

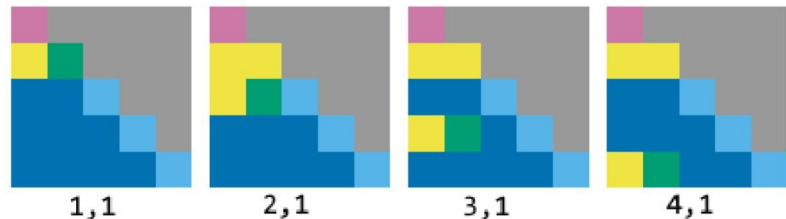
# <Cholesky\_kernel>

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# CHOLESKY DECOMPOSITION (or Cholesky Factorization)

```
for (i = 0; i < _PB_N; ++i)
{
    x = A[i][i];
    for (j = 0; j <= i - 1; ++j)
        x = x - A[i][j] * A[i][j];
    p[i] = 1.0 / sqrt(x);
    for (j = i + 1; j < _PB_N; ++j)
    {
        x = A[i][j];
        for (k = 0; k <= i - 1; ++k)
            x = x - A[j][k] * A[i][k];
        A[j][i] = x * p[i];
    }
}
```

es.



Example of data dependencies of a single column on a 5x5 matrix. Green elements are the active elements for each iteration, which directly depend on the yellow elements, indirectly on the pink ones, and not dependent of the blue ones.

# Sequential Benchmarking

Performance counter stats for './cholesky\_acc':

|                 |                  |   |                |                |
|-----------------|------------------|---|----------------|----------------|
| 361.898.961     | cache-references |   |                |                |
| 24.269.269      | cache-misses     | # | 6,706 % of all | cache refs     |
| 922.929.941     | cycles           |   |                |                |
| 1.087.772.189   | instructions     | # | 1,18           | insn per cycle |
| <not supported> | branches         |   |                |                |
| 581             | faults           |   |                |                |
| 0               | migrations       |   |                |                |

0,629194695 seconds time elapsed

Possible solution:

- **Vectorize** the problem
- Manipulate the memory **init** and **access**

# PARALLELIZED VERSION 1

```
static void kernel_cholesky(int n,
                           DATA_TYPE POLYBENCH_1D(p, N, n),
                           DATA_TYPE POLYBENCH_2D(A, N, N, n, n))
{
    int i, j, k;

    DATA_TYPE x;
    for (i = 0; i < _PB_N; ++i)
    {
        x = A[i][i];

        #pragma omp parallel for reduction(-:x)
        for (j = 0; j <= i - 1; ++j)
            x = x - A[i][j] * A[i][j];

        p[i] = 1.0 / sqrt(x);

        #pragma omp parallel for private(x, k)
        for (j = i + 1; j < _PB_N; ++j)
        {
            x = A[i][j];

            #pragma omp simd reduction(-:x)
            for (k = 0; k <= i - 1; ++k)
                x = x - A[j][k] * A[i][k];

            A[j][i] = x * p[i];
        }
    }
}
```

Exec time: ~14s

# PARALLELIZED VERSION 2

```
static void opt_kernel_cholesky(int n,
                                DATA_TYPE POLYBENCH_1D(p, N, n),
                                DATA_TYPE POLYBENCH_2D(A, N, N, n, n))
{
    int i, j, k;

    DATA_TYPE x;
    for (i = 0; i < _PB_N; ++i) {
        p[i] = 1 / sqrt(A[i][i] - p[i]);

        #pragma omp parallel for private(j, k, x)
        for (j = i + 1; j < _PB_N; j++) {
            x = A[i][j];

            #pragma omp simd reduction(-:x)
            for (k = 0; k <= i - 1; ++k)
                x = x - A[j][k] * A[i][k];

            A[j][i] = x * p[i];
            p[j] += A[j][i] * A[j][i];
        }
    }
}
```

Exec time: ~13s

# AMDAHL'S LAW COMPARISON

## Benchmark :

Dataset = EXTRALARGE

Sequential execution time = 32 sec

---

## Amdahl's Law :

$$speedup = \frac{1}{(1-p) + \frac{p}{n}}$$

Amdahl's Law -> n = 4 p = 90%

Expected SpeedUp = 3x

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## Parallelized Version :

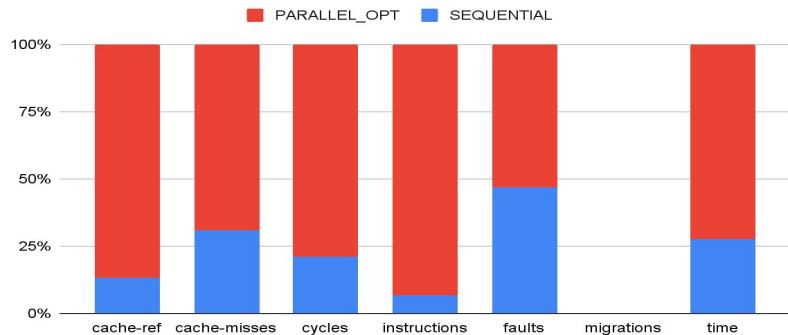
Parallel Execution time = 13 sec

**Achieved SpeedUp = 2,46x**

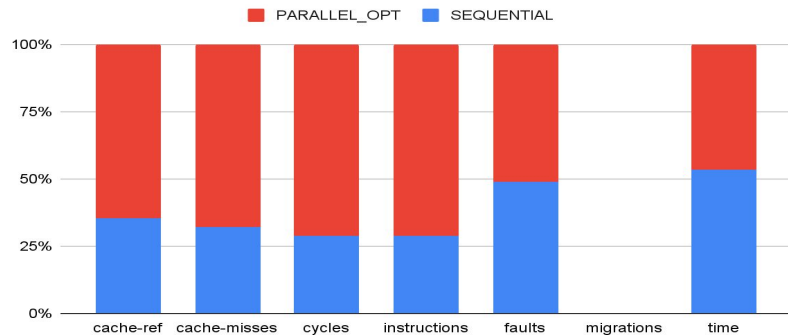
# CONCLUSIONS

Let's analyze the results obtained in detail :

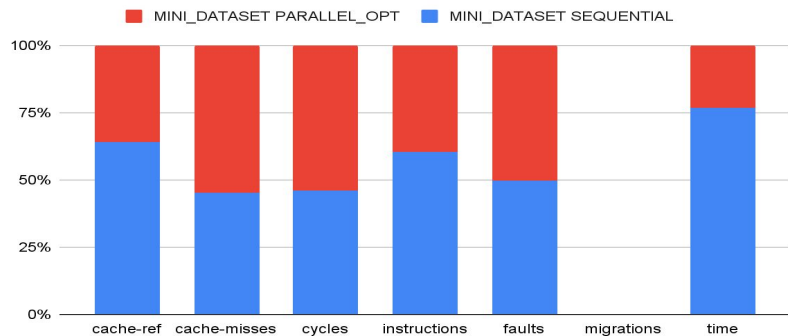
Mini Dataset = 32



Small Dataset = 128



Standard Dataset = 1024



Extralarge Dataset = 4000

