view\_frames Result Recorded at time: 1657.358 map Broadcaster: /amcl Average rate: 40.253 Hz Most recent transform: 1657.384 (-0.026 sec old) Buffer length: 3.478 sec odom Broadcaster: /gazebo Average rate: 10.297 Hz Most recent transform: 1657.291 (0.067 sec old) Buffer length: 3.399 sec robot\_footprint Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1657.358 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10.297 Hz Average rate: 10.297 Hz Most recent transform: 1657.261 (0.097 sec old) Most recent transform: 1657.261 (0.097 sec old) Buffer length: 0.000 sec Buffer length: 3.399 sec Buffer length: 3.399 sec

camera

Broadcaster: /robot\_state\_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1657.358 sec old)

Buffer length: 0.000 sec

Most recent transform: 0.000 (1657.358 sec old)

hokuyo

right\_wheel

left\_wheel