

# TROY

## Tiered Resource OverlaY

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<http://saga-project.github.com/troy/>



- ① Motivation / Use Cases
- ② Conceptual Architecture
- ③ Implementation Architecture / Design
- ④ API, Code Example

# Motivation for TROY

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- support for application level **scheduling across** those PFs

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- NGS data on storage archive on XSEDE/Ionestar
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- ...
- publish ;-)

# TROY Placement and Scope

- **is-a** application framework
  - application defines resource requirments
  - application defines data and compute workload

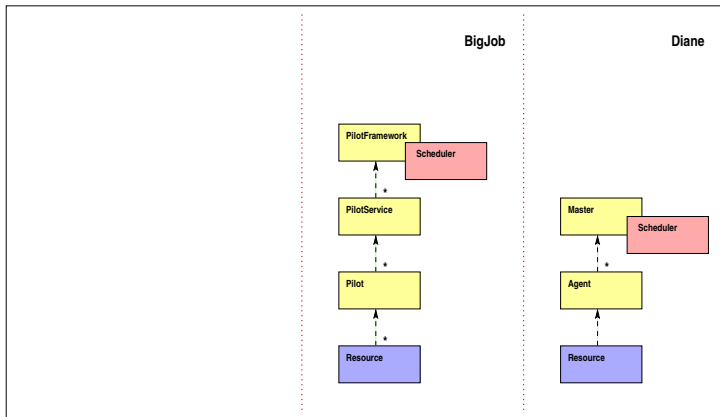
# TROY Placement and Scope

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  - application defines data and compute workload
- **is-a** scheduling framework
  - hosts scheduling algorithms
  - interfaces to external schedulers
  - enacts scheduling decisions

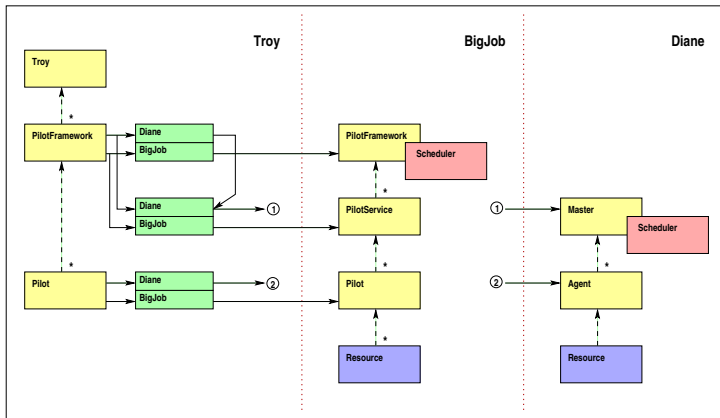
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  - application defines data and compute workload
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  - hosts scheduling algorithms
  - interfaces to external schedulers
  - enacts scheduling decisions
- **interface to** pilot job frameworks
  - assumes P\*, and possibly Pilot API

# Architecture

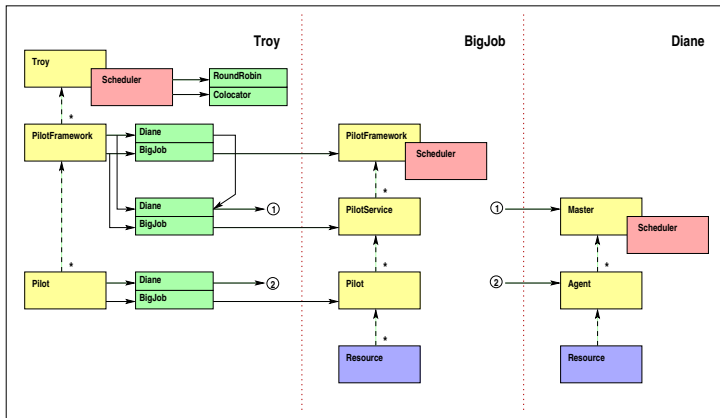


# Architecture

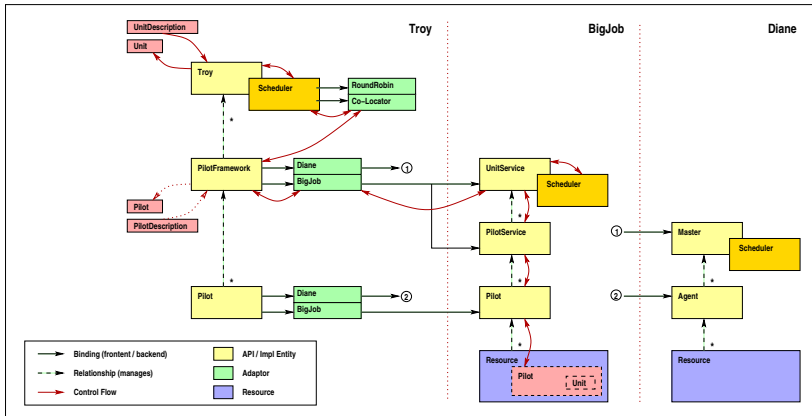




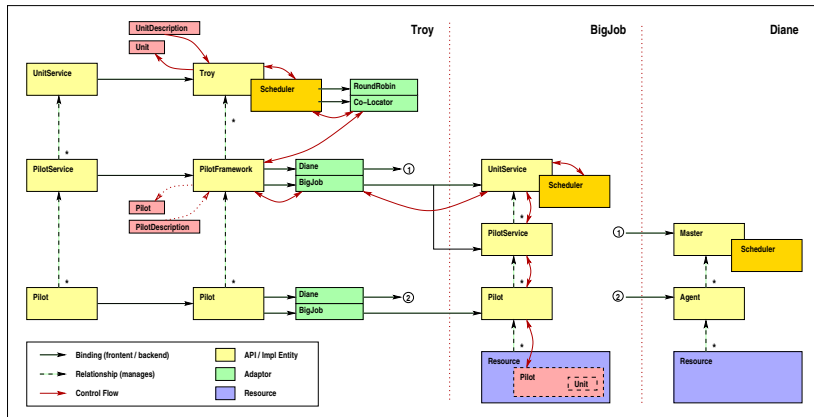
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# Troy API Classes

Troy classes interfacing to backend pilot systems:

- `troy.Scheduler`
- `troy.PilotFramework`  
interfaces to the `XXXUnitService` and `XXXPilotService`  
classes of Pilot API
- `troy.ComputePilot`
- `troy.ComputeUnit`
- `troy.DataPilot`
- `troy.DataUnit`

# Troy API

## API Example

```
pf1 = troy.PilotFramework ('bigjob//lonestar')
pf2 = troy.PilotFramework ('bigjob//kraken')

cpd = troy.ComputePilotDescription ()
pf1.submit_pilot (cpd)
pf2.submit_pilot (cpd)

t = troy.Troy ()
t.add_pilot_framework (pf1)
t.add_pilot_framework (pf2)

s = troy.Scheduler ('Random')
t.add_scheduler (s)
```

# Troy API

## API Example Cont.

```
cud = troy.ComputeUnitDescription ()

cud['executable'] = '/bin/sh'
cud['arguments']  = ['-c', 'touch /tmp/hello_troy_pj && sleep 10']

cu  = t.submit_unit (cud)
```

# Troy API

## API Example Cont.

```
while cu.state not in (troy.Done, troy.Failed) :  
  
    print "? cu %s: %s" % (cu.id, cu.state)  
    time.sleep (1)  
  
print "! cu %s: %s" % (cu.id, cu.state)  
  
pf1.cancel ()  
pf2.cancel ()
```

# Troy API

## Scheduler

```
def my_scheduler (troy, ud) :  
  
    pilots = []  
  
    for pf_id in troy.list_pilot_frameworks () :  
        pf = troy.PilotFramework (pf_id)  
  
        for p_id in pf.list_pilots () :  
            p = troy.ComputePilot (p_id)  
            pilots.append (p)  
  
    tgt = pilots[random.randint (0, len (pilots) - 1)]  
    return tgt.submit_unit (ud)
```



# Troy API

## Scheduler Cont.

```
p = pilots[random.randint (0, len (pilots) - 1)]  
  
return p.submit_unit (ud)
```

# Troy API

## API Example + Scheduler

```
t    = troy.Troy ()
pf   = troy.PilotFramework ('bigjob//')
t.add_pilot_framework (pf)

s    = troy.Scheduler ('Random')
t.add_scheduler (s)

cpd  = troy.ComputePilotDescription ()
cp1  = pf.submit_pilot (cpd)
cp2  = pf.submit_pilot (cpd)
```

# Troy API

## API Example + Scheduler

```
t    = troy.Troy ()
pf   = troy.PilotFramework ('bigjob//')
t.add_pilot_framework (pf)

t.add_scheduler (my_scheduler)

cpd  = troy.ComputePilotDescription ()
cp1  = pf.submit_pilot (cpd)
cp2  = pf.submit_pilot (cpd)
```