# The Indian Buffet Process: An Introduction and Review T. L. Griffiths, and Z. Ghahramani.

Andrea Teruzzi

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#### Latent Class Models

• Assume we have N row vectors (objects)  $\mathbf{x}_i$  each having D observable properties and the matrix  $\mathbf{X} = [\mathbf{x}_1^{\top} \mathbf{x}_2^{\top} \dots \mathbf{x}_N^{\top}]$  to indicate the properties of all the objects.



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- We assign each  $\mathbf{x}_i$  to a single class  $c_i$  and we indicate with  $\mathbf{c}$  the class assignment of each object.
- The statistical model for a latent class model consists in specifying

$$P(\mathbf{c})$$

$$p(\mathbf{X}|\mathbf{c})$$

 Mixture models assume that the assignment of an object to a class is independent of the assignments of all other objects. In finite mixture model we have K classes.

$$P(\mathbf{c}) = \prod_{i=1}^{N} P(c_i | \theta) = \prod_{i=1}^{N} \theta_{c_i},$$

with  $\theta$  multinomial distribution and  $\theta_k$  the probability of class k under that distribution (i.e.  $\sum_{k=1}^{K} \theta_k = 1$ )

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• Under this assumption:

$$p(\mathbf{X}|\mathbf{c}) = \prod_{i=1}^{N} \sum_{k=1}^{K} p(\mathbf{x}_i|c_i = k)\theta_k,$$

that is a mixture of the K class distributions  $p(\mathbf{x}_i | c_i = k)$ , with  $\theta_k$  determining the weight of class k.

• In Bayesian modeling,  $\theta$  is assumed to follow a prior distribution  $p(\theta)$ , with conjugate choice the **Dirichlet distribution over K classes** with parameters  $\alpha_1, \alpha_2, \ldots, \alpha_K$ .

$$p(\theta) = \frac{\prod_{k=1}^{K} \theta_k^{\alpha_k - 1}}{D(\alpha_1, \alpha_2, \dots, \alpha_K)},$$

with normalizing constant  $D(\alpha_1, \alpha_2, \dots, \alpha_K)$  define as

$$D(\alpha_1, \alpha_2, \dots, \alpha_K) = \int_{\Delta_K} \prod_{k=1}^K \theta_k^{\alpha_k - 1} d\theta$$
$$= \frac{\prod_{k=1}^K \Gamma(\alpha_k)}{\Gamma(\sum_{k=1}^K \alpha_k)},$$

where  $\Delta_K$  is the simplex of multinomials over K classes and  $\Gamma(m)=(m-1)!$  is the gamma function.

• Using a symmetric Dirichlet (i.e.  $\alpha_k = \frac{\alpha}{K}$  for all k):

$$\theta \mid \alpha \sim \mathsf{Dirichlet}\Big(\frac{\alpha}{K}, \frac{\alpha}{K}, \dots, \frac{\alpha}{K}\Big)$$
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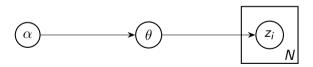


Figure 1: Graphical model for the Dirichlet-multinomial model



• Integrating over all values of  $\theta$  the probability of an assignment vector  $\mathbf{c}$  is:

$$P(\mathbf{c}) = \int_{\Delta_{K}} \prod_{i=1}^{n} P(c_{i}|\theta) p(\theta) d\theta = \int_{\Delta_{K}} \frac{\prod_{k=1}^{K} \theta_{k}^{m_{k}+\alpha/K-1}}{D(\frac{\alpha}{K}, \frac{\alpha}{K}, \dots, \frac{\alpha}{K})} d\theta$$

$$= \frac{D(m_{1} + \frac{\alpha}{K}, m_{2} + \frac{\alpha}{K}, \dots, m_{k} + \frac{\alpha}{K})}{D(\frac{\alpha}{K}, \frac{\alpha}{K}, \dots, \frac{\alpha}{K})}$$

$$= \frac{\prod_{k=1}^{K} \Gamma(m_{k} + \frac{\alpha}{K})}{\Gamma(\frac{\alpha}{K})^{K}} \frac{\Gamma(\alpha)}{\Gamma(N+\alpha)}, \qquad (1)$$

where  $m_k = \sum_{i=1}^N \delta(c_i = k)$  is the number of objects assigned to class k.



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- Class assignments **c** are not independent, rather they are **exchangeable**.
- Equation 1 assumes an upper bound on the number of classes of objects



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• We specify the probability of **X** for infinitely many classes

$$p(\mathbf{X}|\mathbf{c}) = \prod_{i=1}^{N} \sum_{k=1}^{\infty} p(\mathbf{x}_i|c_i = k)\theta_k$$

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with  $K_+$  is the number of classes for which  $m_k > 0$  for the ordered sequence of indices such that  $m_k > 0$  for all  $k < K_+$ .

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• Since there are  $K^N$  possible configurations for  $\mathbf{c}$ ,  $P(\mathbf{c}) \to 0$  as  $K \to \infty$ .

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- A partition defines an equivalence class of assignment vectors, which we denote [c]
- p(X|c) is the same for all vectors c corresponding to the same partition [c]
- Assume we have a partition of N objects into  $K_+$  subsets with  $K = K_0 + K_+$  classes. There are  $\frac{K!}{K_0}$  assignments of vector  $\mathbf{c}$  that belong to the equivalence class defined by that partition  $[\mathbf{c}]$

# Distribution over partitions

• The limiting probability of those class assignments is:

$$P([\mathbf{c}]) = \sum_{\mathbf{c} \in [\mathbf{c}]} P(\mathbf{c}) = \lim_{K \to \infty} \frac{K!}{K_0!} P(\mathbf{c})$$

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• Equation 3 is consistent with the other derivation, as Dirichlet Process (Blackwell and MacQueen, 1973) or stick breaking priors (Sethuraman, 1994).

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Imagine a restaurant with an infinite number of tables, each with an infinite number of seats. The ith client will seat to the kth table with probability:

$$P(c_i=k|c_1,c_2,\ldots,c_{i-1}) = egin{cases} rac{m_k}{i-1+lpha} & k \leq \mathcal{K}_+ \ rac{lpha}{i-1+lpha} & k = \mathcal{K}+1 \end{cases}$$

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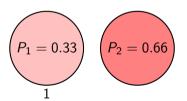


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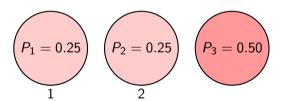


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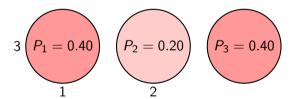


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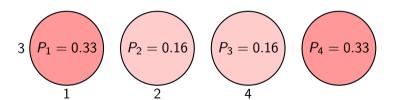


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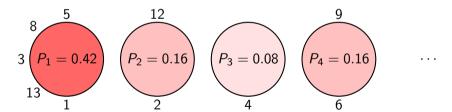


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# Inference by Gibbs Sampling

In a mixture model the variables to be sampled are the class assignments c, applying Bayes' rule

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• For the infinite case we can use **exchangeability** and choose an ordering in which the *i*th object is the last to be assigned to a class. **We sample directly from the CRP** 

$$P(c_i = k | \mathbf{c}_{-i}) = egin{cases} rac{m_{-i,k} + rac{lpha}{K}}{i - 1 + lpha} & m_{-i,k} > 0 \ rac{lpha}{i - 1 + lpha} & k = K_{-i,+} + 1 \ 0 & ext{otherwise} \end{cases}$$

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- We assume that each object possesses feature k a probability  $\pi_k$  and that the features are **generated independently**, forming  $\pi = \{\pi_1, \pi_2, \dots, \pi_K\}$ ,.

Latent Feature Model: 
$$\theta \in [0,1]$$
 with  $\sum_{k=1}^K \theta_k = 1$ 

Latent Class Model:  $\pi_k \in [0,1]$ 

#### Latent Feature Model

- Assume we have N objects and K features and the possession of feature k by object i is indicated by a binary variable  $z_{ik}$  which forms a binary  $N \times K$  feature matrix  $\mathbf{Z}$
- We assume that each object possesses feature k a probability  $\pi_k$  and that the features are **generated independently**, forming  $\pi = \{\pi_1, \pi_2, \dots, \pi_K\}$ ,.

Latent Feature Model: 
$$\theta \in [0,1]$$
 with  $\sum_{k=1}^K \theta_k = 1$  Latent Class Model:  $\pi_k \in [0,1]$ 

• The statistical model for a latent class model consists in

$$P(\pi)$$
 $p(\mathbf{Z}|\pi)$ 



• The probability of a matrix **Z** given  $\pi$  is:

$$P(\mathbf{Z}|\,\boldsymbol{\pi}) = \prod_{k=1}^K \prod_{i=1}^N P(z_{ik}|\,\pi_k) = \prod_{k=1}^K \pi_k^{m_k} (1-\pi_k)^{N-m_k},$$

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where  $m_k = \sum_{i=1}^N z_{ik}$ 

• We assume each  $\pi_k$  follows a Beta(r,s), which is conjugate to the binomial

$$p(\pi_k) = \frac{\pi_k^{r-1}(1-\pi_k)^{s-1}}{B(r,s)},$$

where B(r, s) is the beta function

$$B(r,s) = \int_0^1 \pi_k^{r-1} (1 - \pi_k)^{s-1} d\pi_k$$
$$= \frac{\Gamma(r)\Gamma(s)}{\Gamma(r+s)}$$



• We take  $r = \frac{\alpha}{K}$  and s = 1:

$$egin{aligned} \pi_k | & lpha \sim \mathsf{Beta}\Big(rac{lpha}{K}, 1 \Big) \ & z_{ik} | \pi_k \sim \mathsf{Bernoulli}(\pi_k) \end{aligned}$$

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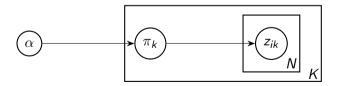


Figure 3: Graphical model for the beta-binomial model

• Integrating over all values of  $\pi$ , the probability of a binary matrix **Z** is

$$P(\mathbf{Z}) = \prod_{k=1}^{K} \int \left( \prod_{i=1}^{N} P(z_{ik} | \pi_k) \right) p(\pi_k) d\pi_k$$

$$= \prod_{k=1}^{K} \frac{B(m_k + \frac{\alpha}{K}, N - m_k + 1)}{B(\frac{\alpha}{K}, 1)}$$

$$= \prod_{k=1}^{K} \frac{\frac{\alpha}{K} \Gamma(m_k + \frac{\alpha}{K}) \Gamma(N - m_k + 1)}{\Gamma(N + 1 + \frac{\alpha}{K})}, \tag{4}$$



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the result follows from the beta-binomial conjugacy and the distribution is **exchangeable**, depending only on the counts  $m_k$ .



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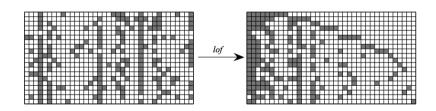


Figure 4:  $\mathbf{Z}$  and  $lof(\mathbf{Z})$ 



• From Equation 3, the probability of a particular lof-equivalence class is

$$P([\mathbf{Z}]) = \sum_{\mathbf{Z} \in [\mathbf{Z}]} P(\mathbf{Z})$$

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andrea.teruzzi@proton.me IBP. Griffiths and Ghahramani VSI – BavesLab 20 / 27

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where  $H_N = \sum_{i=1}^N \frac{1}{i}$ .

• The distribution is **exchangeable** and it is coherent with the prior distribution defined by Hjort (1990) and the stick breaking construction suggested in Teh et al. (2007).

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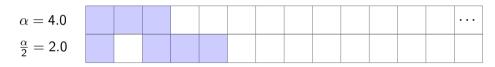


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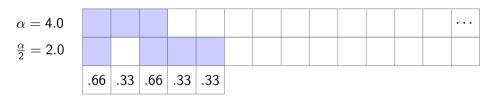


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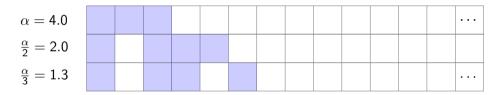


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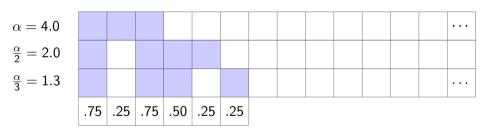


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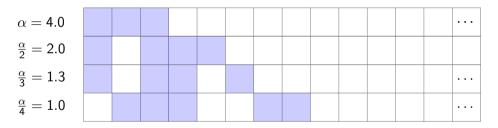


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e.g. 
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- **3** The number of features possessed by each object follows a Poisson( $\alpha$ ) distribution.
- **1** The expected number of entries in **Z** is  $N\alpha$ , so **Z** remains sparse as  $K \to \infty$ .

## Inference by Gibbs Sampling

• To sample from the distribution defined by the IBP we need to compute the full conditional  $P(z_{ik} = 1 | \mathbf{Z}_{-(ik)})$ , where  $\mathbf{Z}_{-(ik)}$  denotes the entries of  $\mathbf{Z}$  other than  $z_{ik}$ .

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• For the infinite case, we arbitrary choose object ith to be the last one to visit the buffet

$$P(z_{ik} = 1 | \mathbf{z}_{-i,k}) = \frac{m_{-i,k}}{N},$$
 (7)

that is also the limit of the full conditional for the finite case.

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### IBP sampling algorithm

### Algorithm 1 Gibbs sampler for IBP

```
1: Initialize binary matrix Z
 2: for i = 1 to N do
      for k = i to K do
         if m_{-i,k} > 0 then
 4:
            z_{ik} \sim P(z_{ik} = 1 | \mathbf{z}_{-i,k})
 5:
6:
          else
             Delete column k
8:
          end if
         Add Poisson(\frac{\alpha}{N}) new columns
9:
       end for
10:
11: end for
```

• IBP has only one parameter  $\alpha$  which controls both the sparsity of **Z** and its dimensionality.

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  - ② The *i*th customer takes any dish previously sampled with probability  $m_k/(\beta+i-1)$ , then he takes additional Poisson $(\alpha\beta/(\beta+i-1))$  dishes.
- Parameter  $\beta$  controls the number of shared features between objects.



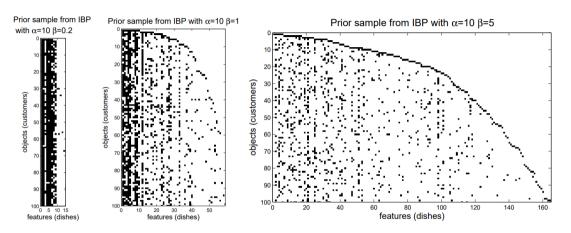


Figure 6: Three samples from the two-parameter IBP with  $\alpha=10$  and  $\beta=0.2$  (left),  $\beta=1$  (middle), and  $\beta=5$  (right).

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