# hw3 writeup

February 24, 2024

# 0.1 Q6 Isocontours of Normal Distributions

```
if sys.version_info[0] < 3:
    raise Exception("Python 3 not detected.")
import numpy as np
import matplotlib.pyplot as plt
import matplotlib
from sklearn import svm
from scipy import io, stats, cluster, ndimage
import math
import pandas as pd

# import learners</pre>
```

/var/folders/x3/qp9ctxln0n7bxhll0\_4rvqmc0000gn/T/ipykernel\_9947/2713042443.py:11
: DeprecationWarning:

Pyarrow will become a required dependency of pandas in the next major release of pandas (pandas 3.0),

(to allow more performant data types, such as the Arrow string type, and better interoperability with other libraries)

but was not found to be installed on your system.

If this would cause problems for you,

please provide us feedback at https://github.com/pandas-dev/pandas/issues/54466

import pandas as pd

```
[]: def create_pdf(mean, cov, start, stop):
    """create the pdf for a normal dist"""

# create a grid of points to evaluate pdf

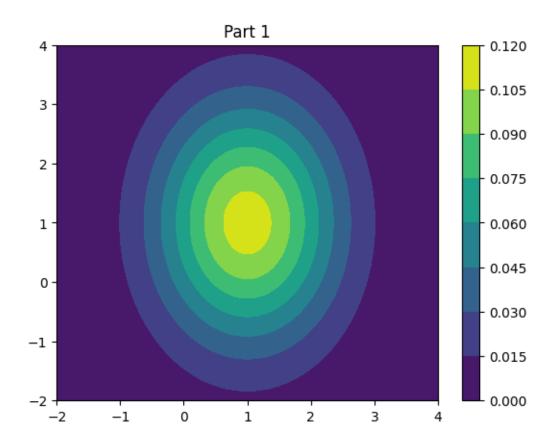
x = np.linspace(start, stop, 100)

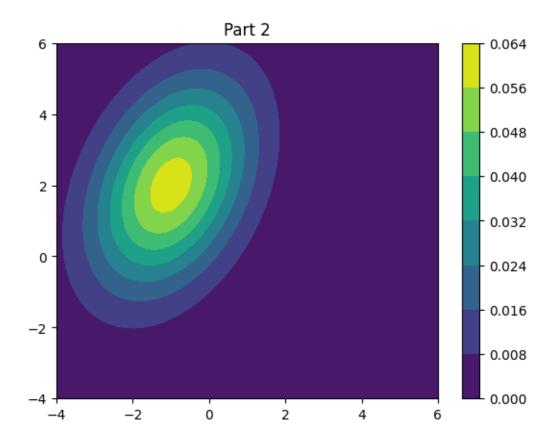
y = np.linspace(start, stop, 100)

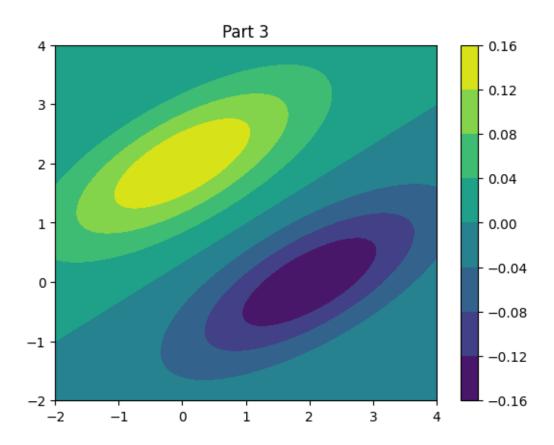
X, Y = np.meshgrid(x, y) # create 2d grid

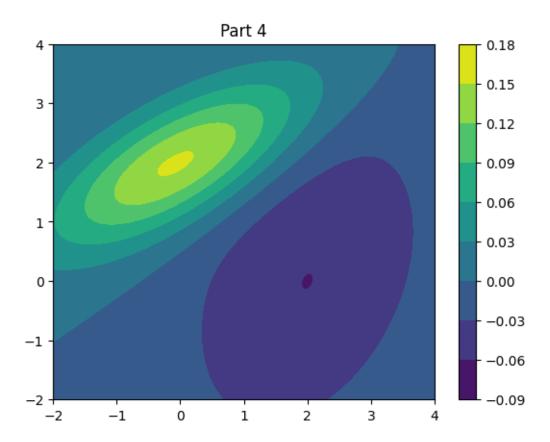
pos = np.dstack((X, Y))
```

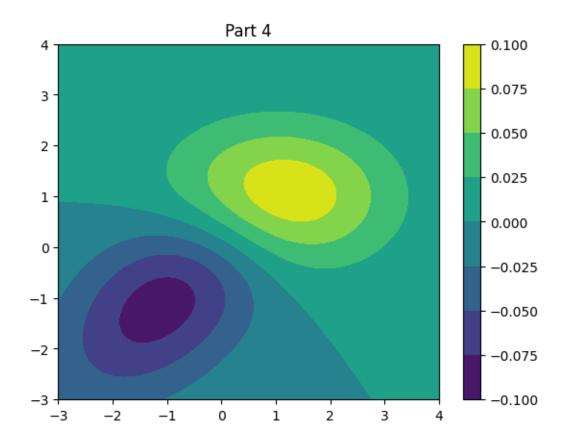
```
# create multivariate normal dist.
    rv = stats.multivariate_normal(mean, cov)
    # evaluate pdf on the grid of points
    Z = rv.pdf(pos) # method for stats.multivariate_normal objects
    return X, Y, Z
def plot contours(name, X, Y, Z):
    """plot the contours of the pdf"""
    # Plot the contours
    plt.contourf(X, Y, Z) # contour w filled colors
    plt.colorbar()
    plt.title(f"Part {name}")
    plt.show()
# Part 1
X, Y, Z = create_pdf([1, 1], [[1, 0], [0, 2]], -2, 4)
plot_contours(1, X, Y, Z)
# Part 2
X, Y, Z = create_pdf([-1, 2], [[2, 1], [1, 4]], -4, 6)
plot_contours(2, X, Y, Z)
# Part 3
X, Y, Z1 = create_pdf([0, 2], [[2, 1], [1, 1]], -2, 4)
_, _, Z2 = create_pdf([2, 0], [[2, 1], [1, 1]], -2, 4)
plot_contours(3, X, Y, Z1-Z2)
# Part 4
X, Y, Z1 = create_pdf([0, 2], [[2, 1], [1, 1]], -2, 4)
_, _, Z2 = create_pdf([2, 0], [[2, 1], [1, 4]], -2, 4)
plot_contours(4, X, Y, Z1 - Z2)
# Part 4
X, Y, Z1 = create_pdf([1, 1], [[2, 0], [0, 1]], -3, 4)
_, _, Z2 = create_pdf([-1, -1], [[2, 1], [1, 2]], -3, 4)
plot_contours(4, X, Y, Z1 - Z2)
```







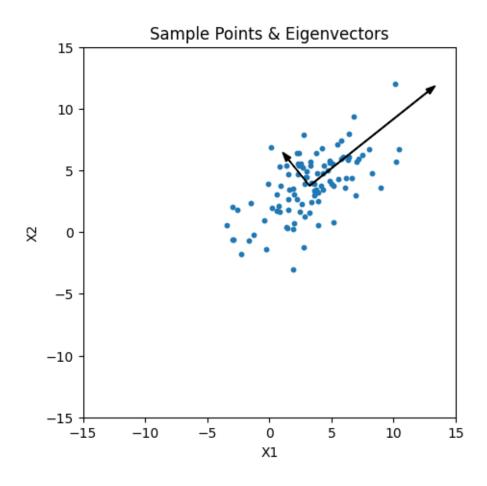


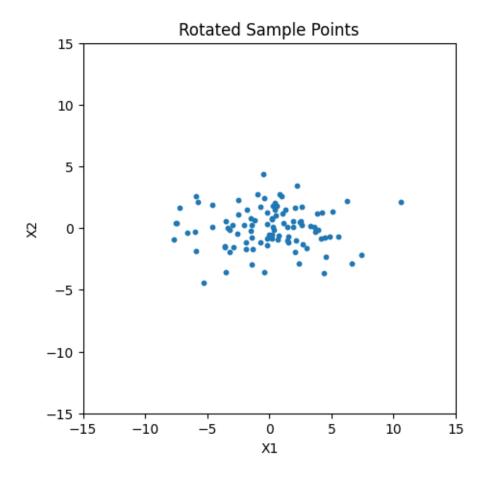


#### 0.1.1 Q7 Eigenvectors of the Gaassian Covariance Matrix

```
[]: np.random.seed(10)
     # Part 1
     N39 = np.random.normal(3, 3, 100) # mean, sd, samples
     N44 = np.random.normal(2, 2, 100)
     samples = np.array([(x, 0.5 * x + y) for (x, y) in zip(N39, N44)])
     sample_mean = np.mean(samples, axis=0) # mean of X, Y respectively
     print(f"Sample Mean: {sample_mean}")
     # print(samples)
     # print(len(samples)) # 100 samples
     # Part 2
     sample_cov = np.cov(samples.T) # each col is a sample point
     print(f"Sample Covariance: {sample_cov}") # Var(X), Cov(X, Y), Cov(Y, X), U
      \hookrightarrow Var(Y)
     # Part 3
     # Each col is an eigenvector
     # eigenvectors[:,i] is the eigenvector corresponding to the eigenvalue_
      ⇔eigenvalues[i]
     eig_val, eig_vect = np.linalg.eig(sample_cov)
     print(f"Eigenvalues: {eig_val}; Eigenvectors: {eig_vect}")
     # Part 4
     plt.figure(figsize=(5, 5)) # square figures
     plt.xlim(-15, 15)
     plt.ylim(-15, 15)
     plt.xlabel("X1")
     plt.ylabel("X2")
     plt.title("Sample Points & Eigenvectors")
     plt.scatter(samples[:, 0], samples[:, 1], s=10) # plot x as 1st col, y as 2nd_1
      ⇔col
     # arrows: covariance eigenvectors; orig at mean; mag: eigenvalues
     mean_x, mean_y = sample_mean
     eig_vect_1 = eig_vect[:, 0] * eig_val[0]
     eig_vect_2 = eig_vect[:, 1] * eig_val[1]
     plt.arrow(
         mean_x,
         mean_y,
         eig_vect_1[0],
         eig_vect_1[1],
         width=0.05,
         head_width=0.5,
```

```
color="black",
)
plt.arrow(
    mean_x,
    mean_y,
    eig_vect_2[0],
    eig_vect_2[1],
    width=0.01,
    head_width=0.5,
    color="black",
plt.show()
# Part 5
# Aligns data with eigenvectors as axes -> often a step in PCA
UT = eig_vect.T # np.linalg.eig is already unit eigen vectors
samples_minus_mean = samples - sample_mean
rotated_samples = np.dot(
    UT, samples_minus_mean.T
).T # revert to each row is a sample point
plt.figure(figsize=(5, 5)) # square figures
plt.xlim(-15, 15)
plt.ylim(-15, 15)
plt.xlabel("X1")
plt.ylabel("X2")
plt.title("Rotated Sample Points")
plt.scatter(rotated_samples[:, 0], rotated_samples[:, 1], s=10)
plt.show()
Sample Mean: [3.23824999 3.75751936]
Sample Covariance: [[8.50150318 4.62655915]
 [4.62655915 6.42395033]]
Eigenvalues: [12.20446758 2.72098593]; Eigenvectors: [[ 0.78072745 -0.62487171]
 [ 0.62487171  0.78072745]]
```





#### 0.1.2 Q8 Gaussian Classifers for Digits and Spam

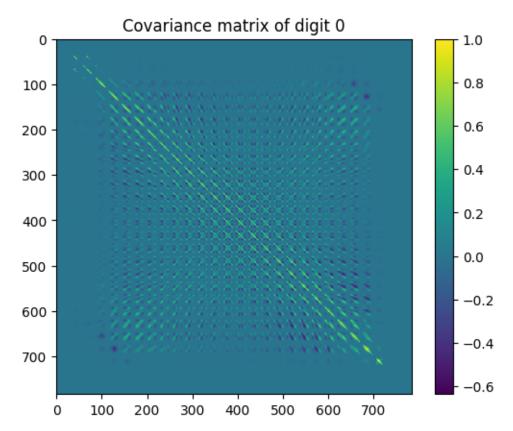
```
[]: def train_val_partition(data, labels, validation_size):
         if len(data) != len(labels):
             raise ValueError("The lengths of data and labels must match.")
         total size = len(labels)
         # in the case where a percentage is given
         if validation_size < 1:</pre>
             validation_size = int(validation_size * total_size)
         shuffled_idx = np.random.permutation(total_size)
         # uses fancy indexing, first reshuffling data, then getting the validation_
      \hookrightarrowset
         val_data = data[shuffled_idx][:validation_size]
         val_label = labels[shuffled_idx][:validation_size]
         train_data = data[shuffled_idx][validation_size:]
         train_label = labels[shuffled_idx][validation_size:]
         return train_data, train_label, val_data, val_label
     mnist = np.load("data/mnist-data-hw3.npz")
     m_train_data, m_train_labels = mnist['training_data'], mnist['training_labels']
     labels = np.unique(m_train_labels) # 0-9
     # 8.1 & 8.2
     # Normalize samples by dividing by the L2-norm
     norms = np.linalg.norm(m_train_data, axis=1, keepdims=True)
     norms[norms < 1e-8] = 1 # to handle small norms</pre>
     m train data norm = m train data / norms
     # reshapes m_train_data_norm by keeping the first dimension and flattening the_
     →rest -> each row is an image
     m_train_data_norm = np.reshape(m_train_data_norm, (m_train_data_norm.shape[0],_
      -1))
     new_mnist = {}
     for label in labels:
         class_idx = (m_train_labels == label).flatten()
         class_data = m_train_data_norm[class_idx]
         mean = np.mean(class_data, axis=0) # mean: array([])
         cov = np.cov(
            class_data, rowvar=False
         ) # cov matrix: array([[], [], ...]); rowvar=false -> column represents a_{\sqcup}
      ⇔variable, while the rows contain observations.
```

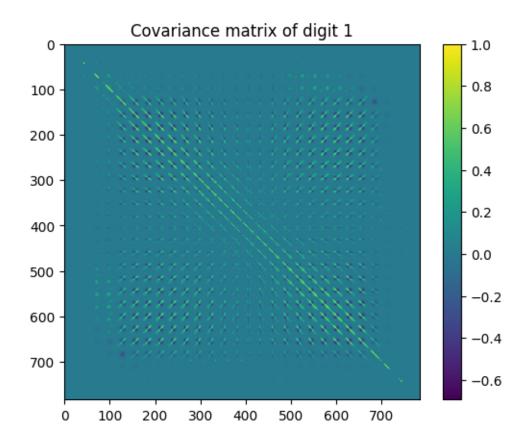
```
# dict with labels as keys and values as array(mean, cov matrix)
new_mnist[label] = (
    mean,
    cov
)

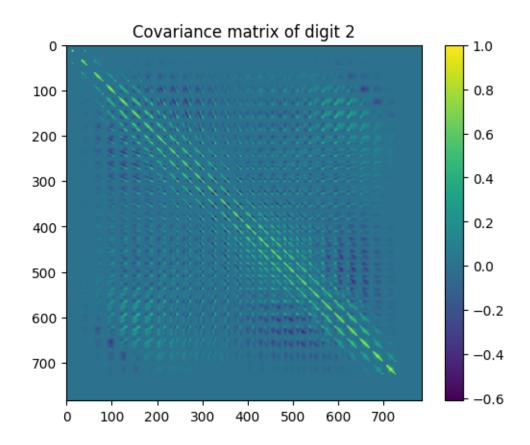
# standardize cov by sd of each var, so its (-1, 1) -> normalized cov matrix
cor = np.corrcoef(class_data, rowvar=False)
cor[np.isnan(cor)] = 0

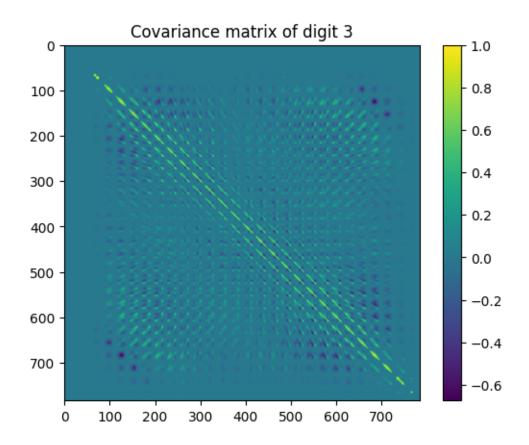
plt.imshow(cor)
plt.colorbar()
plt.title(f"Covariance matrix of digit {label}")
plt.show()

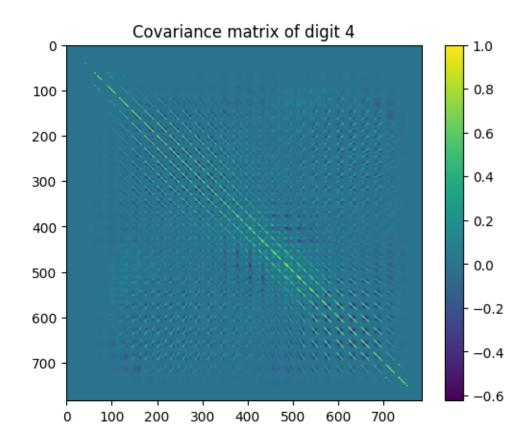
# print(new_mnist[0])
print(len(m_train_data_norm), len(m_train_labels))
```

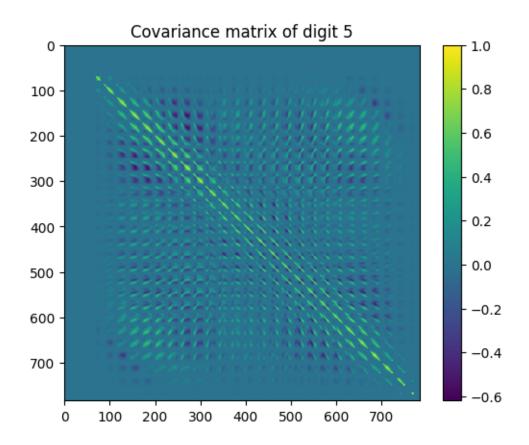


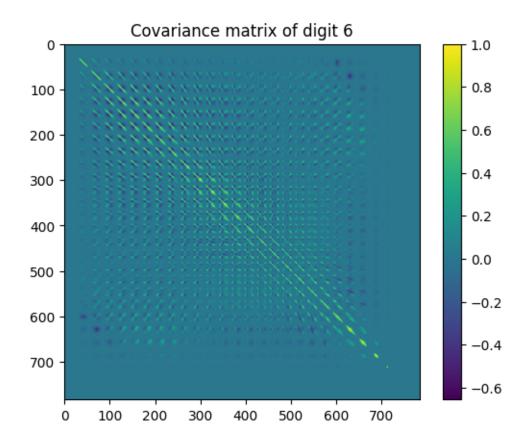


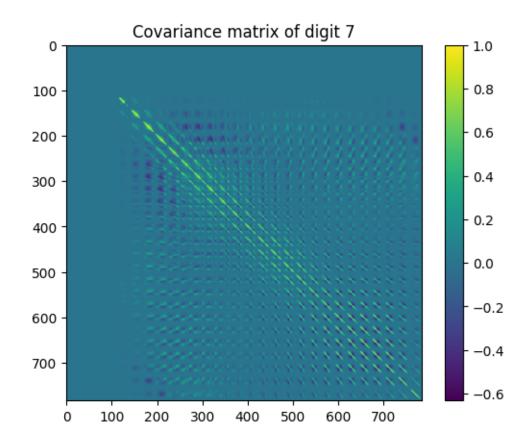


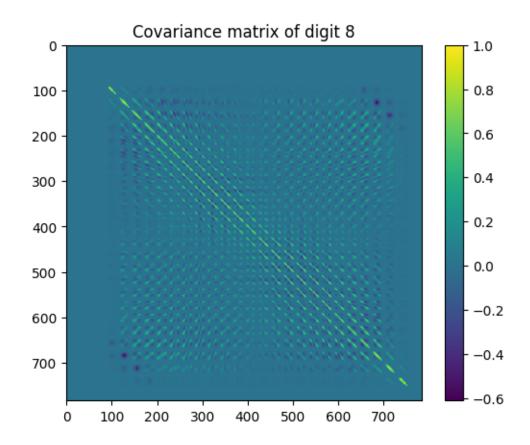


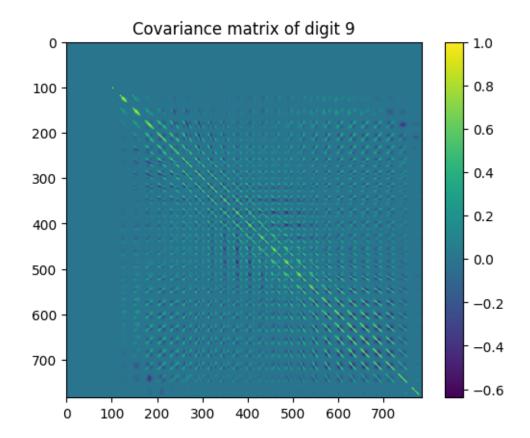












60000 60000

#### 0.1.3 8.2

In order to visualize better, I visualized the correlation matrix, which is a standardization of the cov matrix. As seen in the graphs, the diagonal elements have a higher value, and values tend to be closer to 0 the further it is away from the diagonal. This can be interpretted as: the correlation between nearer pixels are larger than the pixels further apart.

```
[]: # 8.3
class GDA:

def fit(self, train_data, train_label):
    """Train model"""
    self.classes = np.unique(train_label) # unique classes in the dataset
    self.means = {} # Dict to store mean of each class
    self.covmat = {} # Dict to store covariance of each class
    self.priors = {}

# Init pooled covariance matrix: an avg of indiv class cov_mat, ___
weighted by class sample sizes
```

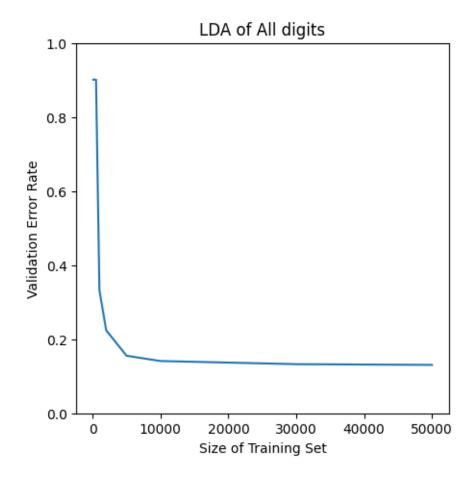
```
self.pooled_covariance = 0
      n_total = train_data.shape[0] # Total number of samples
      for c in self.classes: # for each class
           data_c = train_data[
              train label == c
          ] # Extract samples for class c; train_label == c is a array of TF
          mean_c = np.mean(data_c, axis=0) # Mean of class c, of each column
           covmat_c = np.cov(data_c, rowvar=False) # cov of class c, col are_
\rightarrow variables
           # Store into dictionary
           self.means[c] = mean_c
           self.covmat[c] = covmat c
           self.priors[c] = len(data_c) / n_total
           # Formula: Weighted sample size for pooled covariance
           self.pooled covariance += (len(data c) - 1) * covmat c
       # accounts for the degrees of freedom in each class's covariance matrix
      self.pooled_covariance /= n_total - len(self.classes)
  def predict(self, data, mode):
       """Use the trained model to predict"""
      predictions = []
      for c in self.classes:
           if mode == "lda":
               # Use pooled covariance for LDA
               cov = self.pooled_covariance
           elif mode == "qda":
               # Use class-specific covariance for QDA
               cov = self.covmat[c]
           # Log solves overflowing and underflowing; using + instead of *_
⇔prior bc log
           log_prob = stats.multivariate_normal.logpdf(
               data, mean=self.means[c], cov=cov, allow_singular=True
           ) + math.log(self.priors[c])
           predictions.append(log_prob)
       # finds index of maximum prob across classes for each sample
      highest_idx = np.argmax(predictions, axis=0)
       # get predicted label, and reshape into 1 column vector
      return self.classes[highest_idx].reshape((-1, 1))
```

```
def eval_accuracy(self, data, label, mode):
    """ " Predict the labels and eval accuracy with 0-1 loss"""
    pred = self.predict(data, mode=mode).flatten()
    # print(np.sum(pred == label))
    return np.sum(pred == label) / label.shape[0]
```

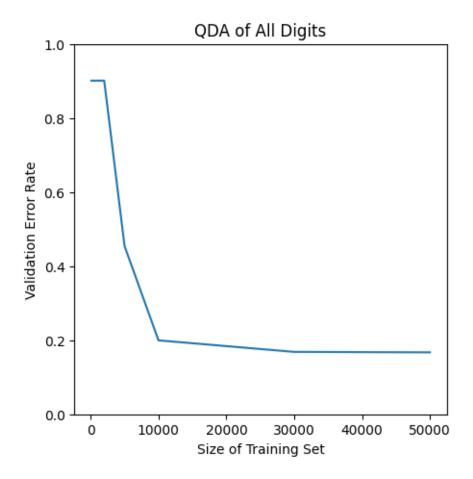
```
[]: # Part 8.3 (Gaussian/linear discriminant analysis)
     # Split the data, with randomly chosed validation size of 10000
     print(len(m_train_data_norm), len(m_train_labels))
     m train data, m train labels, m val data, m val labels = train val partition(
         m_train_data_norm, m_train_labels, 10000
     \# Compute the error rate (1 - \# points correctly classified ) on the val set \sqcup
      \hookrightarrow and plot it
     m val labels.flatten()
     training_size = [100, 200, 500, 1000, 2000, 5000, 10000, 30000, 50000]
     lda_errors = []
     qda_errors = []
     for size in training_size:
         gda = GDA()
         gda.fit(m_train_data[:size], m_train_labels[:size])
         lda_err = 1 - gda.eval_accuracy(m_val_data, m_val_labels, mode="lda")
         lda_errors.append(lda_err)
         qda_err = 1 - gda.eval accuracy(m_val_data, m_val_labels, mode="qda")
         qda_errors.append(qda_err)
     # Part 8.3.a
     plt.figure(figsize=(5, 5))
     plt.plot(training_size, lda_errors)
     plt.xlabel("Size of Training Set")
     plt.ylabel("Validation Error Rate")
     plt.title("LDA of All digits")
     plt.ylim((0, 1))
     plt.show()
     print(lda_errors)
     # Part 8.3.b
     plt.figure(figsize=(5, 5))
     plt.plot(training_size, qda_errors)
     plt.xlabel("Size of Training Set")
     plt.ylabel("Validation Error Rate")
```

```
plt.title("QDA of All Digits")
plt.ylim((0, 1))
plt.show()
print(qda_errors)
```

## 60000 60000



[0.901, 0.901, 0.901, 0.332400000000003, 0.2239, 0.1553, 0.1411, 0.132600000000005, 0.130600000000005]



[0.901, 0.901, 0.901, 0.901, 0.454099999999995, 0.1996, 0.168499999999998, 0.1672000000000002]

## 0.2 8.3.c

LDA seemed to perform a little better than QDA with smaller training sets, but LDA and QDA produces similar error rates on the validation set, especially for training sets that were greater than 10k. We generally may expect QDA to perform better with its increased flexibility, but QDA may result in overfitting especially if the decision boundary is linear

## 0.3 8.3.d

```
[]: # Prepare to store error rates for LDA and QDA for each digit
lda_errors_per_digit = {digit: [] for digit in range(10)}
qda_errors_per_digit = {digit: [] for digit in range(10)}

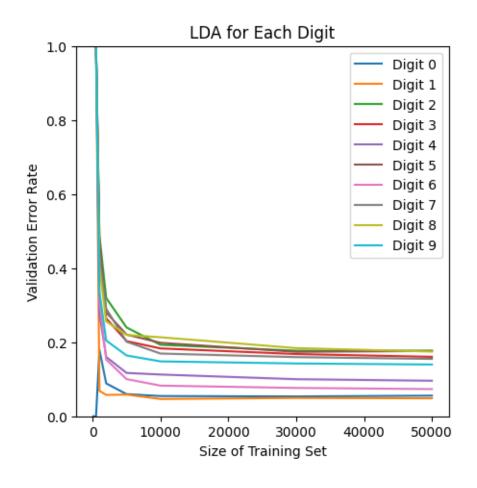
# Partition the data
m_train_data, m_train_labels, m_val_data, m_val_labels = train_val_partition(
    m_train_data_norm, m_train_labels, 10000
)
```

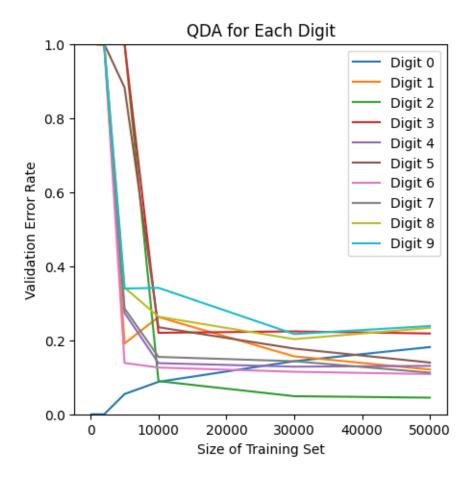
```
# Flatten the validation labels for comparison
m_val_labels = m_val_labels.flatten()
# Define the training sizes
training_size = [100, 200, 500, 1000, 2000, 5000, 10000, 30000, 50000]
# Loop over each training size
for size in training size:
   # Initialize the model
   gda = GDA()
    # Train model
   gda.fit(m_train_data[:size], m_train_labels[:size])
   # Predict for the entire validation set once using LDA
   lda_predictions = gda.predict(m_val_data, mode="lda")
    # Predict for the entire validation set once using QDA
   qda_predictions = gda.predict(m_val_data, mode="qda")
    # Calculate error rates for each digit based on these predictions
   for digit in range(10):
        # Select the indices for the current digit
        digit_indices = m_val_labels == digit
       m_val_labels_digit = m_val_labels[digit_indices]
        # Calculate errors for LDA
       lda_digit_predictions = lda_predictions[digit_indices].flatten()
        lda_errors = np.mean(lda_digit_predictions != digit)
       lda_errors_per_digit[digit].append(lda_errors)
        # Calculate errors for QDA
        qda_digit_predictions = qda_predictions[digit_indices].flatten()
        qda_errors = np.mean(qda_digit_predictions != digit)
        qda_errors_per_digit[digit].append(qda_errors)
   print(f"Training size {size} done.")
# Plotting the errors for LDA
plt.figure(figsize=(5, 5))
for digit, errors in lda_errors_per_digit.items():
   plt.plot(training_size, errors, label=f"Digit {digit}")
plt.xlabel("Size of Training Set")
plt.ylabel("Validation Error Rate")
plt.title("LDA for Each Digit")
```

```
plt.legend()
plt.ylim(0, 1)
plt.show()

# Plotting the errors for QDA
plt.figure(figsize=(5, 5))
for digit, errors in qda_errors_per_digit.items():
    plt.plot(training_size, errors, label=f"Digit {digit}")
plt.xlabel("Size of Training Set")
plt.ylabel("Validation Error Rate")
plt.title("QDA for Each Digit")
plt.legend()
plt.ylim(0, 1)
plt.show()
```

```
Training size 100 done.
Training size 200 done.
Training size 500 done.
Training size 1000 done.
Training size 2000 done.
Training size 5000 done.
Training size 10000 done.
Training size 30000 done.
Training size 50000 done.
Training size 50000 done.
```





# 1 8.3.d

For LDA, our experiments show that 0 and 1 were the easiest to classify, whereas QDA best classifies 0 and 1 but with the error rate for 0 increasing as training set gets larger.

#### 1.1 8.4

My kaggle username is and rewcchuang, I got a accuracy score of .798 for the MNIST set. I used my LDA model without adding new features

```
test_labels = test_labels.astype(int).flatten()
df = pd.DataFrame({"Category": test_labels})
df.index += 1
df.to_csv(f"{dataset}_gda_pred.csv", index_label="Id")
kaggle_submit("mnist", m_train_data, m_train_labels, mnist["test_data"])
```

```
[]: spam = np.load(f"data/spam-data-hw3.npz")

kaggle_submit(
    "spam",
    spam["training_data"],
    spam["training_labels"],
    spam["test_data"],
)
```

## 1.2 8.5

My kaggle username is and rewcchuang, I got a accuracy score of .783 for the Spam set. I used my LDA model without adding new features