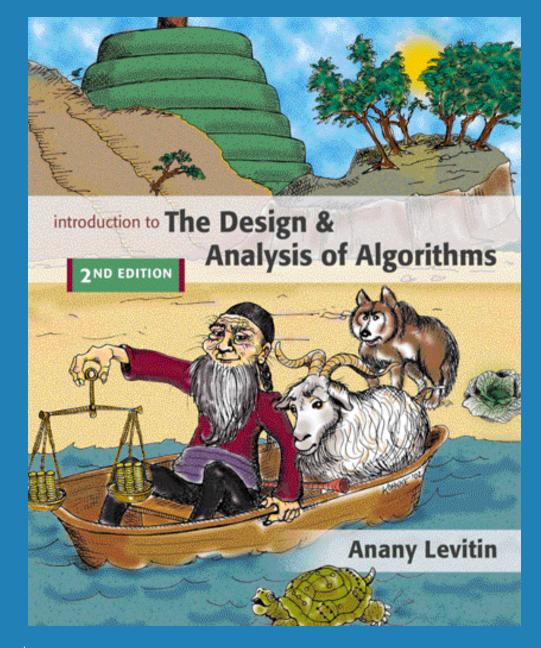
Chapter 1

Introduction





Why Study Algorithms?

Al Khawarizmi

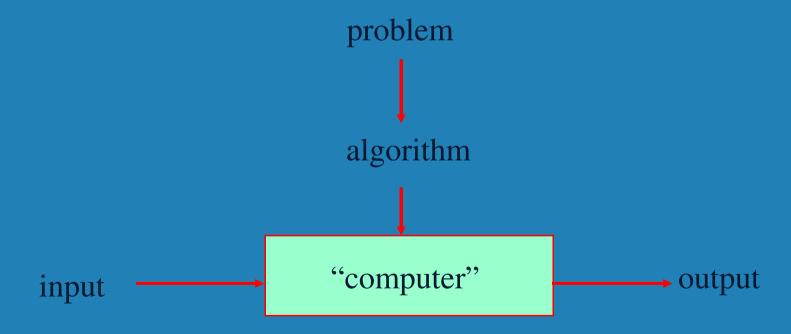
• "A great Iranian mathematician, geographer and astronomer. He introduced the zero, negative numbers, algebra, and the decimal system to the West. He also invented mathematical programming using a set of instructions to perform complex calculations. The term algorithm is named after a variation of his name, Algorithmi. "

What is it?

- Briefly speaking, algorithms are procedure solution to problems.
- Algorithms are not answers but rather precisely defined procedures for getting answers. (Example of sorting 3 numbers.)
- Cornerstone of computer science. Programs will not exist without algorithms.
- Algorithm design techniques, or problem-solving strategies, are useful in fields beyond computer science.

Algorithms

An algorithm is a sequence of <u>unambiguous instructions</u> for solving a computational problem, i.e., for obtaining a required <u>output</u> for any <u>legitimate input</u> in a <u>finite amount of time</u>.



Example of Computational Problem: Sorting

- Statement of problem:
 - *Input:* A sequence of *n* numbers $\langle a_1, a_2, ..., a_n \rangle$
 - Output: A reordering of the input sequence $\langle a'_1, a'_2, ..., a'_n \rangle$ so that $a'_i \leq a'_j$ whenever i < j
- Instance: The sequence <5, 3, 2, 8, 3>
- Algorithms:
 - Selection sort
 - Insertion sort
 - Merge sort
 - (many others)

Properties of Algorithms

- What distinguish an algorithm from a recipe, process, method, technique, procedure, routine...?
 - Finiteness terminates after a finite number of steps
 - <u>Definiteness</u>
 Each step must be rigorously and unambiguously specified.
 -e.g., "stir until <u>lumpy</u>"
 - <u>Input</u>
 Valid inputs must be clearly specified.
 - <u>Output</u>

 The data that result upon completion of the algorithm must be specified.
 - <u>Effectiveness</u>
 Steps must be sufficiently simple and basic.
 - -e.g., check if 2 is the largest integer n for which there is a solution to the equation $x^n + y^n = z^n$ in positive integers x, y, and z

Examples

• Is the following a legitimate algorithm?

```
i ←1
While (i <= 10) do
    a ← i + 1
Print the value of a
End of loop
Stop</pre>
```

Greatest Common Divisor of Two Integers

- gcd(m, n): <u>the largest integer that divides both m</u>
 and n
- First try -- Euclid's algorithm: gcd(m, n) = gcd(n, m mod n)
 - Step1: If n = 0, return the value of m as the answer and stop; otherwise, proceed to Step 2.
 - Step2: Divide m by n and assign the value of the remainder to r.
 - Step 3: Assign the value of n to m and the value of r to n. Go to Step 1.

Methods of Specifying an Algorithm

- Natural language
 - Ambiguous

"Mike ate his sandwich on a bed of lettuce."

- Pseudocode
 - A mixture of a natural language and programming language-like structures
 - Precise and succinct
 - Notation may
 - omit declarations of variables
 - use indentation to show the scope of such statements as for, if, and while.
 - use ← for assignment

Pseudocode of Euclid's Algorithm

```
Algorithm Euclid(m, n)

//Computes gcd(m, n) by Euclid's algorithm

//Input: Two nonnegative, not-both-zero integers m and n

//Output: Greatest common divisor of m and n

while n ≠ 0 do

r ← m mod n

m ← n

n ← r

return m
```

- Questions:
 - Finiteness: how do we know that Euclid's algorithm actually comes to a stop?
 - Definiteness: nonambiguity
 - Effectiveness: effectively computable

Second Try for gcd(m, n)

- Consecutive Integer Checking Algorithm
 - Step1: Assign the value of min{m, n} to t.
 - Step2: Divide m by t. If the remainder of this division is 0, go to Step3; otherwise, go to Step 4.
 - Step3: Divide n by t. If the remainder of this division is 0, return the value of t as the answer and stop; otherwise, proceed to Step4.
 - Step4: Decrease the value of t by 1. Go to Step2.
- Questions
 - Finiteness
 - Definiteness
 - Effectiveness
 - Which algorithm is faster, the Euclid's or this one?

Third try for gcd(m, n)

- Middle-school procedure
 - Step1: Find the prime factors of m.
 - Step2: Find the prime factors of n.
 - Step3: Identify all the common factors in the two prime expansions found in Step1 and Step2. (If p is a common factor occurring Pm and Pn times in m and n, respectively, it should be repeated in min{Pm, Pn} times.)
 - Step4: Compute the product of all the common factors and return it as the gcd of the numbers given.
- gdc(6-,24) =

Third try for gcd(m, n)

- Middle-school procedure
 - Step1: Find the prime factors of m.
 - Step2: Find the prime factors of n.
 - Step3: Identify all the common factors in the two prime expansions found in Step1 and Step2. (If p is a common factor occurring Pm and Pn times in m and n, respectively, it should be repeated in min{Pm, Pn} times.)
 - Step4: Compute the product of all the common factors and return it as the gcd of the numbers given.
- 60 = 2.2.3.5
- 24 = 2.2.2.3
- $\mathbf{gdc}(6-,24) = 2 \cdot 2 \cdot 3 = 12$
- Question
 - Is this a legitimate algorithm?
 - Homework: algorithm for the Sieve of Erastosthenes

What can we learn from the previous 3 examples?

- Each step of an algorithm must be unambiguous.
- The same algorithm can be represented in several different ways (different pseudocodes).
- There might exists more than one algorithm for a certain problem.
- Algorithms for the same problem can be based on very different ideas and can solve the problem with dramatically different speeds.

Fundamentals of Algorithmic Problem Solving

- Understanding the problem
 - Asking questions, do a few examples by hand, think about special cases, etc.
- Deciding on
 - Exact vs. approximate problem solving
 - Appropriate data structure
- Design an algorithm
- Proving correctness
- Analyzing an algorithm
 - Time efficiency: how fast the algorithm runs
 - Space efficiency: how much extra memory the algorithm needs.
 - Simplicity and generality
- Coding an algorithm

Algorithm design strategies

- Brute force
- Divide and conquer
- Decrease and conquer
- Transform and conquer
- Space and time tradeoffs
 - Sorting, Matching, Hashing, B-Trees
- Dynamic programming
- Greedy approach
- Iterative Improvement
- Limitations of Algorithm Power
 - Decision Trees, P/NP, Numerical Algorithms
- Coping with Limitations
 - Backtracking, Branch and bound, Approximation

Important Problem Types

- Sorting
- Searching
- String processing
- Graph problems

Sorting (I)

- Rearrange the items of a given list in ascending order.
 - Input: A sequence of n numbers $\langle a_1, a_2, ..., a_n \rangle$
 - Output: A reordering $\langle a_1, a_2, ..., a_n \rangle$ of the input sequence such that $a_1 \leq a_2 \leq ... \leq a_n$.
- Why sorting?
 - Help searching
 - Algorithms often use sorting as a key subroutine.
- Sorting key
 - A specially chosen piece of information used to guide sorting. I.e., sort student records by names.

Sorting (II)

- Examples of sorting algorithms
 - Selection sort
 - Bubble sort
 - Insertion sort
 - Merge sort
 - Heap sort ...
- Evaluate sorting algorithm complexity: the number of key comparisons.
- Two properties
 - Stability: A sorting algorithm is called stable if it preserves the relative order of any two equal elements in its input.
 - <u>In place</u>: A sorting algorithm is in place if it does not require extra memory, except, possibly for a few memory units.

Selection Sort

```
Algorithm SelectionSort(A[0..n-1])
//The algorithm sorts a given array by selection sort
//Input: An array A[0..n-1] of orderable elements
//Output: Array A[0..n-1] sorted in ascending order
for i \leftarrow 0 to n-2 do
  min ← i
  for j \leftarrow i + 1 to n - 1 do
       if A[j] < A[min]
               \min \leftarrow j
  swap A[i] and A[min]
```

Searching

- Find a given value, called a <u>search key</u>, in a given set.
- Examples of searching algorithms
 - Sequential searching
 - Binary searching...

String Processing

- A string is a sequence of characters from an alphabet.
- Text strings: letters, numbers, and special characters.
- String matching: searching for a given word/pattern in a text.

Graph Problems

- Informal definition
 - A graph is a collection of points called <u>vertices</u>, some of which are connected by line segments called <u>edges</u>.
- Modeling real-life problems
 - Modeling WWW
 - communication networks
 - Project scheduling ...
- Examples of graph algorithms
 - Graph traversal algorithms
 - Shortest-path algorithms
 - Topological sorting

Fundamental Data Structures

- Linear data structures
- Stacks, queues, and heaps
- Graphs
- Trees

Linear Data Structures

Arrays

• A sequence of n items of the same data type that are stored contiguously in computer memory and made accessible by specifying a value of the array's index.

Linked List

- A sequence of zero or more nodes each containing two kinds of information: some data and one or more links called pointers to other nodes of the linked list.
- Singly linked list (next pointer)
- Doubly linked list (next + previous pointers)

Arrays

fixed length (need preliminary reservation of memory) contiguous memory locations direct access

Insert/delete

Linked Lists

dynamic length
arbitrary memory locations
access by following links
Insert/delete

Stacks, Queues, and Heaps (1)

Stacks

- A stack of plates
 - insertion/deletion can be done only at the top.
 - LIFO
- Two operations (push and pop)

Queues

- A queue of customers waiting for services
 - Insertion/enqueue from the rear and deletion/dequeue from the front.
 - FIFO
- Two operations (enqueue and dequeue)

Stacks, Queues, and Heaps (2)

- Priority queues (implemented using heaps)
 - A data structure for maintaining a set of elements, each associated with a key/priority, with the following operations
 - Finding the element with the highest priority
 - Deleting the element with the highest priority
 - Inserting a new element
 - Scheduling jobs on a shared computer.

Graphs

- Formal definition
 - A graph $G = \langle V, E \rangle$ is defined by a pair of two sets: a finite set V of items called <u>vertices</u> and a set E of vertex pairs called <u>edges</u>.
- Undirected and directed graphs (digraph).
- What's the maximum number of edges in an undirected graph with |V| vertices?
- Complete, dense, and sparse graph
 - A graph with every pair of its vertices connected by an edge is called complete. $K_{|V|}$

Graph Representation

Adjacency matrix

- n x n boolean matrix if |V| is n.
- The element on the ith row and jth column is 1 if there's an edge from ith vertex to the jth vertex; otherwise 0.
- The adjacency matrix of an undirected graph is symmetric.

Adjacency linked lists

- A collection of linked lists, one for each vertex, that contain all the vertices adjacent to the list's vertex.
- Which data structure would you use if the graph is a 100-node star shape?

Weighted Graphs

- Weighted graphs
 - Graphs or digraphs with numbers assigned to the edges.

Graph Properties -- Paths and Connectivity

Paths

- A path from vertex u to v of a graph G is defined as a sequence of adjacent (connected by an edge) vertices that starts with u and ends with v.
- Simple paths: All edges of a path are distinct.
- Path lengths: the number of edges, or the number of vertices 1.

Connected graphs

• A graph is said to be connected if for every pair of its vertices u and v there is a path from u to v.

Connected component

• The maximum connected subgraph of a given graph.

Graph Properties -- Acyclicity

- Cycle
 - A simple path of a positive length that starts and ends a the same vertex.
- Acyclic graph
 - A graph without cycles
 - <u>DAG</u> (Directed Acyclic Graph)

Trees (I)

- Trees
 - A tree (or free tree) is a connected acyclic graph.
 - Forests: a graph that has no cycles but is not necessarily connected.
- Properties of trees
 - For every two vertices in a tree there always exists exactly one simple path from one of these vertices to the other. Why?
 |E| = |V| 1
 - Rooted trees: The above property makes it possible to select an arbitrary vertex in a free tree and consider it as the root of the so-called rooted tree.
 - Levels of rooted tree.

Trees (II)

ancestors

• For any vertex *v* in a tree *T*, all the vertices on the simple path from the root to that vertex are called ancestors.

descendants

• All the vertices for which a vertex *v* is an ancestor are said to be descendants of *v*.

parent, child and siblings

- If (u, v) is the last edge of the simple path from the root to vertex v (and $u \ddagger v$), u is said to be the parent of v and v is called a child of u.
- Vertices that have the same parent are called siblings.

Leaves

A vertex without children is called a leaf.

Subtree

A vertex v with all its descendants is called the subtree of T rooted at v.

Trees (III)

- Depth of a vertex
 - The length of the simple path from the root to the vertex.
- Height of a tree
 - The length of the longest simple path from the root to a leaf.

Ordered Trees

Ordered trees

• An ordered tree is a rooted tree in which all the children of each vertex are ordered.

Binary trees

• A binary tree is an ordered tree in which every vertex has no more than two children and each children is designated s either a left child or a right child of its parent.

Binary search trees

- Each vertex is assigned a number.
- A number assigned to each parental vertex is larger than all the numbers in its left subtree and smaller than all the numbers in its right subtree.
- $\lfloor \log_2 n \rfloor \le h \le n 1$, where h is the height of a binary tree.