

NMPDE/ATSC 2025

Lecture 18

Fully discrete schemes

Model problem $\forall t \in (0, T] = I$, find $u(t) \in V$:

$$\begin{cases} \frac{d}{dt}(u(t), v) + \mathcal{A}(u(t), v) = F(t, v) & \forall v \in V \\ u(0) = u_0 \end{cases}$$

\mathcal{V} -method + FEM

$$\begin{array}{ccc} \downarrow & & \downarrow \\ k = T/N_t & & V_h^k \end{array}$$

$\forall n = 1, \dots, N_t$, find $u_n^n \in V_h^k$:

$$\begin{cases} \left(\frac{u_n^{n+1} - u_n^n}{k}, v_h \right) + \mathcal{A}(\underbrace{\vartheta u_n^{n+1} + (1-\vartheta)u_n^n}_{u_v^{n+1}}, v_h) = F_{\vartheta}^{n+1}(v_h) & u_n \in V_h^k \\ u_n^0 = u_{0,h} \in V_h^k \end{cases}$$

$$\begin{cases} F_{\vartheta}^{n+1}(v_h) := (\vartheta f(t^{n+1}) + (1-\vartheta)f(t^n), v_h) \\ \sum_t u_h^{n+1} := \frac{u_n^{n+1} - u_n^n}{k} \\ u_v^{n+1} := \vartheta u_n^{n+1} + (1-\vartheta)u_n^n \end{cases}$$

or, equivalently

$$(\sum_t u_h^{n+1}, v_h) + \mathcal{A}(u_v^{n+1}, v_h) = F_{\vartheta}^{n+1}(v_h)$$

$$\text{e.g. } \begin{cases} \nu=0 & \text{Exp. (Forward) Euler} \\ \nu=1 & \text{Imp (Backward) Euler} \\ \nu=1/2 & \text{CN} \end{cases}$$

Analysis

Stability

example: Imp. Euler

- test the scheme with $v_h = u_h^{n+1}$ gives

$$\|u_h^{n+1}\|^2 - \underbrace{(u_h^n, u_h^{n+1})} + k \Omega(u_h^{n+1}, u_h^{n+1}) = k(f^{n+1}, u_h^{n+1})$$

$$\Omega(u_h^{n+1}, u_h^{n+1}) > 0$$

$$(u_h^n, u_h^{n+1}) \leq \|u_h^n\|_0 \|u_h^{n+1}\|_0$$

$$(f^{n+1}, u_h^{n+1}) \leq \|f^{n+1}\|_0 \|u_h^{n+1}\|_0$$

$$\|u_h^{n+1}\|_0 - \|u_h^n\|_0 \|u_h^{n+1}\|_0 \leq k \|f^{n+1}\|_0 \|u_h^{n+1}\|_0$$

$$\Rightarrow \|u_h^{n+1}\|_0 \leq \|u_h^n\|_0 + k \|f^{n+1}\|_0$$

$$\Rightarrow \boxed{\|u_h^n\|_0 \leq \|u_h^0\|_0 + k \sum_{j=1}^n \|f^j\|_0}$$

exercise: do same analysis for CN.

(Quarteroni-Volli, 1994)

Theorem: Assume Ω Coercive, $\|f(t)\|_0$ bounded,

Moreover, if $0 \leq \nu < 1/2$ assume the \mathcal{T}_h is quasi-uniform

$$k \left(1 + \underbrace{C_{\mathcal{I}}^2}_{\text{inverse est. const}} h^2 \right) < \underbrace{\frac{2 L_0}{(1-2\nu) \gamma^2}}_{T \times}$$

$$\text{Then } \|u_h^n\|_0 \leq C_{\mathcal{Q}} \left(\|u_{0,h}\| + \sup_{t \in [0,T]} \|f(t)\|_0 \right)$$

(Q, p. 135)

Theorem (convergence). Assume u_0, f, u are sufficiently smooth, under the condition of stability theorem, $\forall n \geq 1$

$$\|u(t_n) - u_n^n\|_0^2 + 2\alpha_0 k \sum_{m=1}^n \|u(t_m) - u_m^m\|_V^2 \leq C(u_0, f, u).$$

$l_2 - l^2$ $l_2 - H^1$ $\cdot \left(h^{2k} + \begin{cases} k^2 & v \neq 1/2 \\ k^4 & v = 1/2 \end{cases} \right)$

higher-order time-stepping

① FD: use higher-order FD formulas

Example: 2nd order Backward Differentiation Formula (BDF)

[3 BDF formulas of any order]

$$\bar{D}u^{n+1} := \bar{D}u^{n+1} + \frac{1}{2}k \bar{D}^2 u^{n+1}$$

$$= \frac{u^{n+1} - u^n}{k} + \frac{1}{2}k \bar{D} \left(\frac{u^{n+1} - u^n}{k} \right)$$

$$= \frac{u^{n+1} - u^n}{k} + \frac{1}{2}k \left[\frac{u^{n+1} - 2u^n + u^{n-1}}{k} \right]$$

exercise:

$$\bar{D}u(t_{n+1}) = u_t(t_{n+1}) + O(k^2)$$

To use this starting from some u_h^0 requires also u_h^1 which can be provided by any 1-step method (e.g. θ -method)

Theorem (Thomée): Under usual assumptions, using IE for 1st step and BDF of order 2 afterwards,

$$\|u(t_n) - u_h^n\| \leq C h^{k+1} \left(\|u_0\|_{k+1} + \int_0^{t_n} \|u_{tt}\|_{k+1} \right) + C k \int_0^k \|u_{ttt}\|_0 + C k^2 \int_0^t \|u_{ttt}\|_0$$

② Discontinuous Galerkin time-stepping

• use FE in space over the time steps
 (• + continuous FE in space)
 ($V \rightarrow V_h^k$)

semidiscrete version

$$0 = t_0 < t_1 < \dots < t_n < \dots < T \quad t_n = kn \quad M_t = T/k$$

$$J_n = (t_{n-1}, t_n) \quad \text{For } q \geq 0$$

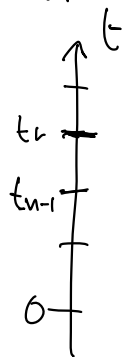
$$W_k^q = \{v: [0, T] \rightarrow V : v(t)|_{J_n} \in \mathbb{P}_q(V), \forall n=1, \dots, N_t\}$$

$$\forall n, \quad v(t) \Big|_{J_n} = \sum_{j=0}^q v_j t^j \quad ; v_j \in V$$

* v is not required to be cont. at t_n

$$\forall n \quad v_{\pm}^n = \lim_{\delta \rightarrow 0^{\pm}} v(t_n \pm \delta)$$

$$[v^n] = v_+^n - v_-^n \quad \text{"jump"}$$



Derivation of DG method

$$\textcircled{1} \quad \int_0^T (u_t, v) = - \int_0^T (u, v_t) + (u(T), \underbrace{v(T)}_0) - (u(0), v(0))$$

\uparrow
 some Smooth v such that $v(T) = 0$

$$\textcircled{2} \Rightarrow \underline{- \int_0^T (u, v_t) + \int_0^T (f, v) = (u_0, v(0)) + \int_0^T (f, v) dt}$$

$\textcircled{3}$ Replace u with $u_k \in \mathcal{W}_k^q$ and integrate back:

$$- \int_0^T (u_k, v') = - \sum_{n=1}^{N_t} \int_{J_n} (u_k, v_t)$$

$$= \sum_{n=1}^{N_t} \int_{J_n} (u_k', v) - \sum_{n=1}^{N_t} (u_k, v) \Big|_{t=t_{n-1}}^{t=t_n}$$

$$= \int_0^T (u', v) + \sum_{n=1}^{N_t-1} ([u_k^n], v) \Big|_{t_n} + (u_{k,+}, v) \Big|_{t=0} - \cancel{(u_{\Delta t}^{N_t}, v) \Big|_{t=T}} \quad \text{or } v|_{t=0}$$

(4) substitute back into (2)

Find $u^k \in W_k^q$


choice?

$$\left\{ \begin{aligned} & \int_0^T [(u_k', v) + f(u_k, v)] dt + \sum_{n=1}^{N_t-1} ([u_k^n], v^n) \Big|_{t_n} \\ & ((u^k)_+, v_+) \quad \text{PDE} \\ & = (u_{k,-}^0, v_+) + \int_0^T (f, v) \end{aligned} \right.$$

$\forall v \in W_k^q$

DB-in-time method (monolithic version)

$u_{k,-}^0 = u_0$





The test functions v are also discontinuous in time \Rightarrow we can test, for any n , with all and only test functions v with support in J_n .

$\forall n = 1, \dots, N_t$, find $u_{\Delta t}|_{J_n} \in \mathbb{P}^q(V)$:

DG method in time
 (time-stepping version)

$$\left\{ \begin{array}{l} \int_{J_n} \left[\left(\frac{d}{dt} u_k, v \right) + \mathcal{R}(u_k, v) \right] dt + (u_{k,+}^{n-1}, v_+^{n-1}) \\ \quad \quad \quad = (u_{k,-}^{n-1}, v_+^{n-1}) + \int_{J_n} (f, v) dt \quad \forall v \in \mathbb{P}^q(V) \\ \text{with } u_{k,-}^0 = u_0 \end{array} \right.$$

solve one time-step at a time ,

starting from $(u^k)_-^0 = u_0$! ∇_0

Remark : the method is fully-consistent as it is satisfied by the exact solution.