

OPTIMIZATION - OPTIMALISATIE

EXERCISE SESSION 2: FITTING PROBLEMS

The computational exercises are all in Python. First, we will set up the Python environment. To this end, we will import the following modules:

- **numpy**: package for multi-dimensional arrays
- **matplotlib**: package for plotting results
- **time**: package for various time-related functions
- **scipy**: library for optimization, integration, interpolation, eigenvalue problems, algebraic equations ...

You can do this by using the following commands:

```
import numpy as np
import matplotlib.pyplot as plt
import time
from scipy.optimize import linprog
```

Exercise 1 (Least squares fitting).

In linear least squares line fitting problems we have a set of measurements $(a_i, b_i) \in \mathbb{R}^2$, where $i \in \{1 \dots N\}$ onto which we would like to fit a line $b = x_1 a + x_2$. This can be expressed as an optimization problem by minimizing the residuals

$$\underset{x \in \mathbb{R}^2}{\text{minimize}} \sum_{i=1}^N (x_1 a_i + x_2 - b_i)^2 = \left\| \underbrace{\begin{pmatrix} a_1 & 1 \\ \vdots & \vdots \\ a_N & 1 \end{pmatrix}}_A \underbrace{\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}}_x - \underbrace{\begin{pmatrix} b_1 \\ \vdots \\ b_N \end{pmatrix}}_b \right\|_2^2. \quad (1.1)$$

The optimal solution can be calculated explicitly by solving the linear system

$$A^\top A x = A^\top b.$$

Tasks:

- First generate a vector of “measurements”: take $N = 50$ points. Define a to be a vector of evenly spaced points (tip: use the function `np.linspace(0,1,N)`). Then for b we set $b = 4a - 1$.
- Use $b = b + \text{np.random.randn}(N, 1)$ to add some Gaussian noise of standard deviation 1 to the vector b . Plot the obtained measurements using the command `plt.plot(a,b)`. (note: in Python you can always use `help()` to learn about the syntax of a command.)

- (1c) Find the coefficients x_1, x_2 of the ℓ_2 fitting problem above by either using `np.linalg.pinv(A)` or `np.linalg.solve(ATA, ATb)`, which should give the same result. Plot the obtained line into the same graph as the measurements.
- (1d) Introduce three outliers in your measurements b with standard deviation of 20, and check what happens with the fitted line in your plot.
- (1e) Keep the measurements b (both with and without outliers) and the matrix A for the next exercise.

Exercise 2 (ℓ_∞ fitting).

In this case we also want to fit a line to a set of measurements, but we have a different cost function:

$$\underset{x \in \mathbb{R}^2}{\text{minimize}} \quad \max_{i=1 \dots N} \{|x_1 a_i + x_2 - b_i|\} = \underset{x \in \mathbb{R}^2}{\text{minimize}} \quad \|Ax - b\|_\infty.$$

This objective function is not differentiable, so we use a trick to form an equivalent problem. We introduce a slack variable s and solve the optimization problem

$$\begin{aligned} &\underset{x \in \mathbb{R}^2, s \in \mathbb{R}}{\text{minimize}} \quad s \\ &\text{subject to} \quad -s \leq a_i x_1 + x_2 - b_i \leq s, \quad i = 1, \dots, N. \end{aligned} \tag{2.1}$$

Tasks:

- (2a) Which type of optimization problem is this? The solver in Python to solve these problems is called `linprog`.
- (2b) Use `? linprog` or `help(linprog)` to learn how to use the `linprog()` function to solve the problem.
- (2c) Formulate the problem in `linprog`'s form of linear programming (use $\tilde{x} = (x_1, x_2, s)$)

$$\begin{aligned} &\underset{\tilde{x}}{\text{minimize}} \quad c^\top \tilde{x} \\ &\text{subject to} \quad A_{\text{ub}} \tilde{x} \leq b_{\text{ub}} \\ &\quad \quad \quad A_{\text{eq}} \tilde{x} = b_{\text{eq}} \\ &\quad \quad \quad l \leq \tilde{x} \leq u. \end{aligned} \tag{LP}$$

- (2d) Solve the problem using the measurements b from the previous exercise (both with and without outliers) and compare the results. (Disclaimer: the fit with outliers will be pretty bad.)

Exercise 3 (ℓ_1 fitting).

In this case we also want to fit a line to a set of measurements, but we have a different cost function:

$$\underset{x \in \mathbb{R}^2}{\text{minimize}} \sum_{i=1}^N |x_1 a_i + x_2 - b_i| = \underset{z}{\text{minimize}} \|Ax - b\|_1.$$

This objective function is not differentiable, so we use a trick to form an equivalent problem. Introduce the slack variables $s = (s_1, \dots, s_N)$ and solve the optimization problem

$$\begin{aligned} &\underset{x \in \mathbb{R}^2, s \in \mathbb{R}^N}{\text{minimize}} && \sum_{i=1}^N s_i \\ &\text{subject to} && -s_i \leq a_i x_1 + x_2 - b_i \leq s_i, \quad i = 1, \dots, N. \end{aligned} \tag{3.1}$$

Tasks:

- (3a) Which type of optimization problem is this? The solver in Python to solve these problems is called `linprog`.
- (3b) Formulate the problem in `linprog`'s form of linear programming ([LP](#)).
- (3c) Solve the problem using the measurements b from the previous exercise (both with and without outliers) and compare the results.