${\tt MSOpt} \hspace{1cm} MSOpt$

Description

The MSOpt function allows the user to define the structure of the experiment, the set of optimization criteria and the a priori model to be considered. The output is a list containing all information about the settings of the experiment. According to the declared criteria, the list also contains the basic matrices for their implementation, such as information matrix, matrix of moments and matrix of weights. This function returns the msopt argument of the Score and MSSearch functions of the multiDoE package.

Usage

MSOpt(facts, units, levels, etas, criteria, model)

Arguments

facts

A list of vectors representing the distribution of factors across strata. Each item in the list represents a stratum and the first item is the highest stratum of the multi-stratum structure of the experiment. Within the vectors, experimental factors are indicated by progressive integer from 1 (the first factor of the highest stratum) to the total number of experimental factors (the last factor of the lowest stratum). Blocking factors are differently denoted by empty vectors.

units

A list whose *i*-th element, n_i , is the number of experimental units within each unit at the previous stratum (i-1). The first item in the list, n_1 , represents the number of experimental units in the stratum 0. The latter is defined as the entire experiment, such that $n_0 = 1$.

levels

A vector containing the number of available levels for each experimental factor in facts (blocking factors are excluded). If all experimental factors share the number of levels one integer is sufficient.

etas

A list specifying the ratios of error variance between subsequent strata. It follows that length(etas) must be equal to length(facts)-1.

criteria

A list specifying the criteria to be optimized. It can contain any combination of:

"I": I-optimality
"Id": Id-optimality
"D": D-optimality
"A": Ds-optimality
"Ds": A-optimality
"As": As-optimality

These criteria are well explained in Borrotti, Sambo, Mylona and Gilmour (2017). More detailed information on the available criteria is also given under **Details**.

model

A string which indicates the type of model, among "main", "interaction" and "quadratic".

1

Details

A little notation is introduced to show the criteria that can be used in the multi-objective approach of the multiDoE package.

For an experiment with N runs and s strata, with stratum i having n_i units within each unit at stratum (i-1) and stratum 0 being defined as the entire experiment $(n_0 = 1)$, the general form of the model can be written as:

$$y = X\beta + \sum_{i=1}^{s} Z_i \varepsilon_i$$

where y is an N-dimensional vector of responses $(N = \prod_{j=1}^s n_j)$, X is an N by p model matrix, β is a p-dimensional vector containing the p fixed model parameters, Z_i is an N by b_i indicator matrix of 0 and 1 for the units in stratum i (i.e. the (k,l)th element of Z_i is 1 if the kth run belongs to the lth block in stratum i and 0 otherwise) and $b_i = \prod_{j=1}^i n_j$. Finally, the vector $\varepsilon_i \sim N(0, \sigma_i^2 I_{b_i})$ is a b_i -dimensional vector containing the random effects, which are all uncorrelated. The variance components $\sigma_i^2 (i = 1, \ldots, s)$ have to be estimated and this is usually done using the REML ($REstricted\ Maximum\ Likelihood$) method.

The best linear unbiased estimator for the parameter vector β is the generalized least square estimator:

$$\hat{\beta}_{GLS} = (X'V^{-1}X)^{-1}X'V^{-1}y$$

This estimator has variance-covariance matrix:

$$Var(\hat{\beta}_{GLS}) = \sigma^2 (X'V^{-1}X)^{-1}$$

where
$$V = \sum_{i=1}^{s} \eta_i Z_i' Z_i$$
, $\eta_i = \frac{\sigma_i^2}{\sigma^2}$ and $\sigma^2 = \sigma_s^2$.

Let $M = (X'V^{-1}X)$ be the information matrix of $\hat{\beta}$.

 D-optimality. It is based on minimizing the generalized variance of the parameter estimates. This can be done either by minimizing the determinant of the variancecovariance matrix of the factor effects' estimates or by maximizing the determinant of M.

The objective function to be minimized is:

$$f_D(d;\eta) = \left(\frac{1}{\det(M)}\right)^{1/p}$$

where d is the design with information matrix M and p is the number of model parameters.

• **A-optimality.** This criterion is based on minimizing the average variance of the estimates of the regression coefficients. The sum of the variances of the parameter estimates (elements of $\hat{\beta}$) is taken as a measure, which is equivalent to considering the trace of M^{-1} .

The objective function to be minimized is:

$$f_A(d;\eta) = \operatorname{tr}(M^{-1})$$

where d is the design with information matrix M.

• I-optimality. It seeks to minimize the average prediction variance. The objective function to be minimized is:

$$f_I(d;\eta) = \frac{\int_{\chi} f'(x)(M)^{-1} f(x) dx}{\int_{\chi} dx}$$

where d is the design with information matrix M and χ represents the design region. It can be proved that when there are k treatment factors each with two levels, so that the experimental region is of the form $[-1,+1]^k$, the objective function can also be written as:

$$f_I(d;\eta) = trace \left[(M)^{-1} B \right]$$

where d is the design with information matrix M and $B = 2^{-k} \int_{\chi} f'(x) f(x) dx$ is the moments matrix. To know the implemented expression for calculating the moments matrix for a cuboidal design region see Hardin and Sloane (1991).

• **Ds-optimality.** Its aim is to minimize the generalized variance of the parameter estimates by excluding the intercept from the set of parameters of interest. Let β_i be the model parameter vector of dimension $(p_i - 1)$ to be estimated in stratum i. Let X_i be the associated model matrix m_i by $(p_i - 1)$, where m_i is the number of units in stratum i. The partition of interest of the matrix of variances and covariances of $\hat{\beta}_i$ is

$$(M_i^{-1})_{22} = [X_i'(I - \frac{1}{m_i}11')X_i]^{-1}$$

The objective function to be minimized is:

$$f_{D_s}(d;\eta) = |(M_i^{-1})_{22}|$$

As-optimality. This criterion is based on minimizing the average variance of the estimates of the regression coefficients excluding the intercept from the set of parameters of interest.

With reference to the notation introduced for the previous criterion, the objective function to be minimized is:

$$f_{A_s}(d;\eta) = \operatorname{tr}(W_i(M_i^{-1})_{22})$$

where W_i is a diagonal matrix of weights, with the weights scaled so that the trace of W_i is equal to 1.

• Id-optimality. It seeks to minimize the average prediction variance excluding the intercept from the set of parameters of interest.

The objective function to be minimized is the same as the I-optimality criterion where the first row and columns of the B matrix are deleted.

Value

MSOpt returns a list containing the following components:

- facts: The argument facts.
- nfacts: An integer. The number of experimental factors (blocking factors are excluded from the count).
- nstrat: An integer. The number of strata.
- units: The argument units.
- runs: An integer. The number of runs.

- etas: The argument etas.
- avlev: A list showing the available levels for each experimental factor.
- levs: A vector showing the number of available levels for each experimental factor.
- Vinv: The inverse of the variance-covariance matrix of the responses.
- model: The argument model.
- crit: The argument criteria.
- ncrit: An integer. The number of criteria.
- M: The moment matrix. Only with *I*-optimality criteria.
- M0: The moment matrix. Only with *Id*-optimality criteria.
- W: The diagonal matrix of weights. Only with As-optimality criteria. This matrix assigns to each main effect and each interaction effect an absolute weight equal to 1, while to the quadratic effects it assigns an absolute weight equal to 1/4.

References

- R. H. Hardin and N. J. A. Sloane. Computer generated minimal (and larger) response-surface designs: (II) The cube. Technical report, 1991.
- M. Borrotti and F. Sambo and K. Mylona and S. Gilmour. A multi-objective coordinate-exchange two-phase local search algorithm for multi-stratum experiments. Statistics & Computing, 2017.