

Implicit navigation in vEB layout

Consider $N = 2h - 1$ keys where h is a power of 2, and the implicit cache-oblivious vEB layout of their corresponding complete binary tree, where the keys are suitably permuted and stored in an array of length N without using pointers (as it happens in the classical implicit binary heap but the rule here is different). The root is in the first position of the array. Find a rule that, given the position of the current node, it is possible to locate in the array the positions of its left and right children. Discuss how to apply this layout to obtain (a) a static binary search tree and (b) a heap data structure, discussing the cache complexity

SOLUTION

Assumptions

Suppose you have a binary vEB tree T stored in an array $T[]$ in external memory, as seen in class. Let the tree be complete and let its height, H , be a power of two. Also suppose you can store H locally.

N.B. In the code that follows, all division signs (/) represent integer division (div).

ZoomSequence

The following function generates a sequence zs of indexes of *nested* subtrees of T that uniquely identifies the position of node **target** in both T and $T[]$.

Starting from T , the decomposition will split a generic binary vEB tree A of height h into a *top tree* of index 0 and height $\frac{h}{2}$ and $2^{\frac{h}{2}}$ *bottom trees* (two per leaf of the top tree) of indexes $1 \dots 2^{\frac{h}{2}}$ and again height $2^{\frac{h}{2}}$.

An element zs_i will thus correspond to the index of a subtree of height $2^{\frac{H}{2^{i+1}}}$, nested into the subtree identified by zs_{i-1} (or T for zs_0).

Note that the sequence zs contains exactly $\log_2(H)$ entries.

```
ZoomSequence(target, H)
  let zs = Sequence.Empty; /* empty ordered list, first element will have index 0 */
  let h = H, i = target, blocksize = 0;
  while (h > 1)
    blocksize = 2^(h/2) - 1;
    zs.Enqueue(i/blocksize);
    i = i mod blocksize;
    h = h/2;
  end
  return zs;
end
```

Note that this requires no accesses to the tree, generating no cachefaults.

GetElement

The following function retrieves node i of the tree from the array $T[]$.

```
GetElement(i):
  let zs = ZoomSequence(i, H)
  let h = H, curr = 0, blocksize = 0;
  for t in zs do
    blocksize = 2^(h/2) - 1;
    curr = curr + t*blocksize;
    h = h/2;
  end
  return T[curr];
end
```

This only accesses the one element/node we need: $O(1)$ I/O's.

GetChildren

The following (absolutely horrific...) function returns the *tree node* indexes of the left and right children of tree node i . These can be fed to `GetElement` to obtain the contents of the actual nodes.

The basic idea is to traverse zs looking for the largest j such that $zs_j = 0$, which identifies the biggest vEB subtree that i is a leaf of (it is T if there is no such j , which means i has no children). Then it is a matter of going up one level from that, and moving ahead by an appropriate amount of subtrees of height $\frac{H}{2^{j+1}}$.

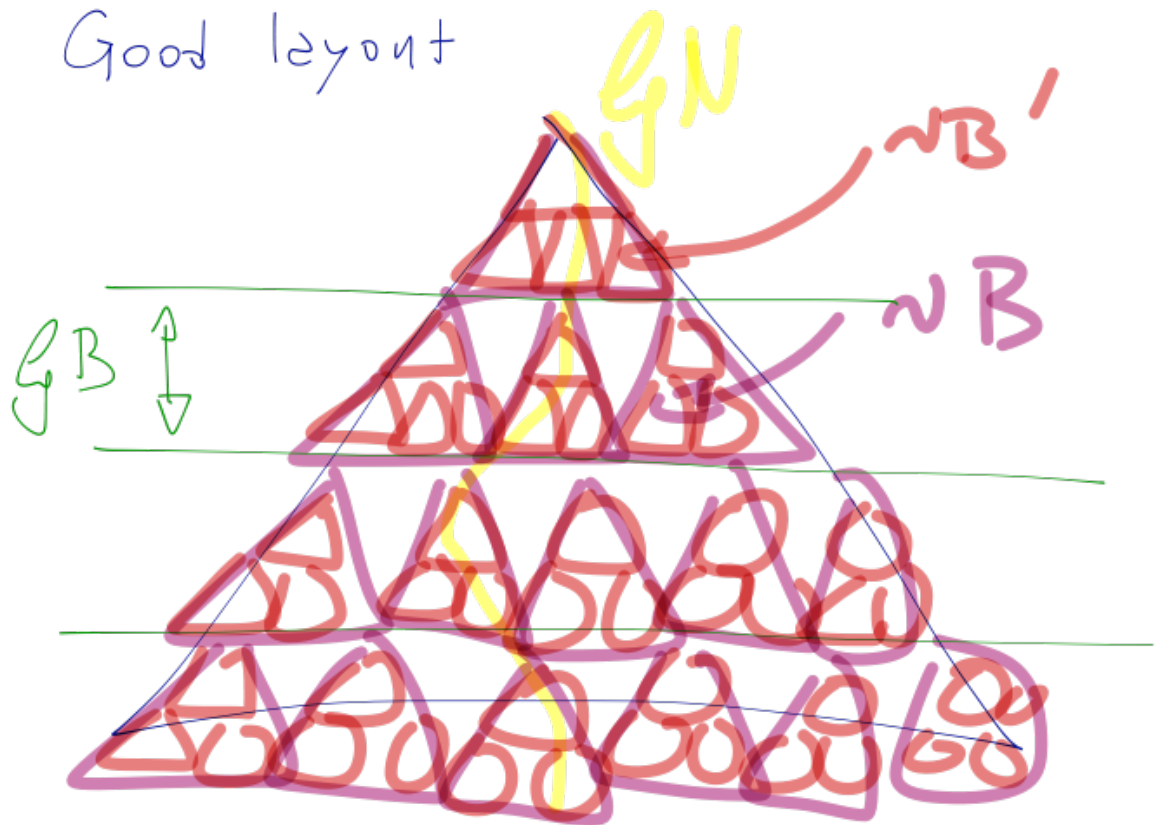
```

GetChildren(i)
  if (i mod 3 = 0) then /* subtrees of height 2 are stored consecutively */
    return <i+1, i+2>; /* note that such children nodes necessarily exist
      because T is a complete tree */
  end
  let zs = ZoomSequence(i, H);
  let idx0 = zs.LastIndexOf(0); /* index of last zero element in zs
    or -1 if no such element exists */
  if (idx0 = -1) then /* i is a leaf of T, so it has no children */
    return <-1, -1>
  end
  /* from here on out we're sure we're not a leaf of T itself */
  let h = H, blocksize = 0;
  let k = H/2^(idx0+1); /* height of the biggest tree i is a leaf of */
  let off = 0; /* will be the index of the root of the tree immediately
    encompassing the biggest tree i is a leaf of */
  for i = 0 to idx0-1 do
    blocksize = 2^(h/2)-1;
    off = off + zs.Get(i)*blocksize;
    h = h/2;
  end
  h = H;
  let leafidx = 0; /* leafidx will be s.t. i is the leafidx-th leaf
    of the tree of height k, starting from 0 */
  for i = idx0+1 to zs.Length do /* stuff following last zero element in zs */
    blocksize = 2^(h/2 -1);
    leafidx = (zs.Get(i)-1);
    h = h/2;
  end
  let left = off + (2^k -1)*(2*leafidx +1); /* 2 children per leaf of top tree
    +1 because of top tree */
  let right = off + (2^k -1)*(2*leafidx +2); /* +2 because of top tree and left child */
  return <left, right>;
end

```

Again, the function never accessed the tree itself, generating no cachefaults.

Binary Search Tree



As is quite evident from Professor Grossi's very excellent picture, given any block size B (which we can reasonably assume to be a power of two), a block will be able to hold a subtree of height $\log_2(B)$.

For a binary vEB tree T made up of N nodes, a single lookup will traverse $H = \log_2(N)$ nodes. Such nodes residing into blocked memory, we will observe a total of

$$O\left(\frac{\log_2(N)}{\log_2(B)}\right) = O(\log_B(N))$$

cache faults.

ReachLeaf

The following function returns a pointer to the i^{th} leaf of a non-singleton vEB BST. We number leaves starting from 0, left to right.

```
ReachLeaf(curr, l, h) /* curr root of tree, l-th leaf to reach, h height of tree */
  if (h = 2) then
    /* recursion endcase (we won't need to contemplate a singleton tree) */
    if (l = 0) then
      return curr.L;
    else
      return curr.R;
    end
  end
  curr = ReachLeaf(curr, l/2^(h-1), h/2);
  /* we have traversed the top half of the tree; now we must reach the bottom half.
  To do so, we look at the position of leaf l in a tree of height h+1 */
  if (l mod 2^h >= 2^(h/2)) then
    root = curr.R;
  else
```

```

    root = curr.L;
end
curr = ReachLeaf(curr, 1 mod 2(h-1), h/2);
return curr;
end

```

GetNode

The following function allows navigating a vEB BST saved as a tree with pointers, returning a pointer to the i^{th} node.

The intuition is to recursively split the tree in two by halving its height and navigating to the leaves of the subtrees thus defined that lie on the path to the destination.

```

GetNode(curr, i, h) /* curr root of tree, i-th node to reach, h height of tree */
if (h <= 2) then
    /* recursion endcase. Note that it takes care of singleton trees,
       assuming a sensible query (i.e. h = 1 => i = 0) */
    if (i = 0) then
        return curr;
    elif (i = 1) then
        return curr.L;
    else
        return curr.R;
    end
end
let zs = ZoomSequence(i, h);
let b = zs.Dequeue();
if (b = 0) then
    /* path to destination stays in the top tree */
    return GetNode(curr, i mod 2(h/2 - 1), h/2);
end
/* path to destination reaches a bottom tree so let's traverse the top tree */
curr = ReachLeaf(curr, (b-1)/2, h/4); /* navigate first half of top tree */
curr = ReachLeaf(curr, b mod 2(h/4 - 1), h/4); /* navigate second half of top tree */
/* we're on a leaf of the top tree, so let's reach the appropriate bottom tree */
if (b-1 mod 2 = 0) then
    curr = curr.L;
else
    curr = curr.R;
end
return GetNode(curr, i mod 2(h/2 - 1), h/2); /* recursion on bottom tree */
end

```