Various Methods for Estimating Volatility

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The GARCH Process

The GARCH(p,q) process is given by

$$\epsilon_t = \sigma_t z_t$$

$$\sigma_t^2 = \alpha_0 + \sum_{i=1}^q \alpha_i \epsilon_{t-i}^2 + \sum_{i=1}^p \beta_i \sigma_{t-i}^2,$$

with ϵ_t being errors around a mean process, and z_t is standard Brownian motion.

The most common set of parameters are p=1 and q=1. Hansen and Lunde [4] show that GARCH(1,1) does as well, or better, than more complicated models in forecasting volatility. As a result, it is useful to focus on the properties of GARCH(1,1) as the time-step in the finite difference stochastic difference equation approaches zero.

Small-step asymptotics for GARCH(1,1)

If one is to use (regularly spaced) high-frequency data, it is useful to develop theory for ARCH processes where the time-step in the stochastic difference equation approaches zero. Nelson [5] develops such asymptotic relations. Most notably, with respect to estimation of parameters, we expect to observe

$$\begin{array}{ccc} \alpha_h + \beta_h & \to & 1 \text{ as } h \to 0 \\ & \alpha_h & \to & 0 \\ & \beta_h & \to & 1 \end{array}$$

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Empirical evidence for high-frequency data does not support this. What could cause theoretical deviations?

Reasons for GARCH failure at higher frequencies

- intraday volatility patterns
- Short-term bursts in volatility associated with news releases
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The most commonly used method to model an intraday volatility process is Andersen and Bollerslev's sequential estimation approach [1], [2]

Realized Volatility

Assuming that logarithmic price of a financial asset is given by the diffusion process

$$p_t = \int_0^t \mu(s)ds + \int_0^t \sigma(s)dW(s), \tag{1}$$

we are interested in the integrated volatility over a past time interval Δ ,

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From [3],
$$\frac{\sqrt{m}(RV^{(m)}-IV)}{\sqrt{2\int_0^1\sigma^4(s)ds}} o N(0,1)$$

Microstructure Noise

The very high-frequency prices are contaminated by market microstructure effects (noise), which lead to biases in realized volatility. Realized volatility estimators are derived based on the assumptions for the microscruture noise:

$$r_i^{(m)} = r_i^{*(m)} + \epsilon_i^{(m)}, i = 1, 2, \dots, m,$$
 (4)

where $r_i^{*(m)}$ is the true log-difference of prices, $\epsilon_i^{(m)}$ is the contamination noise, and $r^{(m)}$ is the observed log-difference price.

RV decomposition in the presence of microstructure noise

$$RV^{(m)} = RV^{*(m)} + 2\sum_{i=1}^{m} r_i^{*(m)} \epsilon_i^{(m)} + \sum_{j=1}^{m} \epsilon_j^{(m)^2}$$

Under the assumptions that a) the noise process is independent and identically distributed with mean zero and finite variance ω^2 and finite fourth moments, and b) the noise is independent of the true price.

$$E[RV^{(m)}] = IV + 2m\omega^2 \tag{5}$$

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Sampling at lower frequencies reduces bias but leads to an increase in variance (bias-variance trade-off).

Averaging and Subsampling

Average a number of IV estimators for different sampling frequencies over the high-frequency samples:

$$TTSRV^{(m,m_1,...,m_K,K)} = \frac{1}{K} \sum_{k=1}^{K} RV^{(k,m_k)} - \frac{\bar{m}}{m} RV^{(all)}$$
 (6)

Under independent noise assumptions, the estimator is consistent. Under equidistant observations and under regular allocation of the grids, there is an asymptotic distribution result.

Kernel-Based Estimation

$$KRV^{(m,H)} = RV^{(m)} + 2\sum_{h=1}^{H} \frac{m}{m-h} \gamma_h,$$
 (7)

with
$$\gamma_h = \sum_{i=1}^m r_i^{(m)} r_{i+h}^{(m)}$$
.

Stochastic Volatility

We model the log-price $y^*(t)$ follows the solution to the stochastic differential equation

$$dy^*(t) = \{\mu + \beta \sigma^2(t)\}dt + \sigma(t)dw(t)$$
 (8)

Here μ is the familiar drift and β is the *risk-premium*. Over an interval $\Delta > 0$ returns are defined as

$$y_n = y^*(\Delta n) - y^*\{(n-1)\Delta\}$$

$$y_n|\sigma_n^2 \sim N(\mu\Delta + \beta\sigma_n^2, \sigma_n^2)$$

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Models is subject to microstructure noise. We therefore fit the models to realized volatility over the trading periods Δ .

References I

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