## Machine Learning Exercise Sheet 3

#### Probabilistic Inference

Exercise sheets consist of two parts: homework and in-class exercises. You solve the homework exercises on your own or with your registered group and upload it to Moodle for a possible grade bonus. The inclass exercises will be solved and discussed during the tutorial along with some difficult and/or important homework exercises. You do not have to upload any solutions of the in-class exercises.

### In-class Exercises

Consider the probabilistic model

$$p(\mu \mid \alpha) = \mathcal{N}(\mu \mid 0, \alpha^{-1}) = \sqrt{\frac{\alpha}{2\pi}} \exp\left(-\frac{\alpha}{2}\mu^{2}\right)$$
$$p(x \mid \mu) = \mathcal{N}(x \mid \mu, 1) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}(x - \mu)^{2}\right)$$

and a set of observations  $\mathcal{D} = \{x_1, ..., x_N\}$  consisting of N samples  $x_i \in \mathbb{R}$ .

Note: We parametrize  $\mu \mid \alpha$  with the precision parameter  $\alpha = 1/\sigma^2$  instead of the usual variance  $\sigma^2$  because it leads to a nicer solution.

**Problem 1:** Derive the maximum likelihood estimate  $\mu_{\text{MLE}}$ . Show your work.

Our goal is to find

$$\begin{split} \mu_{\text{MLE}} &= \operatorname*{arg\,max}_{\mu \in \mathbb{R}} p(\mathcal{D} \mid \mu) \\ &= \operatorname*{arg\,max}_{\mu \in \mathbb{R}} \, \log p(\mathcal{D} \mid \mu) \end{split}$$

We solve this problem in two steps:

- 1. Write down & simplify the expression for  $\log p(\mathcal{D} \mid \mu)$ .
- 2. Solve  $\frac{\partial}{\partial \mu} \log p(\mathcal{D} \mid \mu) \stackrel{!}{=} 0$  for  $\mu$ .

$$\begin{split} \log p(\mathcal{D} \mid \mu) &= \log \operatorname{p}(x_1, ..., x_N \mid \mu) \\ &= \log \left( \prod_{i=1}^N \operatorname{p}(x_i \mid \mu) \right) & \text{iid assumption} \\ &= \sum_{i=1}^N \log \operatorname{p}(x_i \mid \mu) \\ &= \sum_{i=1}^N \left[ \log \left( \frac{1}{\sqrt{2\pi}} \right) + \log \left( \exp \left( -\frac{1}{2} (x_i - \mu)^2 \right) \right) \right] \\ &= \sum_{i=1}^N \left[ -\frac{1}{2} (x_i - \mu)^2 \right] + \operatorname{const.} \\ &= -\frac{1}{2} \sum_{i=1}^N (x_i^2 - 2x_i \mu + \mu^2) + \operatorname{const.} \\ &= \left[ -\frac{1}{2} \sum_{i=1}^N x_i^2 \right] + \left[ \sum_{i=1}^N x_i \mu \right] - \left[ \frac{1}{2} \sum_{i=1}^N \mu^2 \right] + \operatorname{const.} \\ &= \mu \sum_{i=1}^N x_i - \frac{N}{2} \mu^2 + \operatorname{const.} \end{split}$$

Now compute the derivative and set it to zero.

$$\frac{\partial}{\partial \mu} \log p(\mathcal{D} \mid \mu) = \frac{\partial}{\partial \mu} \left( \mu \sum_{i=1}^{N} x_i - \frac{N}{2} \mu^2 + \text{const.} \right)$$
$$= \sum_{i=1}^{N} x_i - N\mu \stackrel{!}{=} 0$$

Solving for  $\mu$  we obtain

$$\mu_{\text{MLE}} = \frac{1}{N} \sum_{i=1}^{N} x_i$$

That is,  $\mu_{\text{MLE}}$  is just the average of the datapoints.

## **Problem 2:** Derive the maximum a posteriori estimate $\mu_{MAP}$ . Show your work.

Our goal is to find

$$\begin{split} \mu_{\text{MAP}} &= \mathop{\arg\max}_{\mu \in \mathbb{R}} p(\mu \mid \mathcal{D}, \alpha) \\ &= \mathop{\arg\max}_{\mu \in \mathbb{R}} \log p(\mu \mid \mathcal{D}, \alpha) \\ &= \mathop{\arg\max}_{\mu \in \mathbb{R}} \left[ \log p(\mathcal{D} \mid \mu) + \log p(\mu \mid \alpha) \right] \end{split}$$

We solve this problem in two steps:

- 1. Write down & simplify the expression for  $\log p(\mathcal{D} \mid \mu) + \log p(\mu \mid \alpha)$ .
- 2. Solve  $\frac{\partial}{\partial \mu} (\log p(\mathcal{D} \mid \mu) + \log p(\mu \mid \alpha)) \stackrel{!}{=} 0$  for  $\mu$ .

$$\begin{split} \log p(\mu \mid \alpha) &= \log \left( \sqrt{\frac{\alpha}{2\pi}} \right) + \log \left( \exp \left( -\frac{\alpha}{2} \mu^2 \right) \right) \\ &= -\frac{\alpha}{2} \mu^2 + \text{const.} \end{split}$$

From the previous task, we know that

$$\log p(\mathcal{D} \mid \mu) = \mu \sum_{i=1}^{N} x_i - \frac{N}{2} \mu^2 + \text{const.}$$

Therefore, we get

log p(
$$\mathcal{D} \mid \mu$$
) + log p( $\mu \mid \alpha$ ) =  $\mu \sum_{i=1}^{N} x_i - \frac{N}{2} \mu^2 - \frac{\alpha}{2} \mu^2 + \text{const.}$ 

Now compute the derivative and set it to zero.

$$\frac{\partial}{\partial \mu} \left( \log p(\mathcal{D} \mid \mu) + \log p(\mu \mid \alpha) \right) = \frac{\partial}{\partial \mu} \left( \mu \sum_{i=1}^{N} x_i - \frac{N}{2} \mu^2 - \frac{\alpha}{2} \mu^2 + \text{const.} \right)$$
$$= \sum_{i=1}^{N} x_i - N\mu - \alpha\mu \stackrel{!}{=} 0$$

Solving for  $\mu$  we obtain

$$\mu_{\text{MAP}} = \frac{1}{N + \alpha} \sum_{i=1}^{N} x_i$$

By comparing this to  $\mu_{\text{MLE}}$ , we can understand the effect of a 0-mean Gaussian prior on our estimate of  $\mu$ . Since  $\alpha > 0$ , we see that  $\mu_{\text{MAP}}$  is always closer to zero than  $\mu_{\text{MLE}}$ .

**Problem 3:** Does there exist a prior distribution over  $\mu$  such that  $\mu_{\text{MLE}} = \mu_{\text{MAP}}$ ? Justify your answer.

Let's compare the expressions for  $\mu_{\text{MLE}}$  and  $\mu_{\text{MAP}}$ 

$$\mu_{\text{MAP}} = \frac{1}{N} \sum_{i=1}^{N} x_i \qquad \qquad \mu_{\text{MAP}} = \frac{1}{N+\alpha} \sum_{i=1}^{N} x_i$$

As  $\alpha$  approaches zero ( $\alpha \to 0$ ),  $\mu_{\text{MAP}}$  gets closer to  $\mu_{\text{MLE}}$ . As the *precision* of the prior distribution decreases, its variance increases. The prior distribution is getting more and more flat, thus being less informative and having a smaller effect on the posterior.

If we could set  $\alpha = 0$ , we would have a uniform prior on  $\mu$ , and thus  $\mu_{\text{MLE}} = \mu_{\text{MAP}}$ . However, technically, we are not allowed to do that — since the distribution  $p(\mu \mid \alpha)$  is defined over all of  $\mathbb{R}$ , it has to integrate to one  $(\int_{-\infty}^{\infty} p(\mu \mid \alpha) d\mu = 1)$ .

We can ignore this restriction and assume that we have a uniform prior over  $\mu$ . Such prior would be called *improper*. While in many cases it's fine to use an improper prior, it might lead to subtle problems in certain situations.

#### **Problem 4:** Derive the posterior distribution $p(\mu \mid \mathcal{D}, \alpha)$ . Show your work.

We obtain the posterior distribution using Bayes formula

$$p(\mu \mid \mathcal{D}, \alpha) = \frac{p(\mathcal{D} \mid \mu) p(\mu \mid \alpha)}{p(\mathcal{D} \mid \alpha)}$$

$$\propto p(\mathcal{D} \mid \mu) p(\mu \mid \alpha)$$

$$\propto \left( \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}(x_i - \mu)^2\right) \right) \sqrt{\frac{\alpha}{2\pi}} \exp\left(-\frac{\alpha}{2}\mu^2\right)$$

$$\propto \left( \prod_{i=1}^{N} \exp\left(-\frac{1}{2}(x_i - \mu)^2\right) \right) \exp\left(-\frac{\alpha}{2}\mu^2\right)$$

$$\propto \exp\left(-\frac{1}{2}\sum_{i=1}^{N} (x_i - \mu)^2 - \frac{\alpha}{2}\mu^2\right)$$

$$\propto \exp\left(-\frac{1}{2}\sum_{i=1}^{N} x_i^2 + \mu \sum_{i=1}^{N} x_i - \frac{1}{2}\sum_{i=1}^{N} \mu^2 - \frac{\alpha}{2}\mu^2\right)$$

$$\propto \exp\left(-\frac{N + \alpha}{2}\mu^2 + \mu \sum_{i=1}^{N} x_i\right)$$
(1)

We know that the posterior distribution has to integrate to 1, but we don't know the normalizing constant. However, we know that it's proportional to  $\exp(a\mu^2 + b\mu)$ . This looks very similar to a normal distribution — we have an quadratic form inside the exponential.

How can we use this fact? Consider a normal distribution over  $\mu$  with mean m and precision  $\beta$ 

$$\mathcal{N}(\mu \mid m, \beta^{-1}) = \sqrt{\frac{\beta}{2\pi}} \exp\left(-\frac{\beta}{2}(\mu - m)^2\right)$$
$$\propto \exp\left(-\frac{\beta}{2}\mu^2 + \beta m\mu\right) \tag{2}$$

If we find  $\beta$  and m such that Equations 1 and 2 are equal, we will know that our posterior  $p(\mu \mid \mathcal{D}, \alpha)$  is a normal distribution with mean m and precision  $\beta$ .

First we observe that

$$\beta = N + \alpha$$

Now we need to find m such that

$$\beta m = \sum_{i=1}^{N} x_i$$

$$m = \frac{1}{\beta} \sum_{i=1}^{N} x_i$$

$$m = \frac{1}{N+\alpha} \sum_{i=1}^{N} x_i$$

Putting everything together we see that

$$p(\mu \mid \mathcal{D}, \alpha) = \mathcal{N}\left(\mu \mid \frac{1}{N+\alpha} \sum_{i=1}^{N} x_i, (N+\alpha)^{-1}\right)$$

Since the posterior is a normal distribution, its mean coincides with its mode — this means that  $\mathbb{E}_{p(\mu|\mathcal{D},\alpha)}[\mu] = \mu_{MAP}$ . We can see that this is indeed the case, which is a good sanity check.

# **Problem 5:** Derive the posterior predictive distribution $p(x_{new} \mid \mathcal{D}, \alpha)$ . Show your work.

The posterior over  $\mu$  is  $p(\mu \mid \mathcal{D}, \alpha) = \mathcal{N}(\mu \mid m, \beta^{-1})$ . Our goal is to find the *posterior predictive* distribution over the next sample  $p(x_{new} \mid \mathcal{D}, \alpha)$ . For brevity, we will drop the new subscript.

From the lecture we remember that thanks to the conditional independence assumption the posterior predictive is

$$p(x \mid \mathcal{D}, \alpha) = \int_{-\infty}^{\infty} p(x \mid \mu) p(\mu \mid \mathcal{D}, \alpha) d\mu$$

There are two (equivalent) ways to approach this problem.

**Approach 1.** Basically, we are modeling the following process

- We draw  $\mu$  from the posterior distribution  $\mu \sim \mathcal{N}(m, \beta^{-1})$ .
- We draw x from the conditional distribution  $x \sim \mathcal{N}(\mu, 1)$ .

This process is identical to the following procedure

- We draw  $\mu$  from the posterior distribution  $\mu \sim \mathcal{N}(m, \beta^{-1})$ .
- We draw y from the standard normal distribution  $y \sim \mathcal{N}(0,1)$ .
- We calculate x as  $\mu + y$ .

Clearly, x is a sum of two *independent* normally distributed random variables. Hence, x also follows a normal distribution with mean m + 0 and precision  $(\beta^{-1} + 1)^{-1}$ .

$$p(x \mid \mathcal{D}, \alpha) = \mathcal{N}(x \mid m, \beta^{-1} + 1)$$

where m and  $\beta$  were computed in the previous problem.

**Approach 2.** We can directly look at the integral

$$p(x \mid \mathcal{D}, \alpha) = \int_{-\infty}^{\infty} p(x \mid \mu) p(\mu \mid \mathcal{D}, \alpha) d\mu$$
$$= \int_{-\infty}^{\infty} \mathcal{N}(x \mid \mu, 1) \mathcal{N}(\mu \mid m, \beta^{-1}) d\mu$$
$$= \int_{-\infty}^{\infty} \mathcal{N}(x - \mu \mid 0, 1) \mathcal{N}(\mu \mid m, \beta^{-1}) d\mu$$

This a convolution of two Gaussian densities — the result is a Gaussian density as well

$$= \mathcal{N}(x \mid m, \beta^{-1} + 1)$$

You can find the proof on Wikipedia https://en.wikipedia.org/wiki/Sum\_of\_normally\_distributed\_random\_variables#Proof\_using\_convolutions.

The two approaches are effectively identical, and both rely on two facts:

- 1.  $\mu$  is the location parameter of the normal distribution. That means that if  $p(x) = \mathcal{N}(x \mid \mu, \sigma^2)$  and y = x + a (for a fixed  $a \in \mathbb{R}$ ), then  $p(y) = \mathcal{N}(y \mid \mu + a, \sigma^2)$ .
- 2. the sum of two normally distributed RVs is a normally distributed RV