



Tutorial 6: Decision Trees

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### **Classifiers**

Classifiers from previous lectures:

Zero-Rule: class with the most instances (rule)

One-Rule: rules for one attribute

Naïve Bayes: conditional probability attribute – class

What is the difference between classification and regression?

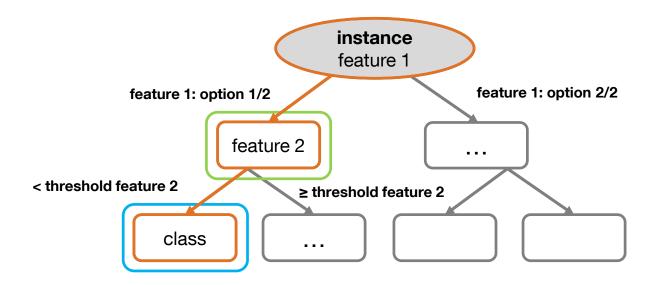
Classification	Regression
Prediction of a class label by means of the attributes	Prediction of a numerical value by means of the attributes





### **Classification Decision Trees**

- A decision tree for n different classes is created based on some training data
- An internal node is a test on an attribute
- A branch represents an outcome of the test
- A leaf node represents a class
- A new instance is classified by following a matching path to a leaf node







## **Optimal Tree**

For m attributes and n = 2 classes, there are  $2^{2^m}$  possible trees already

That is equal to the number of Boolean functions

### Finding the optimal tree is NP-complete

Not feasible for data mining applications

### Solution: Greedy algorithm for tree construction

- Top down approach: The tree is created recursively from the root node
- Every possible split is assessed with a measure
- The best split is chosen
- Repeat until all leaf nodes are pure or all attributes have been used





## **Evaluating splits**

## Which split is better?

- Instances should be classified as easy as possible
- Good separation of classes (ideally leaf nodes contain instances of a single class only)
- In the worst case the separation does not affect the class distribution
- Possible measure: information





## Information and entropy

- Let us denote  $c_i$  to be the absolute number of training examples being in class i at the current stage
- The probability (relative frequency) of class i then is  $p_i = \frac{c_i}{c}$  with  $C = \sum_{i=1}^n c_i$

Entropy measures information content in bits (uncertainty of a node):

entropy
$$(p_1, ..., p_n) = -\sum_{i=1}^n p_i \cdot \log_2 p_i$$
.

**Information** necessary to classify:

$$info([c_1, ..., c_n]) = entropy\left(\frac{c_1}{C}, ..., \frac{c_n}{C}\right).$$

Represents the expected amount of information that would be needed to specify the class of this node.





## Information gain

The quality of a split is equal to the gained information

gain(attribute) = info(before split by attribute) - info(after split by attribute)





### **Formulas**

Entropy:

$$entropy(p_1, ..., p_n) = -\sum_{i=1}^n p_i \cdot \log_2 p_i$$

Information for  $C = \sum c_i$ :

$$info([c_1, ..., c_n]) = entropy\left(\frac{c_1}{C}, ..., \frac{c_n}{C}\right)$$

Average information for a numeric split into m branches, with  $L_i = [c_{i,1}, ..., c_{i,n}]$  being the set of class counts in this split,  $C_i = \sum_k c_{i,k}$  the corresponding number of instances, and  $L = \sum C_i$ :

$$\mathsf{info}(L_1, \dots, L_m) = \sum_{i=1}^m \frac{C_i}{L} \cdot \mathsf{info}(L_i)$$

Information gain:

gain(attribute) = info(before split by attribute) - info(after split by attribute)

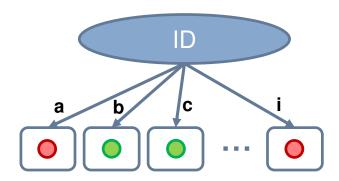




## Information gain problems

## Biased against attributes with a lot of edges

- For example: ID attribute
- Highest information gain because every leaf is pure
- Results in overfitting



#### Solution

- Take number and size of leafs into account: Intrinsic Information
- Intrinsic information: s is the size of a leaf (number of affected instances)

$$intrinsicInfo([s_1, ..., s_n]) = info([s_1, ..., s_n])$$

New criterion: Gain ratio





### **Numerical attributes**

### Considering nominal attributes

- one edge per attribute value works well
- bad in case of numerical values

### Solution: Binary Splits

- values are separated into two sections: below (<) and above (≥) some chosen threshold
- the split is evaluated with the information gain: set threshold to a value, s.t. information gain is maximized
- common practice to place numeric thresholds halfway between the values that delimit the boundaries
- Numeric attributes may be tested several times in a tree