

# Sistemas de Operação / Fundamentos de Sistemas Operativos

Processes in Unix/Linux

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# Outline

- 1 Program vs. Process
- 2 Process creation
- 3 The fork system call
- 4 A fork illustration program
- 5 Execution of a C/C++ program
- 6 Address space of a Unix program

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### **Process**

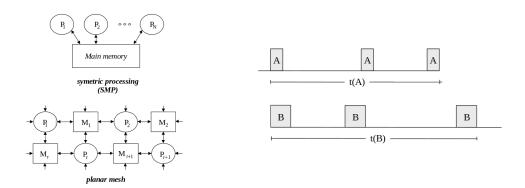
### Program vs. process

- Program set of instructions describing how a task is performed by a computer
  - In order for the task to be actually performed, the corresponding program has to be executed
- Process an entity that represents a computer program being executed
  - it represents an activity of some kind
  - it is characterized by:
    - addressing space code and data (actual values of the diferent variables) of the associated program
    - input and output data (data that are being transferred from input devices and to output devices)
    - process specific variables (PID, PPID, ...)
    - actual values of the processor internal registers
    - state of execution
- Different processes can be running the same program
- In general, there are more processes than processors multiprogramming

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# Multiprocessing vs. Multiprogramming Multiprocessing

- Parallelism ability of a computational system to simultaneously run two or more programs
  - more than one processor is required (one for each simultaneous execution)
- The operating systems of such computational systems supports multiprocessing

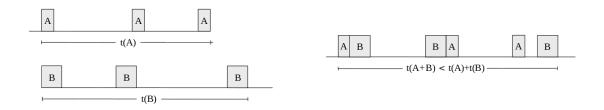


 Programs A and B are executing parallelly in at least two-processors computational system

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# Multiprocessing vs. Multiprogramming Multiprogramming

- Concurrency illusion created by a computational system of apparently being able to simultaneously run more programs than the number of existing processors
  - The existing processor(s) must be assigned to the different programs in a time multiplexed way
- The operating systems of such computational systems supports multiprogramming

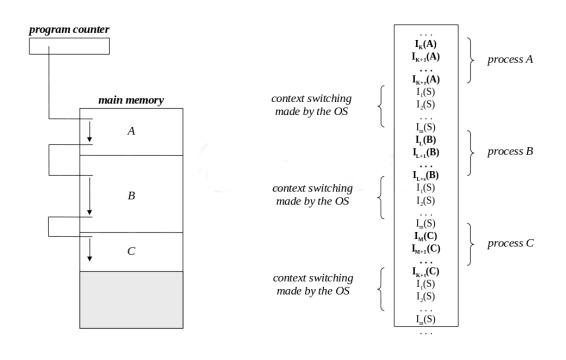


Programs A and B are executing concurrently in a single processor computational system

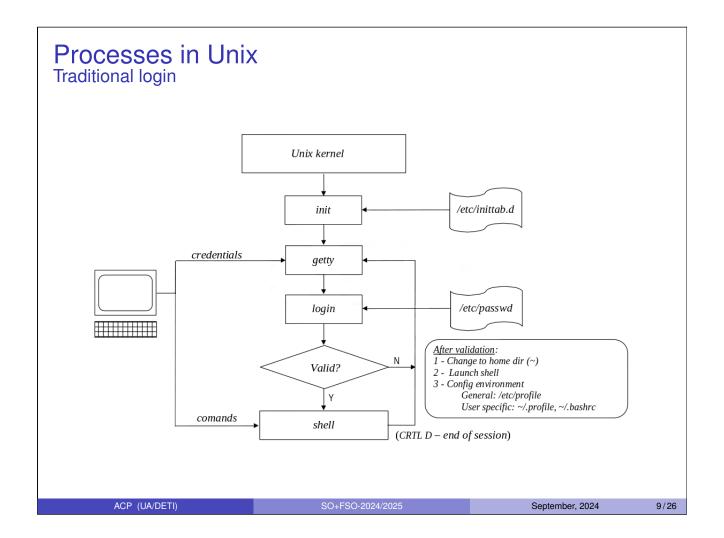
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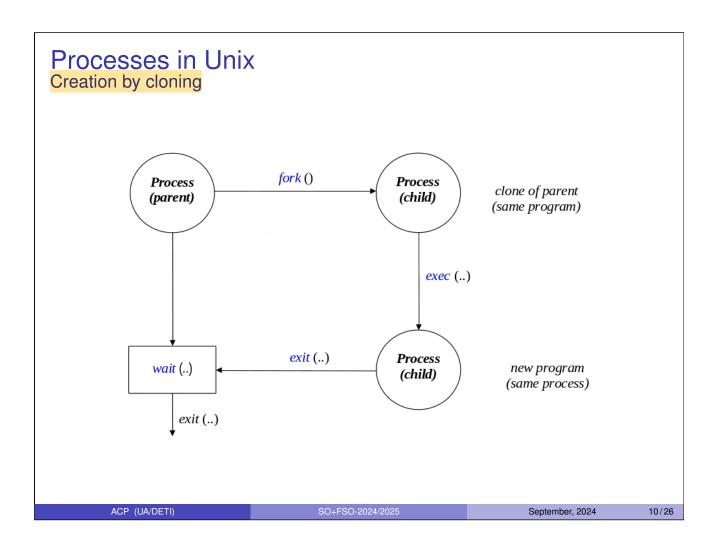
# **Process**

Execution in a multiprogrammed environment



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Process creation: fork0

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <unistd.h>

int main(void)
{
    printf("Hello, World!\n");
    fork();
    printf("Hello, World! Again\n");
    return EXIT_SUCCESS;
}
```

- The fork clones the executing process, creating a replica of it
- The address spaces of the two processes are equal
  - actually, just after the fork, they are the same
  - typically, a copy on write approach is followed
- The states of execution are the same
  - including the value of the program counter

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### Processes in Unix

Process creation: fork1

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <unistd.h>

int main(void)
{
   printf("Before the fork:\n");
   printf(" PID = %d, PPID = %d.\n",
        getpid(), getppid());

   fork();

   printf("After the fork:\n");
   printf("PID = %d, PPID = %d.\n"
        "Am I the parent or the child?"
        "How can I know it?\n",
            getpid(), getppid());

   return EXIT_SUCCESS;
}
```

- The fork clones the executing process, creating a replica of it
- The address spaces of the two processes are equal
  - actually, just after the fork, they are the same
  - typically, a copy on write approach is followed
- The states of execution are the same
  - including the value of the program counter
- Some process variables are different (PID, PPID, ...)
- What can we do with this?

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Process creation: fork2 and fork3

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <unistd.h>

int main(void)
{
   printf("Before the fork:\n");
   printf(" PID = %d, PPID = %d.\n",
        getpid(), getppid());

int ret = fork();

printf("After the fork:\n");
   printf("PID = %d, PPID = %d.\n",
        getpid(), getppid());
   printf(" ret = %d\n", ret);

return EXIT_SUCCESS;
}
```

- The value returned by the fork is different in parent and child processes
  - in the parent, it is the PID of the child
  - in the child, it is always 0

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### Processes in Unix

Process creation: fork2 and fork3

```
#include <stdio.h>
#include < stdlib . h>
#include <sys/types.h>
#include <unistd.h>
int main(void)
  printf("Before the fork:\n");
  printf(" PID = %d, PPID = %d.\n",
      getpid(), getppid());
  int ret = fork();
  if (ret == 0)
    printf("I'm the child:\n");
    printf(" PID = %d, PPID = %d n",
        getpid(), getppid());
  else
    printf("I'm the parent:\n");
    printf(" PID = %d, PPID = %d\n",
        getpid(), getppid());
```

return EXIT\_SUCCESS;

- The value returned by the fork is different in parent and child processes
  - in the parent, it is the PID of the child
  - in the child, it is always 0
- This return value can be used as a boolean variable
  - so we can distinguish the code running on child and parent
- Still, what can we do with it?

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Process creation: fork4

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <unistd.h>
int main(void)
  printf("Before the fork:\n");
  printf(" PID = \%d, PPID = \%d.\n",
      getpid(), getppid());
  int ret = fork();
  if (ret == 0)
    \texttt{execlp("Is", "Is", "-I", NULL);}\\
    return EXIT_FAILURE;
  else
  {
    getpid(), getppid());
  return EXIT_SUCCESS;
```

- In general, used alone, the fork is of little interest
- In general, we want to run a different program in the child
  - exec system call
  - there are different versions of exec
- Sometimes, we want the parent to wait for the conclusion of the program running in the child
  - wait system call
- In this code, we are assuming the fork doesn't fail
  - in case of an error, it returns −1

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### Processes in Unix

fork illustration program

• What are the possible outputs of the execution of this program?

```
int main(int argc, char *argv[])
    uint32_t t t = 1000;
    printf("1"); fflush(stdout);
    int pid = fork();
    switch (pid)
         case 0:
             bwDelay(t);
              printf("2"); fflush(stdout);
             bwDelay(t);
printf("3"); fflush(stdout);
             break;
         default:
             bwDelay(t);
printf("4"); fflush(stdout);
             bwDelay(t);
printf("5"); fflush(stdout);
              wait (NÙLL);
              printf("\n");
    return EXIT_SUCCESS;
```

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fork illustration program

#### parent process

```
int main(int argc, char *argv[])
    uint32_t t = 1000;
    printf("1"); fflush(stdout);
    int pid = fork();
    switch (pid)
         case 0:
              bwDelay(t);
              printf("2"); fflush(stdout);
              bwDelay(t);
printf("3"); fflush(stdout);
              break;
         default:
             bwDelay(t);
printf("4"); fflush(stdout);
              bwDelay(t);
printf("5"); fflush(stdout);
              wait (NULL);
printf ("\n");
    return EXIT_SUCCESS;
}
```

At the beginning, there is only the parent process

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# Processes in Unix

fork illustration program

#### parent process

So, the first printf only occurs in the parent

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fork illustration program

#### parent process

```
int main(int argc, char *argv[])
    uint32_t t = 1000;
     printf("1"); fflush(stdout);
    int pid = fork();
    switch (pid)
         case 0:
              bwDelay(t);
              printf("2"); fflush(stdout);
              bwDelay(t);
printf("3"); fflush(stdout);
              break;
         default:
             bwDelay(t);
printf("4"); fflush(stdout);
              bwDelay(t);
printf("5"); fflush(stdout);
              wait (NULL);
printf ("\n");
    return EXIT_SUCCESS;
}
```

When the fork starts, still only the parent process exists

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# Processes in Unix

fork illustration program

}

#### parent process

#### child process

```
int main(int argc, char *argv[])
                                                  int main(int argc, char *argv[])
    uint32_t t = 1000;
                                                       uint32_t t t = 1000;
    printf("1"); fflush(stdout);
                                                       printf("1"); fflush(stdout);
   int pid = fork();
                                                      int pid = fork();
    switch (pid)
                                                       switch (pid)
         case 0:
                                                           case 0:
             bwDelay(t);
printf("2"); fflush(stdout);
                                                                bwDelay(t);
printf("2"); fflush(stdout);
                                                                bwDelay(t);
printf("3"); fflush(stdout);
             bwDelay(t);
             printf("3"); fflush(stdout);
             break;
                                                                break;
         default:
                                                           default:
                                                                bwDelay(t);
             bwDelay(t);
                                                                printf("4"); fflush(stdout);
             printf("4"); fflush(stdout);
             bwDelay(t);
                                                                bwDelay(t);
             printf("5"); fflush(stdout);
                                                                printf("5"); fflush(stdout);
             wait(NULL);
printf("\n");
                                                                wait (NULL);
                                                                printf("\langle n'' \rangle;
    return EXIT_SUCCESS;
                                                       return EXIT_SUCCESS;
                                                  }
```

But when it ends, the child exists, so there is a return value on both parent and child

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fork illustration program

#### parent process

```
int main(int argc, char *argv[])
                                                     int main(int argc, char *argv[])
     uint32_t t = 1000;
                                                           uint32_t t = 1000;
    printf("1"); fflush(stdout);
int pid = fork();
                                                           printf("1"); fflush(stdout);
                                                           int pid = fork();
    switch (pid)
                                                          switch (pid)
         case 0:
                                                               case 0:
              bwDelay(t);
                                                                    bwDelay(t);
              printf("2"); fflush(stdout);
                                                                    printf("2"); fflush(stdout);
                                                                    bwDelay(t);
printf("3"); fflush(stdout);
              bwDelay(t);
printf("3"); fflush(stdout);
              break;
                                                                    break:
         default:
                                                               default:
              bwDelay(t);
printf("4"); fflush(stdout);
                                                                    bwDelay(t);
printf("4"); fflush(stdout);
              bwDelay(t);
printf("5"); fflush(stdout);
                                                                    bwDelay(t);
printf("5"); fflush(stdout);
              wait (NULL);
                                                                    wait (NULL):
              printf("\langle n'' \rangle;
                                                                    printf("\n");
     return EXIT_SUCCESS;
                                                          return EXIT_SUCCESS;
                                                     }
```

The value of pid is 0 in child and different from 0 in parent

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# Processes in Unix

fork illustration program

#### parent process

#### child process

child process

```
int main(int argc, char *argv[])
                                                    int main(int argc, char *argv[])
    uint32_t t t = 1000;
                                                         uint32_t t = 1000;
     printf("1"); fflush(stdout);
                                                         printf("1"); fflush(stdout);
    int pid = fork();
                                                         int pid = fork();
    \dot{\text{switch}} \ (\, \text{pid} \,)
                                                         switch (pid)
                                                              case 0:
         case 0:
             bwDelay(t);
printf("2"); fflush(stdout);
                                                                  bwDelay(t);
printf("2"); fflush(stdout);
                                                                  bwDelay(t);
printf("3"); fflush(stdout);
              bwDelay(t);
              printf("3"); fflush(stdout);
              break;
                                                                   break;
                                                              default:
         default:
              bwDelay(t);
                                                                  bwDelay(t);
                                                                   printf("4"); fflush(stdout);
              printf("4"); fflush(stdout);
              bwDelay(t);
                                                                   bwDelay(t);
              printf("5"); fflush(stdout);
                                                                   printf("5"); fflush(stdout);
              wait(NULL);
printf("\n");
                                                                   wait (NULL);
                                                                  printf("\langle n'' \rangle;
    return EXIT_SUCCESS;
                                                         return EXIT_SUCCESS;
}
                                                    }
```

So, parent and child follow different directions

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fork illustration program

#### parent process

```
int main(int argc, char *argv[])
                                                   int main(int argc, char *argv[])
    uint32_t t = 1000;
                                                        uint32_t t = 1000;
    printf("1"); fflush(stdout);
                                                        printf("1"); fflush(stdout);
    int pid = fork();
                                                        int pid = fork();
    switch (pid)
                                                        switch (pid)
                                                            case_0:
         case 0:
                                                                bwDelay(t);
             bwDelay(t);
              printf("2"); fflush(stdout);
                                                                 printf("2"); fflush(stdout);
             bwDelay(t);
printf("3"); fflush(stdout);
                                                                 bwDelay(t);
printf("3"); fflush(stdout);
             break;
                                                                 break:
         default:
                                                            default:
             bwDelay(t);
                                                                bwDelay(t);
printf("4"); fflush(stdout);
              printf("4"); fflush(stdout);
             bwDelay(t);
printf("5"); fflush(stdout);
                                                                 bwDelay(t);
printf("5"); fflush(stdout);
              wait (NULL);
                                                                 wait (NULL):
              printf("\langle n'' \rangle;
                                                                 printf("\n");
    return EXIT_SUCCESS;
                                                        return EXIT_SUCCESS;
                                                   }
```

Parent and child are concurrent and the delay may influence multiprogramming

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# Processes in Unix

fork illustration program

#### parent process

```
int main(int argc, char *argv[])
    uint32_t t t = 1000;
    printf("1"); fflush(stdout);
    int pid = fork();
    switch (pid)
         case 0:
             bwDelay(t);
printf("2"); fflush(stdout);
             bwDelay(t);
             printf("3"); fflush(stdout);
             break;
         default:
             bwDelav(t):
             printf("4"); fflush(stdout);
             bwDelay(t);
             printf("5"); fflush(stdout);
             wait(NULL);
printf("\n");
    return EXIT_SUCCESS;
```

#### child process

child process

```
int main(int argc, char *argv[])
    uint32_t t t = 1000;
    printf("1"); fflush(stdout);
    int pid = fork();
    switch (pid)
         case 0:
             bwDelay(t)
             printf("2"); fflush(stdout);
             bwDelay(t);
printf("3"); fflush(stdout);
             break;
         default:
             bwDelay(t);
             printf("4"); fflush(stdout);
             bwDelay(t);
             printf("5"); fflush(stdout);
             wait (NULL);
             printf("\langle n'' \rangle;
    return EXIT_SUCCESS;
}
```

So, no way to know who prints first

}

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### fork illustration program

#### parent process

```
int main(int argc, char *argv[])
    uint32_t t = 1000;
    printf("1"); fflush(stdout);
    int pid = fork();
    switch (pid)
         case 0:
              bwDelay(t);
              printf("2"); fflush(stdout);
              bwDelay(t);
printf("3"); fflush(stdout);
              break;
         default:
             bwDelay(t);
printf("4"); fflush(stdout);
              bwDelay(t);
printf("5"); fflush(stdout);
              wait(NULL);
printf("\n");
    return EXIT_SUCCESS;
}
```

#### child process

```
int main(int argc, char *argv[])
     uint32_t t = 1000;
     printf("1"); fflush(stdout);
     int pid = fork();
     switch (pid)
          case 0:
               bwDelay(t);
               printf("2"); fflush(stdout);
               bwDelay(t);
printf("3"); fflush(stdout);
              break;
          default:
              bwDelay(t);
printf("4"); fflush(stdout);
bwDelay(t);
printf("5"); fflush(stdout);
               wait (NULL);
               printf("\n");
     return EXIT_SUCCESS;
```

Because code is sequential: the 5 is always after the 4; the 3 is always after the 2

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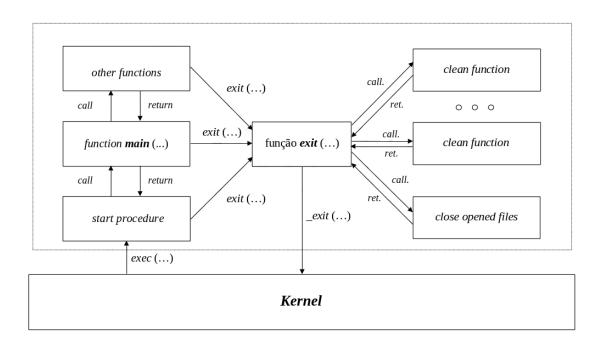
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### Processes in Unix Execution of a C/C++ program



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### Executing a C/C++ program: atexit

```
<stdio.h>
#include
#include
          <stdlib.h>
#include <unistd.h>
#include <assert.h>
/* cleaning functions */
static void atexit_1 (void)
    printf("atexit 1\n");
}
static void atexit_2(void)
    printf("atexit 2\n");
/* main programa */
int main(void)
    /* registering at exit functions */
    assert(atexit(atexit_1) == 0);
    assert(atexit(atexit_2) == 0);
    /* normal work */
    printf("hello world 1!\n");
    for (int i = 0; i < 5; i++) sleep(1);
    return EXIT_SUCCESS:
}
```

- The atexit function allows to register a function to be called at the program's normal termination
- They are called in reverse order relative to their register
- What happens if the termination is forced?

R: não é garantido que executem

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### Processes in Unix

#include

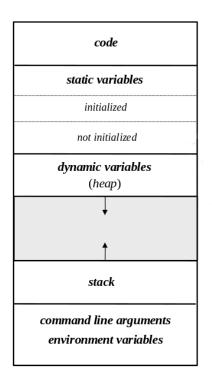
### Command line arguments and environment variables

```
<stdio.h>
#include
           <stdlib.h>
#include
           <unistd.h>
int main(int argc, char *argv[], char *env[])
    /* printing command line arguments */
    printf("Command line arguments:\n");
    for (int i = 0; argv[i] != NULL; i++)
        printf(" %s\n", argv[i]);
    /* printing all environment variables */
    printf("\nEnvironment variables:\n");
for (int i = 0; env[i] != NULL; i++)
        printf(" %s\n", env[i]);
    /* printing a specific environment variable */
    unsetenv("HOME");
printf(" env[\"HOME\"] = \"%s\"\n", getenv("HOME"));
    return EXIT_SUCCESS;
}
```

- argv is an array of strings
- argv[0] is the program reference
- env is an array of strings, each representing a variable, in the form name-value pair
- getenv returns the value of a variable name

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### Address space of a Unix process



- loaded by  $\mathbf{exec}$  system call  $(\dots)$ 

- initialized by exec system call (...)

reserved by malloc, calloc, realloc, new (C++)
released by free, delete (C++)

- function calls

reserved by alloca

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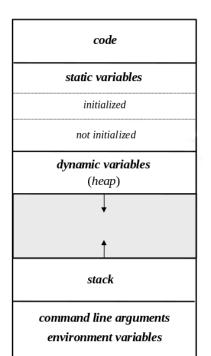
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# **Processes in Unix**

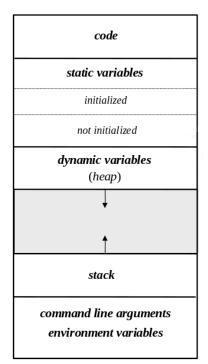
Address space of a Unix process (2)



```
int n1 = 1;
static int n2 = 2;
int n3;
static int n4;
int n5;
static int n6 = 6;
int main(int argc, char *argv[], char *env[])
                     extern char** environ;
                     static int n7;
                     static int n8 = 8;
                     int *p9 = (int*) malloc(sizeof(int));
                     int *p10 = new int;
                     int *p11 = (int*)alloca(sizeof(int));
                     int n12;
                     int n13 = 13;
                   \label{eq:continuity} \begin{array}{ll} \mbox{int } n14; \\ \mbox{printf("\ngetenv(n0): $\%p\n", getenv("n0"));} \\ \mbox{printf("\nargv: $\%p\nenv: $\%p\nenv: $\%p\nmain: $\%p\n", $\%p\nenv: $\%
                      argv, environ, env, main);
printf("\n&argc: %p\n&argv: %p\n&env: %p\n",
                                                           &argc, &argv, &env);
                      "p11: %p\n&n12: %p\n&n13: %p\n&n14: %p\n", &n1, &n2, &n3, &n4, &n5, &n6, &n7, &n8, p9, p10, p11, &n12, &n13, &n14);
```

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### Address space of a Unix process (3)



```
#include
           <stdio.h>
#include
           <stdlib.h>
#include
           <unistd.h>
#include
            <wait.h>
int n01 = 1;
int main(int argc, char *argv[], char *env[])
    int pid = fork();
if (pid != 0)
        fprintf(stderr, "%5d: n01 = \%-5d (\%p) \setminus n",
                pid, n01, &n01);
        wait (NULL);
        fprintf(stderr, "%5d: n01 = \%-5d (%p)\n",
                pid, n01, &n01);
    else
        n01 = 1111;
        fprintf(stderr, "%5d: n01 = %-5d (%p)\n", pid, n01, &n01);
    return 0;
}
```

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