

NMPDE/ATSC 2025

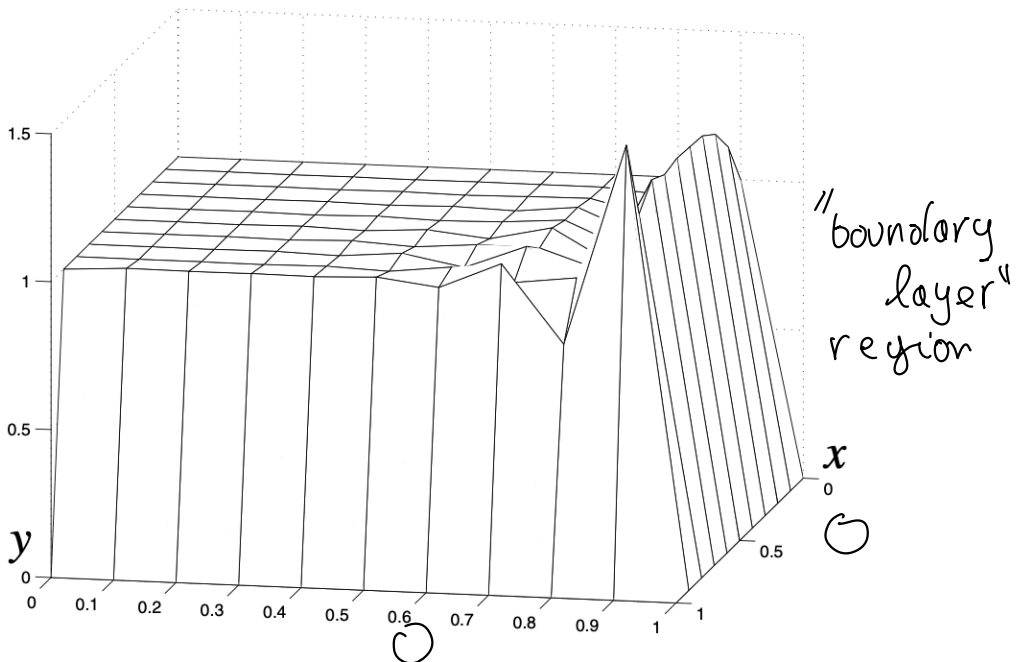
Lecture 14

$$\begin{cases} -\alpha \Delta u + \underline{b} \cdot \nabla u = f & \Omega \\ u = g & \partial \Omega \end{cases}$$

$$f \equiv 0 \quad g(x, y) = \begin{cases} 1 & \text{at } x=0 \text{ or } y=0 \\ 0 & \text{at } x=1 \text{ or } y=1 \end{cases}$$

$$\underline{b} = (1, 1) \quad \alpha = \varepsilon = 10^{-3}$$

Solution by the SD-FEM $k=1$

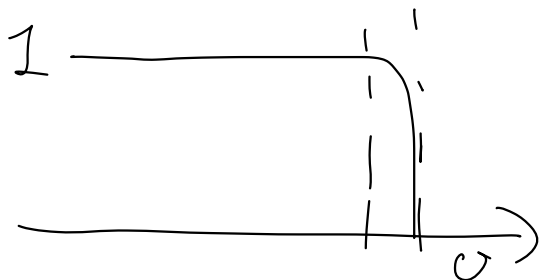


{

$$x = 1/2$$

σ

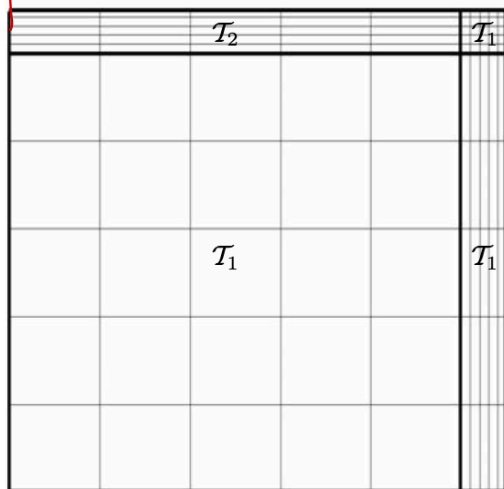
$$y = 1/2$$



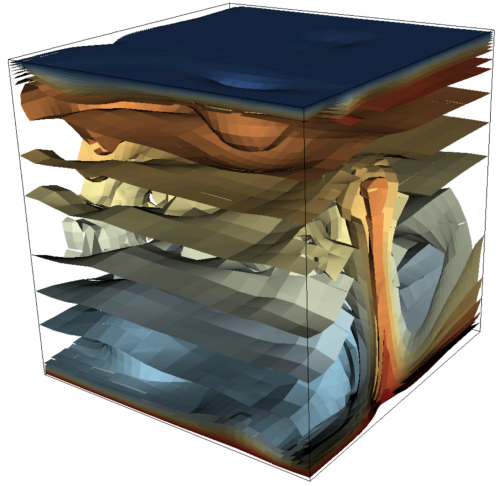
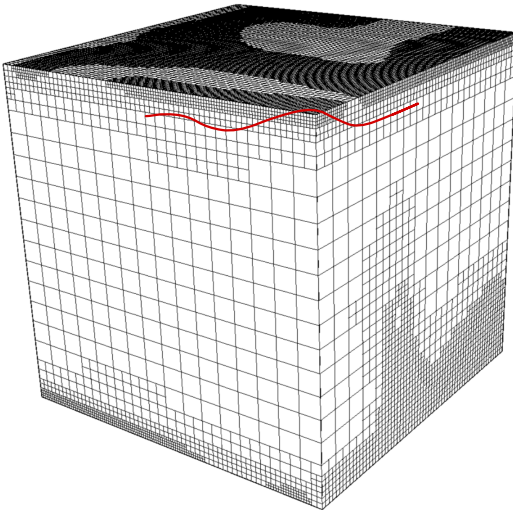
$\langle \cdot \rangle$

$$O(\bar{b}/q) \quad \bar{b} = \|b\|_{\infty}$$

$y \uparrow$ Shishkin mesh



ϵ
 $O(\epsilon)$



Mesh adaptivity and a posteriori error estimators

$$\|u - u_h\| \leq C h^k |u|_{k+1}$$

\uparrow exact \uparrow computed

a priori error bound

$$\|u - u_h\| \leq C \eta(u_h)$$

\uparrow estimator

a posteriori error bound

$$\eta^2 = \sum_{T \in \mathcal{T}_h} \eta_T^2$$

η_T = local error estimator

used to drive

automatic adaptivity:

- ① SOLVE (Compute u_h on given mesh)
- ② ESTIMATE (η_T)
- ③ MARK subset of elements T with larger η_T
- ④ REFINER the mesh based on ③

example (motivation):

Suppose want to solve the linear system

$$AU = F$$

and suppose U_0 is given approx. of U .

Can I estimate error $U - U_0$?

$$A(U - U_0) = AU - AU_0 = \underbrace{F - AU_0}_{\text{residual}}$$

$$U - U_0 = \underbrace{A^{-1}(F - AU_0)}_{\text{error representation}}$$

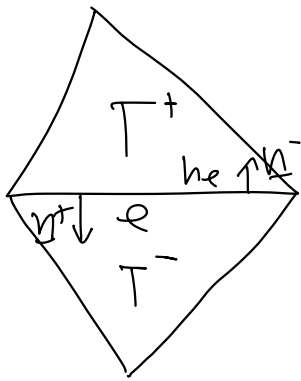
$$\|U - U_0\| \leq \underbrace{\|A^{-1}\|}_{\text{estimating this norm}} \|F - AU_0\|$$

would provide a residual based error estimator

example: on residual based a posteriori error estimator for

$$\begin{cases} -\nabla \cdot (a \nabla u) = f & \text{in } \Omega \\ + \text{b.c.} \end{cases}$$

$$|u - u_h|_1 \leq C \left(\sum_{T \in \mathcal{T}_h} \underbrace{\left(h_T^2 \|f + \nabla \cdot a \nabla u_h\|_{0,T}^2 \right)}_{\substack{\text{elemental residual} \\ 3_T^2}} \right)^{1/2}$$



$$+ \sum_{e \in \partial T} h_e \left\| \alpha \left[\nabla u_h \cdot \bar{n} \right] \right\|_{0,e}^2$$

\uparrow edges of T

outward normal

$$\left[\nabla u_h \cdot \bar{n} \right]_e = \left(\nabla u_h \cdot \bar{n} \right) \Big|_{T^+} + \left(\nabla u_h \cdot \bar{n} \right) \Big|_{T^-}$$

$$h_e = |e|$$

Jump residual

Parabolic problem

(LT, online notes,
Q, MM)

$$(\mathcal{L} u = f)$$

Model problem:

• \mathcal{L} a linear elliptic operator in \mathbb{R}^d .

• $t \in (0, T]$

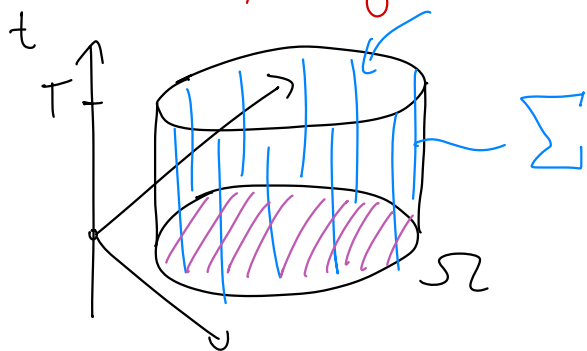
• PDE: $u_t + \mathcal{L} u = f$

example: $\mathcal{L} u = -\Delta u \rightarrow u_t - \Delta u = f$

heat equation

Couady-Dirichlet (CD) problem: $\frac{I}{II}$

$$\begin{cases} u_t + \mathcal{L}u = f & \text{over } \Omega \times (0, T] \\ u(x, 0) = u_0(x) & \text{on } \Omega \quad \text{initial cond.} \\ u(t, x) = g(t, x) & \text{on } \underbrace{\partial\Omega \times I}_{\Sigma} \quad \text{boundary condition} \end{cases}$$



Analysis of the heat equation

$$\textcircled{*} \begin{cases} u_t - \Delta u = f & \Omega \times I \\ u(x, 0) = u_0 & \text{in } \Omega \\ u(x, t) = 0 & \text{on } \Sigma \end{cases}$$

(LT)

Maximum principle: If u smooth function

s.t. $u_t - \Delta u \leq 0$ in $\Omega \times I$ then u attains maximum on $\Omega \times \{0\} \cup \Sigma$.

Corollary: if u solves $(*)$, then
(stability)

$$\|u\|_{C(\bar{\Omega} \times \bar{I})} \leq \|u_0\|_{C(\bar{\Omega})} + \frac{r^2}{2d} \|f\|_{C(\bar{\Omega} \times \bar{I})}$$

$d = \dim$ of Ω

$r = \text{radius of a ball containing } \bar{\Omega} \times \bar{I}$

Existence by providing solution:

$$u(\cdot, t) = u(t) = E(t)u_0 + \int_0^t \underline{E(t-s)} f(s) ds$$

where $E(t)$ solution of the homogeneous problem
($f=0$)

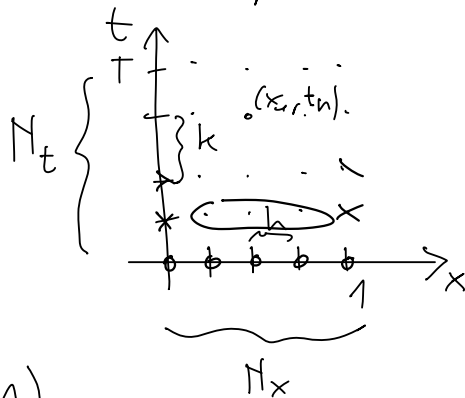
Duhamel principle

proof in LT₀

FD Discretisation

$$\Omega = (0, 1)$$

$$\begin{cases} u_t - \alpha u_{xx} = 0 & (0,1) \times (0,T] \\ u(x,0) = u_0(x) \\ u(x,t) = 0 & x=0; x=1 \end{cases}$$



$$h = 1/N_x \quad ; \quad k = T/N_t$$

$$(x_i, t_n) = (hi, kn)$$

space-time grid

$$\begin{aligned} i &= 0, \dots, N_x \\ n &= 0, \dots, N_t \end{aligned}$$

$$u(x_i, t_n) = U_i^n$$

Explicit Euler method

$$u_t(x,t) \approx \int_{k,t}^t u(x,t) = \frac{u(x,t+k) - u(x,t)}{k}$$

$$u_{xx}(x,t) \approx \left(\int_h^x \right)^2 u(x,t) \quad \alpha_i^n := \alpha(x_i, t_n)$$

$$\text{time stepping} \left\{ \frac{U_i^{n+1} - U_i^n}{k} - \alpha_i^n \frac{U_{i+1}^n - 2U_i^n + U_{i-1}^n}{h^2} = 0 \right.$$

$$n=1, \dots, N_t-1$$

$$U_0^{n+1} = 0 = U_{N_x}^{n+1}$$

$$\text{given } U_i^0 = u_0(x_i)$$

$$\left\{ \begin{aligned} U_1^{n+1} &= -a_1^n \left(\frac{k}{h^2} U_{1+1}^n + \left(2a_1^n \frac{k}{h^2} + 1 \right) U_1^n - a_1^n \frac{k}{h^2} U_{1-1}^n \right) \\ U_0^{n+1} &= 0 = U_{Mx}^{n+1} \end{aligned} \right.$$

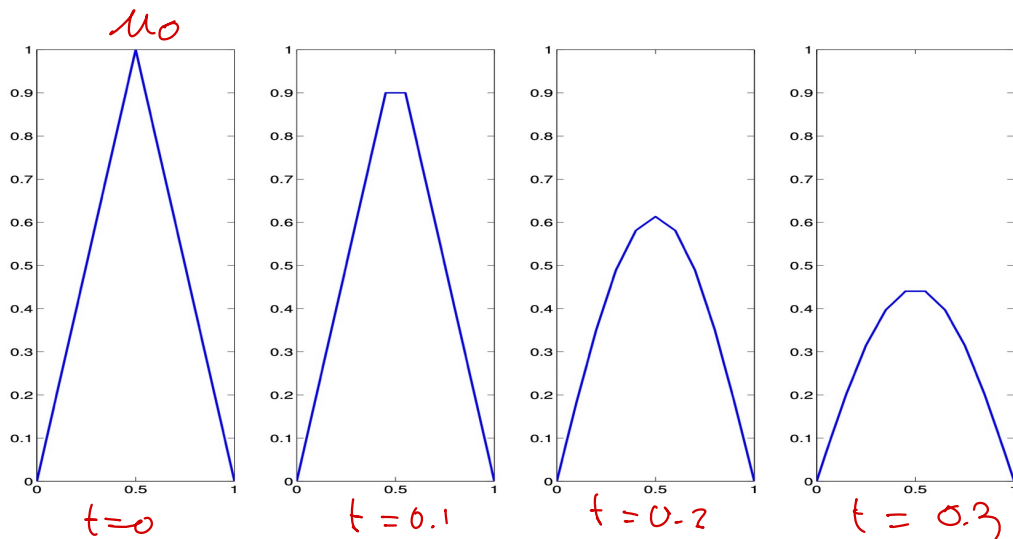
$n+1$ μ courant number

explicit, stencil



$$a=1$$

$$h=0.05, k=0.00125 \text{ giving } \mu=0.5$$



$$h=0.05, k=0.0013 \text{ giving } \mu=0.52$$

instability

