TROY

Tiered Resource OverlaY

Andre Merzky

http://saga-project.github.com/troy/



- Motivation / Use Cases
- 2 Conceptual Architecture
- 3 Implementation Architecture / Design
- 4 API, Code Example

Motivation for TROY

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- support for application level scheduling across those PFs

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- publish ;-)

TROY Placement and Scope

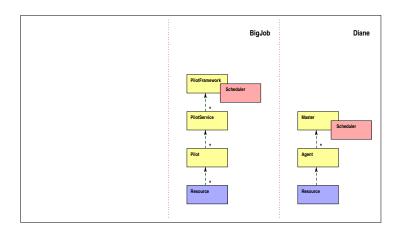
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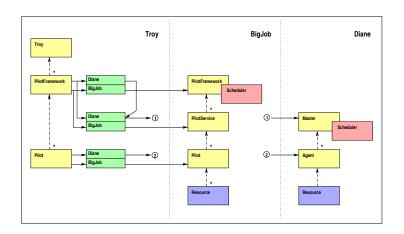
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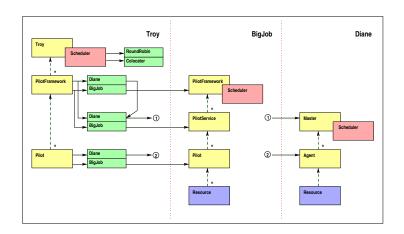
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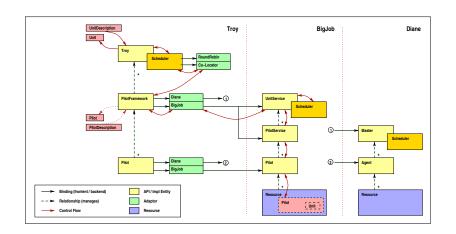
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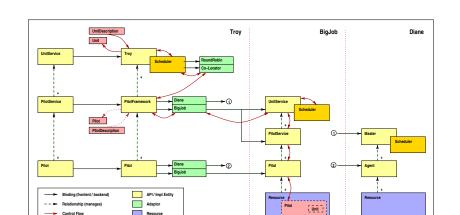
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- interface to pilot job frameworks
 - assumes P*, and possibly Pilot API











Troy API Classes

Troy classes interfacing to backend pilot systems:

- troy.Scheduler
- troy.PilotFramework interfaces to the XXXUnitService and XXXPilotService classes of Pilot API
- troy.ComputePilot
- troy.ComputeUnit
- troy.DataPilot
- troy.DataUnit

API Example

```
pf1 = troy.PilotFramework ('bigjob//lonestar')
pf2 = troy.PilotFramework ('bigjob//kraken')
cpd = troy.ComputePilotDescription ()
pf1.submit_pilot (cpd)
pf2.submit_pilot (cpd)
   = troy.Troy ()
t.add_pilot_framework (pf1)
t.add_pilot_framework (pf2)
   = troy.Scheduler ('Random')
t.add scheduler
                     (s)
```

API Example Cont.

```
cud = troy.ComputeUnitDescription ()
cud['executable'] = '/bin/sh'
cud['arguments'] = ['-c', 'touch /tmp/hello_troy_pj && sleep 10']
cu = t.submit_unit (cud)
```

API Example Cont.

```
while cu.state not in (troy.Done, troy.Failed) :
    print "? cu %s: %s" % (cu.id, cu.state)
    time.sleep (1)

print "! cu %s: %s" % (cu.id, cu.state)

pf1.cancel ()
pf2.cancel ()
```

Scheduler

```
def my_scheduler (troy, ud) :
   pilots = []
    for pf_id in troy.list_pilot_frameworks () :
        pf = troy.PilotFramework (pf_id)
        for p_id in pf.list_pilots () :
            p = troy.ComputePilot (p_id)
            pilots.append (p)
    tgt = pilots[random.randint (0, len (pilots) - 1)]
    return tgt.submit_unit (ud)
```

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t.add_pilot_framework (pf2)
t.add_scheduler
                   (my_scheduler)
```

Questions?