DATA STRUCTURES

Trees. Binary trees.

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2022 - 2023

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In previous lecture

- Hash tables
 - Coalesced chaining
 - Open addressing

Today

- Trees
 - Terminology
 - Binary Trees

Trees

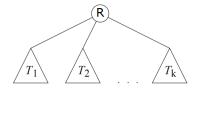
- Trees represent one of the most commonly used data structures.
- In graph theory, a **tree** is a connected, acyclic and usually undirected graph.
- When talking about trees as data structures, we actually mean **rooted trees** in which one node is designated to be the *root* of the tree.

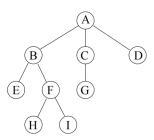
Tree - Definition

 \square A **tree** is a finite set \mathcal{T} of 0 or more elements, called *nodes*, with the following properties:

- If $\mathcal T$ is empty, then the tree is empty
- If T is not empty then:
 - There is a special node, R, called the root of the tree
 - The rest of the nodes are divided into k (k ≥ 0) disjunct trees, T₁, T₂, ..., T_k, the root node R being linked by an edge to the root of each of these trees. The trees T₁, T₂, ..., T_k are called the subtrees of R.

Tree - visualization





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- The **degree** of a node is defined as the number of its children.
- The nodes with the degree 0 are called leaf nodes.
- The nodes that are not leaf nodes are called internal nodes.

The **depth** or **level** of a node is the length of the unique path (measured as the number of edges on the path) from the root to the node.

The root of the tree is at level 0 (and has depth 0).

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All leaves are at height 0.

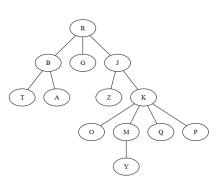
The **depth** or **level** of a node is the length of the unique path (measured as the number of edges on the path) from the root to the node.

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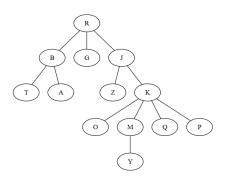
The **height** of a node is the length of the longest path from the node to a leaf.

All leaves are at height 0.

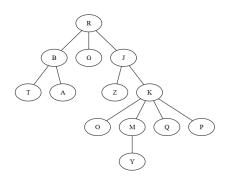
The **height of the tree** is defined as the height of the root node, i.e. the length of the longest path from the root to a leaf.



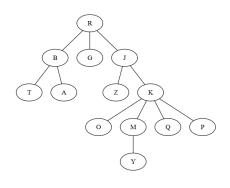
Root of the tree:



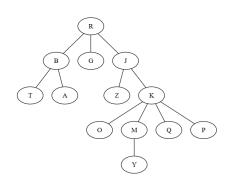
- Root of the tree: R
- Children of R:



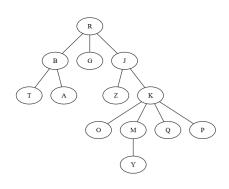
- Root of the tree: R
- Children of R: B, G, J
- Parent of *M*:



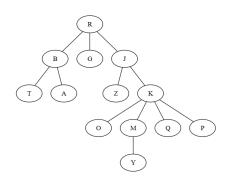
- Root of the tree: R
- Children of R: B, G, J
- Parent of M: K
- Leaf nodes:



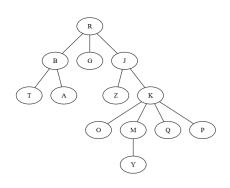
- Root of the tree: R
- Children of R: B, G, J
- Parent of M: K
- Leaf nodes: T, A, G, Z, O, Y, Q, P
- Internal nodes:



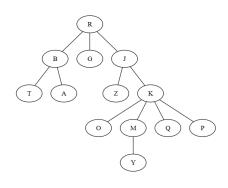
- Root of the tree: R
- Children of R: B, G, J
- Parent of M: K
- Leaf nodes: T, A, G, Z, O, Y, Q, P
- Internal nodes: R, B, J, K, M
- Depth of node *K*:



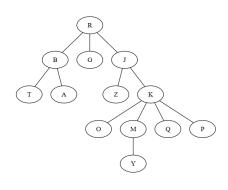
- Root of the tree: R
- Children of R: B, G, J
- Parent of M: K
- Leaf nodes: T, A, G, Z, O, Y, Q, P
- Internal nodes: R, B, J, K, M
- Depth of node K: 2 (path R-J-K)
- Height of node *K*:



- Root of the tree: R
- Children of R: B, G, J
- Parent of M: K
- Leaf nodes: T, A, G, Z, O, Y, Q, P
- Internal nodes: R, B, J, K, M
- Depth of node K: 2 (path R-J-K)
- Height of node K: 2 (path K-M-Y)
- Height of the tree (height of node R):



- Root of the tree: R
- Children of R: B, G, J
- Parent of M: K
- Leaf nodes: T, A, G, Z, O, Y, Q, P
- Internal nodes: R, B, J, K, M
- Depth of node K: 2 (path R-J-K)
- Height of node K: 2 (path K-M-Y)
- Height of the tree (height of node R): 4
- Nodes on level 2:



- Root of the tree: R
- Children of R: B, G, J
- Parent of M: K
- Leaf nodes: T, A, G, Z, O, Y, Q, P
- Internal nodes: R, B, J, K, M
- Depth of node K: 2 (path R-J-K)
- Height of node K: 2 (path K-M-Y)
- Height of the tree (height of node R): 4
- Nodes on level 2: T, A, Z, K

Representing k-ary trees

- How can we represent a tree in which every node has at most *k* children?
- One option is to have a structure *node* with the following:
 - information from the node
 - address of the parent node (not mandatory)
 - k fields, one for each (possible) child
- Obs: this is doable if k is not too large

Representing k-ary trees

- \square Another option is to have a structure *node* with the following:
 - information from the node
 - address of the parent node (not mandatory)
 - an array of length k, in which each element is the address of a child
 - number of children (number of occupied positions from the above array)

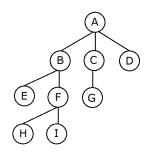
The disadvantage of these approaches is that we occupy space for k children even if most nodes have less children.

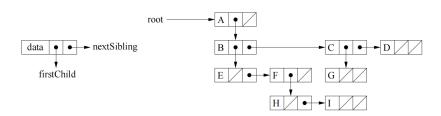
Representing k-ary trees

A third option is the so-called *left-child right-sibling* representation in which we have a structure for a node which contains the following:

- information from the node
- address of the parent node (not mandatory)
- address of the leftmost child of the node
- address of the right sibling of the node (next node on the same level from the same parent).

Left-child right sibling representation - Example





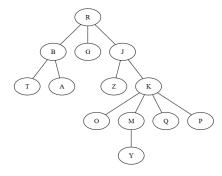
Tree traversals

- Traversing a tree means visiting all of its nodes.
- A node is said to be *visited* when the program control arrives at the node, usually with the purpose of performing some operation on it.
- For a k-ary tree there are 2 possible traversals:
 - Depth-first traversal
 - Breadth-first traversal (level order traversal)

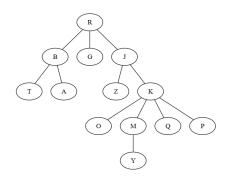
Depth-first traversal

- Traversal starts with visiting the root of the tree
- We visit one of the children, than one child of that child, and so on. We go down (in depth) as much as possible, and continue with other children of a node only after all descendants of the "first" child were visited.
- For depth first traversal we use a stack to remember the nodes in the traversal.

Depth-first traversal - Example



Depth-first traversal - Example

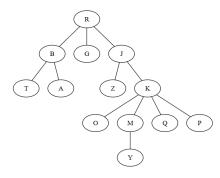


- ▶ Stack s with the root: R
- ▶ Visit *R* (pop from stack) and push its children: *s* = [B G J]
- Visit B and push its children: s = [T A G J]
- ▶ Visit *T* and push nothing: *s* = [AG J]
- Visit A and push nothing: s = [GJ]
- ▶ Visit G and push nothing: s = [J]
- Visit J and push its children: s = [Z K]
- ▶ etc...

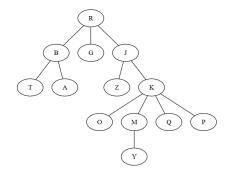
Level-order traversal

- Traversal starts with visiting the root of the tree
- We visit all children of the root (one by one) and once all of them have been visited we go to their children and so on.
 - We go down one level, only when all nodes from a level have been visited.
- For level order traversal we use a queue to remember the nodes that have to be visited.

Level-order traversal - Example



Level-order traversal - Example



- Queue q with the root: R
- ▶ Visit *R* (pop from queue) and push its children: *q* = [B G J]
- Visit B and push its children: q= [G J T A]
- ▶ Visit *G* and push nothing: *q* = [JT A]
- ▶ Visit J and push its children: q = [T A Z K]
- ▶ Visit *T* and push nothing: *q* = [A Z K]
- ▶ Visit A and push nothing: q = [Z K]
- ▶ etc...

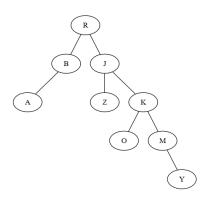
Binary trees

An ordered tree in which each node has at most two children is called **binary tree**.

In a binary tree we call the children of a node the **left child** and **right child**.

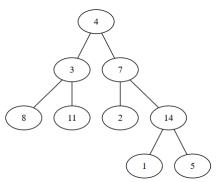
Even if a node has only one child, we still have to know whether that is the left or the right one.

Binary tree - Example

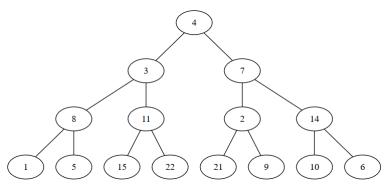


- A is the left child of B
- Y is the right child of M

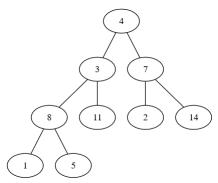
A binary tree is called **full** if every internal node has exactly two children.



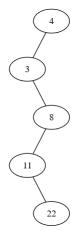
A binary tree is called **complete** if every level of the tree is completely filled.



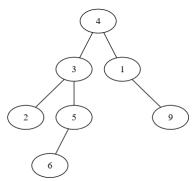
A binary tree is called **almost complete** if every level of the tree is completely filled, except possibly the bottom level, which is filled from left to right.



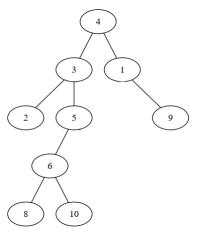
A binary tree is called **degenerated** if every internal node has exactly one child (it is actually a chain of nodes).



A binary tree is called **balanced** if the difference between the height of the left and right subtrees is at most 1 for every node from the tree.



There are many binary trees that are none of the above categories, for example:



How many edges are there in a binary tree with *n* nodes?

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- \bigcirc How many edges are there in a binary tree with n nodes?
- \triangle A binary tree with n nodes has exactly n-1 edges.
 - This is true for every tree, not just binary trees
- How many nodes are there in a complete binary tree of height N?
- The number of nodes in a complete binary tree of height N is $2^{N+1} 1$ $(1 + 2 + 4 + 8 + ... + 2^{N})$

What is the maximum number of nodes in a binary tree of height *N*?

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The maximum number of nodes in a binary tree of height N is $2^{N+1} - 1$ - if the tree is complete.

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- What is the minimum number of nodes in a binary tree of height N?
- The minimum number of nodes in a binary tree of height N is N+1 if the tree is degenerated.
- A binary tree with N nodes has a height between $[log_2(N+1)]$ and N-1.

Domain of ADT Binary Tree:

$$\mathcal{BT} = \{ \textit{bt} \mid \textit{bt} \text{ binary tree with nodes containing information}$$
 of type TElem $\}$

- init(bt)
 - descr: creates a new, empty binary tree
 - pre: true
 - **post:** $bt \in \mathcal{BT}$, bt is an empty binary tree

- initLeaf(bt, e)
 - descr: creates a new binary tree, having only the root with a given value
 - pre: *e* ∈ *TElem*
 - post: bt ∈ BT, bt is a binary tree with only one node (its root) which contains the value e

- initTree(bt, left, e, right)
 - descr: creates a new binary tree, having a given information in the root and two given binary trees as children
 - **pre:** *left*, $right \in \mathcal{BT}$, $e \in TElem$
 - post: bt ∈ BT, bt is a binary tree with left child equal to left, right child equal to right and the information from the root is e

- insertLeftSubtree(bt, left)
 - descr: sets the left subtree of a binary tree (if the tree had a left subtree, it will be changed)
 - pre: bt, $left \in \mathcal{BT}$
 - **post:** $bt' \in \mathcal{BT}$, the left subtree of bt' is equal to *left*

- insertRightSubtree(bt, right)
 - descr: sets the right subtree of a binary tree (if the tree had a right subtree, it will be changed)
 - pre: bt, $right \in \mathcal{BT}$
 - **post:** $bt' \in \mathcal{BT}$, the right subtree of bt' is equal to *right*

- root(bt)
 - descr: returns the information from the root of a binary tree
 - pre: $bt \in \mathcal{BT}$, $bt \neq \Phi$
 - **post:** root = e, $e \in TElem$, e is the information from the root of bt
 - throws: an exception if bt is empty

- left(bt)
 - descr: returns the left subtree of a binary tree
 - pre: $bt \in \mathcal{BT}$, $bt \neq \Phi$
 - **post:** left = I, $I \in \mathcal{BT}$, I is the left subtree of bt
 - throws: an exception if bt is empty

- right(bt)
 - descr: returns the right subtree of a binary tree
 - pre: $bt \in \mathcal{BT}$, $bt \neq \Phi$
 - **post:** $right = r, r \in \mathcal{BT}, r$ is the right subtree of bt
 - throws: an exception if bt is empty

- isEmpty(bt)
 - descr: checks if a binary tree is empty
 - pre: $bt \in \mathcal{BT}$
 - post:

$$empty = \begin{cases} \textit{True}, & \text{if } \textit{bt} = \Phi \\ \textit{False}, & \text{otherwise} \end{cases}$$

- iterator (bt, traversal, i)
 - descr: returns an iterator for a binary tree
 - pre: bt ∈ BT, traversal represents the order in which the tree has to be traversed
 - **post:** $i \in \mathcal{I}$, i is an iterator over bt that iterates in the order given by traversal

- destroy(bt)
 - descr: destorys a binary tree
 - pre: $bt \in \mathcal{BT}$
 - post: bt was destroyed

- Other possible operations:
 - changing the information from the root of a binary tree
 - removing a subtree (left or right) of a binary tree
 - searching for an element in a binary tree
 - returning the number of elements from a binary tree



We have several options for representing binary trees:

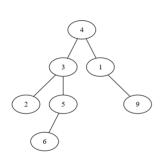
- Representation using an array
- Linked representation
 - · with dynamic allocation
 - on array



Representation using an array:

- The root of the tree is at the first index
- The left child of the node at index i is at index 2 * i, while the right child is at index 2 * i + 1.
- The parent of the node at index i > 1 is at index [i/2]





Pos	Elem
1	4
2	3
3	1
4	2
5	5
6	-1
7	9
8	-1
9	-1
10	6
11	-1
12	-1
13	-1

Disadvantage: depending on the form of the tree, we might waste a lot of space.



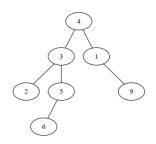
Linked representation with dynamic allocation:

- There is one node for every element of the tree
- The structure representing a node contains:
 - the information
 - · a pointer to the left child
 - · a pointer to the right child
 - · optionally, a pointer to the parent
- NIL denotes the absence of a node
 - ⇒ the root of an empty tree is NIL



Linked representation on an array:

- There are arrays storing:
 - · the information from the nodes
 - · the index of the left child
 - · the index of the right child
 - · optionally, the index of the parent



Pos	1	2	3	4	5	6	7	8
Info	4	3	2	5	6	1	9	
Left	2	3	-1	5	-1	-1	-1	
Right	6	4	-1	-1	-1	7	-1	
Parent	-1	1	2	2	4	1	6	

We need to know that the index of the root

E Here is 1, but it could be any other

If the array is full, we have to resize it



We can keep a linked list of empty indexes

Has to be created when creating the tree.

Even if the tree is non-linear, we can still use left (and/or right) to link it



Reallocating \Rightarrow linking again the empty positions

info								
left	2	3	4	5	6	7	8	-1
right								

firstEmpty = 1

root = -1

cap = 8

Trees- Applications



Real-word applications of tree data structure:



Hierarchical data storage

Storing folder structure, XML/HTML data



Layout of a webpage

 The homepage is the root, the main sections are its children. the subsections are the children's children...



Machine Learning

Representing Decision Trees



Working with Morse Code

• The organization of Morse code is done in the form of a binary tree



Binary Expression Trees

 For evaluating arithmetic expressions: operators are stored in the internal nodes, while the operands are stored in the leaves



- David M. Mount, Lecture notes for the course Data Structures (CMSC 420), at the Dept. of Computer Science, University of Maryland, College Park, 2001
- Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, and Clifford Stein, Introduction to Algorithms, Third Edition, The MIT Press. 2009
- Narasimha Karumanchi, Data Structures and Algorithms Made Easy: Data Structures and Algorithmic Puzzles, Fifth Edition, 2016
- Clifford A. Shaffer, A Practical Introduction to Data Structures and Algorithm Analysis, Third Edition, 2010

Thank you

