Problem 1: The similarity in the low dimensional space is defined as:

$$q_{ij} = \frac{\left(1 + \|y_k - y_j\|^2\right)^{\frac{1}{2}}}{\sum_k \sum_{k \neq l} \left(1 + \|y_k - y_l\|^2\right)^{-1}}$$

The objective is to obtain a low-dimensional projection capturing the similarity structure of the highdimensional data. This is achieved via optimizing the Kullback-Leibler divergence

$$C = \mathrm{KL}(P||Q) = \sum_i \sum_{j \neq \underline{i}} p_{ij} \log \frac{p_{ij}}{q_{ij}}$$

Please derive the gradient  $\frac{\partial C}{\partial y_s}$  for t-SNE for the coordinate  $y_s$  in the low dimensional space. Please note that this gradient can be used to update  $y_s$  with first-order methods.

Arguably, the most difficult part is to keep track of  $y_s$  in various sums. To simplify this we denote Arguably, the most difficult part is to differ the intermediate distance term  $d_{ij} = 1 + ||y_i - y_j||^2$ .

Next, we use the chain rule on C, so that we can take the derivative with respect to the individual "interactions"  $d_{ij}$  instead of the coordinate  $y_s$ .

$$\begin{split} \frac{\partial C}{\partial y_s} &= \frac{\partial C(d(y))}{\partial y_s} \\ &= \sum_i \sum_j \frac{\partial C}{\partial d_{ij}} \frac{\partial d_{ij}}{\partial y_s} \end{split}$$

 $\frac{\partial d_{ij}}{\partial y_s}$  is only non-zero if either i = s or j = s. Furthermore,  $d_{ij} = d_{ji}$ .

$$=2\sum_{j}\frac{\partial C}{\partial d_{sj}}\frac{\partial d_{sj}}{\partial y_{s}}$$

At this point we can already compute  $\frac{\partial d_{sj}}{\partial y_s}$ 

$$=4\sum_{i}(y_{s}-y_{j})\frac{\partial C}{\partial d_{sj}}$$

Now we are left with computing the gradient of C with respect to some  $d_{nm}$ .

$$\begin{split} \frac{\partial C}{\partial d_{nm}} &= \frac{\partial}{\partial d_{nm}} \left[ \sum_{i} \sum_{j \neq i} p_{ij} \log \frac{p_{ij}}{q_{ij}} \right] \\ &= \underbrace{\partial}_{\partial d_{nm}} \left[ \sum_{i} \sum_{j \neq i} p_{ij} \log \frac{p_{ij}}{q_{ij}} \right] \end{split}$$

Linearity of differentiation and p is constant with respect to d.

$$= -\sum_i \sum_{j \neq i} p_{ij} \frac{\partial \log q_{ij}}{\partial d_{nm}}$$

Expand the definition of  $q_{ij}$ .

$$\begin{split} &= -\sum_{i} \sum_{j \neq i} p_{ij} \frac{\partial}{\partial d_{nm}} \left[ \log \frac{d_{ij}^{-1}}{\sum_{k} \sum_{k \neq l} d_{kl}^{-1}} \right] \\ &= -\sum_{i} \sum_{j \neq i} p_{ij} \frac{\partial}{\partial d_{nm}} \left[ \log d_{ij} - \log \sum_{k} \sum_{k \neq l} d_{kl}^{-1} \right] \\ &= \sum_{i} \sum_{j \neq i} p_{ij} \frac{\partial \log d_{ij}}{\partial d_{nm}} + \sum_{i} \sum_{j \neq i} p_{ij} \frac{\partial}{\partial d_{nm}} \log \sum_{k} \sum_{k \neq l} d_{kl}^{-1} \end{split}$$

 $\frac{\partial \log d_{ij}}{\partial d_{nm}}$  is only non-zero for i = n and j = m.

$$= p_{nm}d_{nm}^{-1} + \sum_{i} \sum_{j \neq i} p_{ij} \frac{1}{\sum_{k} \sum_{k \neq l} d_{kl}^{-1}} \frac{\partial}{\partial d_{nm}} \sum_{k} \sum_{k \neq l} d_{kl}^{-1}$$

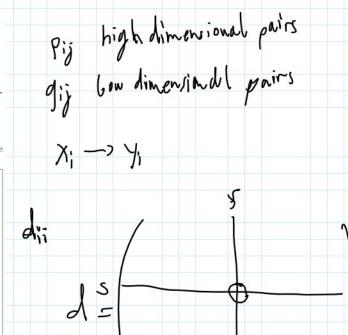
The same is true for  $\frac{\partial d_{kl}^{-1}}{\partial d_{mm}}$ 

$$\begin{split} &= p_{nm} d_{nm}^{-1} + \sum_{i} \sum_{j \neq i} p_{ij} \frac{1}{\sum_{k} \sum_{k \neq l} d_{kl}^{-1}} \frac{\partial d_{nm}^{-1}}{\partial d_{nm}} \\ &= p_{nm} d_{nm}^{-1} - \frac{1}{\sum_{k} \sum_{k \neq l} d_{kl}^{-1}} d_{nm}^{-2} \underbrace{\sum_{i} \sum_{j \neq i} p_{ij}}_{p_{ij}} \end{split}$$

 $\sum_{i}\sum_{j\neq i}p_{ij}=1$  and we can also find the definition of  $q_{nm}$  in there.

$$\begin{split} &= p_{nm} d_{nm}^{-1} \cdot \underbrace{\begin{pmatrix} d_{nm}^{-1} \\ \sum_k \sum_{k \neq l} d_{kl}^{-1} \end{pmatrix}}^{l-1} t_{nm}^{-1} \\ &= (p_{nm} - q_{nm}) \cdot \underbrace{d_{nm}^{-1}}_{l-1} \end{split}$$
 Finally, we plug this result into  $\frac{\partial C}{\partial y_s}$  and resolve the definition of  $d_{sj}$ .

$$\frac{\partial C}{\partial y_s} = 4\sum_j (y_s - y_j) \frac{\partial C}{\partial d_{sj}}$$



$$= 4 \sum_{j} (y_s - y_j) (p_{sj} - q_{sj}) d_{sj}^{-1}$$
  
= 
$$4 \sum_{j} (y_s - y_j) (p_{sj} - q_{sj}) (1 + ||y_s - y_j||^2)^{-1}$$

**Problem 2:** We train a linear autoencoder to D-dimensional data. The autoencoder has a single K-dimensional hidden layer, there are no biases, and all activation functions are identity  $(\sigma(x) = x)$ .

- Why is it usually impossible to get zero reconstruction error in this setting if K < D?
- $\bullet$  Under which conditions is this possible?

We have  $f(x) = XW_1W_2$  where X is the data matrix and the dimensions of the weight matrices are  $D \times K$  for  $W_1$  and  $K \times D$  for  $W_2$ .

The final multiplication  $W_2$  brings points from K-dimensions up into D-dimensions but the points will still all be in a K-dimensional linear subspace. Unless the data happen to lie exactly in a K-dimensional linear subspace, they can't be exactly fitted.