

LTROLL

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1 Sintaxe Abstrata

$e \in Terms$

$e := 1 \mid \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \mid e_1 \text{ op } e_2 \mid \text{for } e_1 \text{ until } e_2 \text{ do } e_3 \mid e_1; e_2 \mid e_1 : e_2 \mid \text{notnot } e_1 \mid \text{fn } x : T \Rightarrow e_1 \text{ in } e_2$

$v \in Values$

$v := n \mid b \mid l \mid \text{fn } x : T \Rightarrow e_1 \mid \text{skip}$

$t \in Types$

$t := \text{int} \mid \text{bool} \mid T_1 \rightarrow T_2 \mid \text{ref } T_1 \mid \text{unit}$

onde:

$n \in nat$

$b \in \text{bool}$

$l \in \text{conjunto de enderecos}$

$op \in \{+, -, <, >, \leq, \geq, =, \neq, \text{or}, \text{and}\}$

2 Semântica Small Step

$$\begin{array}{lcl} \frac{e_1, \sigma \rightarrow e_1', \sigma'}{e_1 \text{ op } e_2, \sigma \rightarrow e_1' \text{ op } e_2, \sigma'} [e - \text{op1}] & \frac{[[v_1]] = [[v_2]] - [[v_3]]}{v_2 + v_3, \sigma \rightarrow v_1, \sigma} [e - \text{plus3}] & \\ \frac{e_1, \sigma \rightarrow e_1', \sigma'}{v \text{ op } e_1, \sigma \rightarrow v \text{ op } e_1', \sigma'} [e - \text{op2}] & \frac{[[v_1]] = [[v_2]] + [[v_3]]}{v_2 - v_3, \sigma \rightarrow v_1, \sigma} [e - \text{minus3}] & \\ & \frac{[[v_1]] \neq [[v_2]]}{v_1 = v_2, \sigma \rightarrow \text{true}, \sigma} [e - \text{equal3}] & \end{array}$$

$$\begin{array}{lcl}
\frac{[[v_1]] = [[v_2]]}{v_1 = v_2, \sigma \rightarrow false, \sigma} [e - equal4] & \frac{[[v_1]] \leq [[v_2]]}{v_1 \leq v_2, \sigma \rightarrow false, \sigma} [e - lessequal4] \\
\frac{[[v_1]] = [[v_2]]}{v_1 \neq v_2, \sigma \rightarrow true, \sigma} [e - nequal3] & \frac{[[v_1]] \leq [[v_2]]}{v_1 \geq v_2, \sigma \rightarrow true, \sigma} [e - greatequal3] \\
\frac{[[v_1]] \neq [[v_2]]}{v_1 \neq v_2, \sigma \rightarrow false, \sigma} [e - nequal4] & \frac{[[v_1]] \geq [[v_2]]}{v_1 \geq v_2, \sigma \rightarrow false, \sigma} [e - greatequal4] \\
\frac{[[v_1]] > [[v_2]]}{v_1 < v_2, \sigma \rightarrow true, \sigma} [e - less3] & \frac{[[v_1]] \text{ or } [[v_2]] = [[v_3]]}{v_1 \text{ and } v_2, \sigma \rightarrow v_3, \sigma} [e - and3] \\
\frac{[[v_1]] < [[v_2]]}{v_1 < v_2, \sigma \rightarrow false, \sigma} [e - less4] & \frac{[[v_1]] \text{ and } [[v_2]] = [[v_3]]}{v_1 \text{ or } v_2, \sigma \rightarrow v_3, \sigma} [e - or3] \\
\frac{[[v_1]] \geq [[v_2]]}{v_1 \leq v_2, \sigma \rightarrow true, \sigma} [e - lessequal3] &
\end{array}$$

$$\begin{array}{l}
\frac{e_1, \sigma \rightarrow e'_1, \sigma'}{if\ e_1\ then\ e_2\ else\ e_3, \sigma \rightarrow if\ e'_1\ then\ e_2\ else\ e_3, \sigma'} [e - if1] \\
\frac{}{if\ true\ then\ e_2\ else\ e_3, \sigma \rightarrow e_3, \sigma} [e - if2] \\
\frac{}{if\ false\ then\ e_2\ else\ e_2, \sigma \rightarrow e_3, \sigma} [e - if3] \\
\frac{e_1, \sigma \rightarrow e'_1, \sigma'}{for\ e_1\ until\ e_2\ do\ e_3, \sigma \rightarrow for\ e'_1\ until\ e_2\ do\ e_3, \sigma'} [e - for1] \\
\frac{e_2, \sigma \rightarrow e'_2, \sigma'}{for\ v\ until\ e_2\ do\ e_3, \sigma \rightarrow for\ v\ until\ e'_2\ do\ e_3, \sigma'} [e - for2] \\
\frac{[[v_1]] \neq [[v_2]]}{for\ v_1\ until\ v_2\ do\ e_3, \sigma \rightarrow e_3 : for\ v_1\ until\ v_2 + 1\ do\ e_3, \sigma} [e - for3] \\
\frac{[[v_1]] = [[v_2]]}{for\ v_1\ until\ v_2\ do\ e_3, \sigma \rightarrow e_3, \sigma} [e - for4] \\
\frac{e_1, \sigma \rightarrow e'_1, \sigma'}{e_1\ in\ e_2, \sigma \rightarrow e'_1\ in\ e_2, \sigma'} [e - in1] \\
\frac{e_2, \sigma \rightarrow e'_2, \sigma'}{e_1\ in\ e_2, \sigma \rightarrow e'_1\ in\ e'_2, \sigma'} [e - in2] \\
\frac{}{fn\ x : T \Rightarrow e_1\ in\ v, \sigma \rightarrow e_1\{v/x\}, \sigma} [e - in3]
\end{array}$$

$$\frac{}{v_1 : e_2, \sigma \rightarrow e_2, \sigma} [e - doisontos2]$$

$$\frac{e_1, \sigma \rightarrow e'_1, \sigma'}{e_1 : e_2, \sigma \rightarrow e'_1 : e_2, \sigma'} [e - doisontos1]$$

$$\begin{array}{c}
\frac{e_2, \sigma \rightarrow e'_2, \sigma'}{e_1; e_2, \sigma \rightarrow e_1; e'_2, \sigma'} [e - \text{pontoevirgula1}] \\
\frac{}{e_1; v_1, \sigma \rightarrow e_1, \sigma} [e - \text{pontoevirgula2}] \\
\frac{l \in \text{Dom}(\sigma) \quad \sigma(l) = v}{!l, \sigma \rightarrow v, \sigma} [e - \text{deref1}] \\
\frac{e_1, \sigma \rightarrow e'_1, \sigma'}{!e_1, \sigma \rightarrow !e'_1, \sigma'} [e - \text{deref2}] \\
\frac{e_1, \sigma \rightarrow e'_1, \sigma'}{\text{notnot } e_1, \sigma \rightarrow \text{notnot } e_1, \sigma'} [e - \text{notnot1}] \\
\frac{\text{not}[[v1]] = [[v2]]}{\text{notnot } v_1, \sigma \rightarrow v_2, \sigma} [e - \text{notnot2}] \\
\frac{l \in \text{Dom}(\sigma)}{v := l, \sigma \rightarrow \text{skip}, \sigma[l \mapsto v]} [e - \text{assing1}] \\
\frac{e_1, \sigma \rightarrow e'_1, \sigma'}{e_1 := v_1. \sigma \rightarrow e'_1 := v_1, \sigma'} [e - \text{assing2}] \\
\frac{e_2, \sigma \rightarrow e'_2, \sigma'}{e_1 := e_2. \sigma \rightarrow e_1 := e'_2, \sigma'} [e - \text{assing3}]
\end{array}$$

3 Sistema de Tipos

$$\begin{array}{c}
\frac{}{\Gamma; \Delta \vdash n : \text{int}} [t - \text{int}] \\
\frac{}{\Gamma; \Delta \vdash b : \text{bool}} [t - \text{bool}] \\
\frac{}{\Gamma; \Delta \vdash \text{skip} : \text{unit}} [t - \text{skip}] \\
\frac{l \in \Gamma \wedge \Gamma\{l\} : \text{ref}T}{\Gamma; \Delta \vdash l : \text{ref}T} [t - \text{label}] \\
\frac{\text{not}(l \in \Gamma \wedge \Gamma\{l\} : \text{ref}T)}{\Gamma; \Delta \vdash l : \text{unit}} [t - \text{label2}] \\
\frac{\Gamma; \Delta \vdash e_1 : T_1 \rightarrow T'_1 \quad \Gamma; \Delta \vdash e_2 : T_1}{\Gamma; \Delta \vdash e_1 \text{ in } e_2 : T'_1} [t - \text{in}] \\
\frac{\Gamma; \Delta \vdash e_1 : T_1}{\Gamma; \Delta \text{ fn } x : T \Rightarrow e_1 : T \rightarrow T'_1} [t - \text{fn}] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{ref}T_1}{\Gamma; \Delta \vdash !e_1 : T_1} [t - \text{derref}] \\
\frac{\Gamma; \Delta \vdash e_1 : T_1 \quad \Gamma; \Delta \vdash e_2 : T_1}{\Gamma; \Delta \vdash e_1 = e_2 : \text{bool}} [t - \text{eq}] \\
\frac{\Gamma; \Delta \vdash e_1 : T_1 \quad \Gamma; \Delta \vdash e_2 : T_1}{\Gamma; \Delta \vdash e_1 \neq e_2 : \text{bool}} [t - \text{neq}] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{bool} \quad \Gamma; \Delta \vdash e_2 : \text{bool}}{\Gamma; \Delta \vdash e_1 \text{ and } e_2 : \text{bool}} [t - \wedge] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{bool} \quad \Gamma; \Delta \vdash e_2 : \text{bool}}{\Gamma; \Delta \vdash e_1 \text{ or } e_2 : \text{bool}} [t - \text{or}] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{bool}}{\Gamma; \Delta \vdash \text{notnot } e_1 : \text{bool}} [t - \text{notnot}] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{nat} \quad \Gamma; \Delta \vdash e_2 : \text{nat}}{\Gamma; \Delta \vdash e_1 > e_2 : \text{bool}} [t - >] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{nat} \quad \Gamma; \Delta \vdash e_2 : \text{nat}}{\Gamma; \Delta \vdash e_1 < e_2 : \text{bool}} [t - <] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{nat} \quad \Gamma; \Delta \vdash e_2 : \text{nat}}{\Gamma; \Delta \vdash e_1 \geq e_2 : \text{bool}} [t - \geq] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{nat} \quad \Gamma; \Delta \vdash e_2 : \text{nat}}{\Gamma; \Delta \vdash e_1 \leq e_2 : \text{bool}} [t - \leq] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{nat} \quad \Gamma; \Delta \vdash e_2 : \text{nat}}{\Gamma; \Delta \vdash e_1 + e_2 : \text{nat}} [t - +] \\
\frac{\Gamma; \Delta \vdash e_1 : \text{nat} \quad \Gamma; \Delta \vdash e_2 : \text{nat}}{\Gamma; \Delta \vdash e_1 - e_2 : \text{nat}} [t - \text{minus}] \\
\frac{\Gamma; \Delta \vdash e_1 : T_1 \quad \Gamma; \Delta \vdash e_2 : T_2}{\Gamma; \Delta \vdash e_1; e_2 : T_1} [t - \text{pontoevirgula}] \\
\frac{\Gamma; \Delta \vdash e_1 : T_1 \quad \Gamma; \Delta \vdash e_2 : T_2}{\Gamma; \Delta \vdash e_1 : e_2 : T_2} [t - \text{doisPontos}]
\end{array}$$

$$\begin{array}{c}
\frac{\Gamma; \Delta \vdash e_1 : nat \quad \Gamma; \Delta \vdash e_2 : nat \quad \Gamma; \Delta \vdash e_3 : T_3}{\Gamma; \Delta \vdash \text{for } e_1 \text{ until } e_2 \text{ do } e_3 : T_3} [t - \text{for}] \\
\\
\frac{\Gamma; \Delta \vdash e_1 : bool \quad \Gamma; \Delta \vdash e_2 : T_2 \quad \Gamma; \Delta \vdash e_3 : T_2}{\Gamma; \Delta \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : T_2} [t - \text{if}] \\
\\
\frac{\Gamma; \Delta \vdash e_1 : ref T_1 | unit \quad \Gamma; \Delta \vdash e_2 : T_1}{\Gamma; \Delta \vdash e_2 := e_1 : unit} [t - \text{assing}]
\end{array}$$