

NMPDE/ATSC 2025

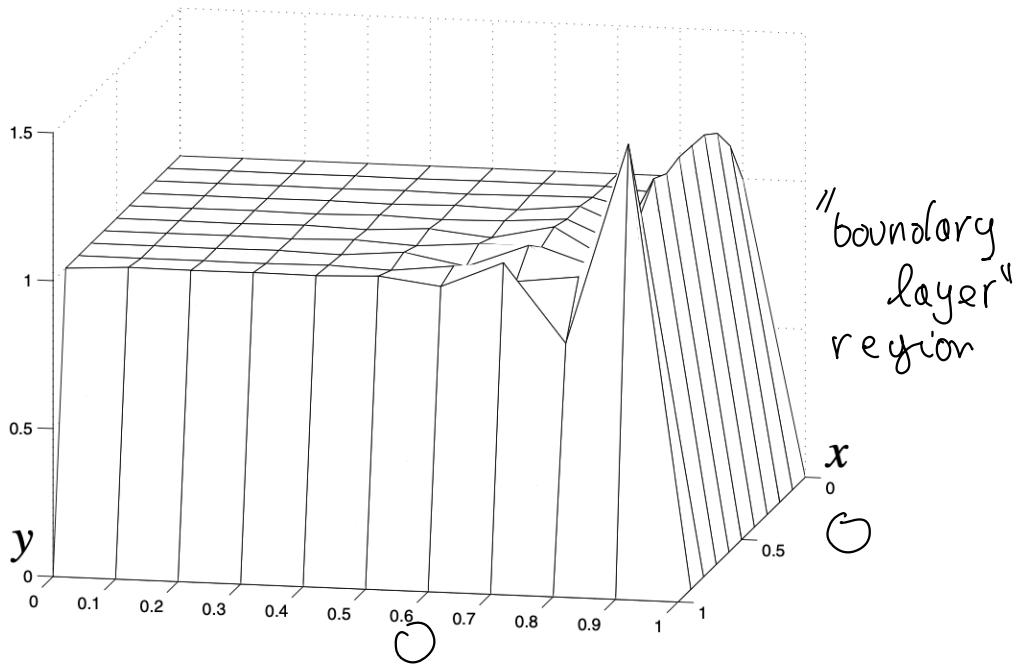
Lecture 14

$$\begin{cases} -\alpha \Delta u + \underline{b} \cdot \nabla u = f & \Omega \\ u = g & \partial\Omega \end{cases}$$

$$f = 0 \quad g(x, y) = \begin{cases} 1 & \text{if } x=0 \text{ or } y=0 \\ 0 & \text{if } x=1 \text{ or } y=1 \end{cases}$$

$$\underline{b} = (1, 1) \quad \varrho = \varepsilon = 10^{-3}$$

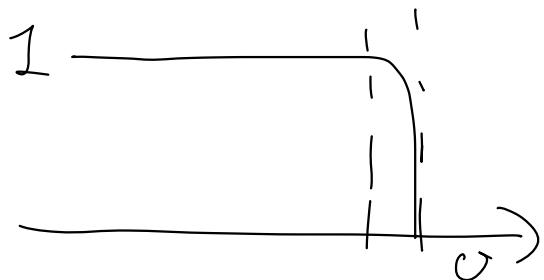
Solution by the SD-FEM $k=1$



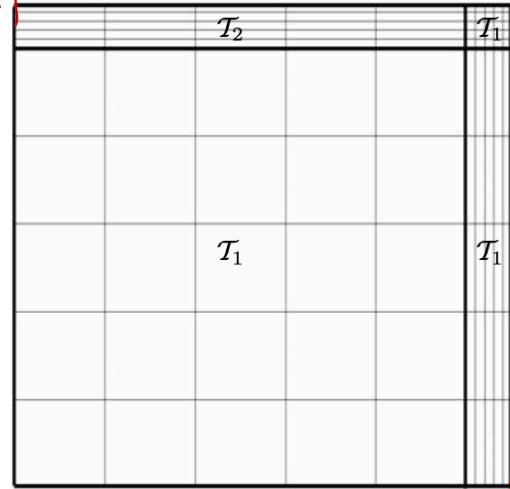
$$x = 1/2$$

or

$$y = 1/2$$

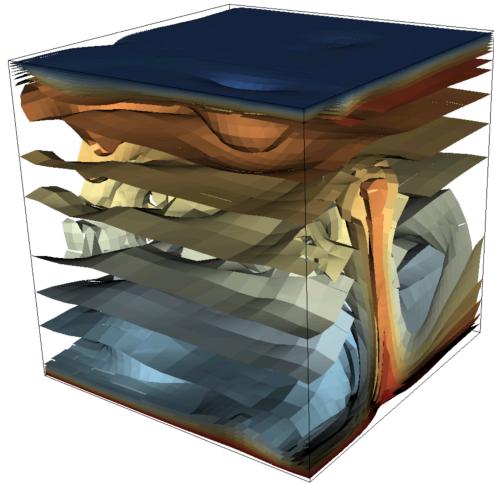
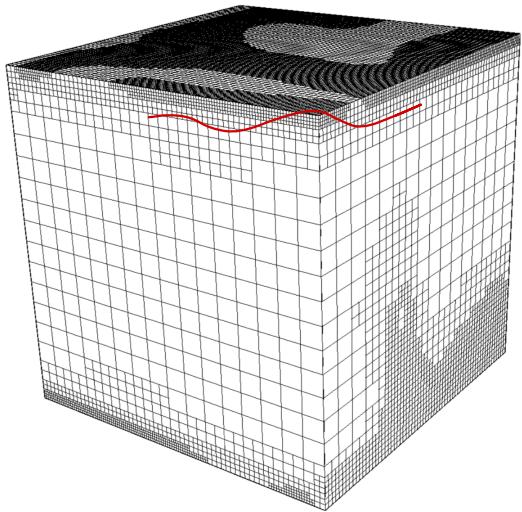


Shishkin mesh



$$\mathcal{O}(\bar{b}/\epsilon) \quad \bar{b} = \|\mathbf{b}\|_\infty$$

ϵ



Mesh adaptivity and ϱ posteriori
error estimators

$$\|u - u_h\| \leq C h^k \|u\|_{k+1}$$

ϱ priori
error bound

\uparrow \uparrow
 exact computed

$$\|u - u_h\| \leq \varrho(u_h)$$

ϱ posteriori
error
bound

\uparrow
 estimator

$$\varrho^2 = \sum_{T \in \mathcal{Z}_h} \varrho_T^2$$

η_T = local error estimator

used to drive

automatic adaptivity:

- ① SOLVE (Compute u_h on given mesh)
- ② ESTIMATE ($\| \eta_T \|_T$)
- ③ MARK subset of elements T
with larger η_T
- ④ REFINE the mesh based on ③

example (motivation):

Suppose want to solve the linear system

$$A U = F$$

and suppose U_0 is given approx. of U .

Can I estimate error $U - U_0$?

$$A(U - U_0) = AU - AU_0 = \underbrace{F - AU_0}_{\text{residual}}$$

$$U - U_0 = \underbrace{A^{-1}(F - AU_0)}_{\text{error representation}}$$

$$\|U - U_0\| \leq \|A^{-1}\| \|F - AU_0\|$$

estimating this norm

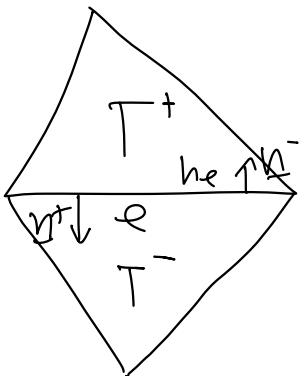
would provide a residual based error estimator

example: on residual based a posteriori error estimator for

$$\left\{ \begin{array}{l} -\nabla \cdot (\alpha \nabla u) = f \text{ in } \Omega \\ \text{+ b.c.} \end{array} \right.$$

$$\|u - u_h\|_1 \leq C \left(\sum_{T \in \mathcal{G}_h} \left(h_T^2 \|f + \nabla \cdot \alpha \nabla u_h\|_{0,T}^2 \right)^{1/2} \right)$$

$$\|u - u_h\|_1 \leq C \left(\sum_{T \in \mathcal{G}_h} \left(h_T^2 \|f + \nabla \cdot \alpha \nabla u_h\|_{0,T}^2 \right)^{1/2} \right)$$



$$\left(+ \sum_{e \in \partial T} h_e \left[\left[\partial u_h \cdot n \right] \right] \right)_e^2$$

↑ edges of T

$$\left[\left[\partial u_h \cdot n \right] \right]_e = \left(\left[\partial u_h \cdot n \right] \Big|_{T^+} + \left[\partial u_h \cdot n \right] \Big|_{T^-} \right)_e$$

outward normal

$$h_e = |e|$$

Jump residual

Parabolic problems

(LT, online notes,
Q, MM)

$$(\mathcal{L} u = f)$$

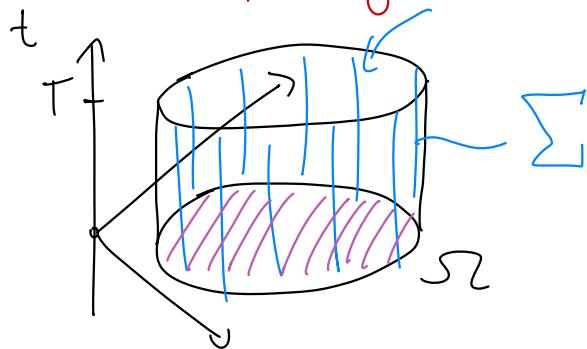
Model problem:

- \mathcal{L} a linear elliptic operator in \mathbb{R}^{Ω} .
- $t \in (0, T]$
- PDE: $u_t + \mathcal{L} u = f$

$$\text{example: } \mathcal{L} u = -\Delta u \rightarrow u_t - \Delta u = f$$

heat equation

Courant-Dirichlet (CD) problem: $\begin{cases} u_t + L u = f & \text{over } \Omega \times (0, T] \\ u(x, 0) = u_0(x) & \text{on } \partial\Omega \quad \text{initial cond.} \\ u(t, x) = g(t, x) & \text{on } \partial\Omega \times [0, T] \end{cases}$ boundary condition



Analysis of the heat equation

* $\begin{cases} u_t - \Delta u = f & \Omega \times I \\ u(x, 0) = u_0 & \text{in } \Omega \\ u(x, t) = 0 & \text{in } \Sigma \end{cases}$

(LT)

Maximum principle: If u smooth function s.t. $u_t - \Delta u \leq 0$ in $\Omega \times I$ then u attains maximum on $\Omega \times \{0\} \cup \Sigma$.

Corollary: if u solves $(*)$, then

(stability)

$$\|u\|_{C(\bar{\Omega} \times \bar{I})} \leq \|u_0\|_{C(\bar{\Omega})} + \frac{r^2}{2d} \|f\|_{C(\bar{\Omega} \times \bar{I})}$$

$d = \dim \text{ of } \Omega$

$r = \text{ radius of a ball containing } \bar{\Omega} \times \bar{I}$

Existence by providing solution:

$$u(\cdot, t) = u(t) = E(t)u_0 + \int_0^t E(t-s)f(s)ds$$

where $E(t)$ solution of the homogeneous problem

$(f=0)$

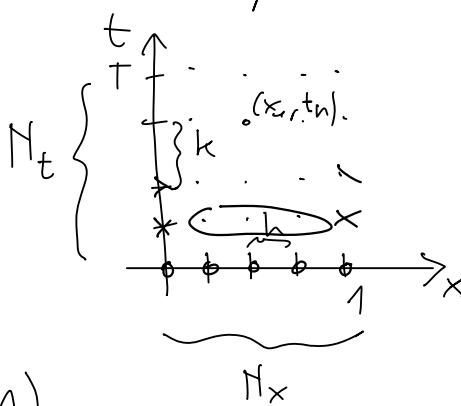
Duhamel principle

Proof in LT.

FD Discretisation

$$\Omega = (0, 1)$$

$$\begin{cases} u_t - \alpha u_{xx} = 0 & (0,1) \times (0,T] \\ u(x,0) = u_0(x) \\ u(x,t) = 0 & x=0; x=1 \end{cases}$$



$$h = 1/N_x \quad ; \quad k = T/N_t$$

$$(x_i, t_n) = (h i, k n)$$

space-time grid

$$\begin{aligned} i &= 0, \dots, N_x \\ n &= 0, \dots, N_t \end{aligned}$$

$$u(x_i, t_n) = \bigcup^n$$

Explicit Euler method

$$u_t(x, t) \approx \sum_{k=1}^t u(x, t) = \frac{u(x, t+k) - u(x, t)}{k}$$

$$u_{xx}(x, t) \approx \left(\sum_h \right)^2 u(x, t) \quad \alpha_i^n := \alpha(x_i, t_n)$$

$$\begin{aligned} \text{time} & \left(\frac{U_i^{n+1} - U_i^n}{k} - \alpha_i^n \right) \quad \frac{U_{i+1}^n - 2U_i^n + U_{i-1}^n}{h^2} = 0 \\ \text{stopping} & \quad n = 1, \dots, N_t - 1 \end{aligned}$$

$$\text{if } U_0^{n+1} = 0 = U_{N_x}^{n+1}$$

$$\text{given } U_i^0 = u_0(x_i)$$

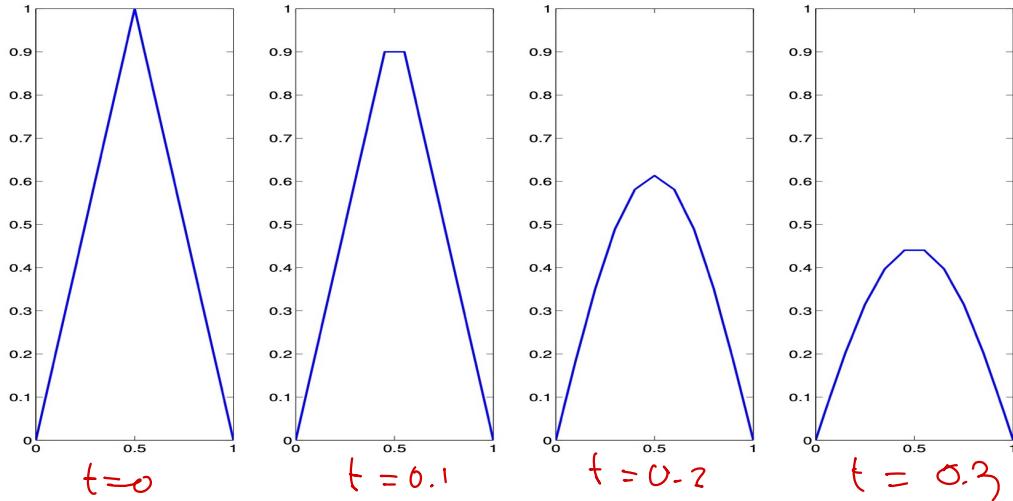
$$\begin{cases}
 U_i^{n+1} = -\alpha_i^n \left(\frac{k}{h^2} U_{i+1}^n + \left(2\alpha_i^n \frac{k}{h^2} + 1 \right) U_i^n - \alpha_i^n \frac{k}{h^2} U_{i-1}^n \right) \\
 U_0^{n+1} = 0 = U_{\text{fix}}^{n+1}
 \end{cases}
 \quad (i, n+1) \quad \text{courant number}$$

explicit, stencil



$$\alpha = 1 \quad h = 0.05, k = 0.00125 \text{ giving } \mu = 0.5$$

μ_0



$$h = 0.05, k = 0.0013 \text{ giving } \mu = 0.52$$

instability

