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Chapter 1

Prerequisites

1.1 Topological Spaces

Definition 1.1.1. Let X be a set and $\mathcal{T} = \{U_i | i \in I, U_i \in X\}$. (X, \mathcal{T}) is a **topological space** if

1. $\phi, X \in \mathcal{T}$
2. $\forall J \subset I, \bigcup_{j \in J} U_j \in \mathcal{T}$
3. $\forall K \subset I, K \text{ finite}, \bigcap_{k \in K} U_k \in \mathcal{T}$

(X is the topological space, \mathcal{T} its topology, U_i the open sets)

Example 1.1.2.

- (a) X is a set and \mathcal{T} the collection of all subset of X
This is called the *Discrete Topology*.
- (b) X is a set and $\mathcal{T} = \{\phi, X\}$. This is called the *Trivial Topology*.
- (c) $X = \mathbb{R}$, \mathcal{T} all open intervals and their unions (the usual topology).
Notice that $\bigcap_{\substack{a < -1 \\ b > +1}} (a, b) = [-1, +1]$ so we have an example of infinite intersection of open sets that does not give an open.
- (d) X is set, $d : X \times X \rightarrow \mathbb{R}$ a metric, that is, $\forall x, y \in X$:
 - (a) $d(x, y) = d(y, x)$
 - (b) $d(x, y) \geq 0$ with $d(x, y) = 0 \Leftrightarrow x = y$
 - (c) $d(x, y) + d(y, x) \geq d(x, z)$ \mathcal{T} open discs $U_\varepsilon(x) = \{y \in X | d(x, y) < \varepsilon\}$ and unions. This is called the *Metric Topology*.
- (e) $(X, \mathcal{T}), (Y, \mathcal{T}')$ topological spaces
 $X \times Y, \mathcal{T}'' = \{\text{unions of } U \times V | U \in \mathcal{T}, V \in \mathcal{T}'\}$
This is called the *Product Topology*

1.1.1 Continuous maps

Definition 1.1.3. X, Y topological spaces. $f : X \rightarrow Y$ is **continuous** if $\forall V \subset Y, \underset{\text{open}}{f^{-1}(V)} \subset X$.

Remark 1.1.4. Previous definition doesn't work with direct images U and $f(U)$. For example take $f(x) = x^2$, then $U = (-1, +1)$ is open but $f(U) = [0, 1)$ doesn't. Nevertheless f is a continuous function.

1.1.2 Neighbourhoods and Hausdorff spaces

Definition 1.1.5. (X, \mathcal{T}) topological space. $N \subset X$ is a **neighbourhood** of $x \in X$ if $\exists U \in \mathcal{T}$ such that $x \in U \subset N$

Example 1.1.6. $X = \mathbb{R}$ with the usual topology. $[-1, +1]$ is a neighbourhood of $0 \in \mathbb{R}$.

Definition 1.1.7. (X, \mathcal{T}) topological space is **Hausdorff** if $\forall x, y \in X$ such that $x \neq y \exists N_1$ neighbourhood of $x, \exists N_2$ neighbourhood of y , such that $N_1 \cap N_2 = \emptyset$.

Exercise 1.1.8. $X = \{\text{John, Paul, Ringo, George}\}$, $U_0 = \emptyset$, $U_1 = \{\text{John}\}$, $U_2 = \{\text{John, Paul}\}$, $U_3 = \{\text{John, Paul, Ringo, George}\}$. Show $\mathcal{T} = \{U_0, U_1, U_2, U_3\}$ is a topology and that (X, \mathcal{T}) is not Hausdorff

Exercise 1.1.9. Show \mathbb{R}^n is Hausdorff. Show any metric space is Hausdorff.

We will always assume all our topological spaces to be Hausdorff.

1.1.3 Closed sets

Definition 1.1.10. (X, \mathcal{T}) topological space. $A \in X$ is **closed** iff $X \setminus A$ is open.

Example 1.1.11. \emptyset, X are both open and closed

Definition 1.1.12. The **closure** \overline{A} of any subset $A \in X$ is the smallest closed set containing A .

The **interior** A^0 of any subset $A \in X$ is the largest open subset of A .

The **boundary** $b(A)$ or ∂A of any subset $A \in X$ is $\overline{A} \setminus A^0 =: b(A)$

1.1.4 Compactness

Definition 1.1.13. (X, \mathcal{T}) topological space. A family $\{A_i\}_{i \in I}$ is called a **covering** of X if $\bigcup_{i \in I} A_i = X$. If all of the $A_i \forall i \in I$ are open, $\{A_i\}_{i \in I}$ is an **open covering**

Definition 1.1.14. (X, \mathcal{T}) topological space. X is **compact** if \forall open covering $\{A_i\}_{i \in I} \exists J \subset I$ finite such that $\{A_j\}_{j \in J}$ is also an open covering

Theorem 1.1.15. $X \subset \mathbb{R}^n$ is compact if and only if X is closed and bounded.

Exercise 1.1.16. (a) A point is compact.

(b) Let $(a, b) \subset \mathbb{R}$ and the open covering $U_n = (a, b - \frac{1}{n})$, $n \in \mathbb{N}$. Indeed $\bigcup_{n \in \mathbb{N}} U_n = (a, b)$. If no finite subfamilies of $\{U_n\}_{n \in \mathbb{N}}$ is a covering then (a, b) is not compact.

(c) $S^n = \{x_1^2 + \dots + x_n^2 = 1 | (x_1, \dots, x_n) \in \mathbb{R}^n\}$ is compact since it is closed and bounded.

1.1.5 Connectedness

Definition 1.1.17. (a) X topological space is **connected** if it cannot be written as $X = X_1 \cup X_2$ where X_1, X_2 are open and $X_1 \cap X_2 = \emptyset$. Otherwise X is called **disconnected**.

(b) X is **arcwise connected** if, $\forall x, y \in X$, $\exists f : [0, 1] \rightarrow X$ continuous with $f(0) = x$, $f(1) = y$.

(c) A **loop** in a topological space is a continuous map $f : [0, 1] \rightarrow X$ with $f(0) = f(1)$. X is **simply connected** if, for any loop $f : [0, 1] \rightarrow X$, there exists a continuous map $g : [0, 1] \times [0, 1] \rightarrow X$ such that

$$\begin{aligned} g(0, t) &= g(1, t) & (\text{i.e. } g(\cdot, t) &=: f_t(\cdot) \text{ is a family of loops}) \\ g(s, 0) &= f(s) \\ g(s, 1) &= \bar{x} \in X & (f_t \text{ strikes } f_0 = f \text{ to a point } f_1 = \bar{x}) \end{aligned}$$

Example 1.1.18. (a) \mathbb{R} is arcwise connected while $\mathbb{R} \setminus \{0\}$ is not. \mathbb{R}^n and $\mathbb{R}^n \setminus \{0\}$, $n \geq 2$, are both arcwise connected.

(b) S^n is arcwise connected $\forall n \geq 1$ but simply connected only for $n \geq 2$.

(c) $T^n := \underbrace{S^1 \times \dots \times S^1}_{n\text{-times}}$ is arcwise but not simply connected

(d) $\mathbb{R}^2 \setminus \mathbb{R}$ is not arcwise connected. $\mathbb{R}^2 \setminus \{0\}$ is arcwise but not simply connected. $\mathbb{R}^3 \setminus \{0\}$ is both arcwise and simply connected.

1.1.6 Homeomorphisms