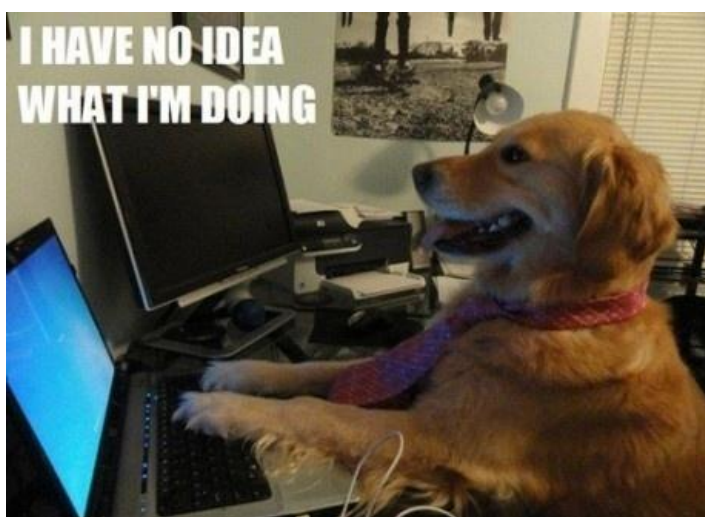


# Project Thesis Bananas and Troika

Isak Hammer

March 5, 2022



# 1 Introduction

This guy [1] has done a good job.

## 2 Cahn Hilliard Equation on a Closed Membrane

Let  $c_0$  and  $c_1$  indicate the concentration profile of the substances in a 2-phase system such that  $c_0(\mathbf{x}, t) : \Omega \times [0, \infty] \rightarrow [0, 1]$  and similarly  $c_1(\mathbf{x}, t) : \Omega \times [0, \infty] \rightarrow [0, 1]$ , where  $\mathbf{x}$  is a element of some surface  $\Omega$  and  $t$  is time. However, in the 2 phase problem will we will restrict ourself so that  $c_0(t, \mathbf{x}) + c_1(t, \mathbf{x}) = 1$  at any  $\mathbf{x}$  at time  $t$ . A property of the restriction is that we now can express  $c_0$  using  $c_1$ , with no loss of information. Hence, let us now define  $c = c_0$  so  $c(\mathbf{x}, t) : \Omega \times [0, \infty] \rightarrow [0, 1]$ . It has been shown that 2 phase system if thermodynamically unstabl can be evolve into a phase separation described by a evolutional differential equation [2] using a model based on chemical energy of the substances. However, further development has been done [3] to solve this equation on surfaces. Now assume model that we want to describe is a phase-seperation on a closed membrane surface  $\Gamma$ , so that  $c(\mathbf{x}, t) : \Gamma \times [0, T] \rightarrow [0, 1]$ . Then is the surface Cahn Hilliard equation described such that

$$\rho \frac{\partial c}{\partial t} - \nabla_\Gamma (M \nabla_\Gamma (f'_0 - \varepsilon^2 \nabla_\Gamma^2 c)) = 0 \quad \text{on } \Gamma. \quad (1)$$

We define here the tangential gradient operator to be  $\nabla_\Gamma c = \nabla c - (\mathbf{n} \nabla c) \mathbf{n}$  applied on the surface  $\Gamma$  restricted to  $\mathbf{n} \cdot \nabla_\Gamma c = 0$ .

Lets define  $\varepsilon$  to be the size of the layer between the substances  $c_1$  and  $c_2$ . The density  $\rho$  is simply defined such that  $\rho = \frac{m}{S_\Gamma}$  is a constant based on the total mass divided by the total surface area of  $\Gamma$ . Here is the mobility  $M$  often derived such that is is dependent on  $c$  and is crucial for the result during a possible coarsening event [3]. However, the free energy per unit surface  $f_0 = f_0(c)$  is derived based on the thermodynamical model and should according to [3] be nonconvex and nonlinear.

A important observation is that equation (1) is a fourth order equation which makes it more challenging to solve using conventional FEM methods. This clear when writing the equation on the equivalent weak form and second order equations arise.

## 3 $C^0$ Interior Penalty Method

In this section do we want to establish a numerical method to fourth order equations. Instead of embarking on the special case of surface PDE described in (1) can we establish a general numerical theory on  $\mathbb{R}^2$  which we can then later generalize on manifolds later.

Assume that we restrict ourself to a surface  $\Omega \in \mathbb{R}^2$  and let  $f \in L_2(\Omega)$  We want to solve the equation on the form

$$\Delta^2 u = f \quad \text{in } \Omega \quad (2)$$

$$u = \frac{\partial u}{\partial n} = 0 \quad (3)$$

$$. \quad (4)$$

### 3.1 Weak Formulation

The weak formulation of (2) has the form

$$a(u, v) = \int_\Omega f v dx \quad u, v \in V. \quad (5)$$

where

$$a(w, v) = \int_\Omega \nabla^2 w : \nabla^2 v dx. \quad (6)$$

Here do we define  $\nabla^2 w : \nabla^2 v$  to be the inner product of the Hessian matrix of  $w$  and  $v$ , and  $V$  is a closed subspace of the sobolev space  $H^2(\Omega)$ .

### 3.2 The general $C^0$ Interior Penalty Method

$C^0$  Interior penalty method says that

$$\begin{aligned} a_h(w, v) &= \sum_{T \in \mathfrak{T}_h} \int_T (\nabla^2 w : \nabla^2 v) dx + \sum_{e \in \mathfrak{E}_h^i} \int_e \left\{ \left\{ \frac{\partial w}{\partial n_e} \right\} \right\} \left[ \left[ \frac{\partial v}{\partial n_e} \right] \right] ds \\ &+ \sum_{e \in \mathfrak{E}_h^i} \int_e \left\{ \left\{ \frac{\partial^2 v}{\partial n_e^2} \right\} \right\} \left[ \left[ \frac{\partial w}{\partial n_e} \right] \right] + \sum_{e \in \mathfrak{E}_h^i} \frac{\sigma}{|e|} \int_e \left[ \left[ \frac{\partial w}{\partial n_e} \right] \right] \left[ \left[ \frac{\partial v}{\partial n_e} \right] \right] ds. \end{aligned}$$

where

$$\begin{aligned}
\left[ \left[ \frac{\partial v}{\partial n_e} \right] \right] &= -n_e \nabla \nu_T, \quad \nu_T = \nu|_T \\
\left\{ \left\{ \frac{\partial^2 u}{\partial n_e^2} \right\} \right\} &= \frac{\partial^2 u}{\partial n_e^2} \\
\left\{ \left\{ \frac{\partial w}{\partial n_e^2} \right\} \right\} &= \frac{1}{2} \left( \frac{\partial^2 w_-}{\partial n_e^2} + \frac{\partial^2 w_+}{\partial n_e^2} \right) \\
\left\{ \left\{ \frac{\partial^2 w}{\partial n_e^2} \right\} \right\} &= \frac{\partial^2 w}{\partial n_e^2}, \quad \text{on edges.}
\end{aligned}$$

## 4 Appendix

### 4.1 $L_2(\Omega)$ space

Using the definition from [4] and we let  $\Omega$  be a an open set in  $\mathbb{R}^d$  and  $p \in \mathbb{R}$  such that  $p \geq 1$ . Then we denote  $L^p(\Omega)$  to be the set of measurable function  $u : \Omega \rightarrow \mathbb{R}$  such that it is equipped in a finite Banach space

$$\|u\|_{L^p(\Omega)} = \left( \int_{\Omega} |u|^p \right)^{\frac{1}{p}}.$$

Now let  $u, v : \Omega \rightarrow \mathbb{R}$ . Then is  $L_2(\Omega)$  a Hilbert space when the inner product is finite such that this exists

$$(u, v)_{L^p(\Omega)} = \int_{\Omega} uv.$$

## References

- [1] Edmund Brekke. *Fundamentals of Sensor Fusion*. Not published. Third edition, August 2, 2021.
- [2] John W. Cahn and John E. Hilliard. “Free Energy of a Nonuniform System. I. Interfacial Free Energy”. In: *The Journal of Chemical Physics* 28.2 (1958), pp. 258–267. DOI: [10.1063/1.1744102](https://doi.org/10.1063/1.1744102). eprint: <https://doi.org/10.1063/1.1744102>. URL: <https://doi.org/10.1063/1.1744102>.
- [3] Vladimir Yushutin et al. “A computational study of lateral phase separation in biological membranes”. In: *International Journal for Numerical Methods in Biomedical Engineering* 35.3 (2019). e3181 cnm.3181, e3181. DOI: <https://doi.org/10.1002/cnm.3181>. eprint: <https://onlinelibrary.wiley.com/doi/pdf/10.1002/cnm.3181>. URL: <https://onlinelibrary.wiley.com/doi/abs/10.1002/cnm.3181>.
- [4] A. Manzoni, A. Quarteroni, and S. Salsa. *Optimal Control of Partial Differential Equations: Analysis, Approximation, and Applications*. Applied Mathematical Sciences. Springer International Publishing, 2021. ISBN: 9783030772253. URL: <https://books.google.no/books?id=V3NpzzgEACAAJ>.