

NMPDE/ATSC 2025

Lecture 19

Recall classification of 2nd order PDEs

(2D case) : $\mathcal{L}u := a u_{xx} + 2b u_{xy} + c u_{yy} + \text{L.O.T.}$

• $\mathcal{L}u = \Delta u = u_{xx} + u_{yy}$ $D = \begin{pmatrix} b^2 - ac \\ b & c \\ 0 & 1 & 1 \end{pmatrix} = -1 < 0$ elliptic

• $\mathcal{L}u = u_t - u_{xx}$ $D = \begin{pmatrix} b^2 - ac \\ b & c \\ 0 & 0 & -1 \end{pmatrix} = 0$ parabolic

• $\mathcal{L}u = u_{tt} - c^2 u_{xx}$ $D = \begin{pmatrix} b^2 - ac \\ b & c \\ 0 & 1 & -c^2 \end{pmatrix} = c^2 > 0$ hyperbolic

Wave equation

hyperbolic model problems

• wave equation

• linear transport $u_t + a u_x = 0$

• conservation laws: $u_t + (f(u))_x = 0$

example: Burger's eq.: $u_t + (\frac{u^2}{2})_x = 0$

See eg: Q, LT, MM (Finite differences)

Cauchy Problem for linear transport:

$$\begin{cases} u_t + a(t, x) u_x = 0 & \text{in } (0, T] \times \mathbb{R} \\ u(x, 0) = u_0(x) \end{cases}$$

$$(1, a) \cdot \nabla_{t,x} u = 0$$

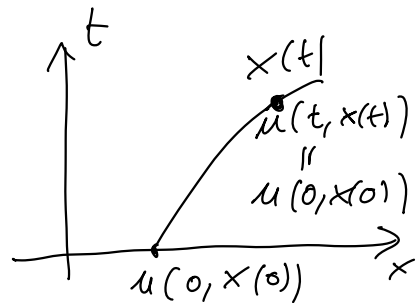
directional derivative along $(1, a)$

characteristic equations

$$\frac{dx}{dt} = a(t, x)$$

along the solution curves of this ODE u is constant or

$$\begin{aligned} \frac{d u(x(t))}{dt} &= \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} \frac{dx}{dt} \\ &\stackrel{= a}{=} 0 \\ &\text{by the PDE} \end{aligned}$$



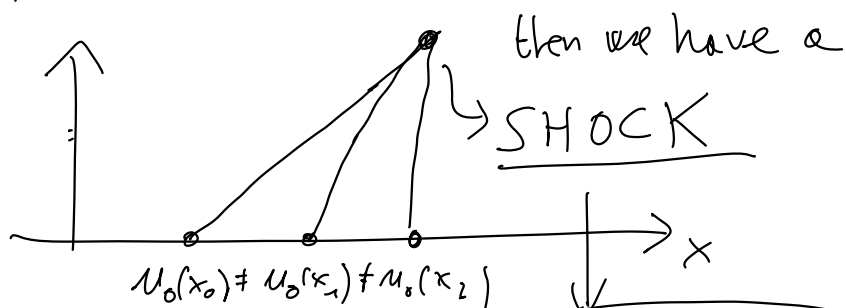
ex: $a \equiv \text{const} \rightarrow$ charact. curves ODE solution:

$$x - at = \text{const.} \Rightarrow \text{straight lines } ?$$

$$\Rightarrow u(t, x) = u_0(x - at)$$

• $Q = Q(u)$ still $u \equiv \text{const}$ along characteristic

if these
meet at
one point:



solution of the word??

Systems

• linear case $\bar{u}_t + A u_x = 0$

assuming A has all real eigenvalues

con $T^{-1}AT = \Lambda = \text{diag}(\lambda_i)$

$$\bar{w} = T^{-1}\bar{u}$$

so that $\bar{w}_t + \Lambda w_x = 0$

the component w_i propagates at speed λ_i

• nonlinear case $\therefore \frac{\partial \bar{u}}{\partial t} + \frac{\partial f(\bar{u})}{\partial x} = 0$

for example Euler eq.:

$$\begin{cases} \frac{d\mu_i}{dt} = \frac{\partial \mu_i}{\partial t} + \underline{\mu} \cdot \nabla \mu_i & i=1, \dots, d \\ \nabla \cdot \underline{\mu} = 0 \end{cases}$$

in conservative form :

$$\frac{d\mu_i}{dt} = \frac{\partial \mu_i}{\partial t} + \frac{\partial}{\partial x_i} (\mu_i^2) + \sum_{j \neq i} \frac{\partial \mu_i \mu_j}{\partial x_j}$$

or or system

$$\underline{\mu}_t + A(\underline{\mu}) \underline{\mu}_x = 0$$

$$A(\underline{\mu}) = \frac{\partial \underline{F}}{\partial \underline{\mu}}(\underline{\mu}) = \text{Jacobian of } \underline{F}$$

i.e system of coupled transport eq. whose charact. curved in general, most often impossible to treat by the method of characteristics.

Also the same eq. can be conf or system of transport eq.

Consider $\frac{u_{tt} - u_{xx} = 0}{\updownarrow}$

$$\begin{aligned} \textcircled{1} \quad & \begin{cases} u_t + v_x = 0 \\ u_x + v_t = 0 \end{cases} \Leftrightarrow U_t + A U_x = 0 \\ \textcircled{2} \quad & \end{aligned}$$

$$U = \begin{pmatrix} u \\ v \end{pmatrix}$$

$$A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\begin{aligned} \textcircled{1}_t \quad & 0 = u_{tt} + v_{tx} \stackrel{\textcircled{2}_x}{=} u_{tt} - u_{xx} \\ \textcircled{2}_t \quad & 0 = u_{tx} + v_{tt} \stackrel{\textcircled{1}_x}{=} -v_{xx} + v_{tt} \end{aligned}$$

Conservation

$\begin{cases} u(0, x) = u_0(x) \\ u_t + a u_x = 0 \end{cases}$ test by u and integrate in x

$a \equiv \text{const}$

$$\int_{\mathbb{R}} u_t u \, dx + \int_{\mathbb{R}} a u_x u \, dx = 0$$

$$\therefore \frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}} u^2 \, dx + \frac{1}{2} a \underbrace{\int_{\mathbb{R}} \frac{\partial}{\partial x} u^2 \, dx}_{\frac{1}{2} a u^2 \Big|_{-\infty}^{+\infty}} = 0$$

assuming $\|u\|_0^2$

assuming $\|u\| \in L^2(\mathcal{R})$

\parallel
0

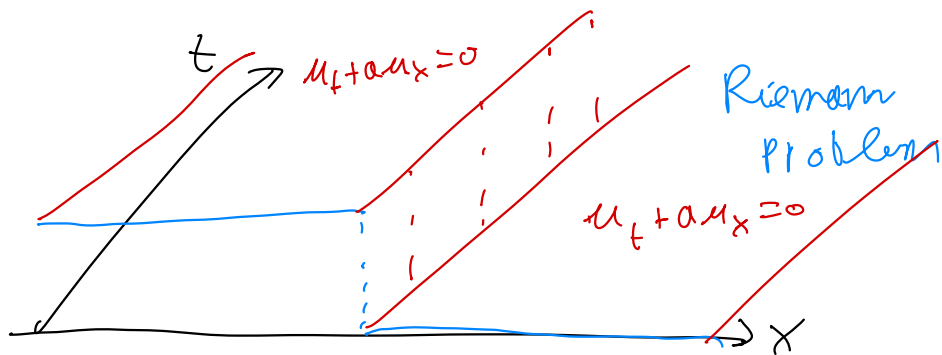
$$\boxed{\|u(t)\|_0^2 = \|u_0\|_0^2} \quad L^2 \text{ norm is conserved}$$

$$\begin{cases} u_{tt} - u_{xx} = 0 & (0, T] \times \mathbb{R} \\ u(0, x) = u_0(x) \\ u_t(0, x) = v_0(x) \end{cases} \quad \Omega$$

$$\text{Total energy: } \mathcal{E}(t) = \frac{1}{2} \int_{\Omega} (u_t^2 + u_x^2) dx = \mathcal{E}(0)$$

Proof: (ex) hint test with u_t

- For these models there is NO DISSIPATION
- Discontinuities of u_0 are propagated



solution satisfies PDE only piecewise

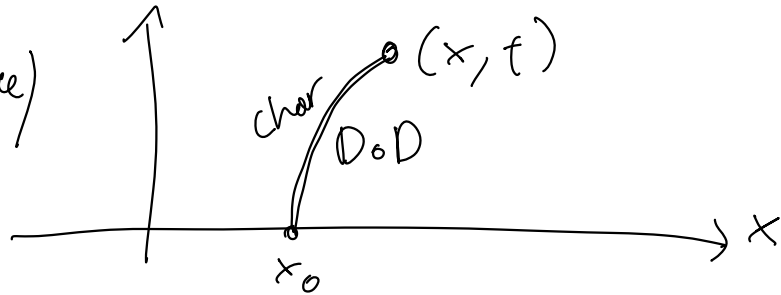
Bad news for numerics ∇ or jump requires dissipation.

CFL condition

PDE has finite propagation speed, and

DoD is the characteristic curve

(Domain of Dependence)



DoD of FD schemes:

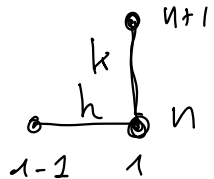
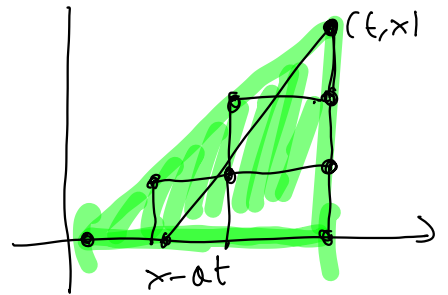
$$\begin{cases} u_t + \alpha u_x = 0 & \alpha \equiv \text{const} \\ u(0, x) = u_0(x) \end{cases} \quad \alpha > 0$$

$$\Rightarrow u(t, x) = u_0(x - \alpha t)$$

(forward int)

use backward FD in x:

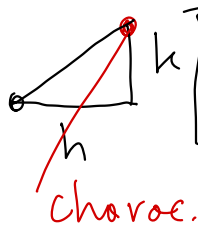
$$\begin{cases} \frac{U_i^{n+1} - U_i^n}{k} + \alpha \frac{U_i^n - U_{i-1}^n}{h} = 0 \\ \Leftrightarrow \sum_{k,t}^t U_i^n + \alpha \sum_{h,-}^x U_i^n = 0 \end{cases}$$



upwind method

$$U_1^0 = u_0(x_i)$$

CFL: DoD of scheme
must include DoD
of PDE



$$v := \frac{k}{h}$$

$$\leq \frac{1}{\alpha}$$

$$\text{i.e. } \alpha v \leq 1$$

Conservation:

$$\begin{cases} U_1^{n+1} = (1 - \alpha v) U_1^n + \alpha v U_{1-1}^n & \forall i \\ U_1^0 = u_0(x_i) \end{cases}$$

$$\sum_i U_1^{n+1} = (1 - \alpha v) \sum_i U_1^n + \alpha v \sum_i U_{1-1}^n$$

$$= \sum_i U_1^n$$

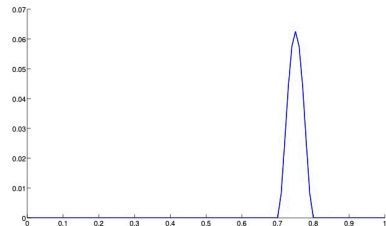
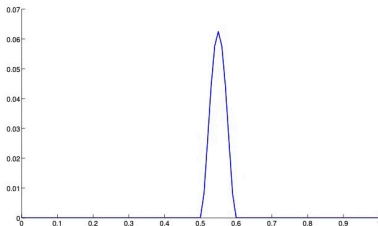
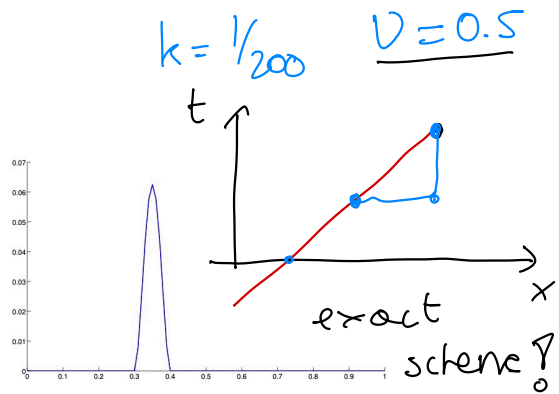
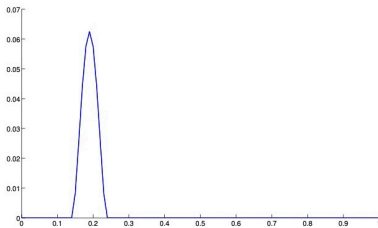
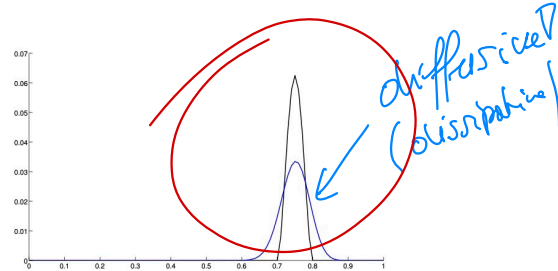
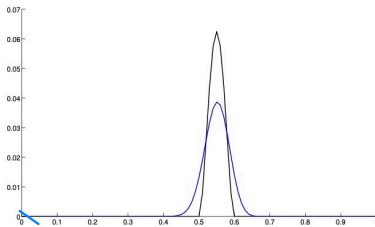
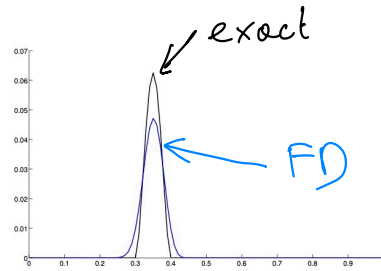
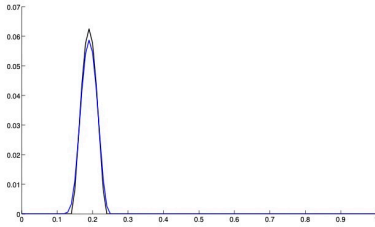
$$= \sum_i U_1^0$$

$$\Omega = \mathbb{R}$$

mass is conserved

example: $u_t + 2u_x = 0$

$h = 1/100$ $k = 1/250$ $V < 0.5$



von Neumann analysis: $U_1^n = \lambda^n e^{i\tau h}$

$$\lambda = (1 - \alpha \nu) + \alpha \nu e^{-i\tau h}$$

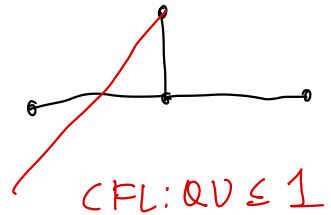
$$|\lambda|^2 = \dots = 1 - 4 \alpha \nu \underbrace{(1 - \alpha \nu)}_{\text{positive}} \sin^2\left(\frac{\tau h}{2}\right) \leq 1$$

$$|\lambda| \leq 1 \Leftrightarrow \boxed{\alpha \nu \leq 1} \equiv \text{CFL cond } \nabla_0$$

Central FD Scheme:

$\alpha > 0$

$$\frac{U_1^{n+1} - U_1^n}{h} + \alpha \frac{U_{1+1}^n - U_{1-1}^n}{2h} = 0$$



stability: $U_1^{n+1} = \frac{\nu}{2} U_{1-1}^n + U_1^n - \frac{\nu}{2} U_{1+1}^n$
 $(\alpha \equiv 1)$

$$\lambda = 1 - \nu i \sin kh$$

$$|\lambda|^2 = 1 + \nu^2 \sin^2 kh > 1 \text{ always unstable } \nabla \nabla$$

Explanation:

$$\alpha > 0 \quad \underbrace{\alpha \int_{h^-}^x U_1^n}_{\text{"upwind"}} = \underbrace{\alpha \int_{2h}^x U_1^n}_{\text{central}} - \underbrace{\frac{\alpha h}{2} \left(\int_h^x \right)^2 U_1^n}_{\text{artificial diffusion?}} + \text{central for } -\frac{\alpha h}{2} U_{xx}$$

control scheme is without \rightarrow

... but upwind "pays" in terms of accuracy

Truncation error of upwind scheme

$$|T_n^n| \leq \frac{1}{2} (k M_{tt} + h M_{xx}) \quad \begin{cases} M_{tt} = \max u_{tt} \\ M_{xx} = \max u_{xx} \end{cases}$$

i.e. $O(k, h)$

Convergence: If $0 < \alpha \nu \leq 1$ then

$$\max_i |u_i^n - U_i^n| \leq \frac{T}{2} (k M_{tt} + h M_{xx})$$

Proof: $e_i^{n+1} = u_i^{n+1} - U_i^{n+1} = (1 - \alpha \nu) e_i^n + \alpha \nu e_{i-1}^n + k T$

$\alpha \nu \leq 1 \Rightarrow$ coeff ≥ 0 and sum to 1

$$E^n = \max |e_i^n| \leq E^n + k T^n \leq \dots \leq \underbrace{nk}_{\leq T} \max_n T^n$$

$$T^n = \max |T_i^n|$$

upwind method (general form): for $u_t + a(t, x) u_x = 0$

$$U_i^{n+1} = \begin{cases} (1 - \alpha_i^n \nu) U_i^n + \alpha_i^n \nu U_{i-1}^n & \text{if } \alpha \geq 0 \\ (1 + \alpha_i^n \nu) U_i^n - \alpha_i^n \nu U_{i+1}^n & \text{if } \alpha < 0 \end{cases}$$

