

#### **Eexam**

Place student sticker here

#### Note:

- During the attendance check a sticker containing a unique code will be put on this exam.
- This code contains a unique number that associates this exam with your registration number.
- This number is printed both next to the code and to the signature field in the attendance check list.

# **Mining Massive Datasets**

**Exam:** IN2323 / Retake **Date:** Monday 30<sup>th</sup> September, 2019

**Examiner:** Prof. Dr. Stephan Günnemann **Time:** 08:00 – 09:30

	P 1	P 2	Р3	P 4	P 5	P 6	P 7	P 8
I								

#### Working instructions

- This exam consists of 12 pages with a total of 8 problems.
   Please make sure that you received a complete copy of the exam.
- · You can earn 43 points.
- · Detaching pages from the exam is prohibited!
- · Allowed resources:
  - A4 sheet of handwritten notes (two sides)
  - no other materials (e.g. books, cell phones, calculators) are allowed!
- · Only write on the sheets given to you by supervisors. If you need more paper, ask the supervisors.
- · Last two pages can be used as scratch paper.
- All sheets (including scratch paper) have to be returned at the end.
- Only use a black or a blue pen (no pencils, red or green pens)!
- · Write your answers only in the provided solution boxes or the scratch paper.
- For problems that say "Justify your answer" or "Show your work" you only get points if you provide a valid explanation. Otherwise it's sufficient to only provide the correct answer.
- · Exam duration 90 minutes.

Left room from	to	/	Early submission at	

## Problem 1 AR models: stationarity (5 points)

Decide whether the following AR models are stationary or not. Everywhere  $\epsilon_t \sim \mathcal{N}(0, \sigma^2)$  with a positive  $\sigma$ .

Mark correct answers with a cross

X

To undo a cross, completely fill out the answer option To re-mark an option, use a human-readable marking

a) 
$$\mathcal{X}_t = c + 0.1 \mathcal{X}_{t-1} + \epsilon_t$$
 with some  $c \in \mathbb{R}$ 

- stationary for |c| > 0.1, otherwise non-stationary
- yes, always stationary
- no, always non-stationary

b)  $\mathcal{X}_t = -3 + 0.2\mathcal{X}_{t-1} - 0.01\mathcal{X}_{t-2} + c\epsilon_t$  with some  $c \in \mathbb{R} \setminus \{0\}$ 

- stationary for c > 0, otherwise non-stationary
- yes, always stationary
- no, always non-stationary

c)  $\mathcal{X}_t = 1 + 0.3\mathcal{X}_{t-1} - 0.03\mathcal{X}_{t-2} + 0.001\mathcal{X}_{t-3} + \epsilon_t$ 

- no, non-stationary
- yes, stationary

d)  $\mathcal{X}_t = -2 + 0.5 \mathcal{X}_{t-n} + \epsilon_t$  with some  $n \in \mathbb{N}$ 

- no, always non-stationary
- stationary for  $n \le 2$ , otherwise non-stationary
- yes, always stationary

e)  $\mathcal{X}_t = 2019 - \sum_{i=1}^n a^i \mathcal{X}_{t-i} + \epsilon_t$  with some  $n \in \mathbb{N}$ ,  $a \in \mathbb{R} \setminus \{0\}$ 

- stationary for |a| < 1, otherwise non-stationary
- $\square$  stationary for  $|a|^n < 2019$ , otherwise non-stationary
- stationary for n = 1, |a| < 1, otherwise non-stationary

# Problem 2 Hidden Markov Models (7 points)

Consider the following Hidden Markov Model where  $Z_t \in \{0,1\}$  are latent variables and  $X_t \in \{a,b\}$  are discrete observed variables. We parametrize the prior and transition probabilities  $P(Z_1 = i) = \pi_i$ ,  $P(Z_{t+1} = j | Z_t = i) = A_{ij}$  and  $P(X_t = j | Z_t = i) = B_{ij}$  by:

$$\pi = \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix}, \quad A = \begin{bmatrix} \alpha & 1-\alpha \\ 1/2 & 1/2 \end{bmatrix}, \quad B = \begin{bmatrix} 3/4 & 1/4 \\ 1/4 & 3/4 \end{bmatrix}$$

We assume we observed X = [a, b, a].

a) Compute $P(Z_2 X_1, X_2)$ and $P(Z_2 X_1, X_2, X_3)$ as a function of $\alpha$ .				

## Problem 3 RNNs & Word vectors (7 points)

You are solving a question-answering task. Given a context and a question, the goal is to find the answer **inside** the context. Bellow are two examples (1 and 2).

id	Context	Question	Answer
1	Mary was in the bathroom. Then she moved to the hallway.	Where is Mary?	hallway
2	John is in the hallway. Mary is there as well.	Where is Mary?	hallway

Assume that the question is represented with the vector  $\mathbf{q}$ . We want to know what is the probability that a word from the context is the answer. We decide to somehow represent every word  $\mathbf{w}_i$  with an embedding  $\mathbf{h}_i$  and pass it together with  $\mathbf{q}$  through a neural network to get the probabilities. The only thing left to do is to decide how to get  $\mathbf{h}_i$ . We propose two approaches: sliding window and RNN.

decide how to get $h_i$ . We propose two approaches: sliding window and RNN.	
a) <b>Sliding window</b> — Every word $w_i$ is represented with a pretrained word vector $\mathbf{v}_i$ . A sliding window of size 2 takes the neighbouring words and constructs the embedding for $w_i$ as a sum of vectors: $\mathbf{h}_i = \sum_{j=i-2}^{i+2} \mathbf{v}_j$ . Is it possible for this model to find the right answer in example 1? What about example 2? Justify.	
b) <b>RNN</b> — As an alternative we use an RNN that takes pretrained word vectors $\mathbf{v}_i$ from left to right and outputs $\mathbf{h}_i$ as a word embedding. Why is this model able to output the right answer in example 1? Explain why it could fail answering example 2?	
c) Propose another model that overcomes the shortcomings of the sliding window and the RNN. Describe what the input would be and how would you calculate the embedding $h_i$ . Explain why this model could work on both examples.	

# Problem 4 Deep Generative Model (5 points)

AutoEncoder 1	AutoEncoder 2	AutoEncoder 3
$oldsymbol{\epsilon}_i \sim \mathcal{N}(oldsymbol{x}_i, oldsymbol{I}_{d})$	$\mathbf{h}_i = f_{\boldsymbol{\theta}}(\mathbf{x}_i)$	$\boldsymbol{h}_i = f_{\boldsymbol{\theta}}(\boldsymbol{x}_i)$
$oldsymbol{h}_i = f_{oldsymbol{ heta}}(oldsymbol{\epsilon}_i)$	$oldsymbol{\epsilon}_i \sim \mathcal{N}(oldsymbol{h}_i, oldsymbol{l}_k)$	$oldsymbol{\epsilon}_i \sim \mathcal{N}(oldsymbol{0}_k, oldsymbol{I}_k)$
$ ilde{oldsymbol{x}}_i = g_{oldsymbol{\phi}}(oldsymbol{h}_i)$	$ ilde{\mathbf{x}}_i = g_{\phi}(\epsilon_i)$	$\tilde{\mathbf{x}}_i = g_{\phi}(\mathbf{h}_i + \epsilon_i)$
$\mathcal{L} = \sum_{i} \ \boldsymbol{x}_{i} - \tilde{\boldsymbol{x}}_{i}\ _{2}$	$\mathcal{L} = \sum_{i} \ \boldsymbol{x}_{i} - \tilde{\boldsymbol{x}}_{i}\ _{2}$	$\mathcal{L} = \sum_{i}   \boldsymbol{x}_{i} - \tilde{\boldsymbol{x}}_{i}  _{2}$
b in the above implementations? modify the pseudo code to implem AutoEncoder 1	Answer with Yes or No and provide nent the reparametrization trick.	e a justification. If the answe
AutoEncoder 2		
AutoEncoder 2  AutoEncoder 3		

a) You are given a pseudo code implementation of 4 different variants of an AutoEncoder. Here,  $\textbf{\textit{x}}_i \in \mathbb{R}^d$ 

b) Assume the same setup as in a). The model specified by the following pseudo code is <b>not well define</b> Specify the reason why, and modify the pseudo code such that the model becomes well-defined. In additional if you think it is <b>necessary</b> to use the reparametrization trick, please include it in your implementation.	
$egin{aligned} m{h}_i &= f_{m{ heta}}(m{x}_i) \ m{\epsilon}_i &\sim \mathcal{N}(m{0}_k,  extit{diag}(m{h}_i)) \ m{ ilde{x}}_i &= g_{m{\phi}}(m{\epsilon}_i) \ \mathcal{L} &= \sum_i \ m{x}_i - m{ ilde{x}}_i\ _2 \end{aligned}$	

Problem 5	Spectral clustering	(3 points)
-----------	---------------------	------------

0	
1	
2	
3	

Given is the following matrix  $\mathbf{M} \in \mathbb{R}^{9 \times 9}$ .

$$\mathbf{M} = \begin{bmatrix} 1 & 0 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & -1 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & -1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 2 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & -1 & 3 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 \end{bmatrix}$$

Write down the **exact** value of the three smallest eigenvalues  $\lambda_1$ ,  $\lambda_2$ ,  $\lambda_3$  of **M** and the respective eigenvectors  $\mathbf{x}_1$ ,  $\mathbf{x}_2$ ,  $\mathbf{x}_3$ .



### **Problem 6** Spectral clustering (3 points)



You are given an undirected graph G = (V, E). It is known that the second smallest eigenvalue of the unnormalized Laplacian L = D - W is equal to 10.

Let  $\phi(G)$  denote the best possible ratio cut achievable on the graph G

$$\phi(G) = \min_{S \subset V} \text{ ratio-cut}(S, \overline{S})$$

What are possible values of  $\phi(G)$  for the given graph? Select all that apply. Justify your answer.

- a) 1
- b) 2
- c) 4
- d) 8
- e) 16

## Problem 7 Ranking (5 points)

Given a graph G with 5 nodes,	assume that you have acce	ess to several topic-se	nsitive PageRank	vectors,
each pre-computed using a dif	ferent teleport set S, and th	ne <b>same (fixed)</b> telepo	rt parameter $\beta$ , 0 <	$\beta < 1$ .

- $\pi_{235} \in \mathbb{R}^5$ , with teleport set  $S = \{2, 3, 5\}$
- $\pi_{124} \in \mathbb{R}^5$ , with teleport set  $S = \{1, 2, 4\}$
- $\pi_{134} \in \mathbb{R}^5$ , with teleport set  $S = \{1, 3, 4\}$
- $\pi_3 \in \mathbb{R}^5$ , with teleport set  $S = \{3\}$

Assume that the random walker always teleports uniformly at random to each node in the teleport set.

Is it possible to compute each of the following PageRank vectors without access to the graph G, i.e. using only the above pre-computed vectors? If so, specify the exact equation as a function of  $\pi_{235}$ ,  $\pi_{124}$ ,  $\pi_{134}$  and  $\pi_3$ . If not, justify why not.

a) Is it possible to compute $\pi_{14} \in \mathbb{R}^5$ with teleport set $S = \{1,4\}$ ?	<u> </u>
b) Is it possible to compute $\pi_5 \in \mathbb{R}^5$ with teleport set $S = \{5\}$ ?	0 1
c) Is it possible to compute $\pi_1 \in \mathbb{R}^5$ with teleport set $S = \{1\}$ ?	
d) Is it possible to compute $\pi_w \in \mathbb{R}^5$ with teleport set $S = \{1, 2, 3, 4, 5\}$ , where we do not teleport to each node uniformly at random but rather with weights 0.2, 0.3, 0.1, 0.2, 0.2, respectively?	012

#### **Problem 8** Graph Neural Networks (8 points)

Given an unweighted, undirected graph G with adjacency matrix  $\mathbf{A} \in \{0,1\}^{N \times N}$  and node attribute matrix  $\mathbf{X} \in \mathbb{R}^{N \times D}$ , your task is to perform semi-supervised node classification with C classes using a graph convolutional network (GCN).

In matrix notation, a GCN with K layers is recursively defined as follows.

$$\mathbf{H}^{(0)} = \mathbf{X}$$

$$\mathbf{H}^{(k)} = \sigma^{(k)} \left( \tilde{\mathbf{A}} \mathbf{H}^{(k-1)} \mathbf{W}^{(k)} \right) \qquad \text{for } k \in 1, ..., K$$

That is,  $\mathbf{H}^{(K)} \in \mathbb{R}^{N \times C}$  contains the class predictions for **all nodes** stacked in a matrix. Here,  $\sigma^{(k)}$  is the ReLU(·) activation function for  $k \in \{1, ..., K-1\}$  and the softmax(·) function for the final (output) layer k = K.  $\mathbf{W}^{(k)}$  is the weight matrix of layer k.

 $\tilde{\mathbf{A}} \in \mathbb{R}^{N \times N}$  is a degree-normalized version of the adjacency matrix whose entries are

$$\tilde{\boldsymbol{A}}_{uv} = \begin{cases} \frac{1}{\sqrt{d_u d_v}} & \text{if } \boldsymbol{A}_{uv} = 1 \\ \frac{1}{d_u} & \text{if } u = v \\ 0 & \text{else,} \end{cases}$$

where  $d_u$  is the degree of node u.

	·			$\sigma^{(k)}$ for all layers.	
b) Assume you	hove a CCN with 2	lovoro i o K. 2 E	ravida tha nan ras	urajvo (uprollod) s	ypropion
That is write do	have a GCN with 3 bown the single-line e	equation of $\mathbf{H}^{(3)}$ in n	natrix form.	ursive (urirolled) e	expression
mat is, write or					

$\mathbf{A}_{uv}=1$ for $u=v$ and 0 else. $\mathbf{)}$ $\sigma^{(k)}(x)=x$ , i.e. identity activation function, for $k\in\{1,2\}$ art from the additional information in each situation, the models are identical to the GCN definition that single-line, matrix-form expression of $\mathbf{H}^{(3)}$ given the additional information providation. $\mathbf{H}^{(3)}=\mathbf{H}$		
The formation of the additional information in each situation, the models are identical to the GCN definitely the single-line, matrix-form expression of $H^{(3)}$ given the additional information providation.  For each situation, find one equivalent model in the table below. You may select each option of the property is a situation.  Recurrent neural network (RNN)   Linear regression   Feed-forward neural network (FFNN)   Label Propagation (LP)   Linear function   Deep Generative Model	$\mathbf{A}_{uv} = 1$ for $u = v$ and 0 else.	
The formation of the additional information in each situation, the models are identical to the GCN definitely the single-line, matrix-form expression of $H^{(3)}$ given the additional information providation.  For each situation, find one equivalent model in the table below. You may select each option of the property is a situation.  Recurrent neural network (RNN)   Linear regression   Feed-forward neural network (FFNN)   Label Propagation (LP)   Linear function   Deep Generative Model	$\sigma^{(k)}(x) = x$ , i.e. identity activation function,	for $k \in \{1,2\}$
Recurrent neural network (RNN) Linear regression Feed-forward neural network (FFNN) Label Propagation (LP) Linear function Deep Generative Model	lify the single-line, matrix-form expressio	tuation, the models are identical to the GC on of ${\it \textbf{H}}^{(3)}$ given the additional information
Recurrent neural network (RNN) Linear regression Feed-forward neural network (FFNN) Label Propagation (Linear function Deep Generative Mod	lify the single-line, matrix-form expressio	on of <b>H</b> <sup>(3)</sup> given the addi
Recurrent neural network (RNN)  Feed-forward neural network (FFNN)  Linear regression  Label Propagation (I  Linear function  Deep Generative Mo		
Recurrent neural network (RNN) Linear regression Feed-forward neural network (FFNN) Label Propagation (L Linear function Deep Generative Mo		
Recurrent neural network (RNN) Linear regression Feed-forward neural network (FFNN) Label Propagation (Linear function Deep Generative Mod		
Recurrent neural network (RNN) Linear regression Feed-forward neural network (FFNN) Label Propagation (LF Linear function Deep Generative Mod	reach cituation find an are to the control of the c	in the table balls
Feed-forward neural network (FFNN) Label Propagation (LP) Linear function Deep Generative Mode		ເກຣ ເສນເຍ ນຍເດW. <b>You m</b>
Feed-forward neural network (FFNN) Label Propagation (LP) Linear function Deep Generative Model		
Linear function Deep Generative Model	Recurrent neural network (PNINI)	Linear regression
Logistic regression on pre	Feed-forward neural network (FFNN)	Label Propagation (LP)
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP) Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP)  Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP)  Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP)  Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP)  Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP)  Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP)  Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP)  Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP)  Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP) Deep Generative Model
	Feed-forward neural network (FFNN) Linear function	Label Propagation (LP) Deep Generative Model

Additional space for solutions-clearly mark the (sub)problem your answers are related to and strike out invalid solutions.

