolution

immediate reward

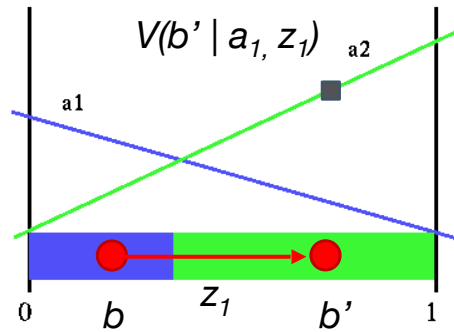


future value

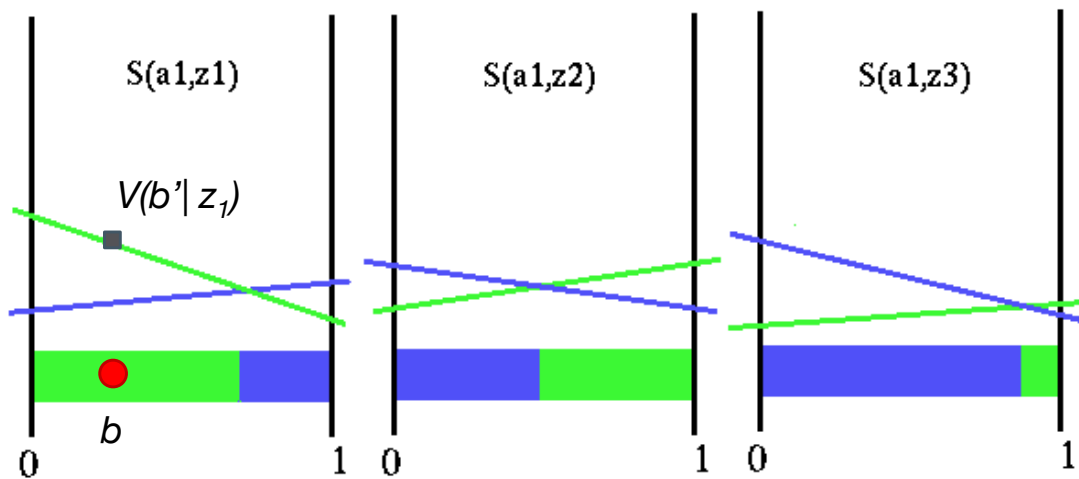


Resolution

immediate reward

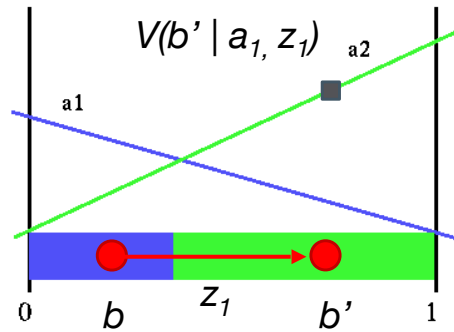


future value

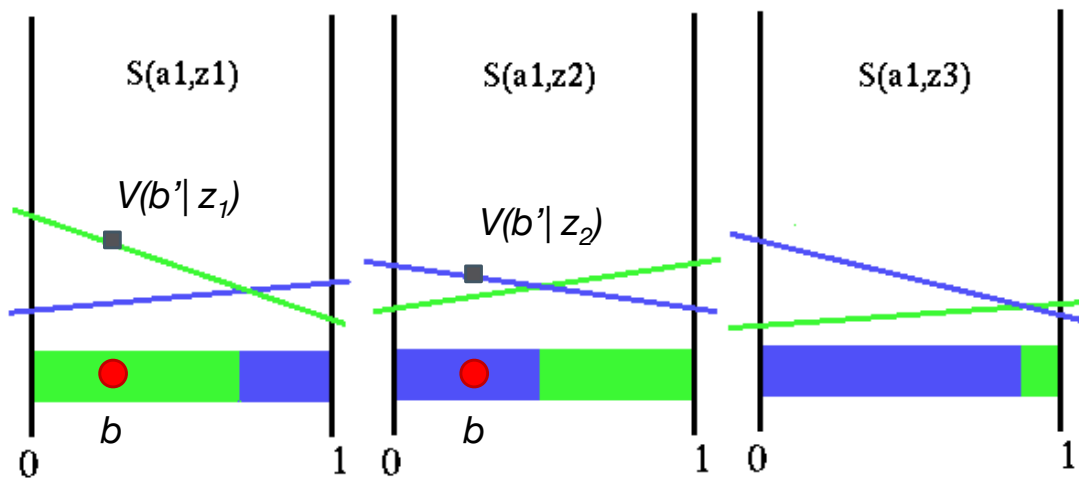


Resolution

immediate reward

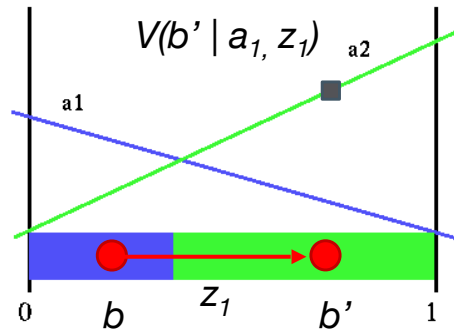


future value

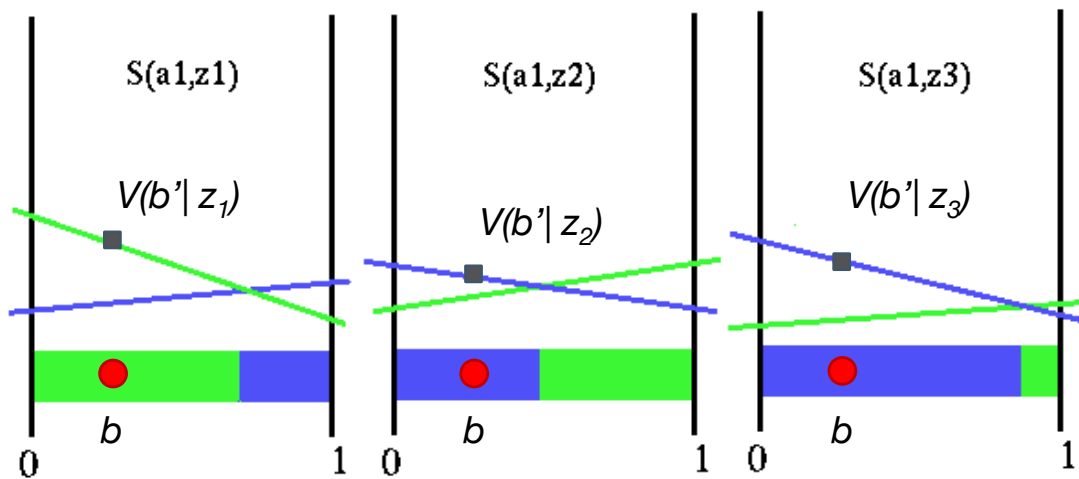


Resolution

immediate reward

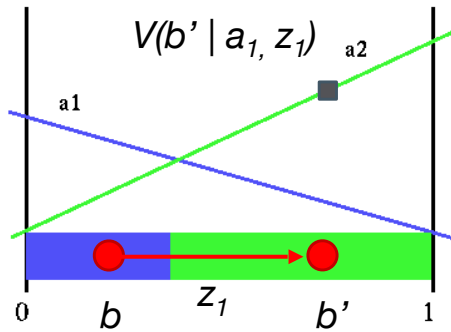


future value

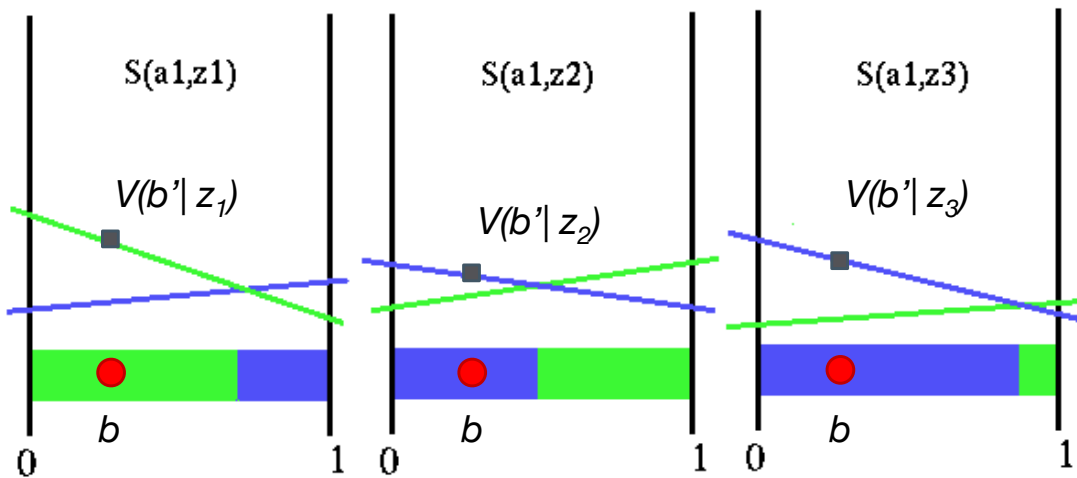


Resolution

immediate reward

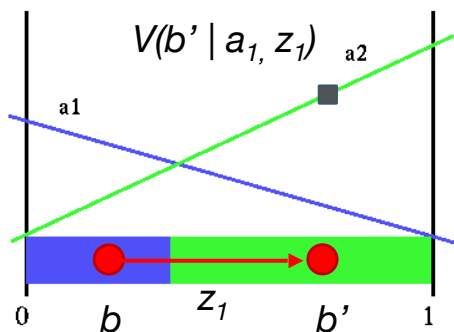


future value $V(b') = \sum V(b'|o)p(o|b)$

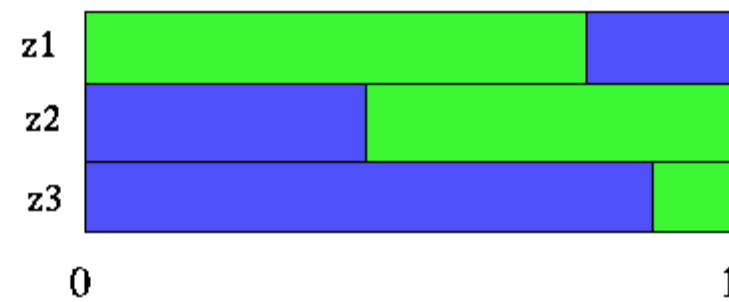
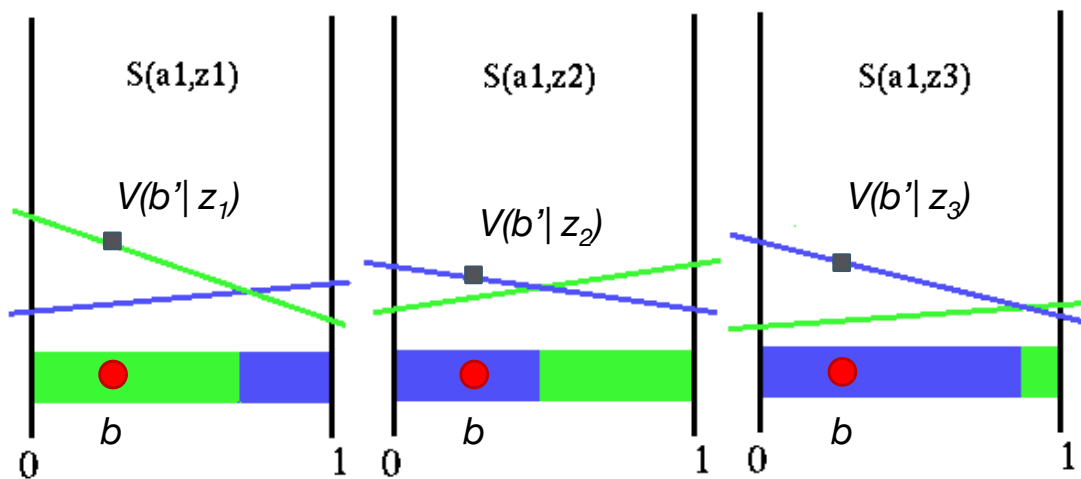


Resolution

immediate reward

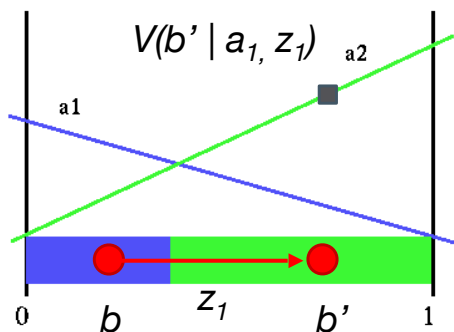


future value $V(b') = \sum V(b'|o)p(o|b)$

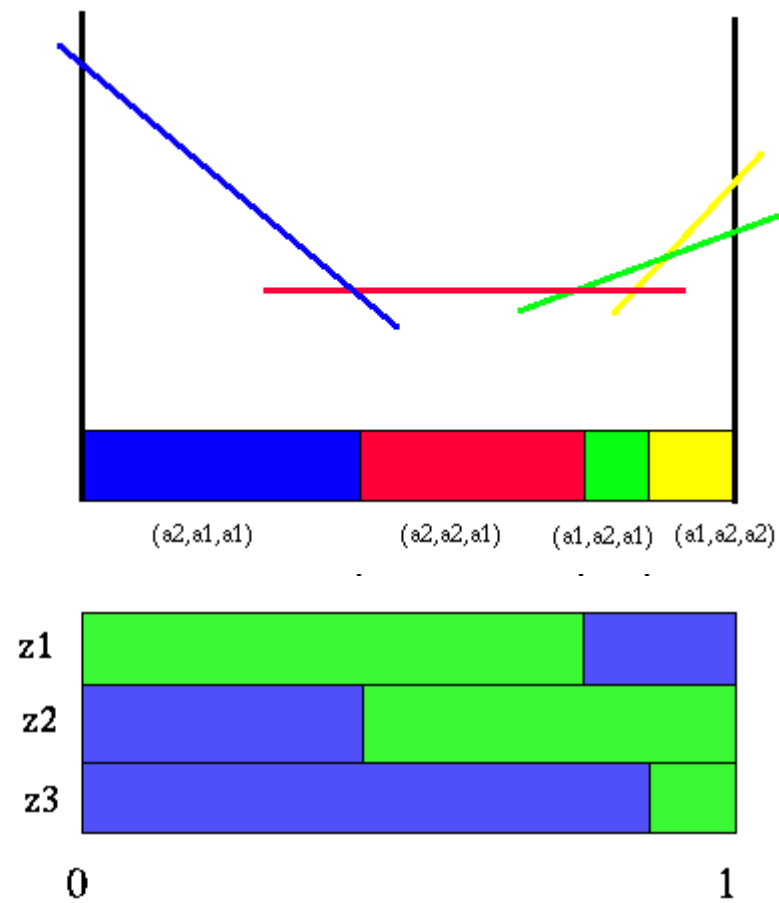
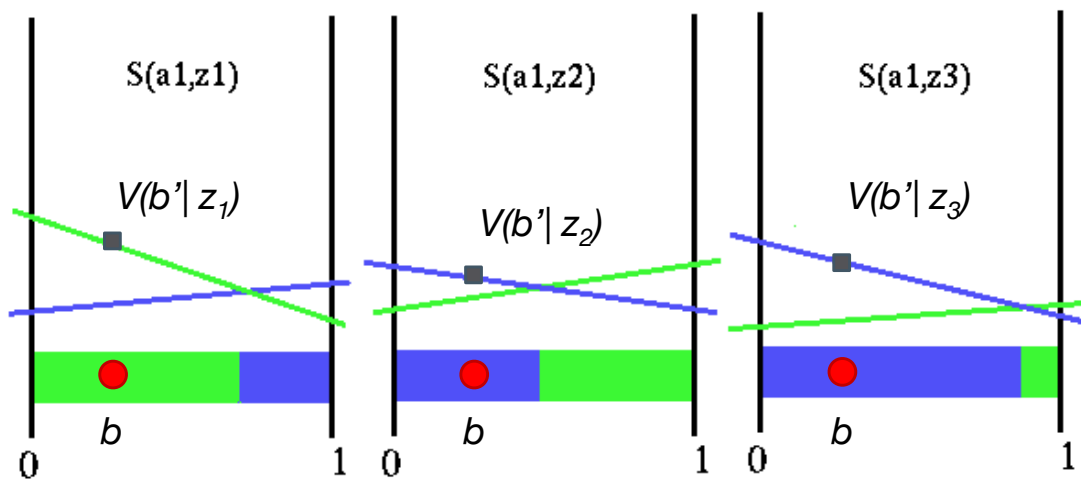


Resolution

immediate reward

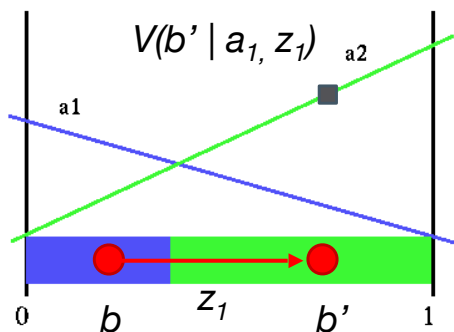


future value $V(b') = \sum V(b'|o)p(o|b)$

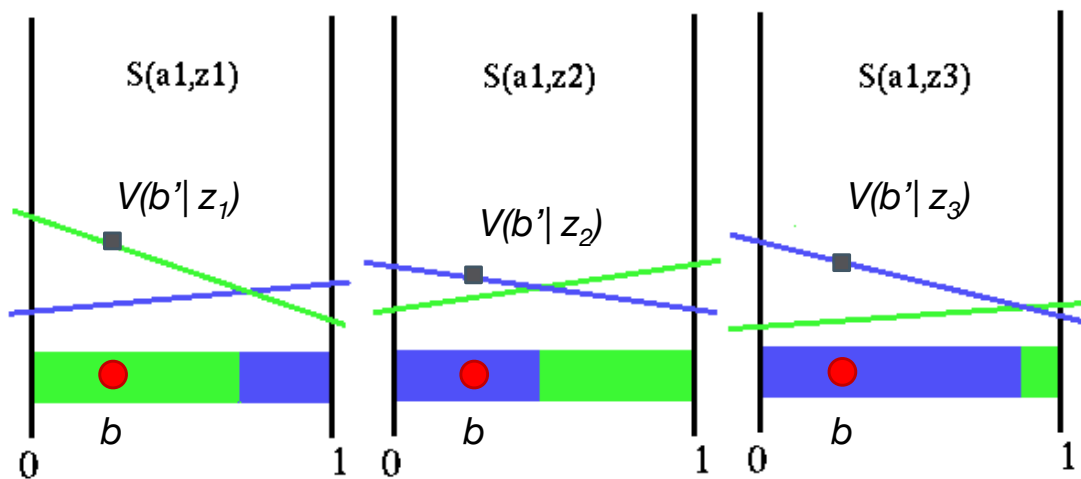


Resolution

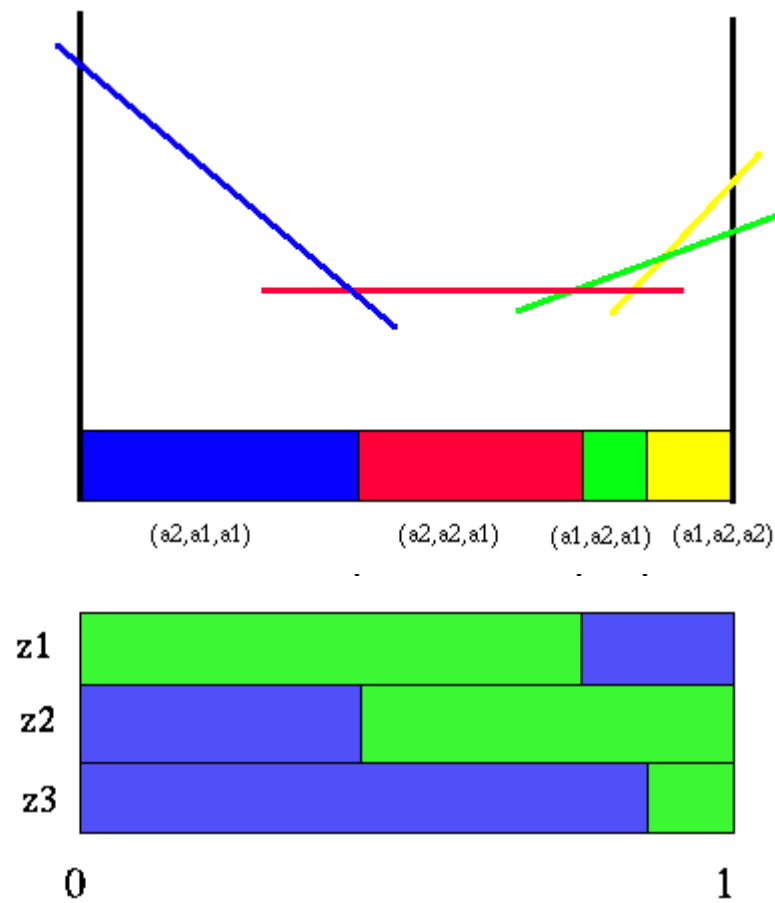
immediate reward



future value $V(b') = \sum V(b' | o) p(o | b)$

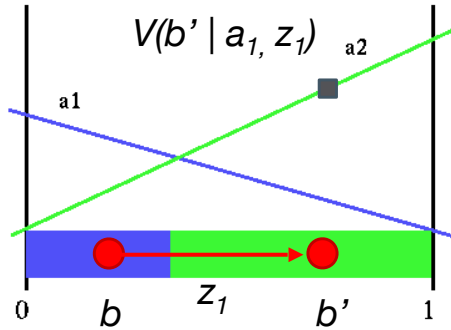


belief value $V(b) = r(b) + \gamma V(b')$

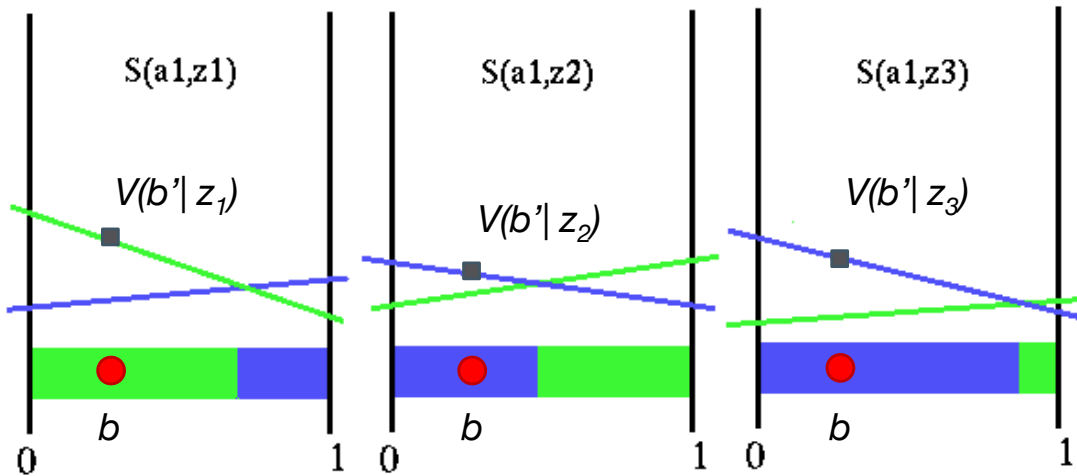


Resolution

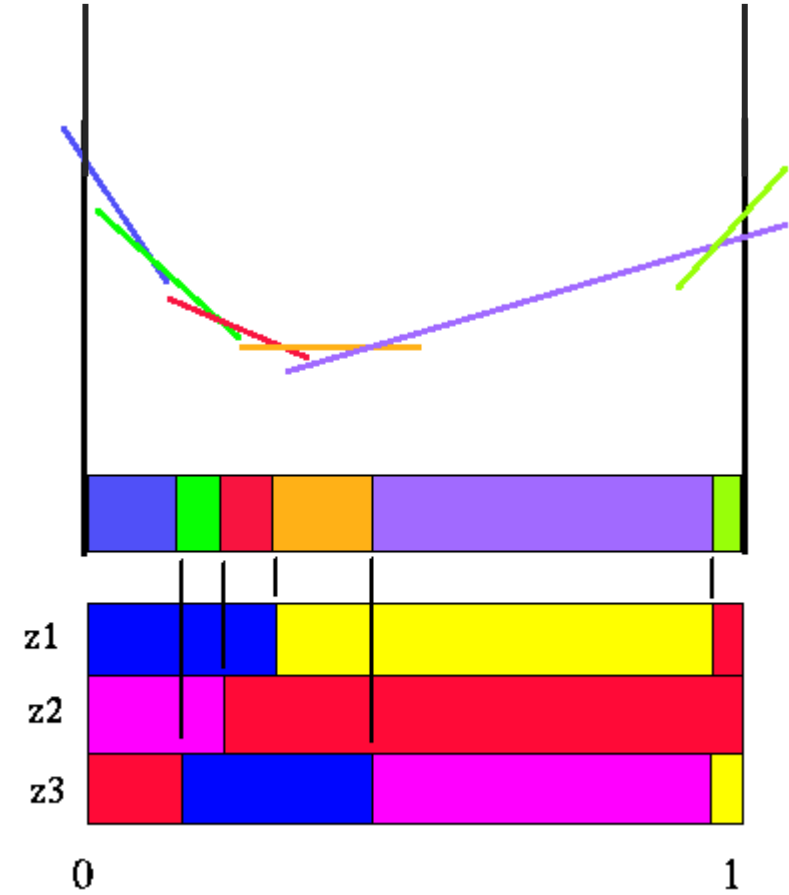
immediate reward



future value $V(b') = \sum V(b' | o) p(o | b)$



belief value $V(b) = r(b) + \gamma V(b')$



POMDP solution

alpha vectors (.alpha file)

```
// action  
// v1 v2 v3 ...  
//  
// ...
```

$b = [p(s=s_1) \ p(s=s_2) \ p(s=s_3) \ \dots]$, sum to 1

$V(\text{action}, b) = v_1 \ p(s=s_1) + v_2 \ p(s=s_2) + v_3 \ p(s=s_3)$

Some actions can have multiple alpha vectors, some none!



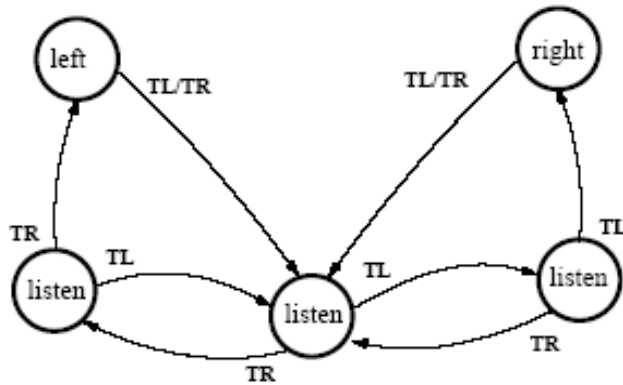
POMDP solution

belief MDP (.pg file)



POMDP solution

belief MDP (.pg file)

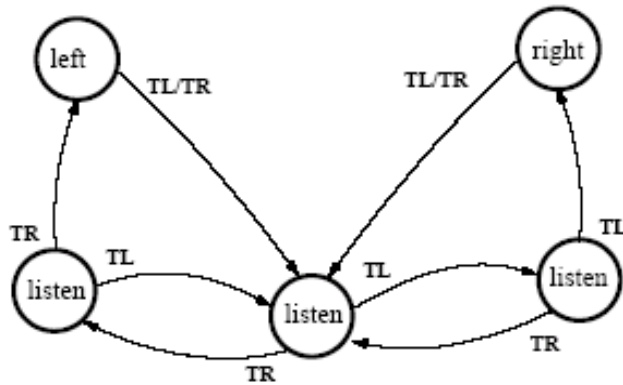


$$p(o_{TL} \mid \text{listen}, TL) = 0.99$$

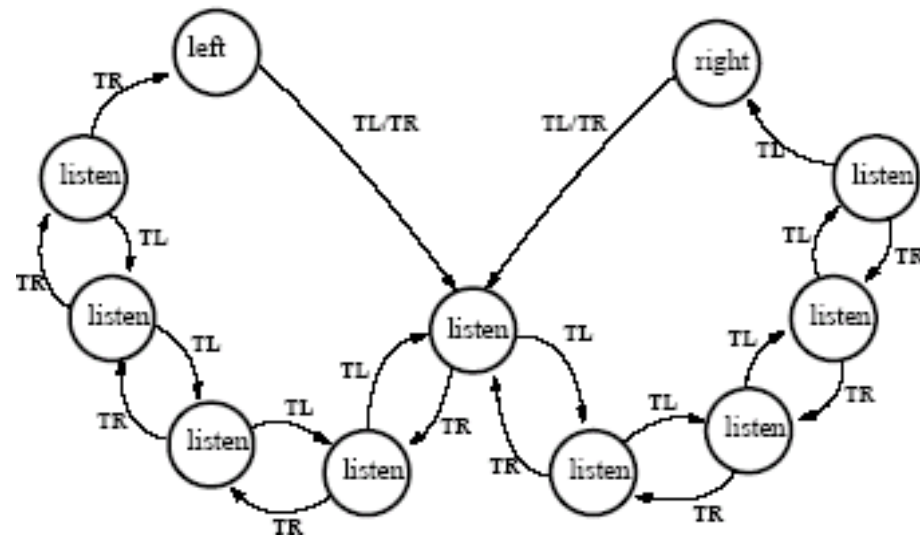


POMDP solution

belief MDP (.pg file)



$$p(o_{TL} \mid \text{listen}, TL) = 0.99$$



$$p(o_{TL} \mid \text{listen}, TL) = 0.75$$





calvin and Hobbes

by WATSON

drawn by BILL WATSON

10/20

