### Memformer

A Memory Guided Transformer for Time Series Forecasting

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## 1. Introduction

# 2. Methodology

#### **Instance normalization**

- Normalize within historical horizon only
- Mitigates the issue of internal covariate shift
- Allows model to effectively grasp the intricate temporal dynamics inherent in time series

$$H' = (H - \mu)/\sqrt{(\sigma^2 + c)}$$
, where

H is the historical horizon

 $\mu$  is the mean

 $\sigma$  is the variance

c ensures numerical stability

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- Mistake in variance?
  - $\bullet$   $\sigma$  is conventional notation for standard deviation
  - $\sigma^2$  is conventional notation for variance

- Explored code to find answer
- data\_provider/data\_loader.py
  - Only place anything related to loading data happens
  - Dataset\_ETT\_hour, Dataset\_ETT\_minute, Dataset\_Custom, Dataset\_Pred

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from sklearn.preprocessing import StandardScaler
class ...:
    def __read_data__(self):
        self.scalar = StandardScaler()
        if self.scale:
            self.scaler.fit(train_data.values)
            data = self.scaler.transform(df_data.values)
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- They fit on training data
- Normalize entire dataset with  $\mu$  and  $\sigma$  from training data

### What are they actually doing?

Preprocessing

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 is the mean

$$\sigma$$
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StandardScaler

$$z = (x - \mu)/\sigma$$
, where

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$$\sqrt{\sigma^2} = \sigma$$

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- Fit on training data, normalize entire dataset  $\rightarrow$  global normalization

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• 41

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Preprocessing StandardScaler 
$$H' = (H - \mu)/\sqrt{(\sigma^2 + c)}, \text{ where} \qquad z = (x - \mu)/\sigma, \text{ where}$$
  $H$  is the historical horizon  $T$  is the sample  $T$  is the mean  $T$  is the wariance  $T$  is the standard deviation  $T$   $T$  is the standard deviation  $T$  is t

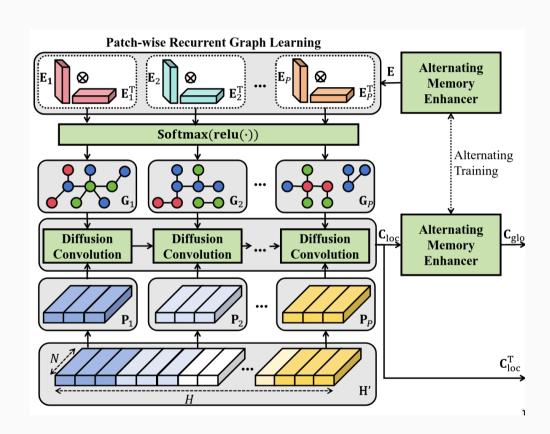
- We know that  $\sqrt{\sigma^2} = \sigma$
- Essentially same formula, except constant
- Fit on training data, normalize entire dataset  $\rightarrow$  global normalization
- None of the stated benefits of instance normalization

#### **Architecture**

Upper part  $\rightarrow$  dynamic correlation

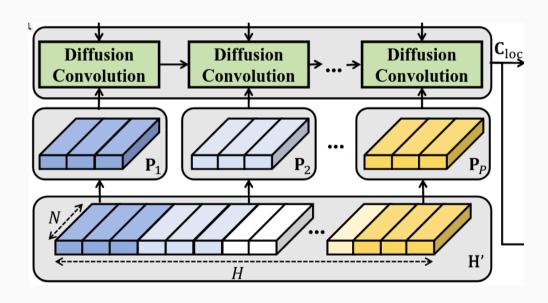
Lower part  $\rightarrow$  normalized data

Output  $\rightarrow$  enriched input features



#### **Normalized Data**

- Normalized as described earlier
  - Not what the paper actually states

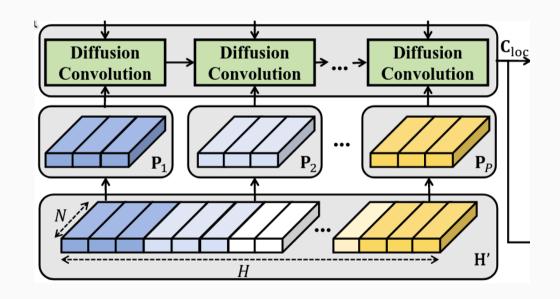


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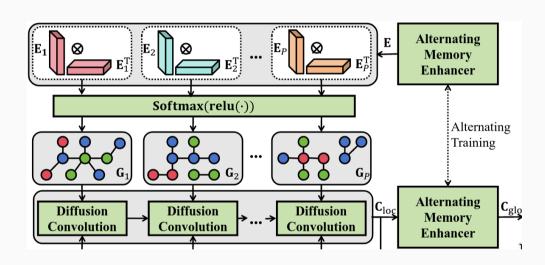
#### **Patches**

- H' is split into p patches
- Stride S
- Size T
- If  $S \geq T$  patches are disjoint
- If S < T patches overlap
  - Common elements for adjacent patches



#### **AME**

- Provides local memory embedding
  - ► These are learnable parameters
- Consistant local memory for patch  $P_i$
- Matrix product of  $E_i \otimes E_i^T$ 
  - Similarity matrix for variables in  $P_i$

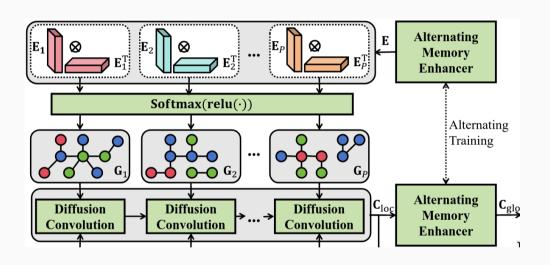


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#### ReLU + Softmax

- ReLU eliminates negative values
  - Removes negative correlations
- Softmax scales into influence scores



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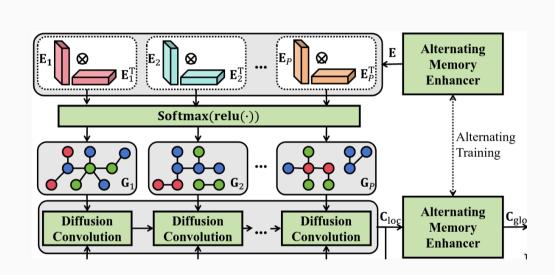
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### Graph

- Translates influence scores into graph
- Captures connection between variables
  - Dynamic correlations



#### **Diffusion Convolution**

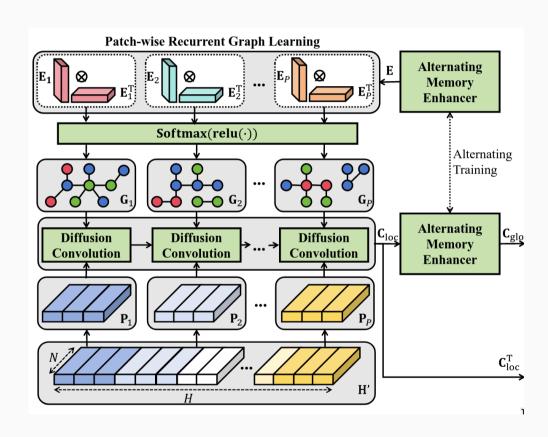
- Normalized data is adjusted based on connections in graph
- Numeric values "diffuse" into neighbours
  - Not only immediate neighbours
- Spatially relates data based on connections

#### **Gated Recurrent Unit**

- Forwards information from  $P_i$  to  $P_{i+1}$
- Temporally relates data in a sequence

### Output

- Enriched input features
- Spatial → dynamic correlations
- Temporal  $\rightarrow$  GRU



## 3. Results