

Recall classification of 2nd order PDES

(2D case) : $\mathcal{L}u := a u_{xx} + 2b u_{xy} + c u_{yy} + L.O.T.$

• $\mathcal{L}u = \Delta u = u_{xx} + u_{yy} \quad D = \begin{matrix} b^2 - ac \\ 0 \end{matrix} = -1 < 0 \text{ elliptic}$

• $\mathcal{L}u = u_t - u_{xx} \quad D = \begin{matrix} b^2 - ac \\ 0 \end{matrix} = 0 \text{ parabolic}$

• $\mathcal{L}u = u_{tt} - c^2 u_{xx} \quad D = \begin{matrix} b^2 - ac \\ 0 \end{matrix} = c^2 > 0 \text{ hyperbolic}$

Wave equation

Hyperbolic model problems

• wave equation

• linear transport $u_t + a u_x = 0$

• conservation laws: $u_t + (f(u))_x = 0$

example: Burger's eq.: $u_t + (u^2)_x = 0$

See eg: Q, LT, MM (Finite differences)

Cauchy problem for linear transport:

$$\begin{cases} u_t + \alpha(t, x) u_x = 0 & \text{in } (0, T] \times \mathbb{R} \\ u(x, 0) = u_0(x) \end{cases}$$

$$(1, \alpha) \circ \nabla_{t,x} u = 0$$

directional derivative along $(1, \alpha)$

(characteristic equations

$$\frac{dx}{dt} = \alpha(t, x)$$

along the solution curves of this ODE u

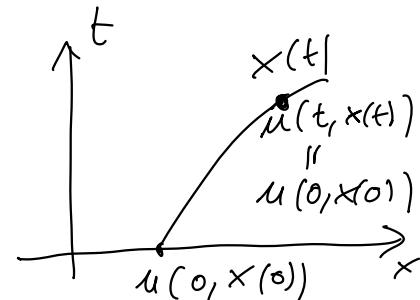
is constant or

$$\frac{du(x(t))}{dt} = \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} \frac{dx}{dt} \stackrel{=} \alpha$$

\uparrow

$$= 0$$

by the PDE



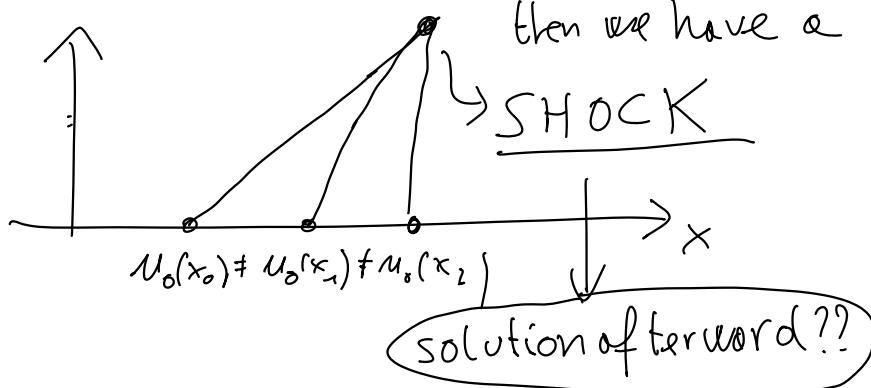
ex: $\alpha \equiv \text{const} \rightarrow$ charact. curves ODE solution:

$x - \alpha t = \text{const.} \Rightarrow$ straight lines \square

$$\Rightarrow \boxed{u(t, x) = u_0(x - \alpha t)}$$

• $\alpha = \alpha(u)$ still $u \equiv \text{const}$ along characteristic

if these meet at one point:



Systems

• linear case $\bar{u}_t + A u_x = 0$

assuming A has all real eigenvalues

con $T^{-1} A T = \Lambda = \text{diag}(\lambda_i)$

$$\bar{w} = T^{-1} \bar{u}$$

so that $\bar{w}_t + \Lambda w_x = 0$

the component w_i propagates at speed λ_i

• nonlinear case : $\frac{\partial \bar{u}}{\partial t} + \frac{\partial \bar{f}(\bar{u})}{\partial x} = 0$

for example Euler eq. :

$$\begin{cases} \frac{d\bar{u}_i}{dt} = \frac{\partial \bar{u}_i}{\partial t} + \bar{u} \cdot \nabla \bar{u}_i \quad \forall i=1, \dots, d \\ \nabla \cdot \bar{u} = 0 \end{cases}$$

in conservative form :

$$\frac{\partial \bar{u}_i}{\partial t} = \frac{\partial \bar{u}_i}{\partial t} + \frac{\partial}{\partial x_i} (\bar{u}_i^2) + \sum_{j \neq i} \frac{\partial u_i u_j}{\partial x_j}$$

or or a system

$$\bar{u}_t + A(\bar{u}) \bar{u}_x = 0$$

$$A(\bar{u}) = \frac{\partial \bar{f}}{\partial \bar{u}}(\bar{u}) = \text{Jacobian of } \bar{f}$$

i.e system of coupled transport eq. whose charact. curved in general, most often impossible to treat by the method of characteristics.

Also the wave eq. can be cast as system of transport eq.

$$\text{Consider } u_{tt} - u_{xx} = 0$$

$\overbrace{\quad\quad\quad}$
 \uparrow

$$\begin{array}{l} \textcircled{1} \left\{ u_t + v_x = 0 \right. \\ \textcircled{2} \left\{ u_x + v_t = 0 \right. \end{array} \Leftrightarrow \begin{array}{l} u_t + A v_x = 0 \\ u = \begin{pmatrix} u \\ v \end{pmatrix} \end{array}$$

$$\textcircled{2}_x$$

$$A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\textcircled{1}_t \quad 0 = u_{tt} + v_{tx} \stackrel{\textcircled{1}_x}{=} u_{tt} - u_{xx}$$

$$\textcircled{2}_t \quad 0 = u_{tx} + v_{tt} \stackrel{\textcircled{2}_x}{=} -v_{xx} + v_{tt}$$

Conservation

$$\begin{cases} u(0, x) = u_0(x) \\ u_t + \alpha u_x = 0 \end{cases} \quad \text{test by } u \text{ and integrate in } x$$

$$\alpha \equiv \text{const} \quad \int_{\mathbb{R}} u_t u \, dx + \int_{\mathbb{R}} \alpha u_x u \, dx = 0$$

$$\therefore \frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}} u^2 \, dx + \frac{1}{2} \alpha \int_{\mathbb{R}} \frac{\partial}{\partial x} u^2 \, dx = 0$$

$$\|u\|_0^2 \quad \underbrace{\left. \frac{1}{2} \alpha u^2 \right|_{-\infty}^{+\infty}}$$

$$\text{assuming } u \in L^2(\mathbb{R})$$

\int_0^{∞}

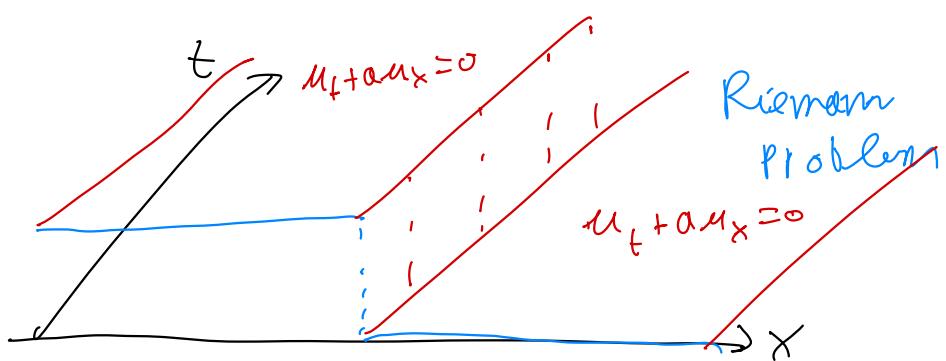
$$\boxed{\|u(t)\|_0^2 = \|u_0\|_0^2} \quad L^2 \text{ norm is conserved}$$

$$\begin{cases} u_{tt} - u_{xx} = 0 & (0, T] \times \mathbb{R} \\ u(0, x) = u_0(x) \\ u_t(0, x) = u_0'(x) \end{cases}$$

$$\text{Total energy: } \mathcal{E}(t) = \frac{1}{2} \int_{\mathbb{R}} (u_t^2 + u_x^2) dx = \mathcal{E}(0)$$

Proof: (ex) hint test with u_t

- For these models there is NO DISSIPATION
- Discontinuities of u_0 are propagated



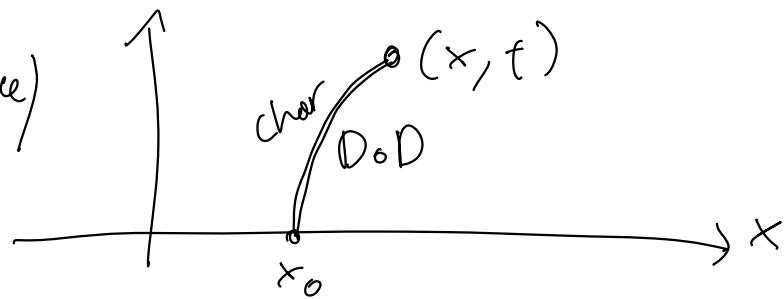
Solution satisfies PDE only piecewise

Bad news for numerics! or jump requires dissipation.

CFL condition

PDE has finite propagation speed, and
DoD is the characteristic curve

(Domain of Dependence)

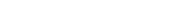


D.oD of FD schemes:

$$\begin{cases} u_t + \alpha u_x = 0 & \alpha \equiv \text{const} \\ u(0, x) = u_0(x) \end{cases} \quad \alpha > 0$$

$\rightarrow u(t, x) = u_0(x - \alpha t)$

(forward int)

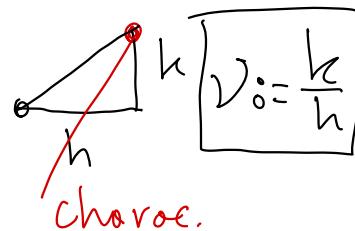


use backward FD in X;

$$\left\{ \begin{array}{l} \frac{U_i^{n+1} - U_i^n}{k} + \alpha \frac{U_i^n - U_{i-1}^n}{h} = 0 \\ \sum_{k=1}^x U_k^n + \alpha \sum_{h=1}^x U_h^n = 0 \end{array} \right. \quad \text{Upwind method}$$


$$(U_1^0 = u_0(x_i))$$

CFL: DoD of scheme
must include DoD
of PDE



$$V_0 := \frac{k}{h} \leq \frac{1}{\alpha} \quad \text{i.e. } \alpha V \leq 1$$

Conservation:

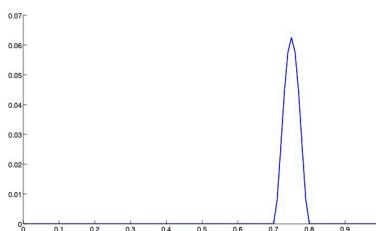
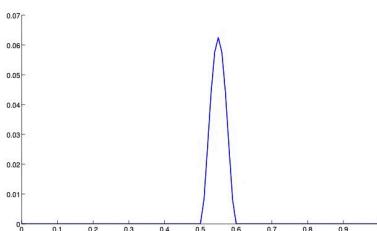
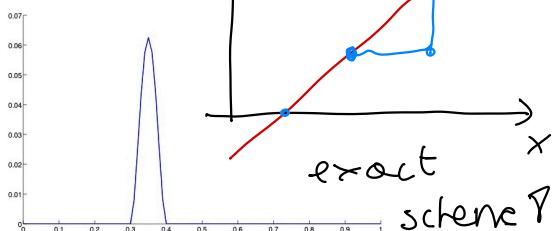
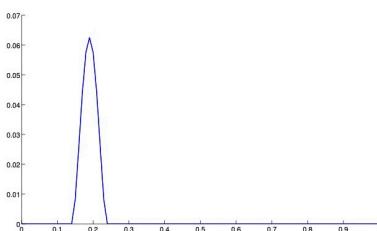
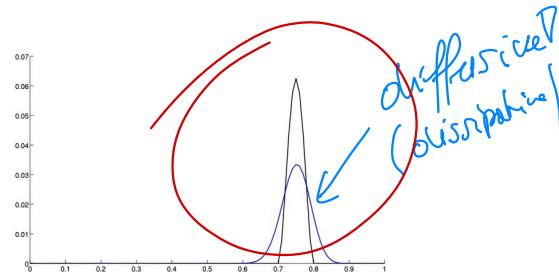
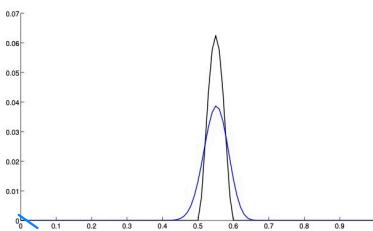
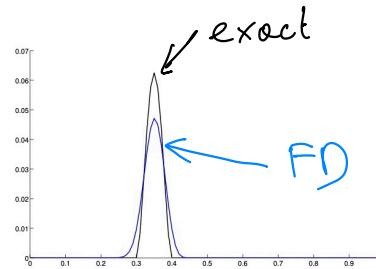
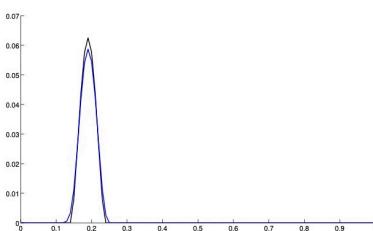
$$\begin{cases} U_i^{n+1} = (1 - \alpha V) U_i^n + \alpha V U_{i-1}^n & \forall i \\ U_1^0 = u_0(x_i) \end{cases}$$

$$\begin{aligned} \boxed{\sum_i U_i^{n+1}} &= (1 - \alpha V) \sum_i U_i^n + \alpha V \sum_i U_{i-1}^n \\ &= \sum_i U_i^n \\ &= \boxed{\sum_i U_i^0} \end{aligned}$$

$\mathcal{L} = \mathbb{R}$
mass is conserved

example: $u_t + 2u_x = 0$

$h = 1/100$ $k = 1/250$ $D < 0.5$



von Neumann analysiert: $U_1^n = \lambda^n e^{i \frac{\pi}{2} h}$

$$\lambda = (1 - \alpha V) + \alpha V e^{-i \frac{\pi}{2} h}$$

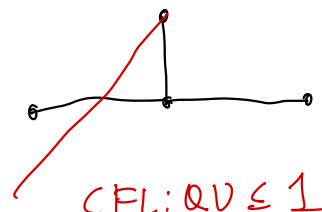
$$|\lambda|^2 = \dots = 1 - 4 \alpha V \underbrace{(1 - \alpha V)}_{\text{positive}} \sin^2 \left(\frac{\pi h}{2} \right) \leq 1$$

$$|\lambda| \leq 1 \Leftrightarrow \boxed{\alpha V \leq 1} \equiv \text{CFL cond} \quad !$$

Central FD Scheme:

$$\frac{U_1^{n+1} - U_1^n}{h} + \alpha \frac{U_{1+1}^n - U_{1-1}^n}{2h} = 0$$

$$\alpha > 0$$



Stability: $U_1^{n+1} = \frac{V}{2} U_{1-1}^n + U_1^n - \frac{V}{2} U_{1+1}^n$
($\alpha = 1$)

$$\lambda = 1 - V i \sin kh$$

$$|\lambda|^2 = 1 + V^2 \sin^2 kh > 1 \quad \text{always unstable} \quad ! !$$

Explanation:

$$\alpha > 0 \quad \underbrace{\alpha \sum_{h_1}^x U_1^n}_{\text{"upwind"}}$$

$$= \alpha \sum_{2h}^x U_1^n - \underbrace{\frac{\alpha h}{2} \left(\sum_h^x \right)^2 U_1^n}_{\text{central}}$$

artificial diffusion!

$$+ \text{central for } -\frac{\alpha h}{2} U_{xx}$$

control scheme

is

without

→

... but upwind "pays" in terms of accuracy

Truncation error of upwind scheme

$$|T_x^n| \leq \frac{1}{2} (h M_{tf} + h M_{xx}) \quad \begin{cases} M_{tf} = \max M_{tf} \\ M_{xx} = \max M_{xx} \end{cases}$$

i.e. $O(h, h)$

Convergence: If $0 < \alpha, \nu \leq 1$ then

$$\max_i |U_i^n - U_i^*| \leq \frac{1}{2} (h M_{tf} + h M_{xx})$$

Proof: $U_i^{n+1} = U_i^n - U_i^{n+1} = (1-\alpha\nu)U_i^n + \alpha\nu U_{i-1}^n + kT$

$\alpha\nu \leq 1 \Rightarrow \text{coeff} \geq 0 \text{ and sum to 1}$

$$E^n = \max |U_i^n| \leq E^n + kT^n \leq \dots \leq \underbrace{nk}_{\leq T} \max T^n$$

$$T^n = \max |T_x^n|$$

upwind method (general form): for $U_f + \alpha(t, x)U_x = 0$

$$U_i^{n+1} = \begin{cases} (1 - \alpha_i^n \nu)U_i^n + \alpha_i^n \nu U_{i+1}^n & \text{if } \alpha > 0 \\ (1 + \alpha_i^n \nu)U_i^n - \alpha_i^n \nu U_{i+1}^n & \text{if } \alpha < 0 \end{cases}$$

