### Problem setup

We are given a set of N+M house locations. This set S of locations is divided into N nobles houses and M common houses. Each house location is represented by a data point lying on the  $\mathbb{R}^2$  plane. The objective of the problem is to find the coefficients of L1 and L2, two non-horizontal and orthogonal lines lying in the  $\mathbb{R}^2$  plane satisfying and maximizing the following conditions:

- Constraint 1 L1 must separate the two classes of houses, having the nobles houses on its left and the commons ones on its right.
- Constraint 2: The sum of every horizontal distance x between any house and its intercepting point at same y height on L1 must be less than a given threshold s.
- Constraint 3: L2 position has to minimize the greatest distance y between any house and its intercepting point at same x coordinate on L2.

## **Problem Modeling**

We are seeking the line coefficients of L1 and L2. Because we know that they are orthogonal, we can reduce the problem to that of finding the following correlated coefficients. We can even check that  $m_1m_2 = -\frac{b}{a}\frac{a}{b} = -1$  which is indeed the orthogonality criterion.

$$L1: ax + by + c_S$$

$$L2: -bx + ay + c_W$$

#### Constraint 1

The first constraint is a linear separation problem given L1. This can be easily optimized with CGAL Linear Program solver. To be more explicit, we are optimizing  $ax + by + c_S$  in such a way that the N noble houses are on the left of the line and the M common houses are on the right of it. This is translate to the following set of constraints:

$$\forall (x_n, y_n) : ax_n + by_n < c_S$$

$$\forall (x_c, y_c) : ax_c + by_c \ge c_S \Leftrightarrow -ax_c - by_c \le -c_S$$

#### Constraint 2

More formally, we require  $\sum_{i \in h} |x_i - x_{L_1}| \le s$  where h denote the set of all houses combined. The situation looks a bit tricky but we now that if the first constraint succeeded, all the noble houses are on L1's left and common ones on its right. We can therefore define  $|x_h - x_{L_1}|$  distance according to its class. We can further simplify the calculation knowing that  $y_h = y_{L_1}$  namely with  $x_{L_1} = \frac{by_{L_1} - c_S}{a} = \frac{by_h - c_S}{a}$ 

$$d_n = x_{L_1} - x_n = \frac{by_h - c_S - ax_n}{a}$$
$$d_c = x_c - x_{L_1} = \frac{ax_c - by_h + c_S}{a}$$

Now the problem is to formulate a CGAL constraint that enforces  $\sum_{i \in h} d_i \leq s$ . For that purpose, we can unfold the inequation and see that what comes out is a valid CGAL constraint because we know every coefficient:

$$\sum_{i \in h} d_i$$

$$= \sum_{i \in h_n} d_n + \sum_{i \in h_c} d_c$$

$$= \sum_{i \in h_n} \frac{by_n - c_S - ax_n}{a} + \sum_{i \in h_c} \frac{ax_c - by_c + c_S}{a}$$

$$= \sum_{i \in h_c} x_c - \sum_{i \in h_n} x_n + \sum_{i \in h_n} \frac{b}{a} y_n - \sum_{i \in h_c} \frac{b}{a} y_c + \frac{1}{a} c_S(M - N) \leq s$$

$$\Leftrightarrow$$

$$= a \left( \sum_{i \in h_c} x_c - \sum_{i \in h_n} x_n \right) + b \left( \sum_{i \in h_n} y_n - \sum_{i \in h_c} y_c \right) + c_S(M - N) \leq as$$

$$\Leftrightarrow$$

$$= a \left( \sum_{i \in h_c} x_c - \sum_{i \in h_n} x_n - s \right) + b \left( \sum_{i \in h_n} y_n - \sum_{i \in h_c} y_c \right) + c_S(M - N) \leq 0$$

#### Constraint 3

Below is the formal description of the problem we are facing with this last constraint optimization. Note that we are forced to introduce the absolute value as we have no clue of whether a data point is on the left or on the right of  $L_2$ .

$$\min\left(\max_{i\in h} |y_i - y_{L_2}|\right)$$

Because CGAL doesn't allow us to deal with a maximization problem, we have to figure out a little trick. Here it is: we introduce a new variable l which represents the maximal length we are searching for. The inner problem then simply reduces to  $\forall i \in h: |y_i - y_{L_2}| \leq l$ . We can again unfold  $|y_i - y_{L_2}|$  and see that it gives us 2(M + N) valid CGAL constraint to add to our LP solver:

$$|y_i - y_{L_2}| \le l \quad \Leftrightarrow \quad -l \le y_i - y_{L_2} \le l \quad \Leftrightarrow \quad -l \le y_i + \frac{c_W - bx_i}{a} \le l$$

If we unfold only one of the 2 side of the inequation for the sake of completeness, we find a last and extra subtelty. Here is what happens:

$$y_i + \frac{c_W - bx_i}{a} \le l \quad \Leftrightarrow \quad ay_i - bx_i + c_W \le al$$

But notice that this is not anymore a linear problem. Indeed, because we have introduced l as a new variable the product al bring our equation to a quadratic form. To get around this concern, we can set a=1. Notice that this simplify the equation of constraint 2. But it also enforce L1 and L2 not to be horizontal, which was required initially in the problem setup.

# Algorithm Design

We can finally write our routine and wrap up what we discussed above. We therefore have 5 variables  $(a, b, c_S, c_W, l)$  to give to the CGAL LP optimizer under the following constraints:

$$\forall (x_n, y_n) : ax_n + by_n \le c_S \tag{1}$$

$$\forall (x_n, y_n) : -ax_c - by_c \le -c_S \tag{2}$$

$$b\left(\sum_{i\in h_n} y_n - \sum_{i\in h_c} y_c\right) + c_S(M - N) \le s - \left(\sum_{i\in h_c} x_c - \sum_{i\in h_n} x_n\right)$$
(3)

$$\forall (x_n, y_n) : -bx_n + c_W - l \le -y_n \tag{4}$$

$$\forall (x_n, y_n) : bx_n - c_W - l \le y_n \tag{5}$$

### Code submission: 100%

```
#include <CGAL/QP_models.h>
#include <CGAL/QP_functions.h>
#include <CGAL/Gmpz.h>
#include <vector>
using namespace std;
typedef CGAL::Gmpz ET;
typedef CGAL::Quadratic_program<long> Program;
typedef CGAL::Quadratic_program_solution<ET> Solution;
void solve() {
  int n, m; long s;
  cin >> n >> m >> s;
  vector<pair<int, int>> nobles(n);
  vector<pair<int, int>> commons(m);
  long sum_nx = 0, sum_ny = 0;
  long sum_cx = 0, sum_cy = 0;
  for (int i = 0; i < n; i++) {
    int x, y; cin >> x >> y;
    sum_nx += x; sum_ny += y;
    nobles[i] = make_pair(x, y);
  }
  for (int i = 0; i < m; i++) {
    int x, y; cin >> x >> y;
    sum_cx += x; sum_cy += y;
    commons[i] = make_pair(x, y);
  }
  Program lp(CGAL::SMALLER, false, 0, false, 0);
  int a = 0, b = 1, cs = 2, cw = 3, l = 4, row = 0;
  // Enforce a == 1
  lp.set_l(a, true, 1);
  lp.set_u(a, true, 1);
  // Cersei constraint:
  for (int i = 0; i < n; i++) {
```

```
lp.set_a(a, row, nobles[i].first);
  lp.set_a(b, row, nobles[i].second);
  lp.set_a(cs, row++, 1);
}
for (int i = 0; i < m; i++) {
  lp.set_a(a, row, -commons[i].first);
  lp.set_a(b, row, -commons[i].second);
  lp.set_a(cs, row++, -1);
}
Solution s1 = CGAL::solve_linear_program(lp, ET());
if (s1.is_infeasible()) {
  cout << "Yuck!" << endl;</pre>
 return;
}
// Tywin constraint:
if (s != -1) {
  lp.set_a(cs, row, m - n);
  lp.set_a(b, row, sum_cy - sum_ny);
  lp.set_b(row++, s - (sum_cx - sum_nx));
  Solution s2 = CGAL::solve_linear_program(lp, ET());
  if (s2.is_infeasible()) {
    cout << "Bankrupt!" << endl;</pre>
    return;
  }
}
// Jaime optimization:
int hx, hy = 0;
for (int i = 0; i < n + m; i++) {
  if (i < n) { hx = nobles[i].first; hy = nobles[i].second; }</pre>
  else { hx = commons[i-n].first; hy = commons[i-n].second; }
  lp.set_a(b, row, hx);
  lp.set_a(cw, row, 1);
  lp.set_a(l, row, -1);
```

```
lp.set_b(row++, hy);
    lp.set_a(b, row, -hx);
    lp.set_a(cw, row, -1);
    lp.set_a(l, row, -1);
    lp.set_b(row++, -hy);
  }
  // Enforce positive length
  lp.set_l(1, true, 0);
  // Minimize length
  lp.set_c(1, 1);
  Solution s3 = CGAL::solve_linear_program(lp, ET());
  cout << fixed << setprecision(0) << ceil(CGAL::to_double(s3.objective_value())) << endl;</pre>
}
int main() {
  ios_base::sync_with_stdio(false);
  int t; cin >> t;
  for (int i = 0; i < t; i++) solve();</pre>
}
```