## RELAZIONI

Def: Il prodotto cartesiano di Ay,..., An é cosí definito:

$$A_1 \times .... \times A_n = \{(a_1, a_2, ..., a_n) \text{ con } a_i \in A_i \text{ dove } i=1,..,n\}$$

$$\overline{\mathsf{tS}}: \ \mathsf{A} = \{1,2\} \ \mathsf{B} = \{0,\square\} \Rightarrow \mathsf{A} \times \mathsf{B} = \{(1,0); (1,\square); (2,0); (2,\square)\}$$

Def: Una relazione n-aria sugli insiemi A, ..., An é un sottoinsieme:

dominio

- ELENCARE ELEMENTI: 
$$R = \{(a_4, b_4); (a_2, b_2)\}$$

- GRAFO DI ADIACENZA: considero vertici gli elementi di 
$$A_1$$
 e  $A_2$  poi disegno una freccia se sono in relazione ES:  $A_1 = \{1,2,3\}$   $A_2 = \{b,c,d\}$   $R = \{(1,b);(1,d)\}$ 

$$M_{R} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

· OPERAZIONI :

- UNIONE: 
$$R, T \subseteq A_n \times A_2 \Rightarrow RUT = \{(a,b) | (a,b) \in R \vee ET\}$$

- INTERSEZIONE: R, T 
$$\subseteq A_n \times A_2 \implies R_n T = \{(a_1 b) | (a_1 b) \in R \land E T\}$$

- PRODOTTO DI RELAZIONI: REAJXA2 TEAZXA3 R'TEAJXA3

$$R \cdot T = \left( (a_1c) \in A_1 \times A_2 \mid \exists b \in A_2 \mid (a_1b) \in R \wedge (b_1c) \in T \right)$$

- INVERSA DI RELAZIONE: REA, XA2 => REA, XA4

$$R = \{ (b,a) \in A_2 \times A_4 \mid (a,b) \in R \}$$

## RAPPRESENTATIONE DELLE OPERATIONI

$$Q_{1} \qquad X_{1} \qquad Q_{2} \qquad X_{2} \qquad T = Q_{2} \qquad X_{2} \qquad X_{2} \qquad X_{2} \qquad X_{2} \qquad X_{2} \qquad X_{2} \qquad X_{3} \qquad X_{4} \qquad X_{5} \qquad X_{5} \qquad X_{6} \qquad X_{7} \qquad X_{7} \qquad X_{8} \qquad$$

$$\Rightarrow RUT = 0_2 \qquad \qquad X_4 \qquad \qquad R \cap T = 0_2 \qquad \qquad X_5 \qquad \qquad X_7 \qquad \qquad X_8 \qquad \qquad X_8$$

$$M_{e} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 1 & 0 \end{bmatrix} \quad M_{T} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$M(RNT) = M_R \wedge M_T = \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$-R : R = \Omega_2.$$

$$X_1 \times X_2 \times X_3 \times X_4 \times$$

$$- : R = \begin{matrix} a \\ b \\ c \end{matrix}$$

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$$M_{e} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$M_{t} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$M(R,T) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} = M_R \cdot M_T \text{ infatti:}$$

