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## Chapter 1

## **Preliminaries**

## 1.1 Quick review of Special Relativity

Here we expose a quick review of Special Relativity in order to set the notations.

Fundamental principles of Special Relativity are followings:

- (i) All inertial reference frames are physically equivalent. There is no way to distinguish between different inertial frames in the sense that there is no preferred one.
- (ii) There exists universal (dimensional) constant:  $c \simeq 3 \times 10^8 \text{m/s}$ , i.e. the speed of massless particles.

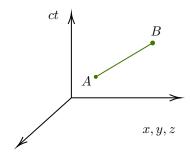
In order to implement these features basic ingredients are

- (i) Space and Time form a unique concept called **spacetime**.
- (ii) A spacetime is a collection of points called **event**.
- (iii) Each inertial frame is associated with a set of *space time coordinates*. Each events is specified through coordinate system of a fixed initial frame.

$$x^{\mu} = (x^0, x^1, x^2, x^3) \equiv (x^0, x^i) \equiv (ct, x, y, z) \equiv (ct, \mathbf{x})$$

Usually x, y, z are assumed to be Cartesian coordinates.

Given 2 events A and B in spacetime



their distance is  $\Delta x^{\mu} = x_B^{\mu} - x_A^{\mu}$ . We introduce the (squared) Minkowski distance

$$\Delta s^2 = \eta_{\mu\nu} \Delta x^{\mu} \Delta^{\nu} \quad \text{where} \quad \eta_{\mu\nu} = \begin{pmatrix} -1 & & \\ & 1 & \\ & & 1 \\ & & & 1 \end{pmatrix}$$

where  $\eta_{\mu\nu}$  is Minkowski metric. This induces the line element

$$\mathrm{d}s^2 = \eta_{\mu\nu} \mathrm{d}x^\mu \mathrm{d}x^\nu$$

This element is scalar quantity and therefore does not depends on the specific inertial frame.

The quantity  $\Delta s^2$  has an intrinsic meaning

 $\begin{cases} \Delta s^2 > 0 & : \quad \Delta x^{\mu} \text{ is } space\text{-like } \text{vector} \\ \Delta s^2 = 0 & : \quad \Delta x^{\mu} \text{ is } time\text{-like } \text{vector} \\ \Delta s^2 < 0 & : \quad \Delta x^{\mu} \text{ is } light\text{-like/null } \text{vector} \end{cases}$ 

Space-like vector means that exists different frames were two events are simultaneous. Time-like vector means that exists different frames where two events have same space coordinates but they happen at different times. Light-like vectors means that two events may be connected by a light signal.

(iv) Allowed transformations for spacetime vectors must preserve the line element:  $\Delta \tilde{s}^2 = \Delta s^2$ . These transformations are the *Poincaré Transformations* 

$$x^{\mu} \rightarrow \tilde{x}^{\mu} = \Lambda^{\mu}{}_{\nu}x^{\nu} + a^{\mu}$$
 with  $\Lambda^{\rho}{}_{\mu}\Lambda^{\sigma}{}_{\nu}\eta_{\rho\sigma} = \eta_{\mu\nu}$ 

Once we have reformulated notions of space and time, we have to reformulate law of physics in such a way they does not depends on the reference frame.

Trajectories of point like-particles are associated to curved *wordlines* in space time and described evolution of events. Mathematically they are described by maps from  $\mathbb{R}$  into a set of four functions:  $\lambda \in \mathbb{R} \to x^{\mu}(\lambda)$ . Near if we consider nearby events separated by infinitesimal shift we can obtain infinitesimal variation of coordinates:

$$dx^{\mu}(\lambda) \equiv x^{\mu}(\lambda + d\lambda) - x^{\mu}(\lambda) = \frac{dx^{\mu}(\lambda)}{d\lambda}d\lambda$$

Since no particles can move at a speed higher then light this implies that  $ds^2$  must be time-like. Notice that choice of parameter  $\lambda$  is free. One possible choice of this parameter is the (differential) proper time:

$$d\tau \equiv \sqrt{-ds^2} = d\lambda \sqrt{-\eta_{\mu\nu}\dot{x}^{\mu}(\lambda)\dot{x}^{\nu}(\lambda)} = c dt \sqrt{1 - \frac{v^2}{c^2}} \equiv \frac{c dt}{\gamma}$$

where third step holds if  $\lambda \equiv t$ . If we define  $\beta \equiv v/c^{-1}$ , then  $\gamma = 1/\sqrt{1-\beta^2}$  is called *Lorentz factor*. Notice that last step implies time dilatation at higher velocities. For  $\lambda = t$  we obtain

$$\tau = c \int \mathrm{d}t \sqrt{1 - \frac{v^2}{c^2}}$$

i.e. with this definition the proper time has dimension of a length  $[\tau] = L$ . Physically the proper times it's the time measured by a clock moving along the trajectory.

Proper time allow us to define a vector called 4-velocity that can be identified as relativistig generalization of velocity. Namely:

$$u^{\mu}(\tau) = \frac{\mathrm{d}x^{\mu}(\tau)}{\mathrm{d}\tau} = \left(\gamma, \gamma \frac{\mathbf{v}}{c}\right)$$

Notice

$$u^{\mu}u_{\mu}=-1$$

i.e. is a time-like vector. Moreover, this vector has only three degrees of freedom, since one component is fixed by previous propriety.

This is the speed in natural units, i.e. in units of  $\beta$ . If we set c=1 then  $v=\beta$ .

Now we can define the generalization of acceleration, 4-acceleration, as follows

$$\alpha^{\mu}(\tau) = \frac{\mathrm{d}u^{\mu}(\tau)}{\mathrm{d}\tau}$$

Notice that, as we expected, 4-acceleration is orthogonal to 4-velocity

$$u_{\mu}\alpha^{\mu}=0$$

and this implies that  $\alpha^{\mu}$  is a space-like since it is orthogonal to a time-like vector.

This proves a relativistic generalization of distance, speed and acceleration. Also laws of dynamic can be generalizated, in particular if we define the *four-force*  $f^{\mu}$  as the generalization of force we can obtain the *Relativistic Second Newton's law*:

$$mc\alpha^{\mu} \equiv \frac{\mathrm{d}p^{\mu}}{\mathrm{d}\tau} = f^{\mu}$$

where we used four acceleration or equivalently the generalization of newtonian momentum, 4-momentum,

$$p^{\mu} \equiv mcu^{\mu} = \left(\frac{E}{c}, \mathbf{p}\right)$$

For example, for Lorentz force

$$\mathbf{F}_L = e \left( \mathbf{E} + \frac{1}{c} \mathbf{v} \times \mathbf{B} \right)$$

can be generalizzated in a manifestly covariant way into<sup>II</sup>

$$f_L^{\mu} = \frac{e}{c} F^{\mu\nu} u_{\nu} \qquad \text{with} \quad F^{\mu\nu} = \begin{pmatrix} 0 & E_1 & E_2 & E_3 \\ -E_1 & 0 & B_3 & -B_2 \\ -E_2 & -B_3 & 0 & B_1 \\ -E_3 & B_2 & -B_1 & 0 \end{pmatrix}$$

where  $F^{\mu\nu}$  is the *EM-Tensor*.

We can also rewrite Maxwell equations into two covariant equation

$$\partial_{\mu}F^{\mu\nu} = -\frac{4\pi}{c}j^{\nu}$$
 ,  $\partial_{[\mu}F_{\nu\rho]} = 0$ 

where the former, inhomogeneous, shows the 4-current  $j^{\mu} = (c\rho, \mathbf{j})$ . The second equation, homogeneous, exhibits total antisymmetrized indexes<sup>III</sup>. Each of these equations contains 2 independent equations.

We can conclude saying that all possible interactions can be written in a covariant way, except from gravitation. In order to include this force General Relativity has been developed.

<sup>&</sup>lt;sup>II</sup>Here is evident that this formula does not change under Poincaré transformations.

 $<sup>^{\</sup>rm III}\partial_{[\mu}F_{\nu\rho]}=\partial_{\mu}F_{\nu\rho}+\partial_{\rho}F_{\mu\nu}+\partial_{\nu}F_{\rho\mu}.$