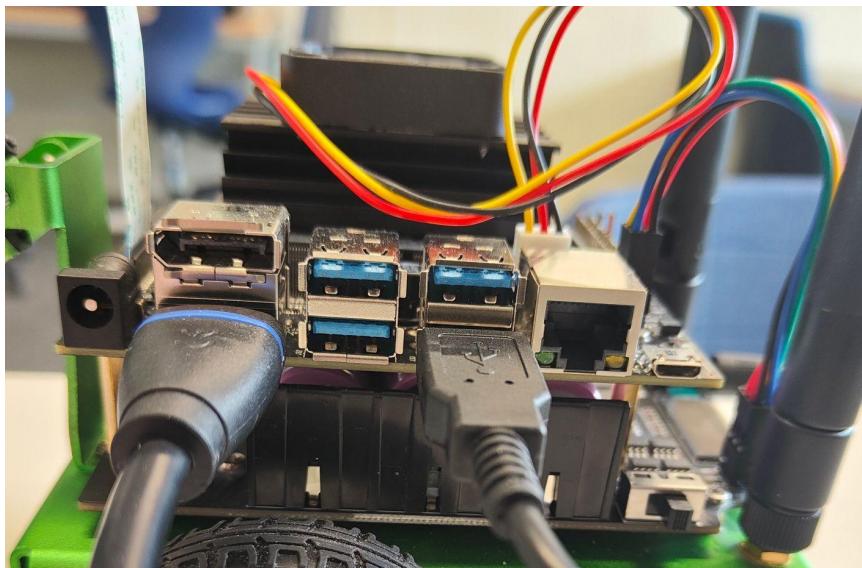
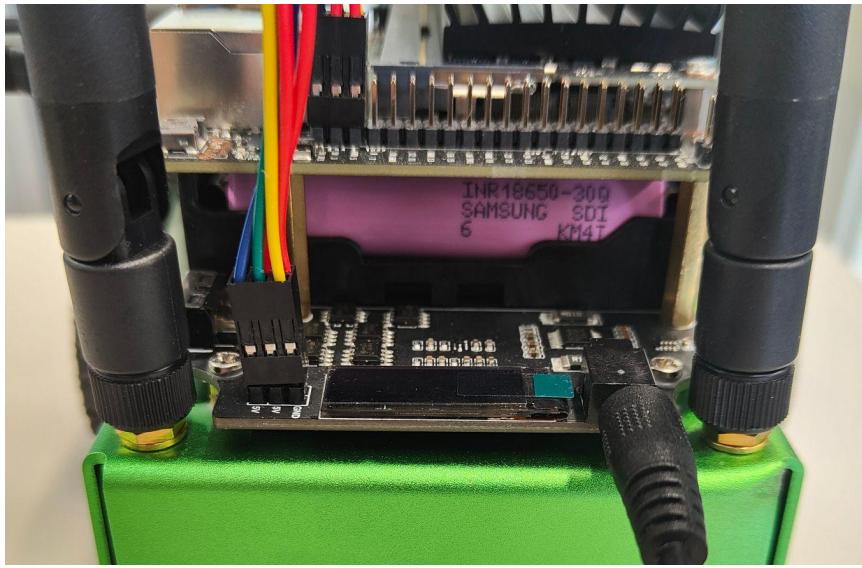


Quick Start: Bilder

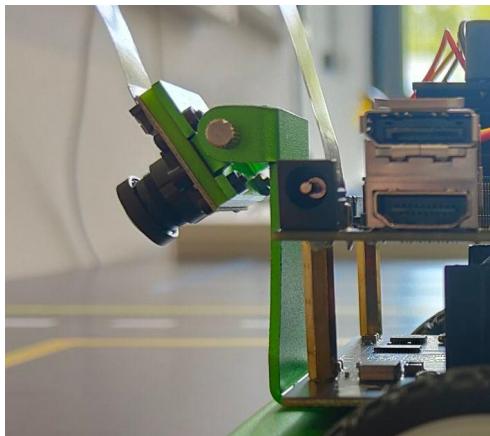
HDMI & USB-Tastatur Anschluss:



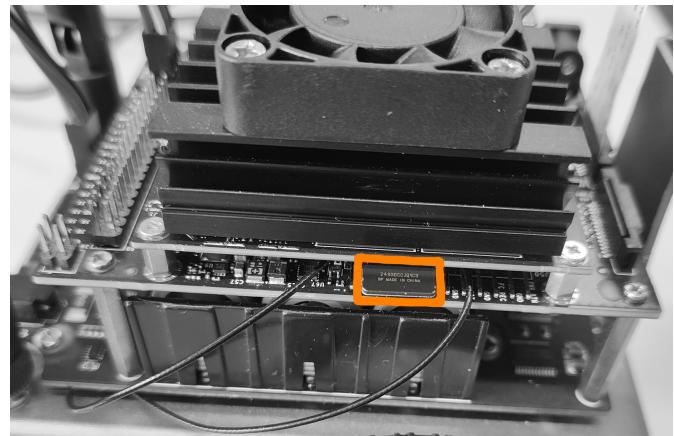
JetBot Display und Netzteil Anschluss:



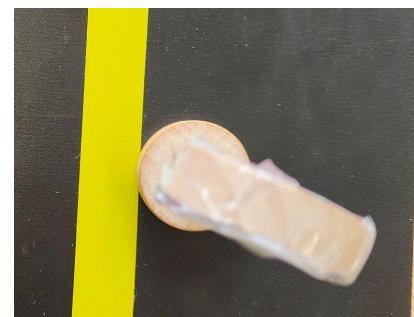
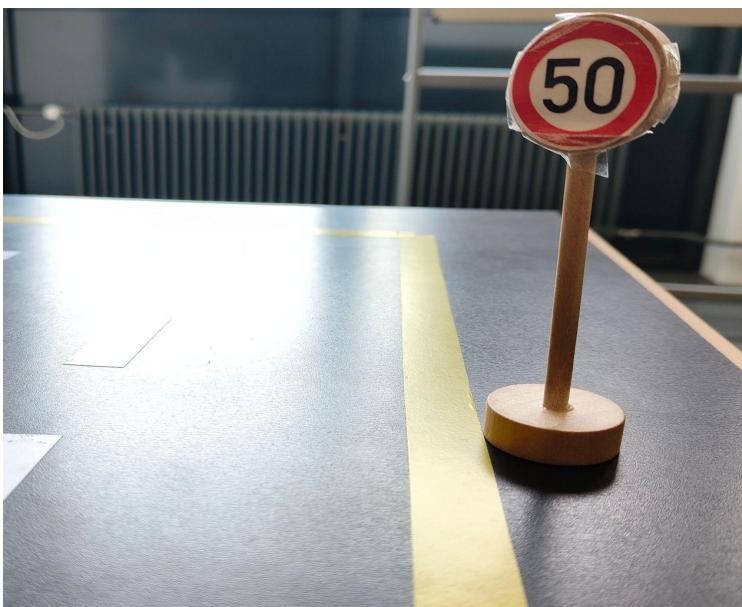
Optimaler Kamerawinkel:



microSD-Slot:



Optimale Schilder-Position und -Ausrichtung



Jupyter Notebook:

jupyter LiveDemo_object_oriented (unsaved changes)

File Edit View Insert Cell Kernel Widgets Help

Interrupt [] [] ▾

Restart [] []

Restart & Clear Output

Restart & Run All Restart the Kernel and clear all output

Reconnect

Shutdown

Change kernel ▾

Demo JetBo

This small demo represents the basic capabilities of the JetBo

For optimal usage, adjust the camera angle to ~55° and consider proper lighting.

Kernel Status:



Logout

| Python 3 (ipykernel) O