

Distribution of Quadratic Forms
Quadratic Forms If \mathbf{A} is a symmetric matrix and \mathbf{y} is a vector, the product $\mathbf{y}^T \mathbf{A} \mathbf{y} = \sum_i a_{ii} y_i^2 + \sum_{i \neq j} a_{ij} y_i y_j$ is called a quadratic form .
Theorem 4.4a Let $\mathbf{x} \sim \mathcal{N}_p(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ and $\mathbf{a} = [a_1, \dots, a_p]^T$. Then, $\mathbf{a}^T \mathbf{x} = \sum_{i=1}^p a_i x_i \sim \mathcal{N}_1(\mathbf{a}^T \boldsymbol{\mu}, \mathbf{a}^T \boldsymbol{\Sigma} \mathbf{a})$. Remark: In this form, we can show that certain sum of squares have χ^2 distributions. Remark: It can be shown that $\mathbf{y}^T \mathbf{I} \mathbf{y} = \mathbf{y}^T (\mathbf{I} - \frac{1}{n} \mathbf{J}) \mathbf{y} + \mathbf{y}^T (\frac{1}{n} \mathbf{J}) \mathbf{y}$.
Sum of Squares Properties (1) $\mathbf{I} = (\mathbf{I} - \frac{1}{n} \mathbf{J}) + (\frac{1}{n} \mathbf{J})$, (2) $\mathbf{I}, \mathbf{I} - \frac{1}{n} \mathbf{J}, \frac{1}{n} \mathbf{J}$ are idempotent; and (3) $(\mathbf{I} - \frac{1}{n} \mathbf{J})(\frac{1}{n} \mathbf{J}) = \mathbf{O}$.
Theorem 5.2a (Mean and Variances) If \mathbf{y} is a random vector with mean $\boldsymbol{\mu}$ and covariance matrix $\boldsymbol{\Sigma}$, and \mathbf{A} is a symmetric matrix of constants, then $\mathbb{E}(\mathbf{y}^T \mathbf{A} \mathbf{y}) = \text{tr}(\mathbf{A} \boldsymbol{\Sigma}) + \boldsymbol{\mu}^T \mathbf{A} \boldsymbol{\mu}$.
Theorem 5.2b-d (Mean and Variances) If $\mathbf{y} \sim \mathcal{N}_p(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, then $M_{\mathbf{y}^T \mathbf{A} \mathbf{y}}(t) = \mathbf{I} - 2t \mathbf{A} \boldsymbol{\Sigma} ^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} \boldsymbol{\mu}^T [\mathbf{I} - (\mathbf{I} - 2t \mathbf{A} \boldsymbol{\Sigma})^{-1}] \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu} \right\}$ $\text{Var}(\mathbf{y}^T \mathbf{A} \mathbf{y}) = 2 \text{tr}[(\mathbf{A} \boldsymbol{\Sigma})^2] + 4 \boldsymbol{\mu}^T \mathbf{A} \boldsymbol{\Sigma} \mathbf{A} \boldsymbol{\mu}$ $\text{Cov}(\mathbf{y}, \mathbf{y}^T \mathbf{A} \mathbf{y}) = 2 \boldsymbol{\Sigma} \mathbf{A} \boldsymbol{\mu}$
Corollary Let \mathbf{B} be a $k \times p$ matrix of constants. Then $\text{Cov}(\mathbf{B} \mathbf{y}, \mathbf{y}^T \mathbf{A} \mathbf{y}) = 2 \mathbf{B} \boldsymbol{\Sigma} \mathbf{A} \boldsymbol{\mu}$.
Theorem 5.2e (Mean and Variances) Let $\mathbf{v} = \begin{bmatrix} \mathbf{y} \\ \mathbf{x} \end{bmatrix}$ be a partitioned random vector with mean vector and covariance vector matrix given by $\begin{bmatrix} \boldsymbol{\mu}_y \\ \boldsymbol{\mu}_x \end{bmatrix}$ and $\begin{bmatrix} \boldsymbol{\Sigma}_{yy} & \boldsymbol{\Sigma}_{yx} \\ \boldsymbol{\Sigma}_{xy} & \boldsymbol{\Sigma}_{xx} \end{bmatrix}$, respectively, where \mathbf{y} is a $p \times 1$, \mathbf{x} is $q \times 1$, $\boldsymbol{\Sigma}_{yx}$ is $p \times q$. Let \mathbf{A} be a $q \times p$ matrix of constants. Then $\mathbb{E}(\mathbf{x}^T \mathbf{A} \mathbf{y}) = \text{tr}(\mathbf{A} \boldsymbol{\Sigma}_{yx}) + \boldsymbol{\mu}_x^T \mathbf{A} \boldsymbol{\mu}_y$.
Central Chi-Square Distribution Let z_1, \dots, z_n be iid $\mathcal{N}(0, 1)$ random variables. Since the z_i 's are independent, the random vector $\mathbf{z} = [z_1, \dots, z_n]^T$ is distributed as $\mathcal{N}_n(0, \mathbf{I}_n)$. Furthermore, $\sum_{i=1}^n z_i^2 = \mathbf{z}^T \mathbf{z}$ is $\chi^2(n)$.
Theorem 5.3a If $u \sim \chi^2(n)$, then (1) $\mathbb{E}(u) = n$, (2) $\text{Var}(u) = 2n$, and (3) $M_u(t) = \frac{1}{(1-2t)^{n/2}}$.
Non-Central Chi-Square Distribution Let y_1, \dots, y_n be random variables independently distributed as $\mathcal{N}(\mu_i, 1)$, so that $\mathbf{y} \sim \mathcal{N}_n(\boldsymbol{\mu}, \mathbf{I}_n)$, where $\boldsymbol{\mu} = [\mu_1, \dots, \mu_n]^T$. The density of $v = \sum_{i=1}^n y_i^2 = \mathbf{y}^T \mathbf{y}$ is called the non-central chi-square distribution and is denoted by $\chi^2(n, \lambda)$, where λ is the noncentrality parameter given by $\lambda = \frac{1}{2} \sum_{i=1}^n \mu_i^2 = \frac{1}{2} \boldsymbol{\mu}^T \boldsymbol{\mu}$. Remark: λ is not an eigenvalue.
Theorem 5.3b If $v \sim \chi^2(n, \lambda)$, then (1) $\mathbb{E}(v) = n + 2\lambda$, (2) $\text{Var}(v) = 2n + 8\lambda$, and (3) $M_v(t) = \frac{1}{(1-2t)^{n/2}} \exp \left\{ -\lambda \left(1 - \frac{1}{1-2t} \right) \right\}$ Remark: The mean of $v = \sum_{i=1}^n y_i^2$ is greater than the mean of $u = \sum_{i=1}^n (y_i - \mu_i)^2$.
Theorem 5.3c If v_1, \dots, v_k are independently distributed as $\chi^2(n_i, \lambda_i)$, then $\sum_{i=1}^k v_i$ is distributed as $\chi^2 \left(\sum_{i=1}^k n_i, \sum_{i=1}^k \lambda_i \right)$.

Non-Central Chi-Square Distribution
Corollary If $\lambda = 0$, then $\mathbb{E}(v)$, $\text{Var}(v)$, and $M_v(t)$ reduce to $\mathbb{E}(u)$, $\text{Var}(u)$, and $M_u(t)$ for the central chi-square distribution. Thus, $\chi^2(n, 0) = \chi^2(n)$
Corollary If u_1, \dots, u_k are independently distributed as $\chi^2(n_i)$, then $\sum_{i=1}^k u_i$ is distributed as $\chi^2(\sum_{i=1}^k n_i)$
Central F-distribution If $u \sim \chi^2(p)$ and $v \sim \chi^2(q)$, where u and v are independent, then $w = \frac{u/p}{v/q}$ has a (central) F distribution with p and q degrees of freedom.
Central t-distribution If $z \sim \mathcal{N}(0, 1)$ and $u \sim \chi^2(q)$, where z and u are independent, then $t = \frac{z}{\sqrt{u/p}}$ has a (central) t distribution with p degrees of freedom.
Theorem If $u \sim \chi^2(p)$ and $v \sim \chi^2(q)$, and u and v are independent, then $w = \frac{u/p}{v/q} \sim F(p, q)$. The mean and variance of w are given by: $\mathbb{E}(w) = \frac{q}{q-2}$, $\text{Var}(w) = \frac{2q^2(p+q-2)}{p(q-1)^2(q-4)}$
Non-Central F-distribution If $u \sim \chi^2(p, \lambda)$ and $v \sim \chi^2(q)$, where u and v are independent, $z = \frac{u/p}{v/q}$ has the non-central F distribution with noncentrality parameter λ , denoted by $F(p, q, \lambda)$, where λ is the same noncentrality parameter as in the non-central chi-square distribution. Remark: The mean of z , $\mathbb{E}(z) = \frac{q}{q-2}(1 + \frac{2\lambda}{p})$, is greater than the mean for the central F distribution.
Non-Central t-distribution If $y \sim \mathcal{N}(\mu, 1)$, $u \sim \chi^2(p)$, where y and u are independent, then $t = \frac{y}{\sqrt{u/p}}$ is said to have a non-central t distribution with p degrees of freedom and noncentrality parameter μ , denoted by $t(p, \mu)$. Furthermore, if $y \sim \mathcal{N}(\mu, \sigma^2)$, then $t = \frac{y/\sigma}{\sqrt{u/p}} \sim t(p, \frac{\mu}{\sigma})$ and $\frac{y}{\sigma} \sim \mathcal{N}(\frac{\mu}{\sigma}, 1)$
Distribution of Quadratic Forms - Theorem 5.5 Let $y \sim \mathcal{N}_p(\mu, \Sigma)$, \mathbf{A} be a symmetric matrix of constants of rank r , and $\lambda = \frac{1}{2}\mu^T \mathbf{A} \mu$. Then, $\mathbf{y}^T \mathbf{A} \mathbf{y} \sim \chi^2(r, \lambda)$ iff $\mathbf{A} \Sigma$ is idempotent.
Independence of Linear and Quadratic Forms - Theorem 5.6 Suppose that \mathbf{B} is a $k \times p$ matrix of constants, \mathbf{A} is a $p \times p$ symmetric matrix of constants, and $y \sim \mathcal{N}_p(\mu, \Sigma)$. Then $\mathbf{B} \mathbf{y}$ and $\mathbf{y}^T \mathbf{A} \mathbf{y}$ are independent iff $\mathbf{B} \Sigma \mathbf{A} = \mathbf{O}$. Let \mathbf{A} and \mathbf{B} be symmetric matrix of constants. If $y \sim \mathcal{N}_p(\mu, \Sigma)$, then $\mathbf{y}^T \mathbf{A} \mathbf{y}$ and $\mathbf{y}^T \mathbf{B} \mathbf{y}$ are independent iff $\mathbf{A} \Sigma \mathbf{B} = \mathbf{O}$.
Multiple Linear Regression Model $y = \beta_0 + \beta_1 x_1 + \dots + \beta_p x_p + \varepsilon$ Remark: To estimate β_i 's, we will use a sample of n observations on y and the associated x variables. The model for the i^{th} observation is: $y_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip} + \varepsilon_i$, $i = 1, \dots, n$
Assumptions $\mathbb{E}(\varepsilon_i) = 0$ for $i = 1, \dots, n$, or equivalently, $\mathbb{E}(y_i) = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip}$ $\text{Var}(\varepsilon_i) = \sigma^2$ for $i = 1, \dots, n$, or equivalently, $\text{Var}(y_i) = \sigma^2$ $\text{Cov}(\varepsilon_i, \varepsilon_j) = 0$ for all $i \neq j$, or equivalently, $\text{Cov}(y_i, y_j) = 0$

Linear Regression Model

$$\begin{cases} y_1 = \beta_0 + \beta_1 x_{11} + \cdots + \beta_p x_{1p} + \varepsilon_1 \\ y_2 = \beta_0 + \beta_1 x_{21} + \cdots + \beta_p x_{2p} + \varepsilon_2 \\ \vdots \\ y_n = \beta_0 + \beta_1 x_{n1} + \cdots + \beta_p x_{np} + \varepsilon_n \end{cases} \Rightarrow \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} & \cdots & x_{1p} \\ 1 & x_{21} & x_{22} & \cdots & x_{2p} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n1} & x_{n2} & \cdots & x_{np} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_p \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Multiple Linear Regression Model

$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$ where

$$\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}, \mathbf{X} = \begin{bmatrix} 1 & x_{11} & x_{12} & \cdots & x_{1p} \\ 1 & x_{21} & x_{22} & \cdots & x_{2p} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n1} & x_{n2} & \cdots & x_{np} \end{bmatrix}, \boldsymbol{\beta} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_p \end{bmatrix}, \boldsymbol{\varepsilon} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}; \mathbb{E}(\boldsymbol{\varepsilon}) = \mathbf{0}, \text{Var}(\boldsymbol{\varepsilon}) = \sigma^2 \mathbf{I}.$$

Remark: Equivalently, $\mathbb{E}(\mathbf{y}) = \mathbf{X}\boldsymbol{\beta}$, $\text{Var}(\mathbf{y}) = \sigma^2 \mathbf{I}$.

Remark:

1. We generally assume $n > p + 1$ and $\text{rank}(\mathbf{X}) = p + 1$.
2. If $n < p + 1$ or if there's a linear relationship among the x 's, then \mathbf{X} will not have full column rank.
3. If the values of x_{ij} 's are planned/chosen, then \mathbf{X} contains the experimental design and is sometimes called the **design matrix**.
4. The β parameters are called the **(partial) regression coefficients**.

Estimating : Least Squares Approach

Goal: Find estimators that minimize the sum of the squared deviations of the n observed y 's from their predicted values \hat{y} .

We seek the estimators $\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_p$ that minimizes $S(\boldsymbol{\beta}) = \sum_{i=1}^n \varepsilon_i^2 = \sum_{i=1}^n (y_i - \hat{y}_i)^2 = (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^\top (\mathbf{y} - \mathbf{X}\boldsymbol{\beta}) = \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|^2$

Remark: The predicted value $\hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_{i1} + \cdots + \hat{\beta}_p x_{ip}$ estimates $\mathbb{E}(y_i)$, not y_i .

OLS Estimator: Theorem 7.3a

If $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$, where \mathbf{X} is $n \times (p + 1)$ of rank $(p + 1) < n$, then the value of $\hat{\boldsymbol{\beta}} = [\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_p]^\top$ that minimizes the sum of the squared deviations $S(\boldsymbol{\beta})$ is $\hat{\boldsymbol{\beta}} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$.

Remark:

1. Note that $\mathbf{X}^\top \mathbf{X}$ contains products of columns of \mathbf{X} , while $\mathbf{X}^\top \mathbf{y}$ contains products of the columns of \mathbf{X} and \mathbf{y}

$$\mathbf{X}^\top \mathbf{X} = \begin{bmatrix} n & \sum_i x_{i1} & \sum_i x_{i2} & \cdots & \sum_i x_{ip} \\ \sum_i x_{i1} & \sum_i x_{i1}^2 & \sum_i x_{i1}x_{i2} & \cdots & \sum_i x_{i1}x_{ip} \\ \sum_i x_{i2} & \sum_i x_{i1}x_{i2} & \sum_i x_{i2}^2 & \cdots & \sum_i x_{i2}x_{ip} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sum_i x_{ip} & \sum_i x_{i1}x_{ip} & \sum_i x_{i2}x_{ip} & \cdots & \sum_i x_{ip}^2 \end{bmatrix} \quad \mathbf{X}^\top \mathbf{y} = \begin{bmatrix} \sum_i y_i \\ \sum_i x_{i1}y_i \\ \vdots \\ \sum_i x_{ip}y_i \end{bmatrix}$$

2. If $\hat{\boldsymbol{\beta}} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$, then $\hat{\boldsymbol{\varepsilon}} = \mathbf{y} - \mathbf{X}\hat{\boldsymbol{\beta}} = \mathbf{y} - \hat{\mathbf{y}}$ is known as the **residual vector**.
3. The residual vector estimates $\boldsymbol{\varepsilon}$ in the model and can be used to check the assumptions of the model.
4. We can also write $\hat{\boldsymbol{\varepsilon}}$ as $\hat{\boldsymbol{\varepsilon}} = \mathbf{y} - \mathbf{X}\hat{\boldsymbol{\beta}} = \mathbf{y} - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y} = [\mathbf{I} - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top] \mathbf{y} = \mathbf{H}\mathbf{y}$, where $\mathbf{H} = \mathbf{I} - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top$ is both symmetric and idempotent.

<p>Properties of $\hat{\beta}$: Theorem 7.3b-c</p> <ol style="list-style-type: none"> 1. If $\mathbb{E}(\mathbf{y}) = \mathbf{X}\beta$, then $\hat{\beta}$ is an unbiased estimator for β. 2. If $\text{Var}(\mathbf{y}) = \sigma^2 \mathbf{I}$, the covariance matrix for $\hat{\beta}$ is given by: $\sigma^2 (\mathbf{X}^\top \mathbf{X})^{-1}$.
<p>Theorem (7.3d Gauss-Markov Theorem)</p> <p>Let $\mathbf{c}^\top \beta$ be a linear function of β, where \mathbf{c} is a $(p+1) \times 1$ vector of constants. If $\mathbb{E}(\mathbf{y}) = \mathbf{X}\beta$ and $\text{Var}(\mathbf{y}) = \sigma^2 \mathbf{I}$, then the best linear unbiased estimator (BLUE) of $\mathbf{c}^\top \beta$ (that is, with minimum variance) is $\mathbf{c}^\top \hat{\beta}$.</p>
<p>Normal Model</p> <p>Recall: The OLS estimator $\hat{\beta} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$ has no assumptions on the distribution of \mathbf{y}</p> <p>Assumption: $\varepsilon \sim \mathcal{N}_n(\mathbf{0}, \sigma^2 \mathbf{I})$, or equivalently, $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\beta, \sigma^2 \mathbf{I})$.</p>
<p>Maximum Likelihood Estimator: Theorem 7.6a</p> <p>If $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\beta, \sigma^2 \mathbf{I})$ (or equivalently, $\varepsilon \sim \mathcal{N}_n(0, \sigma^2 \mathbf{I})$), where \mathbf{X} is $n \times (p+1)$ of rank $(p+1) < n$, the maximum likelihood estimator of β and σ^2 are $\hat{\beta} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$ and $\hat{\sigma}^2 = \frac{1}{n}(\mathbf{y} - \mathbf{X}\hat{\beta})^\top (\mathbf{y} - \mathbf{X}\hat{\beta})$.</p>
<p>Properties of $\hat{\beta}$ and $\hat{\sigma}^2$: Theorem 7.6b</p> <p>Suppose that $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\beta, \sigma^2 \mathbf{I})$, where \mathbf{X} is $n \times (p+1)$ of rank $(p+1) < n$ and $\beta = [\beta_0, \beta_1, \dots, \beta_p]^\top$. Then the maximum likelihood estimators $\hat{\beta}$ and $\hat{\sigma}^2$ for β and σ^2 in the normal model have the following distributional properties:</p> <ol style="list-style-type: none"> 1. $\hat{\beta} \sim \mathcal{N}_{p+1}(\beta, \sigma^2 (\mathbf{X}^\top \mathbf{X})^{-1})$. 2. $\frac{n\hat{\sigma}^2}{\sigma^2} \sim \chi^2(n-p-1)$, or equivalently, $\frac{(n-p-1)s^2}{\sigma^2} \sim \chi^2(n-p-1)$. 3. $\hat{\beta}$ and $\hat{\sigma}^2$ (or s^2) are independent.
<p>Theorem (7.6c-d)</p> <p>If $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\beta, \sigma^2 \mathbf{I})$, then:</p> <ol style="list-style-type: none"> 1. $\hat{\beta}$ and $\hat{\sigma}^2$ are jointly sufficient for β and σ^2. 2. $\hat{\beta}$ and s^2 have minimum variance among all unbiased estimators.
<p>Corollary</p> <p>If $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\beta, \sigma^2 \mathbf{I})$, then the minimum variance unbiased estimator of $\mathbf{c}^\top \beta$ is $\mathbf{c}^\top \hat{\beta}$, where $\hat{\beta}$ is the maximum likelihood estimator for β.</p>
<p>Estimating Mean Response</p> <p>Let $\theta = \mathbb{E}(\mathbf{y})$. Since $\mathbb{E}(\mathbf{y}) = \mathbf{X}\beta$, the best linear unbiased estimator (BLUE) for θ is: $\hat{\theta} = \mathbf{X}\hat{\beta} = \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$. Under the assumption that $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\beta, \sigma^2 \mathbf{I})$, we have: $\mathbf{X}\hat{\beta} \sim \mathcal{N}_n(\mathbf{X}\beta, \sigma^2 \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top)$.</p> <p>Recall: Estimators</p> <p>Under the assumption that $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\beta, \sigma^2 \mathbf{I})$, the MLE are: $\hat{\beta} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$ $\hat{\sigma}^2 = \frac{1}{n}(\mathbf{y} - \mathbf{X}\hat{\beta})^\top (\mathbf{y} - \mathbf{X}\hat{\beta})$.</p> <p>Given values of the predictors $\mathbf{x}_i = (x_{i1}, \dots, x_{ip})$, we can estimate the value \hat{y}_i of the response.</p>
<p>F-Test for the General Linear Hypothesis</p> <p>Recall: By the Gauss-Markov Theorem, the BLUE for $\mathbf{c}^\top \beta$ is $\mathbf{c}^\top \hat{\beta}$.</p> <p>Goal: Test $H_0 : \mathbf{C}\beta = \mathbf{d}$ vs. $H_1 : \mathbf{C}\beta \neq \mathbf{d}$, where \mathbf{C} is $k \times (p+1)$ of rank k, and $\mathbf{d} \in \mathbb{R}^k$.</p>
<p>Theorem (8.4a) If $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\beta, \sigma^2 \mathbf{I})$, then</p> <ul style="list-style-type: none"> • $\mathbf{C}\hat{\beta} \sim \mathcal{N}_k(\mathbf{C}\beta, \sigma^2 \mathbf{C}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{C}^\top)$. • $\frac{(n-p-1)s^2}{\sigma^2} = \frac{\mathbf{y}^\top \mathbf{H} \mathbf{y}}{\sigma^2} \sim \chi^2(n-p-1, 0)$. <p>Remarks: Recall that $\mathbf{H} = \mathbf{I} - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top$.</p>

Theorem (8.4f)

If $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\boldsymbol{\beta}, \sigma^2\mathbf{I})$,

- $(\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d})^\top [\mathbf{C}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{C}^\top]^{-1} (\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d}) / \sigma^2 \sim \chi^2(k, \lambda)$, where

$$\lambda = \frac{(\mathbf{C}\boldsymbol{\beta} - \mathbf{d})^\top [\mathbf{C}^\top (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{C}]^{-1} (\mathbf{C}\boldsymbol{\beta} - \mathbf{d})}{2\sigma^2} = 0 \text{ when } H_0 \text{ is true.}$$

- $(\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d})^\top [\mathbf{C}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{C}^\top]^{-1} (\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d})$ and $\mathbf{y}^\top H \mathbf{y}$ are independent.

Remarks: $(n - p - 1)s^2 = \mathbf{y}^\top H \mathbf{y}$, where $H = \mathbf{I} - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top$.

Theorem (8.4g)

Let $\mathbf{y} \sim \mathcal{N}_n(\mathbf{X}\boldsymbol{\beta}, \sigma^2\mathbf{I})$. If $H_0 : \mathbf{C}\boldsymbol{\beta} = \mathbf{d}$ is true, then

$$F = \frac{(\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d})^\top [\mathbf{C}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{C}^\top]^{-1} (\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d}) / \sigma^2}{k} \bigg/ \frac{\mathbf{y}^\top H \mathbf{y} / \sigma^2}{n - p - 1}$$

$$F = \frac{(\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d})^\top [\mathbf{C}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{C}^\top]^{-1} (\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d})}{k \cdot \mathbf{y}^\top H \mathbf{y} / (n - p - 1)} \sim F(k, n - p - 1, 0).$$

Generalized Linear Hypotheses

Test for the joint effect of the explanatory variables: $H_0 : \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_p \end{bmatrix} = \mathbf{0} \quad \text{vs} \quad H_1 : \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_p \end{bmatrix} \neq \mathbf{0}$

Effect of the i th variable: $H_0 : \beta_i = 0 \quad \text{vs} \quad H_1 : \beta_i \neq 0, \quad i = 1, \dots, p$

F-Test

Decision Rule: Given significance level α , reject H_0 if $F > F_{1-\alpha}(k, n - p - 1)$.

Coefficient of Determination R^2

The total sum of squares, SST , can be written as: $SST = \sum_{i=1}^n (y_i - \bar{y})^2 = \mathbf{y}^\top \mathbf{y} - n\bar{y}^2 = (\hat{\boldsymbol{\beta}}^\top \mathbf{X}^\top \mathbf{y} - n\bar{y}^2) + (\mathbf{y}^\top \mathbf{y} - \hat{\boldsymbol{\beta}}^\top \mathbf{X}^\top \mathbf{y}) = SSR + SSE$.

Remark: $\hat{\boldsymbol{\epsilon}}^\top \hat{\boldsymbol{\epsilon}} = \mathbf{y}^\top \mathbf{y} - \hat{\boldsymbol{\beta}}^\top \mathbf{X}^\top \mathbf{y} = SSE$.

Coefficient of Determination R^2

The proportion of the total sum of squares due to regression

$$R^2 = \frac{SSR}{SST} = \frac{\hat{\boldsymbol{\beta}}^\top \mathbf{X}^\top \mathbf{y} - n\bar{y}^2}{\mathbf{y}^\top \mathbf{y} - n\bar{y}^2} = \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y})^2}{\sum_{i=1}^n (y_i - \bar{y})^2}$$

is known as the **coefficient of determination**, or the squared multiple correlation.

Remark:

1. The positive square root R is called the (multiple) correlation coefficient.
2. The ratio is a measure of model fit and provides an indication of how well the x 's predict y .

Properties

1. The range of R^2 is $0 \leq R^2 \leq 1$.
2. $R = r_{yy}$; that is, the multiple correlation is equal to the simple correlation.
3. Adding a variable x to the model **increases** the value of R^2 .
4. If $\beta_1 = \beta_2 = \dots = \beta_p = 0$, then $\mathbb{E}(R^2) = \frac{p}{n-1}$.

Note that the estimated coefficients $\hat{\beta}_j$ will not be zero even when the β_j 's are zero.

Remarks:

1. R^2 can also be written as

$$R^2 = \frac{(\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d})^\top [\mathbf{C}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{C}^\top]^{-1} (\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d})}{(\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d})^\top [\mathbf{C}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{C}^\top]^{-1} (\mathbf{C}\hat{\boldsymbol{\beta}} - \mathbf{d}) + \mathbf{y}^\top \mathbf{H} \mathbf{y}}$$

2. If all β_j 's were zero, $R^2 = 1$. If $y_i = \hat{y}_i$ for all i , $R^2 = 1$.
3. When p is a relatively large fraction of n , the resulting R^2 will be large, but not meaningful. To compensate for this, the adjusted R^2 can be used instead: $R_{adj}^2 = \frac{(n-1)R^2 - p}{n-p-1}$

Regression Concerns: Variable Selection**Selection Metrics**

1. **Mallow's** C_p , $C_p = \frac{\text{SSR}}{s^2} - (n + 2p)$ where $R^2 = \frac{\text{SSR}}{\text{SST}}$ and $s^2 = \frac{\text{SSE}}{n-p-1} = \frac{\mathbf{y}^\top \mathbf{H} \mathbf{y}}{n-p-1}$
2. **Akaike Information Criterion (AIC)**, $\text{AIC} = -2 \ln L(\hat{\beta}_p, \hat{\sigma}^2) + 2p$
3. **Bayesian Information Criterion (BIC)**, $\text{BIC} = -2 \ln L(\hat{\beta}_p, \hat{\sigma}^2) + p \ln p$

Remark: Here, $L(\cdot)$ represents the likelihood function.

Regression Concerns: Multicollinearity

1. Some of the predictors are functions of one or more other predictors.
2. This problem, known as **multicollinearity**, can distort the standard error of estimate and can lead to incorrect conclusions as to which independent variables are statistically significant.
3. The **variance inflation factor (VIF)** can be used to check this. The VIF for the j^{th} predictor is the multiple R^2 when the j^{th} predictor is regressed to other predictors: $\text{VIF}_j = \frac{1}{1-R_j^2}$

Interpretation: Retain if $\text{VIF}_j < 5$, while remove if $\text{VIF}_j > 10$.

Regression Concerns: Residuals

1. Residuals should be uncorrelated (that is, no patterns on the plot).
2. Normality can be verified using a **normal Q-Q plot**, and the statistical tests **Shapiro-Wilk** test and **Anderson-Darling** test.

In these tests, the null hypothesis is that the data comes from a normal distribution

Motivation

1. Several treatments or treatment combinations are applied to randomly selected experimental units.
2. **Goal:** Compare treatment means

We can use analysis-of-variance and linear models to compare means!

Illustration: Case 1: $y_{ij} = \mu + \alpha_i + \varepsilon_{ij}$

In matrix form,

$$\begin{bmatrix} y_{11} \\ y_{12} \\ y_{13} \\ y_{21} \\ y_{22} \\ y_{23} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mu \\ \alpha_1 \\ \alpha_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{12} \\ \varepsilon_{13} \\ \varepsilon_{21} \\ \varepsilon_{22} \\ \varepsilon_{23} \end{bmatrix} \quad \text{where } \mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$$

Remarks:

1. In most ANOVA applications, there are more than two treatments considered.
2. We focus on **balanced models**: each treatment has the same number of observations.
3. The data matrix \mathbf{X} is not full-rank. As such, $\mathbf{X}^\top \mathbf{X}$ is also not full rank and $(\mathbf{X}^\top \mathbf{X})^{-1}$ does not exist.
4. $\boldsymbol{\beta} = [\mu, \alpha_1, \alpha_2]^\top$ is not unique and *not estimable*. That is, individual parameters μ, α_1, α_2 cannot be *uniquely* estimated unless they are subject to constraints or side conditions.

One-Way ANOVA

The one-way balanced ANOVA model can be expressed as (Case 1) $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$

$$\text{where } \mathbf{y} = \begin{bmatrix} \mathbf{y}_1 \\ \mathbf{y}_2 \\ \vdots \\ \mathbf{y}_k \end{bmatrix}, \mathbf{X} = \begin{bmatrix} \mathbf{j} & \mathbf{j} & \mathbf{0} & \cdots & \mathbf{0} \\ \mathbf{j} & \mathbf{0} & \mathbf{j} & \cdots & \mathbf{0} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \mathbf{j} & \mathbf{0} & \mathbf{0} & \cdots & \mathbf{j} \end{bmatrix}, \boldsymbol{\beta} = \begin{bmatrix} \mu \\ \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_k \end{bmatrix}, \text{ and } \boldsymbol{\varepsilon} = \begin{bmatrix} \boldsymbol{\varepsilon}_1 \\ \boldsymbol{\varepsilon}_2 \\ \vdots \\ \boldsymbol{\varepsilon}_k \end{bmatrix}.$$

Remark: Here, \mathbf{X} is $kn \times (k+1)$, k is the number of treatments, n is the number of observations per treatment, $\mathbf{y}_i = [y_{i1}, \dots, y_{in}]^\top$ and $\boldsymbol{\varepsilon}_i = [\varepsilon_{i1}, \dots, \varepsilon_{in}]^\top$, \mathbf{j} and $\mathbf{0}$ are $n \times 1$, and \mathbf{y} and $\boldsymbol{\varepsilon}$ are $kn \times 1$

Note: for **Case 2**: $y_{ij} = \mu_i + \varepsilon_{ij}$, $\boldsymbol{\beta} = [\mu_1, \dots, \mu_k]^\top$ and \mathbf{X} does not have the first column of 1's.

Assumptions

- $\mathbb{E}(\varepsilon_{ij}) = 0$ for all i, j
- $\text{Var}(\varepsilon_{ij}) = \sigma^2$ for all i, j
- $\text{Cov}(\varepsilon_{ij}, \varepsilon_{rs}) = 0$ for all i, j
- $\varepsilon_{ij} \sim \mathcal{N}(0, \sigma^2)$
- We often use the constraint (side condition) $\sum_{i=1}^k \alpha_i = 0$

Estimating $\boldsymbol{\beta}$ and σ^2

A generalized inverse of $\mathbf{X}^\top \mathbf{X}$ in our model is given by $(\mathbf{X}^\top \mathbf{X})^- = \begin{bmatrix} 0 & 0 & \cdots & 0 \\ 0 & \frac{1}{n} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \frac{1}{n} \end{bmatrix}$ Using this, an

estimator for $\boldsymbol{\beta}$ is $\hat{\boldsymbol{\beta}} = (\mathbf{X}^\top \mathbf{X})^- \mathbf{X}^\top \mathbf{y} = \begin{bmatrix} 0 \\ \bar{y}_{1\cdot} \\ \vdots \\ \bar{y}_{k\cdot} \end{bmatrix}$. where $\bar{y}_{i\cdot} = \frac{1}{n} \sum_{j=1}^n y_{ij}$.

Moreover, an estimator for σ^2 is $s^2 = \frac{\text{SSE}}{k(n-1)}$, where $\text{SSE} = \mathbf{y}^\top \mathbf{y} - \hat{\boldsymbol{\beta}}^\top \mathbf{X}^\top \mathbf{y} = \mathbf{y}^\top [\mathbf{I} - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^- \mathbf{X}^\top] \mathbf{y}$.

Remarks:

1. The rank of the idempotent matrix $[\mathbf{I} - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^- \mathbf{X}^\top]$ is $k(n-1)$.
2. s^2 is an unbiased estimator of σ^2 .
3. SSE can be written as

$$\text{SSE} = \mathbf{y}^\top \mathbf{y} - \hat{\boldsymbol{\beta}}^\top \mathbf{X}^\top \mathbf{y} = \sum_{i=1}^k \sum_{j=1}^n y_{ij}^2 - \sum_{i=1}^k \bar{y}_{i\cdot} y_{i\cdot} = \sum_{ij} (y_{ij} - \bar{y}_{i\cdot})^2 = \sum_{ij} y_{ij}^2 - \sum_i \frac{y_{i\cdot}^2}{n},$$

where $y_{i\cdot} = \sum_{j=1}^n y_{ij}$

Motivation

Goal: Test $H_0: \mu_1 = \mu_2 = \cdots = \mu_k$ vs H_1 : at least two means are unequal.

One-way ANOVA Model: Hypothesis Testing

Recall: One-way ANOVA model can be written as a linear model $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$.

Using $\mu_i = \mu + \alpha_i$, the null hypothesis for the test of equality of means can be written as $H_0: \alpha_1 = \alpha_2 = \dots = \alpha_k$. Assuming $\mathbf{y} \sim \mathcal{N}_{kn}(\mathbf{X}\boldsymbol{\beta}, \sigma^2\mathbf{I})$, a hypothesis test for H_0 can be constructed using the F -distribution.

Linear Models in ANOVA

The general linear model can be expressed as $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$ where \mathbf{y} is the vector of observations, \mathbf{X} is the design matrix, $\boldsymbol{\beta}$ is the vector of parameters, and $\boldsymbol{\varepsilon}$ is the error term.

One-way ANOVA Model: General Linear Hypothesis

Theorem (12.7b)

If $\mathbf{y} \sim N_n(\mathbf{X}\boldsymbol{\beta}, \sigma^2\mathbf{I})$, where \mathbf{X} is $N \times p$ of rank $k < p \leq N$, if \mathbf{C} is $m \times p$ of rank $m \leq k$ such that $\mathbf{C}\boldsymbol{\beta}$ is a set of m linearly independent estimable functions, and if $\hat{\boldsymbol{\beta}} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y}$, then

1. $\mathbf{C}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{C}^T$ is nonsingular.
2. $\mathbf{C}\hat{\boldsymbol{\beta}} \sim \mathcal{N}_m(\mathbf{C}\boldsymbol{\beta}, \sigma^2\mathbf{C}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{C}^T)$.
3. $\frac{SSH}{\sigma^2} = \frac{(\mathbf{C}\hat{\boldsymbol{\beta}})^T[\mathbf{C}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{C}^T]^{-1}(\mathbf{C}\hat{\boldsymbol{\beta}})}{\sigma^2} \sim \chi^2(m, \boldsymbol{\lambda})$, where

$$\boldsymbol{\lambda} = \frac{(\mathbf{C}\hat{\boldsymbol{\beta}})^T[\mathbf{C}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{C}^T]^{-1}(\mathbf{C}\hat{\boldsymbol{\beta}})}{2\sigma^2}.$$

4. $\frac{SSE}{\sigma^2} = \frac{\mathbf{y}^T[\mathbf{I} - \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T]\mathbf{y}}{\sigma^2} \sim \chi^2(N - k)$.

5. SSH and SSE are independent.

Theorem (12.7c)

Let $\mathbf{y} \sim N_N(\mathbf{X}\boldsymbol{\beta}, \sigma^2\mathbf{I})$, where \mathbf{X} is $N \times p$ with rank k , where $k < p \leq N$. Let \mathbf{C} , $\mathbf{C}\boldsymbol{\beta}$, and $\hat{\boldsymbol{\beta}}$ be defined as in the previous theorem. If $H_0: \mathbf{C}\boldsymbol{\beta} = \mathbf{0}$ is true, then

$$F = \frac{SSH/m}{SSE/(N - k)} = \frac{(\mathbf{C}\hat{\boldsymbol{\beta}})^T[\mathbf{C}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{C}^T]^{-1}(\mathbf{C}\hat{\boldsymbol{\beta}})/m}{SSE/(N - k)} \sim F(m, N - k, 0).$$

One-way ANOVA Model: Hypothesis Testing

Note that the hypothesis $H_0: \alpha_1 = \dots = \alpha_k$ can be written as

$$H_0: \begin{bmatrix} \alpha_1 - \alpha_2 \\ \alpha_1 - \alpha_3 \\ \vdots \\ \alpha_1 - \alpha_k \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \Rightarrow H_0: \begin{bmatrix} 1 & -1 & 0 & 0 & \dots & 0 \\ 1 & 0 & -1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & 0 & 0 & 0 & \dots & -1 \end{bmatrix} \begin{bmatrix} \mu \\ \alpha_1 \\ \vdots \\ \alpha_k \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \Rightarrow H_0: \mathbf{C}\boldsymbol{\beta} = \mathbf{0}$$

That is, $H_0: \mathbf{C}\boldsymbol{\beta} = \mathbf{0}$, where $\mathbf{C} = \begin{bmatrix} 0 & 1 & -1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & -1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 1 & 0 & 0 & 0 & \dots & -1 \end{bmatrix}$ is $(k - 1) \times (k + 1)$, and $\boldsymbol{\beta} = [\mu, \alpha_1, \dots, \alpha_k]^T$ is $(k + 1) \times 1$.

For **Case 2:** $y_{ij} = \mu_i + \varepsilon_{ij}$, \mathbf{C} does not have the first column of 0's.

Since $\mathbf{y} \sim N_n(\mathbf{X}\boldsymbol{\beta}, \sigma^2\mathbf{I})$, by previous theorem, we can use the test statistic $F = \frac{(\mathbf{C}\hat{\boldsymbol{\beta}})^T[\mathbf{C}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{C}^T]^{-1}(\mathbf{C}\hat{\boldsymbol{\beta}})/(k-1)}{SSE/k(n-1)} \sim F(k - 1, k(n - 1))$ to test the hypothesis $H_0: \alpha_1 = \dots = \alpha_k$.

One-Way ANOVA Table

Source of Variation	df	SS	MS = $\frac{SS}{df}$	F-statistic
Treatments	$k - 1$	$SSH = \frac{1}{n} \sum_i y_{i.}^2 - \frac{y_{..}^2}{kn}$	$\frac{SSH}{(k-1)}$	$F = \frac{\frac{SSH}{(k-1)}}{\frac{SSE}{k(n-1)}}$
Error	$k(n - 1)$	$SSE = \sum_{ij} y_{ij}^2 - \frac{1}{n} \sum_i y_{i.}^2$	$\frac{SSE}{k(n-1)}$	
Total	$kn - 1$	$SST = \sum_{ij} y_{ij}^2 - \frac{y_{..}^2}{kn}$		

Testing Contrasts

A linear contrast is any linear combination of the individual group means such that the linear coefficients sum to 0: $L = \sum_{i=1}^k c_i \alpha_i$, where $\sum_{i=1}^k c_i = 0$.

Remark:

1. For the one-way model, the contrast $\sum_i c_i \alpha_i$ is equivalent to $\sum_i c_i \mu_i$.
2. The hypothesis of interest is $H_0 : \sum_i c_i \alpha_i$ or $H_0 : \sum_i c_i \mu_i = 0$, which represents a comparison of means if $\sum_i c_i = 0$.

Note that the null hypothesis can be written as $H_0 : \mathbf{c}^T \boldsymbol{\beta}$, where $\mathbf{c} = [0, c_1, \dots, c_k]^T$ and $\boldsymbol{\beta} = [\mu, \alpha_1, \dots, \alpha_k]^T$. Assuming $\mathbf{y} \sim \mathcal{N}_{kn}(\mathbf{X}\boldsymbol{\beta}, \sigma^2 \mathbf{I})$, H_0 can be tested using the previous theorem with $m = 1$ and test statistic $F = \frac{(\mathbf{c}^T \hat{\boldsymbol{\beta}})^T [\mathbf{c}^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{c}]^{-1} (\mathbf{c}^T \hat{\boldsymbol{\beta}})}{SSE/k(n-1)} = \frac{(\mathbf{c}^T \hat{\boldsymbol{\beta}})^2}{s^2 [\mathbf{c}^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{c}]} \sim F(1, k(n-1))$.