Self-Supervised Learning and Large Pretrained Models

Contextualized Representations

- Contextualized representations are embeddings that depend on the context:
- Words can have different meanings depending on the context;
- ELMo is a model that learned context-dependent embeddings;
 - Embeddings from Language Models;
 - ELMo is a bidirectional LSTM model BiLSTM;
 - Save all parameters at all layers;
 - Then, for your downstream task, tune a scalar parameter for each layer. and pass the entire sentence through this encoder.

Pretraining and Fine-Tuning

- Recalling the **language modeling** task: given a sequence of words, predict the next word: $p_{\theta}(y_t|y_1,\ldots,y_{t-1})$;
 - There is lots of data available for this task unlabeled data just raw text;
 - This is called unsupervised pretraining or self-supervised learning;
- Pretraining can be very effective by serving as parameter initialization; there are three architectures:
 - **Decoder-only GPT** Generative Pretrained Transformer;
 - * Language modeling;
 - * Used in sequence generation;
 - Encoder-only BERT;

- * Bidirectional context;
- * Used in classification or sequence tagging;
- Encoder-decoder T5;
 - * Bidirectional context and sequence-to-sequence.

Pretrained Decoders

- For decoder-only models, the pretraining task is language modeling;
- Fine-tuning is done by training a classifier on the last hidden state:

$$h1, \ldots, h_L = \operatorname{Decoder}(x_1, \ldots, x_L)y = \operatorname{softmax}(Ah_L + b)$$

- Where A and b are the classifier parameters;
- There are two common choices for **fine-tuning**:
 - Freeze the pretrained model an **train only** A **and** b;
 - Or fine-tune everything, letting gradients backpropagate through the pretrained model.

Pretrained Encoders

- Encoders get bidirectional context, so we can't do language modeling the pretraining task is masked language modeling;
- The key idea is to replace a fraction of the input tokens with a special **mask** token, and then **predict** the **original** tokens:

$$h1, \ldots, h_L = \operatorname{Encoder}(x_1, \ldots, x_L)y = \operatorname{softmax}(Ah_i + b)$$

Pretrained Encoder-Decoder

• For **Encoder-decoder** models we can do something like language modeling, but where a prefix of every input is provided to the encoder and is not predicted by the decoder:

$$h1, \ldots, h_T = \operatorname{Encoder}(x_1, \ldots, x_T) h_{T+1}, \ldots, h_L 2T = \operatorname{Decoder}(x_{T+1}, \ldots, x_{2T}) y_i = \operatorname{softmax}(Ah_i + b)$$

- The **encoder** portion benefits from **bidirectional context**;
- The decoder portion benefits from unidirectional context;
- **T5** is an example of this architecture;
 - Uses span corruption instead of masking randomly selects a span of text and replaces it with a sentinel token;

Adapters and Prompting

- Adapters are an alternative to **fine-tuning**, which is **computationally expensive**;
- Instead of fine-tuning the entire model, a **small set** of task-specific parameters (an **adapter**) is added to each layer of the pretrained model;
- Adapters can be used to adapt a pretrained model to a new task without fine-tuning.

Few-Shot Learning

- Few-shot learning is a supervised learning task where we have very few labeled examples;
- Powerful models can do this via **prompting**;