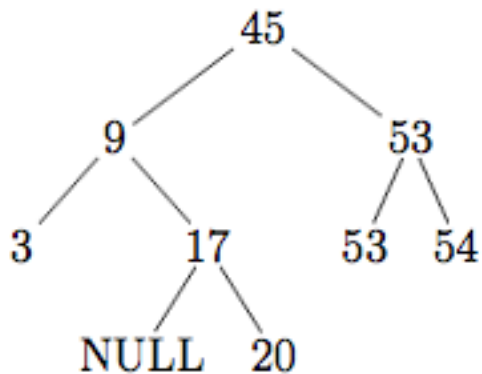


Binary Search Tree Insertion

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Binary Search Tree Storage Rules

- 1 Every entry in n 's left subtree is less than or equal to the entry in node n .
- 2 Every entry in n 's right subtree is greater than (or equal to) the entry in node n .



Sample Binary Search Tree

Binary Search Tree Insertion

```
static DATA_TYPE A[] = { 45, 9, 53, 3, 17, 53, 17, 20, 54 };  
static int nA = sizeof(A)/sizeof(DATA_TYPE);
```

```
for( int i = 0 ; i < nA ; i++ )  
    t1.AddNode( A[i] );
```

t1:

```
graph TD  
    45 --> 9  
    45 --> 53  
    9 --> 3  
    53 --> 17  
    17 --> 20  
    54
```

Q: Does order of insertion matter?

Binary Search Trees—Code

Binary Search Tree Insertion

```
/* BSTree2.h
 *
 * Binary Search Tree class Interface WITH deletion.
 */

#ifndef _BSTREE_H_
#define _BSTREE_H_

typedef int DATA_TYPE; // Type of node's data

class BinarySearchTree
{
private:
    typedef struct BSTreeNode
    {
        DATA_TYPE data;
        BSTreeNode *leftPtr;
        BSTreeNode *rightPtr;
    } *TreePtr;

    TreePtr rootPtr; // root of the BST
```

Private Methods

```
void    InitBSTree()
        { rootPtr = NULL; }

void    AddNodeR( TreePtr& t, DATA_TYPE newData );

//  Delete methods

bool    IsLeaf( TreePtr treePtr );

TreePtr SearchNodeInBST( TreePtr treePtr,
                        DATA_TYPE searchKey );
```

Public Methods

```
public:
    BinarySearchTree()    { InitBSTree(); }
    ~BinarySearchTree();

    bool    IsEmpty()
            { return (rootPtr == NULL); }

    void    AddNode( DATA_TYPE newData );
    void    AddNodeR( DATA_TYPE newData );

    void    SearchNode( DATA_TYPE searchKey );
    void    DeleteNode( DATA_TYPE val );

    // Print methods
};
#endif
```

AddNodeR() – public

Binary Search
Tree Insertion

```
void BinarySearchTree::AddNodeR( DATA_TYPE newData )  
{  
    AddNodeR( rootPtr, newData );  
}
```


AddNodeR() – private

```
void BinarySearchTree::AddNodeR( TreePtr &t, DATA_TYPE newData )
{
    if( t == NULL )
    {
        TreePtr newPtr = new BSTreeNode;
        // Add new data in the new node's data field
        newPtr->data      = newData;
        newPtr->leftPtr   = NULL;
        newPtr->rightPtr  = NULL;

        t = newPtr;
    }
    else if( newData <= t->data )
        AddNodeR( t->leftPtr, newData );
    else
        AddNodeR( t->rightPtr, newData );
}
```

AddNodeR() – private

```
void BinarySearchTree::AddNodeR( TreePtr &t, DATA_TYPE newData )
{
    if( t != NULL )
    {
        if( newData <= t->data )
            AddNodeR( t->leftPtr, newData );
        else
            AddNodeR( t->rightPtr, newData );
    }
    else
    {
        TreePtr newPtr = new BSTreeNode;
        // Add new data in the new node's data field
        newPtr->data      = newData;
        newPtr->leftPtr   = NULL;
        newPtr->rightPtr  = NULL;

        t = newPtr;
    }
}
```

AddNode() – Non-recursive 1

```
// AddNode()
//  Add (insert) new item into the BST, whose
//  root node is pointed to by "rootPtr".  If
//  the data already exists, it is ignored.

void BinarySearchTree::AddNode( DATA_TYPE newData )
{
    TreePtr newPtr;

    newPtr = new BSTreeNode;
        // Add new data in the new node's data field
    newPtr->data      = newData;
    newPtr->leftPtr   = NULL;
    newPtr->rightPtr  = NULL;

        // If the BST is empty, insert the new data in root
    if( rootPtr == NULL )
    {
        rootPtr = newPtr;
    }
}
```

AddNode() – Non-recursive 2

```
else    // Look for the insertion location
{
    TreePtr    treePtr = rootPtr;
    TreePtr    targetNodePtr;

    while( treePtr != NULL )
    {
        targetNodePtr = treePtr;
        if( newData == treePtr->data )
            // Found same data; ignore it.
            return;
        else if( newData < treePtr->data )
            // Search left subtree for insertion location
            treePtr = treePtr->leftPtr;
        else    // newData > treePtr->data
            // Search right subtree for insertion location
            treePtr = treePtr->rightPtr;
    }
}
```

AddNode() – Non-recursive 3

```
        // "targetNodePtr" is the pointer to the parent of
        // the new node. Decide where it will be inserted.
        if( newData < targetNodePtr->data )
            targetNodePtr->leftPtr = newPtr;
        else // insert it as its right child
            targetNodePtr->rightPtr = newPtr;
    }
}
```

AddNode() – Differences

- What are the differences between the AddNode() and AddNodeR() methods?
- Why is this important?

AddNode() – Differences

- What are the differences between the AddNode() and AddNodeR() methods?
 - Traversal: iterative vs. recursive
 - AddNodeR() is overloaded
 - Access: public vs. private
- Why is this important?
 - Non-recursive less likely to blow the stack if tree grossly unbalanced.