

**Eexam**

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## Machine Learning for Graphs and Sequential Data

**Exam:** IN2323 / Endterm

**Date:** Wednesday 5<sup>th</sup> August, 2020

**Examiner:** Prof. Dr. Stephan Günnemann

**Time:** 11:30 – 12:45

### Working instructions

- This exam consists of **14 pages** with a total of **10 problems**.  
Please make sure now that you received a complete copy of the exam.
- The total amount of achievable credits in this exam is 43 credits.
- Detaching pages from the exam is prohibited.
- Allowed resources:
  - all materials that you will use on your own (lecture slides, calculator etc.)
  - **not allowed are any forms of collaboration between examinees and plagiarism**
- You have to sign the code of conduct.
- Make sure that the **QR codes are visible** on every uploaded page. Otherwise, we cannot grade your exam.
- Only write on the provided sheets, **submitting your own additional sheets is not possible**.
- Last two pages can be used as scratch paper.
- All sheets (including scratch paper) have to be submitted to the upload queue. Missing pages will be considered empty.
- **Only use a black or blue color (no red or green)!**
- Write your answers only in the provided solution boxes or the scratch paper.
- **For problems that say "Justify your answer" you only get points if you provide a valid explanation.**
- **For problems that say "Prove" you only get points if you provide a valid mathematical proof.**
- If a problem does not say "Justify your answer" or "Prove" it's sufficient to only provide the correct answer.
- Exam duration - 75 minutes.

Left room from \_\_\_\_\_ to \_\_\_\_\_ / Early submission at \_\_\_\_\_

## Problem 1 Normalizing Flows (4 credits)

We consider two transformations  $f_1(\mathbf{z}) = \begin{bmatrix} z_1 \\ z_2^{1/3} \end{bmatrix}$  and  $f_2(\mathbf{z}) = \begin{bmatrix} z_1(|z_2| + 1) \\ z_2 \end{bmatrix}$  from  $\mathbb{R}^2$  to  $\mathbb{R}^2$ .

The respective inverse transformation are  $f_1^{-1}(\mathbf{x}) = \begin{bmatrix} x_1 \\ x_2^3 \end{bmatrix}$  and  $f_2^{-1}(\mathbf{x}) = \begin{bmatrix} \frac{x_1}{|x_2|+1} \\ x_2 \end{bmatrix}$ .

The respective Jacobians are

$$J_{f_1} = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{3}z_2^{-\frac{2}{3}} \end{bmatrix} \quad J_{f_2} = \begin{bmatrix} |z_2| + 1 & \text{sign}(z_2)z_1 \\ 0 & 1 \end{bmatrix}$$

$$J_{f_1^{-1}} = \begin{bmatrix} 1 & 0 \\ 0 & 3x_2^2 \end{bmatrix} \quad J_{f_2^{-1}} = \begin{bmatrix} \frac{1}{|x_2|+1} & \frac{-\text{sign}(x_2)x_1}{(|x_2|+1)^2} \\ 0 & 1 \end{bmatrix}$$

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3 ☐  
4 ☐

We assume a Gaussian base distribution  $p_1(\mathbf{z}) = \mathcal{N}(\mathbf{0}, \mathbf{I})$ . We observed one point  $\mathbf{x}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ .

We propose to stack the transformations  $f_1, f_2$  to transform the base distribution  $p_1$  in the distribution  $p_2$  with normalizing flows. Compute the likelihood for  $\mathbf{x}$  under the transformed distribution  $p_2$  if the order of transformations is  $f_1$  followed by  $f_2$ .

*Hint: You might use the density of the unit variate Gaussian  $p = \mathcal{N}(0, 1)$  at the following points:  $p(1/2) = 0.3521$ ,  $p(1/3) = 0.3774$ ,  $p(1/9) = 0.3965$ ,  $p(5) = 1.4867e^{-06}$ ,  $p(8) = 5.0523e^{-15}$ ,  $p(10) = 7.6946e^{-23}$*

## Problem 2 Variational Inference (5 credits)

We are performing variational inference in some latent variable model  $p_\theta(x, z)$  using the following family of variational distributions  $\mathcal{Q}_1 = \{\mathcal{N}(z|\phi, 1) : \phi \in \mathbb{R}\}$ .

a) Assume that the variational distribution  $q \in \mathcal{Q}_1$  is fixed, and we are trying to maximize the ELBO w.r.t.  $\theta$  using gradient ascent. Is it necessary to use the reparametrization trick in this case? If yes, explain how to do it for our family of distributions  $\mathcal{Q}_1$ ; if not, provide a justification.

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☐ 1  
☐ 2  
☐ 3

b) Consider another family of distributions  $\mathcal{Q}_2 = \{\mathcal{N}(z|0, s^2) : s \in (0, \infty)\}$ . Which of the following statements is true? Justify your answer.

☐ 0  
☐ 1  
☐ 2

1.  $\max_{\theta, q \in \mathcal{Q}_1} \text{ELBO}(\theta, q) < \max_{\theta, q \in \mathcal{Q}_2} \text{ELBO}(\theta, q)$
2.  $\max_{\theta, q \in \mathcal{Q}_1} \text{ELBO}(\theta, q) = \max_{\theta, q \in \mathcal{Q}_2} \text{ELBO}(\theta, q)$
3.  $\max_{\theta, q \in \mathcal{Q}_1} \text{ELBO}(\theta, q) > \max_{\theta, q \in \mathcal{Q}_2} \text{ELBO}(\theta, q)$
4. It's impossible to tell without additional information.

### Problem 3 Robustness of Machine Learning Models (6 credits)

Suppose we have trained a binary classifier  $f : \mathbb{R}^d \rightarrow \{0, 1\}$  and want to certify its robustness via randomized smoothing. Therefore, the *smoothed classifier*  $g_{\sigma^2}(\mathbf{x}) = \mathbb{E} [\mathbb{I}[f(\mathbf{x} + \varepsilon) = 1]]$ , where  $\varepsilon \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I})$ .

Fact:  $\Phi^{-1}(g_{\sigma^2}(\mathbf{x}))$  is  $1/\sigma$ -**Lipschitz** w.r.t.  $\mathbf{x}$  and the  $L_2$  norm, where  $\Phi(z)$  denotes the cumulative distribution function (CDF) of the standard normal distribution.

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1 ☐  
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3 ☐  
4 ☐
- a) **Using the above fact about the Lipschitz-continuity** of  $\Phi^{-1}(g_{\sigma^2}(\mathbf{x}))$ , show that the largest certifiable  $L_2$  radius  $r$  around a sample  $\mathbf{x}$  is identical to the result shown in the lecture. More precisely, show that

$$r = \sigma \Phi^{-1}(g_{\sigma^2}(\mathbf{x})).$$

Hint: You may assume we can evaluate  $g_{\sigma^2}(\mathbf{x})$  in closed form and you may use the following results:  $\lim_{z \rightarrow 0} \Phi^{-1}(z) = -\infty$ ,  $\Phi^{-1}(0.5) = 0$ ,  $\lim_{z \rightarrow 1} \Phi^{-1}(z) = \infty$ .

- 0 ☐  
1 ☐  
2 ☐
- b) A fellow student has a promising idea: by letting  $\sigma \rightarrow \infty$  we can make the Lipschitz constant of the smoothed classifier arbitrarily small, leading to arbitrarily large certifiable radii, i.e. a very robust model. Is this a good idea? Why or why not?

## Problem 4 Markov Property (3 credits)

We consider the following sequences of random variables  $U_0, U_1, \dots, U_t$ .

- a)  $U_t = \begin{bmatrix} X_t \\ Z_t \end{bmatrix}$  where  $X_t$  are observed variables and  $Z_t$  are latent variables of an Hidden Markov Model. Does the sequence of variables  $U_t$  fulfill the Markov property i.e.  $P(U_t|U_{t-1}) = P(U_t|U_{t-1}, \dots, U_0)$  ? Justify your answer.

☐ 0  
☐ 1

- b) We consider an AR(p) process  $X_t$ . Under what condition on  $p$  and  $k$  does the sequence of variables  $U_t = [X_{t-1}, \dots, X_{t-k}]$  fulfill the Markov property i.e.  $P(U_t|U_{t-1}) = P(U_t|U_{t-1}, \dots, U_0)$  ? Justify your answer.

☐ 0  
☐ 1

- c) We consider a recurrent neural network which produces  $X_t$ . Does the sequence of variables  $U_t = X_t$  fulfill the Markov property i.e.  $P(U_t|U_{t-1}) = P(U_t|U_{t-1}, \dots, U_0)$  ? Justify your answer.

☐ 0  
☐ 1

## Problem 5 Markov Chain (3 credits)

0 ☐  
1 ☐  
2 ☐  
3 ☐

We consider a Markov chain  $X_t$  in  $\{1, C\}$  with parameters  $\pi, \mathbf{A}$ . We assume we observed the sequence  $S_k = [\underbrace{v_0, \dots, v_0}_{k \text{ times}}, \underbrace{v_1, \dots, v_1}_{k \text{ times}}, \dots, \underbrace{v_T, \dots, v_T}_{k \text{ times}}]$  where each value is observed  $k$  times. The parameter  $k$  can be seen as a discretization parameter of the time space.

Compute the likelihood of the sequence under the parameters  $\pi, \mathbf{A}$  i.e.  $P_{\pi, \mathbf{A}}(S_k)$ . What happens to this quantity if you increase the discretization parameter from  $k$  to  $k' > k$  but keep the same model parameter  $\pi, \mathbf{A}$  ?

## Problem 6 Temporal Point Process (6 credits)

Consider an inhomogeneous Poisson process (IPP) on the interval  $[0, 4]$  with the intensity function

$$\lambda(t) = \begin{cases} a & \text{if } t \in [0, 3] \\ b & \text{if } t \in (3, 4] \end{cases}$$

where  $a > 0$ ,  $b > 0$  are some positive parameters.

a) Assume that you observed a sequence of events  $\{0.2, 1.0, 1.5, 2.9, 3.1, 3.8\}$  generated by the above IPP. What is the maximum likelihood estimate of the parameters  $a$  and  $b$ ?

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☐ 1  
☐ 2  
☐ 3  
☐ 4

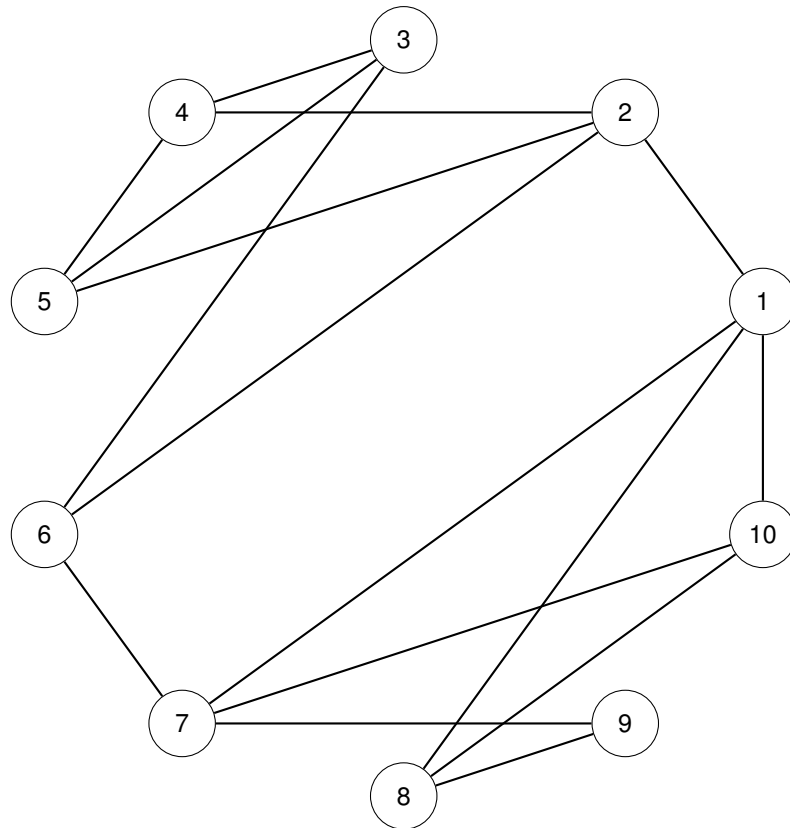
b) Assume that  $a = 1$  and  $b = 5$ . What is the expected number of events generated by the IPP in this case?

☐ 0  
☐ 1  
☐ 2

## Problem 7 Clustering with the Planted Partition Model (4 credits)

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1	<input type="checkbox"/>
2	<input type="checkbox"/>
3	<input type="checkbox"/>
4	<input type="checkbox"/>

The following graph has been generated from a planted partition model with in-community edge probability  $p$  and between-community edge probability  $q$ .



**Assuming**  $p < q$ , find the maximum likelihood community assignments under a PPM.

Give your solution as two sets of node labels making up the two discovered communities. Justify your answer.



## Problem 8 PageRank in a Wheel (6 credits)

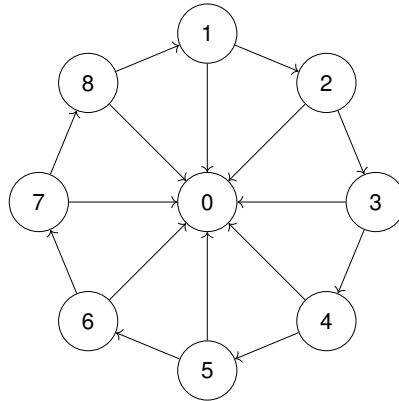


Figure 8.1: Example of a directed wheel graph with  $n + 1 = 9$  nodes

Consider a directed graph of size  $n + 1$  with a cycle of  $n$  nodes and an additional central node that every other node connects to (see figure). So we have a graph with node set  $\mathcal{V} = \{0, 1, \dots, n\}$  and edge set

$$\mathcal{E} = \{(i, i + 1) \mid i \in \{1, \dots, n - 1\}\} \cup \{(n, 1)\} \cup \{(i, 0) \mid i \in \{1, \dots, n\}\}.$$

We want to compute the PageRank scores with a link-follow probability of  $\beta$  (a teleport probability of  $1 - \beta$ ) and some arbitrary teleport vector  $\pi$ ,  $\sum_{i=0}^n \pi_i = 1$ . Note that we index  $\pi$  from 0 to  $n$ .

We define the predecessor function  $\text{pa}$  as the index of the predecessor of a node in the directed cycle, i.e.

$$\text{pa}(1) = n \quad \text{and} \quad \text{pa}(i) = i - 1 \quad \forall i \in \{2, \dots, n\}.$$

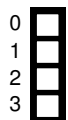
You can write  $\text{pa}^k(i)$  for the  $k$ -th predecessor of node  $i$ , i.e.  $\text{pa}^3(i) = \text{pa}(\text{pa}(\text{pa}(i)))$  and  $\text{pa}^0(i) = i$ .

a) Set up the PageRank equations for all nodes in scalar form, i.e. each  $r_i$  separately instead of matrix form.

0  
1  
2

b) Why is this graph problematic for PageRank without random teleportation ( $\beta = 1$ )?

0  
1

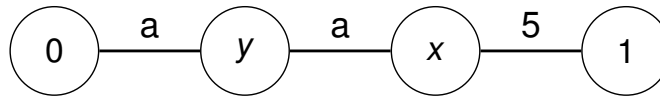


c) Show that the PageRank for node  $i \in \{1, \dots, n\}$  in the outer cycle is given by

$$r_i = \frac{(1 - \beta)}{1 - \left(\frac{\beta}{2}\right)^n} \sum_{j=0}^{n-1} \left(\frac{\beta}{2}\right)^j \pi_{\text{pal}(i)}.$$

## Problem 9 Label Propagation (4 credits)

Consider the following graph



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<input type="checkbox"/>	2
<input type="checkbox"/>	3
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The nodes labeled 0 and 1 are observed and from class 0 and 1, respectively. One edge has a fixed weight, the other two have a variable edge weight of  $a \geq 0$ . The two center nodes are unobserved and we call their labels  $x$  and  $y$ .

We want to predict classes for the two center nodes that minimize the Label Propagation objective exactly,

$$\frac{1}{2} \sum_{ij} w_{ij} (y_i - y_j)^2$$

where  $W$  is the weighted adjacency matrix and  $y_i, y_j$  are the labels of the nodes.

Find the set of all possible edge weights  $a$  that guarantee that node  $x$  is assigned to class 0. Justify your answer.

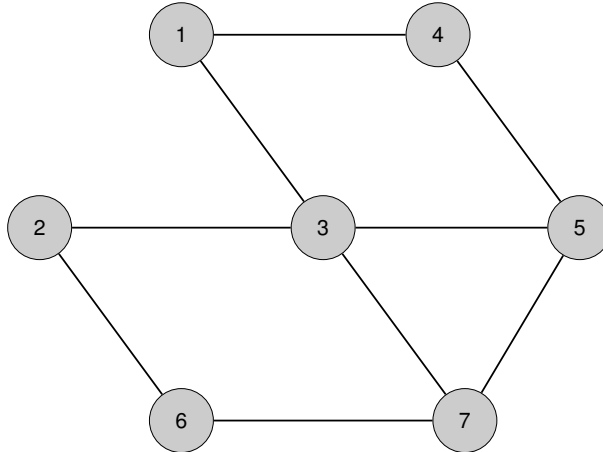
## Problem 10 Adversarial Attacks on Graph Neural Networks (2 credits)

Suppose you are given the following two-layer graph neural network.

$$f(\mathbf{A}, \mathbf{X}) = \mathbf{Z} = \text{Softmax}(\hat{\mathbf{A}} \text{ReLU}(\hat{\mathbf{A}} \mathbf{X} \mathbf{W}_1) \mathbf{W}_2)$$

$\mathbf{X} \in \mathbb{R}^{N \times D}$  are the node features,  $\mathbf{Z}$  are the node predictions,  $\mathbf{W}_x$  are weight matrices of appropriate dimensions and  $\hat{\mathbf{A}} = \tilde{\mathbf{D}}^{-\frac{1}{2}} \tilde{\mathbf{A}} \tilde{\mathbf{D}}^{-\frac{1}{2}}$  is the propagation matrix as defined for GCNs. Here,  $\tilde{\mathbf{A}} = \mathbf{A} + \mathbf{I}$ , where  $\mathbf{A}$  is the adjacency matrix and  $\mathbf{I}$  is the identity matrix, and  $\tilde{\mathbf{D}}$  is a diagonal matrix of node degrees  $\tilde{D}_{ii} = \sum_j \tilde{A}_{ij}$ .

The model was trained for the task of semi-supervised node classification, and we want to predict a class  $c$  for node 6 in the following graph  $\mathbf{A}$ :



0 1 a) An adversary with complete knowledge about the graph  $\mathbf{A}$  and the trained model  $f(\mathbf{A}, \mathbf{X})$  may delete one edge to perturb the prediction for node 6. Deleting which of the following edges would lead to a greater change to the prediction for node 6? Justify your answer.

1. The edge connecting node 5 and 7
2. The edge connecting node 3 and 5
3. There is not enough information to determine which deletion leads to a greater change.

0 1 b) Assume we instead have a Personalized Propagation of Neural Predictions (PPNP) model instead of the two-layer GCN. How does this affect your choice? Justify your answer.

**Additional space for solutions—clearly mark the (sub)problem your answers are related to and strike out invalid solutions.**

This image shows a full page of blank graph paper. The grid consists of small, equal-sized squares formed by thin gray lines. There are 20 columns and 20 rows of squares, creating a total of 400 square units. The grid covers the entire area of the page, leaving no margins or other markings.

