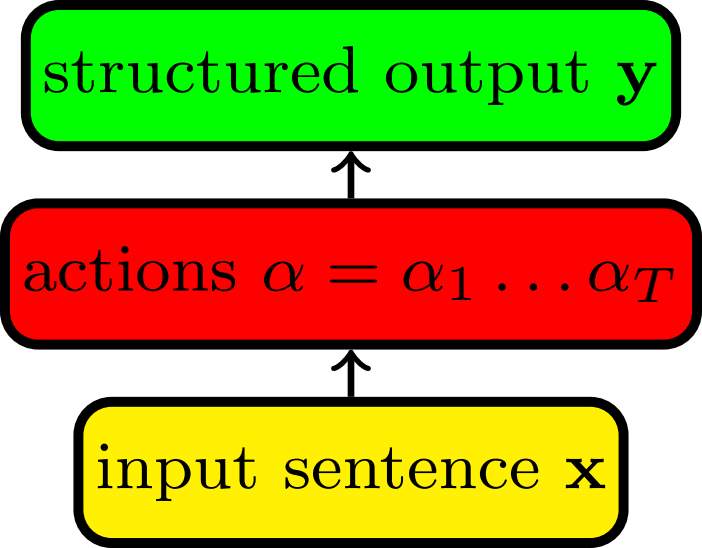
structured output $\mathbf{y}$
actions $\alpha = \alpha_1 \ldots \alpha_T$
input sentence $\mathbf{x}$