

# Real-time Simulation of Granular Matter using Smoothed Particle Hydrodynamics

## Masterarbeit

zur Erlangung des Grades Master of Science (M.Sc.)  
im Studiengang Computervisualistik

vorgelegt von  
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## Erklärung

Ich versichere, dass ich die vorliegende Arbeit selbständig verfasst und keine anderen als die angegebenen Quellen und Hilfsmittel benutzt habe.

Ja    Nein

Mit der Einstellung der Arbeit in die Bibliothek bin ich einverstanden.    ☐    ☐

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## 1 Introduction

## 2 Related Work

## 3 Basics

### 3.1 Granular Matter

## 4 Method

### 4.1 Smoothed Particle Hydrodynamics

Density neighbors

$$\rho_i = \sum_j V_j \rho_j W(x_i - x_j, h) = \sum_j m_j W(x_i - x_j, h) \quad (1)$$

$$W_{ij} \equiv W(x_i - x_j, h)$$

Density boundaries

$$\rho_i = \sum_b V_b \rho_0 W_{ib} \quad (2)$$

Unilateral incompressibility

$$\rho_i \leq \rho_0 \perp p \geq 0 \quad (3)$$

Velocity relative to the air

$$v_{i,rel}^2 = |v_a - v_i|^2 \frac{v_a - v_i}{|v_a - v_i|} \quad (4)$$

Drag

$$F_i^{drag} = \frac{1}{2} \rho_a v_{i,rel}^2 C_{D,i} \omega A_i \quad (5)$$

Velocity gradient

$$\nabla u_i = \sum_j V_j \nabla W_{ij} u_j^T \quad (6)$$

Strain

$$\varepsilon = \frac{1}{2} (\nabla u_i + \nabla u_i^T) \quad (7)$$

D

$$D_i = \frac{2m_i^2 \Delta t}{\rho_i^2} \sum_j \frac{1}{\rho_j} \nabla W_{ij} \nabla W_{ij}^T \quad (8)$$

$$\nabla W_{ij} \nabla W_{ij}^T \equiv W_{ij} \otimes W_{ij}$$

Stress

$$s_i = D^{-1} \varepsilon \quad (9)$$

$$s_{i,hydrostatic} = \frac{1}{2} \text{Tr } s_i \quad (10)$$

$$s_{i,deviatoric} = s_i - s_{i,hydrostatic} \quad (11)$$

$s_i$  refers to  $s_{i,deviatoric}$  for further equations

Drucker-Prager Yield Criterion

$$||s_i|| \leq p_i \sqrt{2} \sin \Theta \quad (12)$$

Friction Force

$$F_i^f = -m_i \sum_{j \neq i} m_j \left( \frac{s_i}{\rho_i^2} + \frac{s_j}{\rho_j^2} \right) \nabla W_{ij} \quad (13)$$

$$F_i^f = -m_i \sum_b V_b \rho_0 \left( \frac{s_i}{\rho_i^2} \right) \nabla W_{ib} \quad (14)$$

Todo: EOS Pressure Force

$$F_i^p = -m_i \sum_{j \neq i} m_j \left( \frac{p_i}{\rho_i^2} + \frac{p_j}{\rho_j^2} \right) \nabla W_{ij} \quad (15)$$

$$F_i^p = -m_i \sum_b V_b \rho_0 \left( \frac{p_i}{\rho_i^2} \right) \nabla W_{ib} \quad (16)$$

Non pressure forces

$$F_i^{adv} = F^g + F_i^f + f_i^{drag} \quad (17)$$

intermediate velocity

$$v_i^{adv} = v_i + \Delta t \frac{F_i^{adv}}{m_i} \quad (18)$$

intermediate density

$$\rho_i^{adv} = \rho_i + \Delta t \sum_j m_j v_{ij}^{adv} \nabla W_{ij} \quad (19)$$

pressure

$$p_i^{l+1} = (1 - \omega) p_i^l + \omega \frac{1}{a_{ii} * \Delta t^2} (\rho_0 - \rho_i^{adv} - \Delta t^2 \psi) \quad (20)$$

$\omega = 0.5$

$$\psi = \sum_j m_j \left( \sum_j d_{ij} p_j^l - d_{jj} p_j^l - \sum_{k \neq i} d_{jk} p_k^l \right) \nabla W_{ij} \quad (21)$$

$$\sum_{k \neq i} d_{jk} p_k^l = \sum_k d_{jk} p_k^l - d_{ji} p_i^l \quad (22)$$

$$\rho_i^{l+1} = |p * a_{ii} * \Delta t^2 - (\rho_0 - \rho_i^{adv} - \Delta t^2 \psi)| + \rho_0 \quad (23)$$

$$a_{ii} = \sum_j m_j (d_{ii} - d_{ji}) \nabla W_{ij} \quad (24)$$

Integration

$$v_i(t + \Delta t) = v_i^{adv} + \Delta t \frac{F_i^p}{m_i} \quad (25)$$

$$x_i(t + \Delta t) = x_i + \Delta t v_i(t + \Delta t) \quad (26)$$

Symbol	Unit	Name
$\rho_i$	$kg/m^3$	Density of particle $i$ at position $x$ for time $t$
$\rho_0$	$kg/m^3$	Rest density of the simulated material
$V_i$	$m^3$	Volume of particle $i$ at position $x$ for time $t$

## 4.2 Vulkan

# 5 Implementation

## 5.1 Libraries & NewTechnologies

## 5.2 Datastructures

## 5.3 Algorithm

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### Algorithm 1 Full Simulation Frame

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- 1: find neighbors
  - 2: compute  $\rho$
  - 3: compute drag
  - 4: compute  $s$
  - 5: compute  $v$  advection
  - 6: compute  $\rho$  advection
  - 7:  $l = 0$
  - 8: **while**  $l < 2 \parallel \rho_{avg} - \rho_0 < \eta$  **do**
  - 9:     compute  $d_{ij} p_j$
  - 10:    compute  $p^{l+1}$
  - 11:     $p(t) = p^{l+1}$
  - 12:     $l = l + 1$
  - 13: **end while**
  - 14: compute  $F^p$
  - 15: integrate
  - 16: advect HR particles
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## **6 Evaluation**

**6.1 Performance**

## **7 Conclusion & Future Work**

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