

ADVANCED TOPICS IN SCIENTIFIC COMPUTING

LECTURE 10

see e.g. Larson-Bengzon

Boffi-Brezzi-Fortin, Springer, 2013

Boffi et al. C.I.M.E. summer school

Girault-Raviart, Springer, 1986.

Fluid Mechanics

Equations derived from

1) conservation of mass

2) " of momentum

1) Consider a generic volume ω ,

ρ = density, u = velocity

$$\int_{\omega} \dot{\rho} dx + \int_{\partial\omega} \rho u \cdot n ds = 0 \quad (\dot{\rho} = \frac{d\rho}{dt})$$

$$\Rightarrow \int_{\omega} (\dot{\rho} + \nabla \cdot (\rho u)) dx = 0$$

$$\Rightarrow \boxed{\dot{\rho} + \nabla \cdot (\rho u) = 0}$$

If $\rho \equiv \text{const} \Rightarrow \boxed{\nabla \cdot u = 0}$ incompressibility condition

2) Momentum balance
 $\hookrightarrow q = m u$, $\dot{q} = F$ ^{Newton}

look at δx , $\delta q = \rho u \delta x$

$$\int_{\omega} (\overset{\circ}{\rho u}) dx + \int_{\omega} \rho u n \cdot n ds = \int_{\omega} F - \int_{\omega} (\nabla \cdot \sigma + f) dx$$

↓

stress

$$\Rightarrow \underbrace{(\rho u) + \nabla \cdot (\rho u \otimes u)}_{\text{LHS}} = \nabla \cdot \sigma + f$$

For incompressible core ($\rho = 0$ $D \cdot (\rho u) = 0$)

$$\Rightarrow \text{LHS} = \rho \ddot{\mu} + \rho (\mu \circ \nabla) \mu$$

Hence,

$$\rho \ddot{u} + \rho (\mu \circ \nabla) u = \nabla \cdot \sigma + f$$

↑

Constitutive equations for Newtonian fluids

only two types of stressors:

- internal stress due to pressure: $-pI$
- II viscous stress

$$\mu \begin{pmatrix} \nabla u + \nabla u^T \end{pmatrix}$$

↑
viscosity

$$\Rightarrow \sigma = -pI + 2\mu \epsilon(u)$$

$$\boxed{\epsilon(u) = \frac{1}{2} [\nabla u + \nabla u^T]} \text{ strain}$$

Inserting in incompressible fluids

eq. :

$$\rho \ddot{u} + \rho(u \cdot \nabla) u = -\nabla p + 2\nabla \cdot \mu \epsilon(u) + f$$

$$\text{If } \mu \equiv \text{const} ; D = \mu / \rho$$

$$\Rightarrow \begin{cases} ii + (\boldsymbol{\sigma} \cdot \nabla) \boldsymbol{u} = -\nabla P + 2\nu \nabla \cdot \boldsymbol{\epsilon}(\boldsymbol{u}) + \boldsymbol{f} \\ \nabla \cdot \boldsymbol{u} = 0 \end{cases}$$

HAVIER-STOKES

$\nabla \cdot \boldsymbol{u}$

if $\boldsymbol{u} \in \mathcal{C}^2(\Omega)$

to fix the constant

$$\left(+ \frac{1}{|S_2|} \int_{S_2} P \, d\mathbf{x} = 0 \right)$$

boundary conditions

- wall conditions

- $\boldsymbol{u} \cdot \mathbf{n} = 0$ (slip)

- $\boldsymbol{u} = \boldsymbol{g}_D$ (no slip) (fixed wall)
 $\boldsymbol{g}_D = 0$

- outflow boundary

- $\boldsymbol{\sigma} \cdot \mathbf{n} = 0$ (stress free)

- $\mathbf{n} \cdot \nabla \boldsymbol{u} - P \mathbf{n} = 0$ (do-nothing)

- inflow boundary

- $\boldsymbol{u} = \boldsymbol{u}_{in}$

Stokes system

Omitting convective term $(\mathbf{u} \cdot \nabla) \mathbf{u}$
 + assuming steady-state

$$\begin{cases} -2\mu \nabla \cdot \boldsymbol{\varepsilon}(\mathbf{u}) + \nabla P = \mathbf{f} & \text{in } \Omega \\ \nabla \cdot \mathbf{u} = 0 & \text{in } \Omega \\ \mathbf{u} = \mathbf{g}_D & \text{on } \partial\Omega \end{cases}$$

Darcy's law

describes flow in porous media
 can be obtained by homogenisation
 of HS.

(At constant elevation) Darcy's law
 expresses relationship between

- discharge Q
- pressure drop $P_f - P_a$
- viscosity μ

$$Q = - \left(\frac{k A' \overset{\text{area}}{(P_b - P_a)}}{\mu L \text{-length}} \right) \rightarrow \text{permeability}$$

$$q = - \frac{k}{\mu} \nabla p$$

volumetric flux

Darcy system

D1	$K^{-1} u + \nabla p = 0$	$\text{in } \Omega$
D2	$-\nabla \cdot u = -f$	$\text{in } \Omega$
	$p = g$	$\text{on } \partial\Omega$

Mixed formula of Poisson problem

$$\begin{cases} -\nabla \cdot (K \frac{u}{\|u\|} p) = f & \text{in } \Omega \\ p = g & \text{on } \partial\Omega \end{cases}$$

weak form for Darcy $\Omega \subset \mathbb{R}^d$

$$H(\text{div}; \Omega) = \left\{ \boldsymbol{v} \in [L^2(\Omega)]^d : \nabla \cdot \boldsymbol{v} \in L^2(\Omega) \right\}$$

Hilbert

$$\|\boldsymbol{v}\|_{H(\text{div})} = \left(\| \boldsymbol{v} \|_{L^2(\Omega)}^2 + \| \nabla \cdot \boldsymbol{v} \|_{L^2(\Omega)}^2 \right)^{1/2}$$

$$\rightarrow H(\text{div}; \Omega) \times L^2(\Omega)$$

Test in D1 with $\boldsymbol{v} \in H(\text{div}; \Omega)$

$$\int_{\Omega} K^{-1} \boldsymbol{u} \cdot \boldsymbol{v} \, dx - \int_{\Omega} p \nabla \cdot \boldsymbol{v} + \int_{\partial\Omega} p \boldsymbol{n} \cdot \boldsymbol{v} \, ds = 0$$

natural condition

Test in D2 with $q \in L^2(\Omega)$

$$-\int_{\Omega} q \nabla \cdot \boldsymbol{u} = -\int_{\Omega} f q$$

Darcy:

Find $(\boldsymbol{u}, p) \in H(\text{div}; \Omega) \times L^2(\Omega)$:

$$\begin{aligned}
 & \stackrel{(MF)}{\left\{ \int_{\Omega} K^{-1} u \cdot v - \int_{\Omega} p \cdot v = - \int_{\partial\Omega} g \cdot v, \forall v \in H(\text{div}) \right.} \\
 & \left. - \int_{\Omega} q \nabla \cdot u = - \int_{\Omega} f q \quad \forall q \in L^2(\Omega) \right.
 \end{aligned}$$

Define:

- $a(u, v) = \int_{\Omega} K^{-1} u \cdot v \quad dx$
- $b(u, q) = \int_{\Omega} (\nabla \cdot u) q \quad dx$

→ (MF) appears in general Saddle point form:

$a(u, v) - b(v, p) = (g, v)_{\partial\Omega}$
$-b(u, q) \qquad \qquad \qquad = - (f, q)_{\Omega}$

Note:

- The Poisson problem is equivalent to minimisation problem (case $g = 0$):

$$\text{Find } P \in H_0^1(\Omega) : p = \arg \min_{q \in H_0^1(\Omega)} \left[\frac{1}{2} \int_{\Omega} K \nabla q \cdot \nabla q - \int_{\Omega} f q \right]$$

- The mixed formulation (Darcy) is equivalent to constraint minimisation problem

Find $u \in H(\text{div}; \Omega)$:

$$u = \arg \min_{v \in H(\text{div}; \Omega)} \int_{\Omega} K^{-1} v \cdot v + \int_{\partial\Omega} g \cdot v \cdot n$$

$$-\nabla \cdot v + f = 0$$

deemed to be more difficult ?

For the moment assume (NP) well posed and look for conforming discretisation

- $P \in L^2(\Omega) \rightarrow P_h \in V_{DG}^k$ piecewise disc. polynomials

- $u \in H(\text{div}; \Omega) \quad u_h \in \text{?}$ $H(\text{div})$ -conforming spa

Raviart-Thomas $H(\text{div})$ -conforming space

Z_h mesh made of simplices

$K \in Z_h, \quad k \geq 0$

$$RT_k(K) = \underbrace{\mathbb{P}_k(K)}^d + x \underbrace{\mathbb{P}_k(K)}$$

polynomial of degree $k+1$

$$v \in RT_k(K) \text{ then } v = w + x \sum_{|\alpha|=k} \alpha_\alpha x^\alpha$$

w $\underbrace{\sum_{|\alpha|=k} \alpha_\alpha}_{P}$

$\alpha = \text{multi-index}$

lemma :

$$(a) \dim RT_k = d \binom{k+d}{k} + \binom{k+d-1}{k}$$

$$\text{as } \dim \mathbb{P}_k(K) = \binom{k+d}{k}; \#(|\alpha|=k) = \binom{k+d-1}{k}$$

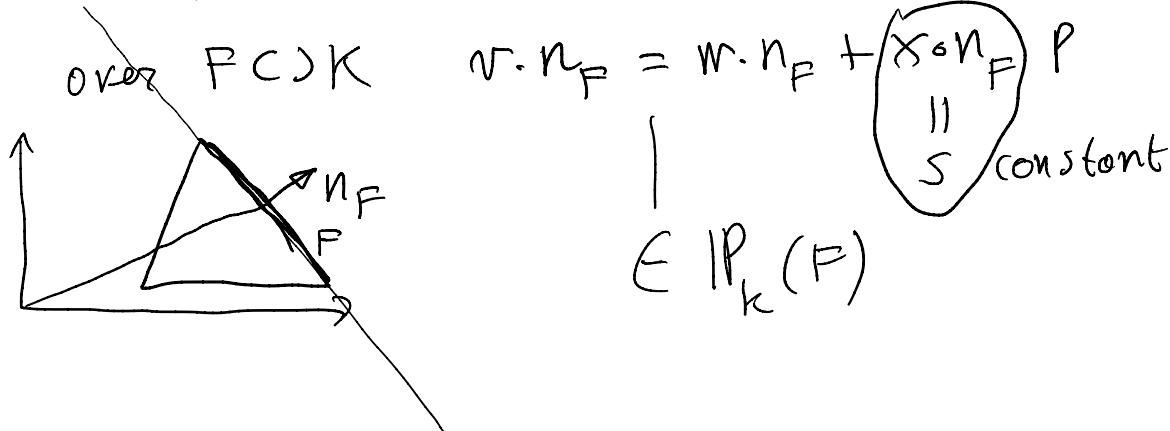
$\nabla v \in RT_k(K)$

(b) $v \circ n_F \in \mathbb{P}_k(F) \quad F \in \mathcal{F}K$

(c) $\forall v \in P_k(K)$ and $\forall RT_k(K) = P_k(K)$

(d) If $v \cdot v = 0 \Rightarrow v \in P_k(K)$

Proof of (b): $v = w + x \cdot p$, $w \in P_k^d$, $p \in P_k$



Dof for $RT_h(K)$

lemma: (RT local interpolant):

Given $v \in H^1(K)^d$ $\exists I_K v \in RT_h(K)$:

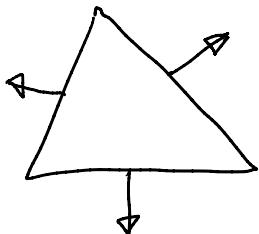
$$\bullet \int_F I_K v \cdot n_F P_k dx = \int_F v \cdot n_F P_k dx \quad \forall P_k \in P_k^d, \forall F \subset K$$

$$\bullet (\text{if } k \geq 1) \quad \int_K I_K v \cdot P_{k-1} dx = \int_K v \cdot P_{k-1} dx \quad \forall P_{k-1} \in P_{k-1}$$

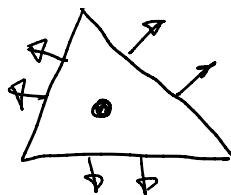
The RHSs above can be used DoF $RT_k(K)$

Examples:

RT_0



RT_1



Theorem: $\forall v \in H^m(K) \quad 1 \leq m \leq k+1$

$$\|v - I_K v\|_{L^2(K)} \leq C h_K^m \|v\|_{H^m(K)}$$

C depends on $d, k, \text{shape ref.}$

Global RT space

$$RT_K = \{v \in H(\text{div}; \Omega) : v_K \in RT_k(K), \forall K \in \mathcal{T}_h\}$$

with global interpolation operator

$$I_h : H(\text{div}; \Omega) \cap \prod_{K \in \mathcal{G}_h} H^1(K)^d \longrightarrow RT_k$$

$$v \longrightarrow I_h v$$

by $I_h v|_K = I_K v \quad \forall K \in \mathcal{G}_h$

proof that $I_h v \in RT_k$

(1) by def. $I_K v \in RT_k(K)$

(2) $I_h v \in H(\text{div}; \Omega)^d$

true $\Leftrightarrow v \cdot n_F$ continuous on all F
mesh faces

as $I_h v|_K$ is polynomial ord



Lemma: $v \in H(\text{div}; \mathcal{G}_h) \cap [v^{i,i}(\mathcal{G}_h)]^d$
(= piecewise)

belongs to $H(\text{div}; \Omega) \Leftrightarrow [v]_F = 0$

$\forall F \in \mathcal{F}_h^i$

$v \in H(\text{div}; \Omega) \Rightarrow v \cdot n$ is continuous on F
 by (6) $(I_K v) \circ n_F \in P_k(F)$

and, by the definition of the interpolant,

$$\int_F I_K v \cdot n_F P_k = \int_F v \cdot n_F P_k$$

such polynomial is fully determined by
 $v|_F \cdot n_F$.

Lemma : $\forall v \in H(\text{div}; \Omega) \cap \bigcap_{K \in \mathcal{E}_h} H^1(K)^d$

$$(0) \int_{\Omega} \nabla \cdot (v - I_h v) q \, dx = 0 \quad \forall q \in V_{DG}^k$$

and $\boxed{\nabla \cdot R T_k = V_{DG}^k}$

RT FEM : Find $(u_h, p_h) \in RT_h \times V_{DG}^k$:

$$(RT) \quad \begin{cases} a(u, v) - b(v, p) = \int_{\partial\Omega} g v \cdot n & \forall v \in RT_k \\ -b(u, q) = \int_{\Omega} f q & \forall q \in V_{DG}^k \end{cases}$$

Galerkin orthogonality

$$(GO1) \quad \begin{cases} a(u - u_h, v) - b(v, p - p_h) = 0 & \forall v \in RT_k \\ b(u - u_h, q) = 0 & \forall q \in V_{DG}^k \end{cases}$$

Lemma :

$$\|u - u_h\|_{L^2(\Omega)} \leq \left(1 + \|K\|_{L^\infty(\Omega)} \|K^{-1}\|_{L^\infty(\Omega)} \right) \|u - I_h u\|_{L^2(\Omega)}$$

Note: the velocity error does not depend on the

pressure error ?

For instance, if $f = 0 \quad \nabla \cdot u = 0$

also the RT solution is div-free

$$\text{Proof : } \|u - u_h\|_{L^2} \leq \|u - I_h u\|_{L^2} + \|I_h u - u_h\|_{L^2}$$

$$\|I_h u - u_h\|_{L^2(\Omega)}^2 = \int_{\Omega} (I_h u - u_h)(I_h u - u_h)$$

$$(A) \leq \|K\|_{L^\infty(K)} \int_{\Omega} K^{-1} (I_h u - u_h)(I_h u - u_h)$$

$$\ominus \|K\|_{L^\infty(K)} \int_{\Omega} K^{-1} (I_h u - u)(I_h u - u_h)$$

Proof : use Galerkin orthogonality

$$\text{by (602) } \int_{\Omega} \nabla \cdot (u - u_h) q = 0$$

$$\text{by (•)} \quad \frac{1}{\Omega} \int_{\Omega} \nabla \cdot (I_h u - u_h) q$$

by fact that $\nabla \cdot R T_h = V_{DG}^k$ can pick

$$q = \nabla \cdot (I_h u - u_h)$$

$$0 = \int_{\Omega} (\nabla \cdot (I_h u - u_h))^2 \Rightarrow \boxed{\nabla \cdot (I_h u - u_h) = 0}$$

(601) test with $\mathcal{V} = I_h u - u_h$

$$\underbrace{\int_{\Omega} K^{-1} (u - u_h) \cdot (I_h u - u_h)}_{=0}$$

Hence we can add this term to A and get the required equality.

In conclusion,

$$\|u_h - I_h u\|_{L^2(\Omega)}^2 \leq \|K\|_{L^\infty(K)} \int_{\Omega} K^{-1} (I_h u - u) (I_h u - u_h)$$

$$\leq \|K\|_{L^\infty(\Omega)} \|K^{-1}\|_{L^\infty(\Omega)} \|u - I_h u\|_{L^2(\Omega)} \|u_h - I_h u\|_{L^2(\Omega)}$$

□