

view_frames Result

Recorded at time: 1427.827

map

Broadcaster: /map_odom_broadcaster
Average rate: 49.743 Hz
Most recent transform: 1427.909 (-0.082 sec old)
Buffer length: 3.699 sec

odom

Broadcaster: /gazebo
Average rate: 10.278 Hz
Most recent transform: 1427.792 (0.035 sec old)
Buffer length: 3.600 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1427.827 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1427.827 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1427.827 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.286 Hz
Most recent transform: 1427.761 (0.066 sec old)
Buffer length: 3.500 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.286 Hz
Most recent transform: 1427.761 (0.066 sec old)
Buffer length: 3.500 sec

right_wheel