Neural Attention Mechanisms

Guest Lecture: Deep Structured Prediction

Vlad Niculae



```
words = [21, 79, 14] # indices
embed = Embedding(vocab sz, dim)
E = embed(words)^{-} # (3 \times dim)
enc = LSTM(dim, dim)
H = enc(E) \# (3 \times dim)
dec = LSTM(2 * dim, dim)
initialize k=1, q[0], y[0]
while not done:
  s = H a q[k - 1] # attn scores
  # s = [-.3, -1.0, 1.8]
  p = softmax(s) # attn proba
  # p = [.10, .05, .85]
  \alpha = p a H # (1 \times dim)
  q[k] = dec(\alpha, u[k - 1], q[k - 1])
```

u[k] = W out a[k] + b

United Nations elections

```
words = [21, 79, 14] # indices
embed = Embedding(vocab sz, dim)
E = embed(words)^{-} # (3 \times dim)
enc = LSTM(dim, dim)
H = enc(E) \# (3 \times dim)
dec = LSTM(2 * dim, dim)
initialize k=1, q[0], q[0]
while not done:
  s = H a q[k - 1] # attn scores
  # s = [-.3, -1.0, 1.8]
  p = softmax(s) # attn proba
  # p = [.10, .05, .85]
  \alpha = p \otimes H \# (1 \times dim)
  q[k] = dec(\alpha, y[k - 1], q[k - 1])
  u[k] = W \text{ out } a[k] + b
```

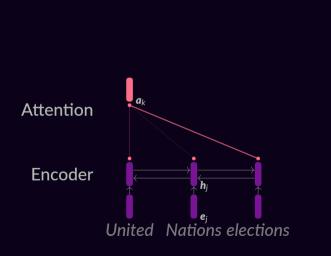
```
Encoder
```

e_i United Nations elections

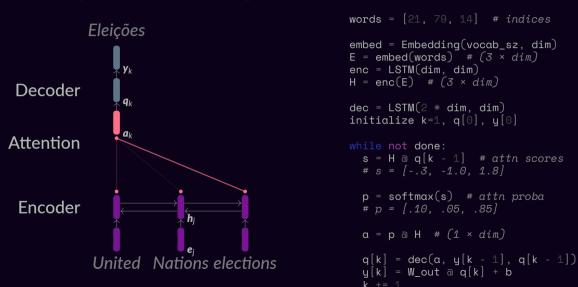
```
words = [21, 79, 14] # indices
embed = Embedding(vocab sz, dim)
E = embed(words)^{-} # (3 \times dim)
enc = LSTM(dim, dim)
H = enc(E) \# (3 \times dim)
dec = LSTM(2 * dim, dim)
initialize k=1, q[0], q[0]
while not done:
  s = H a q[k - 1] # attn scores
  # s = [-.3, -1.0, 1.8]
  p = softmax(s) # attn proba
  # p = [.10, .05, .85]
  \alpha = p \otimes H \# (1 \times dim)
  q[k] = dec(\alpha, y[k - 1], q[k - 1])
  u[k] = W \text{ out } a[k] + b
```

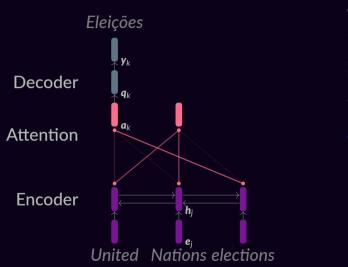
```
Encoder

| Image: Property of the content of the co
```

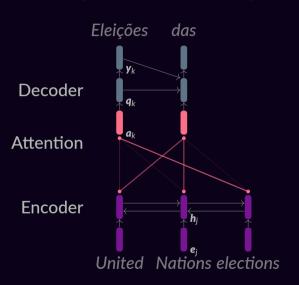


```
words = [21, 79, 14] # indices
embed = Embedding(vocab sz, dim)
E = embed(words)^{-} # (3 \times dim)
enc = LSTM(dim, dim)
H = enc(E) \# (3 \times dim)
dec = LSTM(2 * dim, dim)
initialize k=1, q[0], q[0]
while not done:
  s = H \otimes q[k - 1] + attn scores
  # s = [-.3, -1.0, 1.8]
  p = softmax(s) # attn proba
  # p = [.10, .05, .85]
  \alpha = p \otimes H \# (1 \times dim)
  q[k] = dec(\alpha, y[k - 1], q[k - 1])
  u[k] = W \text{ out } a[k] + b
```

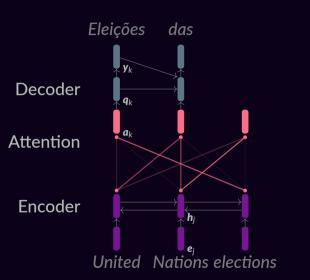




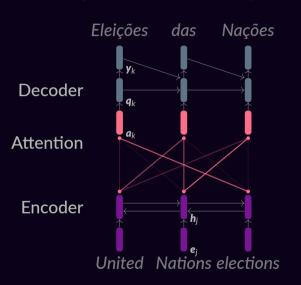
```
words = [21, 79, 14] # indices
embed = Embedding(vocab sz, dim)
E = embed(words)^{-} # (3 \times dim)
enc = LSTM(dim, dim)
H = enc(E) \# (3 \times dim)
dec = LSTM(2 * dim, dim)
initialize k=1, q[0], y[0]
while not done:
  s = H a q[k - 1] # attn scores
  # s = [-.3, -1.0, 1.8]
  p = softmax(s) # attn proba
  # p = [.10, .05, .85]
  \alpha = p \otimes H \# (1 \times dim)
  q[k] = dec(\alpha, y[k - 1], q[k - 1])
  u[k] = W \text{ out } a[k] + b
```



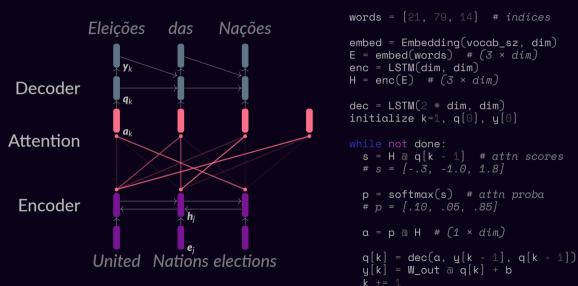
```
words = [21, 79, 14] # indices
embed = Embedding(vocab sz, dim)
E = embed(words)^{-} # (3 \times dim)
enc = LSTM(dim, dim)
H = enc(E) \# (3 \times dim)
dec = LSTM(2 * dim, dim)
initialize k=1, q[0], y[0]
while not done:
  s = H a q[k - 1] # attn scores
  # s = [-.3, -1.0, 1.8]
  p = softmax(s) # attn proba
  # p = [.10, .05, .85]
  \alpha = p \otimes H \# (1 \times dim)
  q[k] = dec(\alpha, y[k - 1], q[k - 1])
  u[k] = W \text{ out } a[k] + b
```

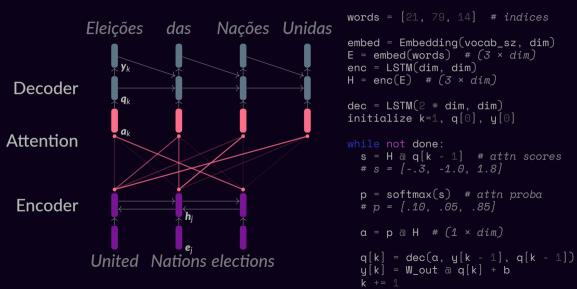


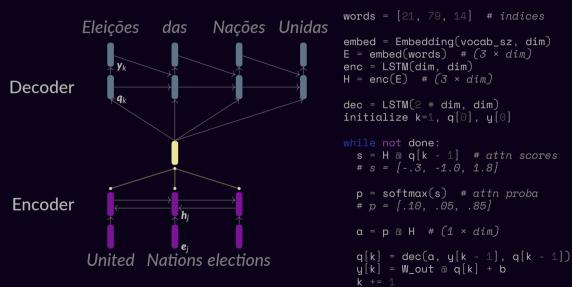
```
words = [21, 79, 14] # indices
embed = Embedding(vocab sz, dim)
E = embed(words)^{-} # (3 \times dim)
enc = LSTM(dim, dim)
H = enc(E) \# (3 \times dim)
dec = LSTM(2 * dim, dim)
initialize k=1, q[0], y[0]
while not done:
  s = H a q[k - 1] # attn scores
  # s = [-.3, -1.0, 1.8]
  p = softmax(s) # attn proba
  # p = [.10, .05, .85]
  \alpha = p \otimes H \# (1 \times dim)
  q[k] = dec(\alpha, y[k - 1], q[k - 1])
  u[k] = W \text{ out } a[k] + b
```

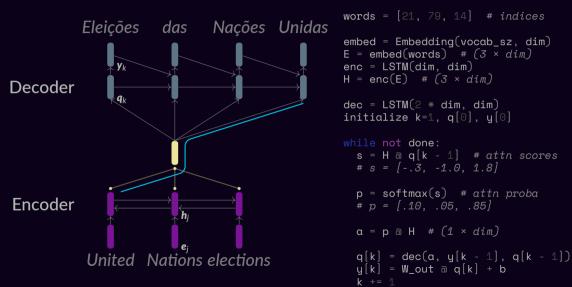


```
words = [21, 79, 14] # indices
embed = Embedding(vocab sz, dim)
E = embed(words)^{-} # (3 \times dim)
enc = LSTM(dim, dim)
H = enc(E) \# (3 \times dim)
dec = LSTM(2 * dim, dim)
initialize k=1, q[0], y[0]
while not done:
  s = H a q[k - 1] # attn scores
  # s = [-.3, -1.0, 1.8]
  p = softmax(s) # attn proba
  # p = [.10, .05, .85]
  \alpha = p \otimes H \# (1 \times dim)
  q[k] = dec(\alpha, y[k - 1], q[k - 1])
  u[k] = W \text{ out } a[k] + b
```









Attention as a shortcut

Attention doesn't make models more expressive, it makes it easier to express "better" functions.

"You May Not Need Attention" for NMT, but reordering is needed for good results.

(Press and Smith, 2018)

```
# attention scores:
s = H a W_attn a state
# s = [-.3, -1.0, 1.8]
```

p = [.10, .05, .85]

p = softmax(s)

record scratch

freeze frame

United

Nations

Elections

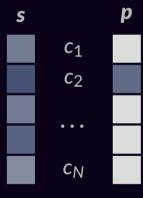
 c_1

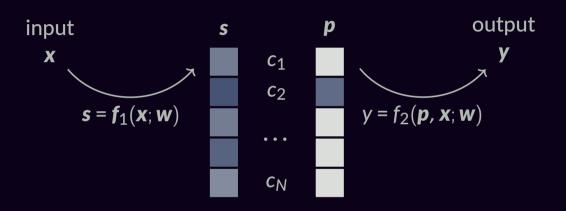
c₂

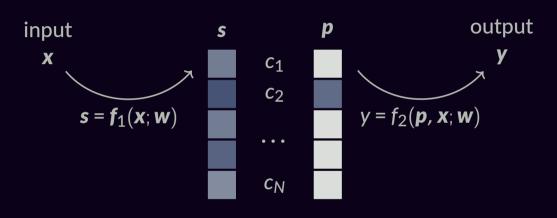
• • •

CN

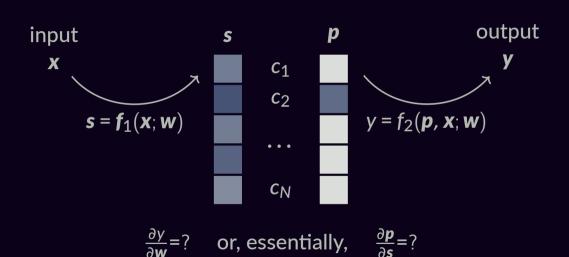


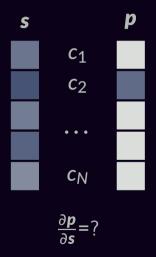


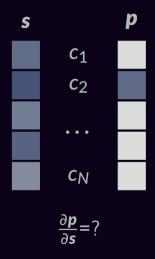


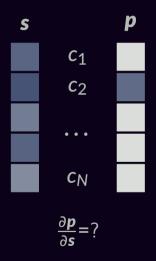


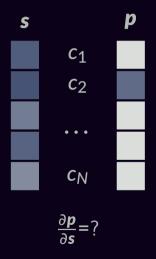
 $\frac{\partial y}{\partial \mathbf{w}} = ?$

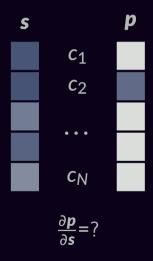


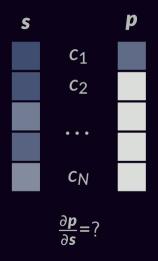


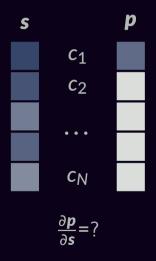


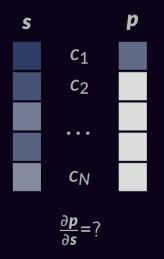




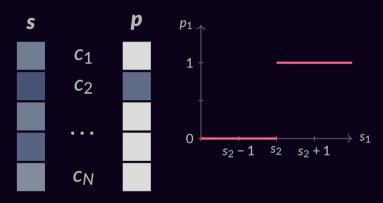






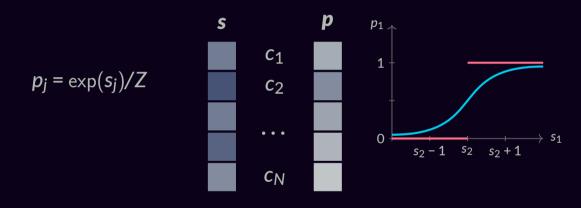


Argmax



$$\frac{\partial \mathbf{p}}{\partial \mathbf{s}} = \mathbf{0}$$

Argmax vs. Softmax



 $\frac{\partial \mathbf{p}}{\partial \mathbf{s}} = \operatorname{diag}(\mathbf{p}) - \mathbf{p}\mathbf{p}^{\mathsf{T}}$

Background: Optimization

$$f: \mathbb{R}^d \to \mathbb{R} \cup \{\infty\}$$

$$\min_{\mathbf{x}} f(\mathbf{x}) := v \text{ s.t. } (a) \ \exists \mathbf{x}^* \in \mathbb{R}^d, f(\mathbf{x}^*) = v$$

$$(b) \ \forall \mathbf{x}' \in \mathbb{R}^d, f(\mathbf{x}') \ge v$$

$$\arg\min_{\mathbf{x}} f(\mathbf{x}) := \{\mathbf{x}^* \in \mathbb{R}^d : f(\mathbf{x}^*) = \min_{\mathbf{x}} f(\mathbf{x})\}$$

f convex: optimization algos available f strictly convex: $arg min_x f(x) = \{x^*\}$

Background: Constrained Optimization

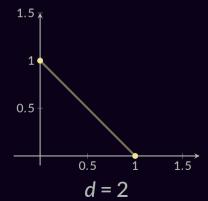
$$\min_{\mathbf{x} \in \mathcal{X} \subset \mathbb{R}^d} \mathbf{f}(\mathbf{x})$$
The indicator function: $\operatorname{Id}_{\mathcal{X}}(\mathbf{x}) = \begin{cases} 0, & \mathbf{x} \in \mathcal{X}, \\ \infty, & \mathbf{x} \notin \mathcal{X}. \end{cases}$

$$\underset{\mathbf{x} \in \mathcal{X}}{\arg \min} f(\mathbf{x}) = \arg \min f(\mathbf{x}) + \operatorname{Id}_{\mathcal{X}}(\mathbf{x}).$$

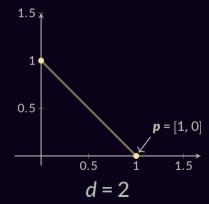
 Id_X is a convex function when X a convex set.

$$\triangle = \{ \mathbf{p} \in \mathbb{R}^d : \mathbf{p} \geq \mathbf{0}, \ \mathbf{1}^\top \mathbf{p} = \mathbf{1} \}$$

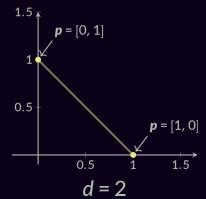
$$\triangle = \{ \boldsymbol{p} \in \mathbb{R}^d : \boldsymbol{p} \geq \boldsymbol{0}, \ \boldsymbol{1}^\top \boldsymbol{p} = 1 \}$$



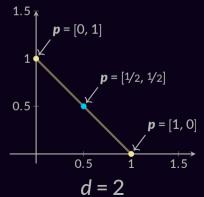
$$\triangle = \{ \boldsymbol{p} \in \mathbb{R}^d : \, \boldsymbol{p} \ge \boldsymbol{0}, \, \boldsymbol{1}^\top \boldsymbol{p} = 1 \}$$



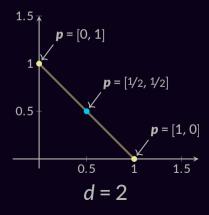
$$\triangle = \{ \boldsymbol{p} \in \mathbb{R}^d : \boldsymbol{p} \geq \boldsymbol{0}, \ \boldsymbol{1}^\top \boldsymbol{p} = 1 \}$$

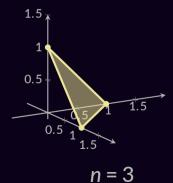


$$\triangle = \{ \boldsymbol{p} \in \mathbb{R}^d : \boldsymbol{p} \geq \boldsymbol{0}, \ \boldsymbol{1}^\top \boldsymbol{p} = 1 \}$$

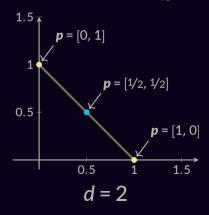


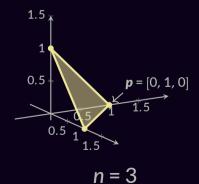
$$\triangle = \{ \mathbf{p} \in \mathbb{R}^d : \mathbf{p} \ge \mathbf{0}, \ \mathbf{1}^\top \mathbf{p} = \mathbf{1} \}$$



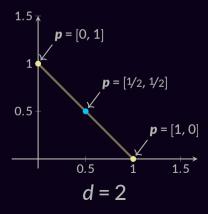


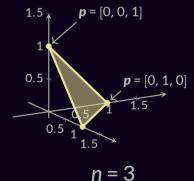
$$\triangle = \{ \boldsymbol{p} \in \mathbb{R}^d : \, \boldsymbol{p} \ge \boldsymbol{0}, \, \boldsymbol{1}^\top \boldsymbol{p} = \boldsymbol{1} \}$$



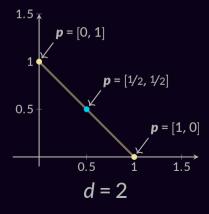


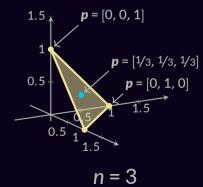
$$\triangle = \{ \mathbf{p} \in \mathbb{R}^d : \mathbf{p} \ge \mathbf{0}, \ \mathbf{1}^\top \mathbf{p} = \mathbf{1} \}$$





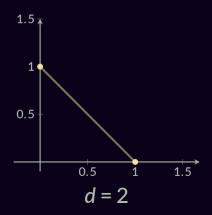
$$\triangle = \{ \mathbf{p} \in \mathbb{R}^d : \mathbf{p} \ge \mathbf{0}, \ \mathbf{1}^\top \mathbf{p} = \mathbf{1} \}$$

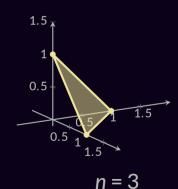




$$\max_{j} s_{j} = \max_{p \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s}$$

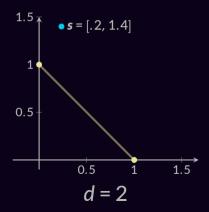
Fundamental Thm. Lin. Prog. (Dantzig et al., 1955)

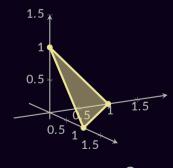




$$\max_{j} s_{j} = \max_{p \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s}$$

Fundamental Thm. Lin. Prog. (Dantzig et al., 1955)

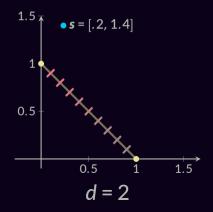


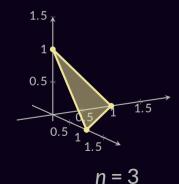


$$n = 3$$

$$\max_{j} s_{j} = \max_{p \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s}$$

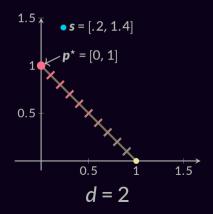
Fundamental Thm. Lin. Prog. (Dantzig et al., 1955)

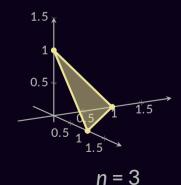




$$\max_{j} s_{j} = \max_{p \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s}$$

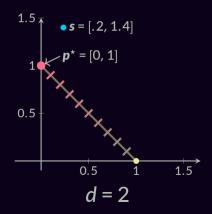
Fundamental Thm. Lin. Prog. (Dantzig et al., 1955)

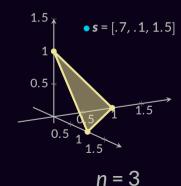




$$\max_{j} s_{j} = \max_{p \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s}$$

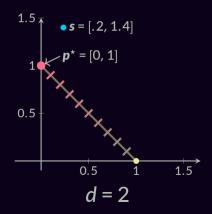
Fundamental Thm. Lin. Prog. (Dantzig et al., 1955)

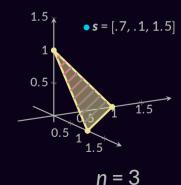




$$\max_{j} s_{j} = \max_{\boldsymbol{p} \in \Delta} \boldsymbol{p}^{\mathsf{T}} \boldsymbol{s}$$

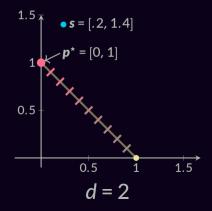
Fundamental Thm. Lin. Prog. (Dantzig et al., 1955)

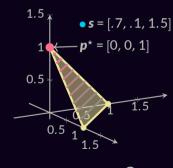




$$\max_{j} s_{j} = \max_{\boldsymbol{p} \in \Delta} \boldsymbol{p}^{\mathsf{T}} \mathbf{s}$$

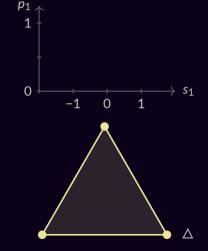
Fundamental Thm. Lin. Prog. (Dantzig et al., 1955)





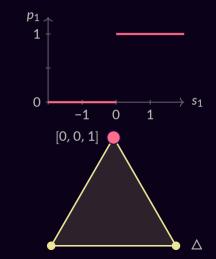
$$n = 3$$

$$\max_{\Omega}(\mathbf{s}) = \max_{\mathbf{p} \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s} - \Omega(\mathbf{p})$$



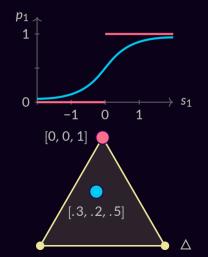
$$\max_{\Omega}(\mathbf{s}) = \max_{\mathbf{p} \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s} - \Omega(\mathbf{p})$$

• argmax: $\Omega(\mathbf{p}) = 0$



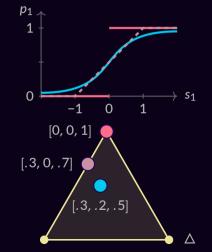
$$\max_{\Omega}(\mathbf{s}) = \max_{\mathbf{p} \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s} - \Omega(\mathbf{p})$$

- argmax: $\Omega(\mathbf{p}) = 0$
- softmax: $\Omega(\mathbf{p}) = \sum_{j} p_{j} \log p_{j}$

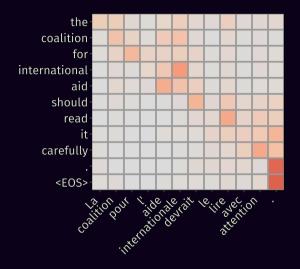


$$\max_{\Omega}(\mathbf{s}) = \max_{\mathbf{p} \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s} - \Omega(\mathbf{p})$$

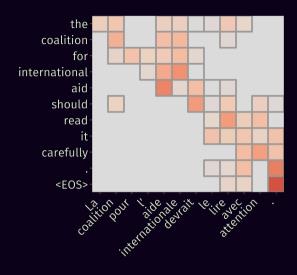
- argmax: $\Omega(\mathbf{p}) = 0$
- softmax: $\Omega(\mathbf{p}) = \sum_{i} p_{i} \log p_{i}$
- sparsemax: $\Omega(p) = 1/2 ||p||_2^2$



(Martins and Astudillo, 2016)



softmax



sparsemax

Sparsemax

sparsemax(
$$\mathbf{s}$$
) = arg max $\mathbf{p}^{\mathsf{T}}\mathbf{s} - 1/2||\mathbf{p}||_2^2$
 $\mathbf{p} \in \Delta$
= arg min $||\mathbf{p} - \mathbf{s}||_2^2$
 $\mathbf{p} \in \Delta$

Computation:

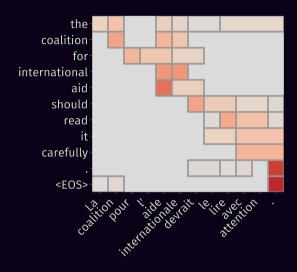
$$p^* = [s - \tau \mathbf{1}]_+$$

 $s_i > s_j \Rightarrow p_i \ge p_j$
 $O(d)$ via partial sort

Backward pass:

$$\begin{aligned} \boldsymbol{J}_{\text{sparsemax}} &= \operatorname{diag}(\boldsymbol{s}) - \frac{1}{|\mathcal{S}|} \boldsymbol{s} \boldsymbol{s}^{\top} \\ &\text{where } \mathcal{S} &= \{j : p_{j}^{\star} > 0\}, \\ &s_{j} &= [\![j \in \mathcal{S}]\!] \end{aligned}$$

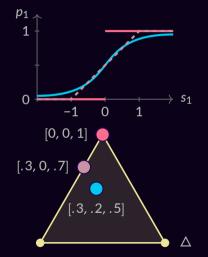
(Martins and Astudillo, 2016)



fusedmax

$$\max_{\boldsymbol{\rho} \in \Delta} (\boldsymbol{s}) = \max_{\boldsymbol{\rho} \in \Delta} \boldsymbol{\rho}^{\top} \boldsymbol{s} - \Omega(\boldsymbol{\rho})$$

- argmax: $\Omega(\mathbf{p}) = 0$
- softmax: $\Omega(\mathbf{p}) = \sum_j p_j \log p_j$
- sparsemax: $\Omega(\mathbf{p}) = 1/2 ||\mathbf{p}||_2^2$



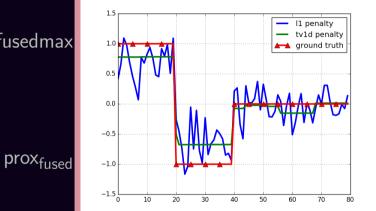
Fusedmax

fusedmax(
$$\mathbf{s}$$
) = arg max $\mathbf{p}^{\mathsf{T}}\mathbf{s} - 1/2||\mathbf{p}||_2^2 - \sum_{2 \le j \le d} |p_j - p_{j-1}|$
= arg min $||\mathbf{p} - \mathbf{s}||_2^2 + \sum_{2 \le j \le d} |p_j - p_{j-1}|$
 $\mathbf{p} \in \Delta$ $\mathbf{p} \in \mathbb{R}^d$ $\mathbf{p} = \mathbf{p} = \mathbf$

Proposition: fusedmax(
$$s$$
) = sparsemax(prox_{fused}(s))

(Niculae and Blondel, 2017)



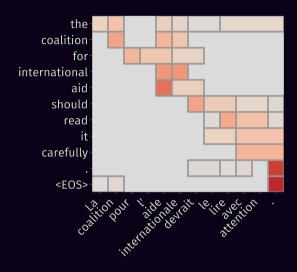


Propos

"Fused Lasso" a.k.a. 1-d Total Variation (Tibshirani et al., 2005)

$$p_j - p_{j-1}$$

 $u_{\mathsf{used}}(\boldsymbol{s})$



fusedmax

Constrained Attention

$$\underset{\boldsymbol{p} \in \Delta \cup \mathcal{X}}{\operatorname{arg max}} \boldsymbol{p}^{\mathsf{T}} \boldsymbol{s} - \Omega(\boldsymbol{p})$$

$$= \underset{\boldsymbol{p} \in \Delta}{\operatorname{arg max}} \boldsymbol{p}^{\mathsf{T}} \boldsymbol{s} - \underbrace{\Omega_{\mathcal{X}}(\boldsymbol{p})}_{\Omega + \operatorname{Id}_{\mathcal{X}}}$$

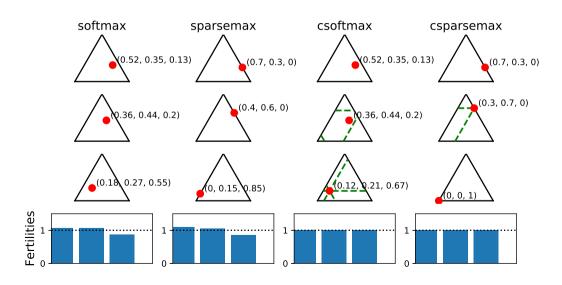
Constrained Attention

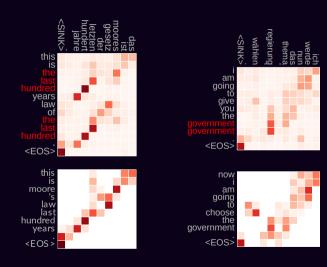
$$\underset{\boldsymbol{p} \in \Delta \cup \mathcal{X}}{\operatorname{arg max}} \boldsymbol{p}^{\mathsf{T}} \boldsymbol{s} - \Omega(\boldsymbol{p})$$

$$= \underset{\boldsymbol{p} \in \Delta}{\operatorname{arg max}} \boldsymbol{p}^{\mathsf{T}} \boldsymbol{s} - \underbrace{\Omega_{\mathcal{X}}(\boldsymbol{p})}_{\Omega + \operatorname{Id}_{\mathcal{X}}}$$

Example: upper bounds $\mathcal{X} = \{ \boldsymbol{p} \in \mathbb{R}^d : p_j \leq b_j \}$ constrained softmax (Martins and Kreutzer, 2017) and sparsemax (Malaviya et al., 2018) Application: incorporating fertility in Neural MT

Example: Source Sentence with Three Words



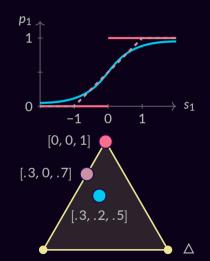


$$\max_{\boldsymbol{\rho} \in \Delta} (\boldsymbol{s}) = \max_{\boldsymbol{\rho} \in \Delta} \boldsymbol{\rho}^{\top} \boldsymbol{s} - \Omega(\boldsymbol{\rho})$$

- argmax: $\Omega(\mathbf{p}) = 0$
- softmax: $\Omega(\mathbf{p}) = \sum_{j} p_{j} \log p_{j}$
- sparsemax: $\Omega(p) = \frac{1}{2} ||p||_2^2$

fusedmax:
$$\Omega(\mathbf{p}) = 1/2 ||\mathbf{p}||_2^2 + \sum_j |p_j - p_{j-1}|$$

csparsemax: $\Omega(\mathbf{p}) = 1/2 ||\mathbf{p}||_2^2 + \mathrm{Id}_{\mathbf{p} \leq \mathbf{b}_1}$

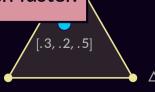


$$\max_{\Omega}(\mathbf{s}) = \max_{\mathbf{p} \in \Delta} \mathbf{p}^{\mathsf{T}} \mathbf{s} - \Omega(\mathbf{p})$$

- argmax: $\Omega(\mathbf{p}) = 0$
- softma Black-box solvers available (e.g. FISTA),
- sparsema specialized solvers can be much faster.

fusedmax.
$$22(\mathbf{p}) = \frac{1}{2}2||\mathbf{p}||_{2} + \frac{1}{2}\frac{1}{2}||\mathbf{p}|| = \frac{1}{2}||\mathbf{p}||_{2}$$

csparsemax:
$$\Omega(p) = 1/2 ||p||_2^2 + |d_{p \le b}|$$



2. Attention

architectures.

Computing the scores

$$s_j = \sigma(\mathbf{h}_j, \mathbf{q})$$

name	$\sigma(\mathbf{h},\mathbf{q})$	
additive	\mathbf{v}^T tanh $(\mathbf{W}_1\mathbf{h} + \mathbf{W}_2\mathbf{q})$	(Bahdanau et al., 2015)
dot-product	$\mathbf{h}^{T}\mathbf{q}$	(Luong et al., 2015)
bilinear	$h^{T} W q$	(Luong et al., 2015)
scaled	$(1/\sqrt{d})~\mathbf{h}^T\mathbf{W}\mathbf{q}$	(Vaswani et al., 2017)

Beyond seq2seq

The spirit of attention mechanisms reaches far:

- ► Key-Value Attention
- ▶ Multi-head Attention
- ► Self-Attention and the Transformer
- ► Hierarchical Attention
- ► Memory Networks, Pointer Networks, Neural Turing Machines...

Key-Value Attention

idea: the objects we average (values) and the objects used to compute scores (keys) don't need to be identical!

$$s_j = \mathbf{h}_j^{\mathsf{T}} \mathbf{q}$$

 $\mathbf{u} = \operatorname{softmax}(\mathbf{s})^{\mathsf{T}} \mathbf{H}$
 $s_j = \mathbf{k}_j^{\mathsf{T}} \mathbf{q}$
 $\mathbf{u} = \operatorname{softmax}(\mathbf{s})^{\mathsf{T}} \mathbf{V}$

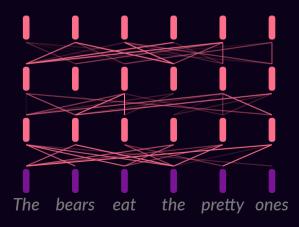
Multi-head Attention

idea: compute *k* different attention averages, & concatenate the outputs.

Self-attention

Attention as an encoder layer

. . .



Self-attention

Attention as an encoder layer

• • •

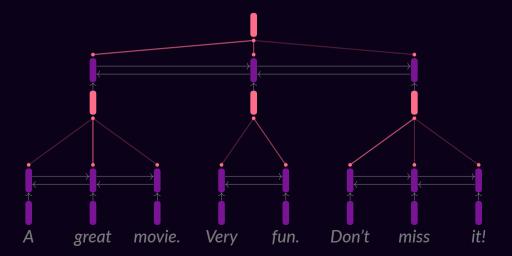


Transformer (Vaswani et al., 2017): very deep self-attention replacing LSTMs in encoder & decoder



Hierarchical Attention

Encode document by first encoding its sentences.





References I

Bahdanau, Dzmitry, Kyunghyun Cho, and Yoshua Bengio (2015). "Neural machine translation by jointly learning to align and translate". In: *Proc. of ICLR*.

Brucker, Peter (1984). "An *O*(*n*) algorithm for quadratic knapsack problems". In: *Operations Research Letters* 3.3, pp. 163–166.

Cheng, Jianpeng, Li Dong, and Mirella Lapata (2016). "Long Short-Term Memory-Networks for Machine Reading". In: *Proc. of EMNLP*.

Condat, Laurent (2016). "Fast projection onto the simplex and the ℓ_1 ball". In: *Mathematical Programming* 158.1-2, pp. 575–585.

Dantzig, George B, Alex Orden, and Philip Wolfe (1955). "The generalized simplex method for minimizing a linear form under linear inequality restraints". In: Pacific Journal of Mathematics 5.2. pp. 183–195.

Held, Michael, Philip Wolfe, and Harlan P Crowder (1974). "Validation of subgradient optimization". In: *Mathematical Programming* 6.1, pp. 62–88.

Luong, Minh-Thang, Hieu Pham, and Christopher D Manning (2015). "Effective approaches to attention-based neural machine

Graves, Alex, Greg Wayne, and Ivo Danihelka (2014), "Neural Turing Machines". In: arXiv preprint arXiv:1410.5401.

translation". In: Proc. of EMNLP.

Malaviya, Chaitanya, Pedro Ferreira, and André F. T. Martins (2018). "Sparse and constrained attention for neural machine translation". In: *Proc. of ACL*.

Martins, André ET and Pamén Fernandez Astudillo (2014). "From softmay to sparsemay: A sparse model of attention and

Martins, André FT and Ramón Fernandez Astudillo (2016). "From softmax to sparsemax: A sparse model of attention and multi-label classification". In: *Proc. of ICML*.

References II

- Martins, André FT and Julia Kreutzer (2017). "Learning What's Easy: Fully Differentiable Neural Easy-First Taggers". In: *Proc. of EMNLP*. pp. 349–362.
- Niculae, Vlad and Mathieu Blondel (2017). "A regularized framework for sparse and structured neural attention". In: Proc. of NeurlPS.
- Press, Ofir and Noah A Smith (2018). "You May Not Need Attention". In: arXiv preprint arXiv:1810.13409.
- Sukhbaatar, Sainbayar, Jason Weston, and Rob Fergus (2015). "End-to-end memory networks". In: Proc. of NeurIPS.
- Tibshirani, Robert, Michael Saunders, Saharon Rosset, Ji Zhu, and Keith Knight (2005). "Sparsity and smoothness via the fused lasso". In: *Journal of the Royal Statistical Society: Series B (Statistical Methodology)* 67.1, pp. 91–108.
- Vaswani, Ashish, Noam Shazeer, Niki Parmar, Jakob Uszkoreit, Llion Jones, Aidan N. Gomez, Lukasz Kaiser, and Illia Polosukhin (2017). "Attention Is All You Need". In: Proc. of NeurIPS.
- Yang, Zichao, Diyi Yang, Chris Dyer, Xiaodong He, Alex Smola, and Eduard Hovy (2016). "Hierarchical attention networks for document classification". In: Proc. of NAACL-HLT.