# Software Development for Data Analysis

#### The explained variance and informational redundancy

• The quantity of variance explained by each pair of canonical variables, in connection with each of the initial data set, is given by the sum of correlations between the canonical variables and the causal variables of the sets:

$$VX_k = \sum_{j=1}^{p} R(z_k, X_j)^2, k = 1,m$$
  
 $VY_k = \sum_{j=1}^{q} R(u_k, Y_j)^2, k = 1,m$ ,

• where  $R(z_k, X_j)^2$  is the determination (correlation) coefficient between the canonical variable  $z_k$  of the pair k, and the variable  $X_j$ , belonging to the first data set (the j column of matrix X),

## The explained variance and informational redundancy

- and  $R(u_k, Y_j)^2$  is the correlation coefficient between the canonical variable  $u_k$  of the pair k, and the causal variable  $Y_j$ , belonging to the second data set (the j column of matrix Y)
- Proportionally, the values are:  $\frac{VX_k}{p}$  and  $\frac{VY_k}{q}$ , p and q being the number of causal variables, columns, of matrices X, and Y, respectively.
- The overall variance explained by all m canonical roots is:  $VX = \sum_{k=1}^{m} VX_k$ , for the first data set X, and  $VY = \sum_{k=1}^{m} VY_k$ , for the second data set Y.

#### The explained variance and informational redundancy

- The redundancy is given by the common information existent in both data sets, and extracted by the canonical roots (pairs).
- The common information is given by the canonical correlation.
- If there is a certain quantity of information extracted by a canonical variable from one of the sets, then the part of this information found in the other set it is retrieved by using the canonical correlation, as follows:

$$SX_k = VX_k \cdot \alpha_k$$
,  $k = 1, m$ 

$$SY_k = VY_k \cdot \alpha_k$$
,  $k = 1, m$ 

where the eigenvalue  $\alpha_k$  is the correlation coefficient between the canonical variables  $z_k$  and  $u_k$ .

#### The explained variance and informational redundancy

• The redundancy of all *m* canonical roots is:

$$SX = \sum_{k=1}^{m} SX_{k} ,$$

$$SY = \sum_{k=1}^{m} SY_k$$
.

#### **Standardizing canonical factors**

• Canonical factors are easier to interpret if standardized. Standardizing canonical factors implies to relate them to the standard deviation of initial and canonical variables.

$$as_{ik} = a_{ik} \cdot \frac{\sigma_{X_i}}{\sigma_{ik}}, i = 1, p; k = 1, m$$

$$bs_{ik} = b_{ik} \cdot \frac{\sigma_{Y_i}}{\sigma_{u_k}}, i = 1, q; k = 1, m$$

• The interpretation of standardized canonical factors is similar to multiple regression: the increase with one unit of variables  $X_i$  or  $Y_i$  standard deviation, generates an increase with  $as_{ik}$  or  $bs_{ik}$  of canonical variables  $z_k$  or  $u_k$  standard deviation.

## Canonical roots - Bartlett $\chi^2$ relevance test

- Bartlett  $\chi^2$  is the most employed test to evaluate canonical correlations.
- For any given canonical root, the result of the test indicates if there is any dependency between the two sets of variables or, on the contrary, the two sets of variables are independent.
- H0 hypothesis: correlation coefficient  $R(z_k, u_k)$  indicates the existence of a linear correlation between the two sets of initial (causal) variables.
- H1, the alternative hypothesis: correlation coefficient  $R(z_k, u_k)$  indicates a lack of connection.

## Canonical roots - Bartlett $\chi^2$ relevance test

- For a canonical root  $(z_k, u_k)$ , the test is applied as follows:
- **1.** The number of degrees of freedom is computed, associated to each canonical root of rank *k*:

$$df_k = (p-k+1)(q-k+1)$$

where p and q are the number of initial variables of the first and second sets, respectively.

2. The statistics of the test is computed as follows:

$$\chi_k^2 = \left(-n+1+\frac{p+q+1}{2}\right)\log(1-\lambda_k)$$

where n is the number of observations, and  $\lambda_k$  is an indicator named lambda Wilks.

## Canonical roots - Bartlett $\chi^2$ relevance test

Lambda Wilks indicator is computed in the following manner:

$$\lambda_k = \prod_{i=k}^m \left(1 - R(z_i, u_i)^2\right)$$
, where *m* is the number of canonical

roots.

3. Using  $\chi^2$  distribution, it is then determined the critical value for the test:

$$\chi c_k^2 (1 - \alpha, df_k)$$
, for a significance threshold  $\alpha$ .

**4.** Then the test is applied:

If 
$$\chi_k^2 \ge \chi c_k^2 (1 - \alpha, df_k)$$
,

the H0 hypothesis is accepted, with a level of confidence  $1 - \alpha$ , otherwise it is rejected.

#### **Generalized Canonical Analysis (gCCA)**

Having given q data sets  $X_1, X_2, ..., X_q$  which describe the same n observations,  $m_i$  the number of columns of matrix  $X_i$  and  $W_i$  the subspace in  $\mathbb{R}^n$  generated by the columns, we make the following notations:

- $P_i$  is the orthogonal projection  $X_i$  on subspace  $W_i$ .
- The total number of causal variables is  $m = \sum_{i=1}^{q} m_i$ .
- Make the assumption that n > m.

## **Generalized Canonical Analysis (gCCA)**

Generalized canonical analysis is to determine in the first phase an auxiliary variable  $Z_1$ , as a linear combination of causal variables and q canonical variables  $z_{i1}$  (i = 1, q), such that:

- $\sum_{i=1}^{q} R^2(Z_1, z_{i1})$  to be maximal, under the restriction of having:
- To ensure their unicity, the restriction of normality has to be imposed:  $(Z_1)^t Z_1 = 1$

## **Generalized Canonical Analysis (gCCA)**

- In order to have the sum of the correlation maximal, the vectors  $z_{i1}$  are selected such that to be orthogonal projection of  $Z_1$  vector on subspaces  $W_i$ :  $z_{i1} = P_i \cdot Z_1$ .
- Returning to the correlation sums, it can be rewritten as follows:

$$\sum_{i=1}^{q} R^{2}(Z_{1}, z_{i1}) = \sum_{i=1}^{q} \frac{Cov(Z_{1}, z_{i1})^{2}}{Var(Z_{1})Var(z_{i1})} =$$

$$= \sum_{i=1}^{q} \frac{\left(\frac{1}{n}(Z_{1})^{t}z_{i1}\right)^{2}}{\frac{1}{n}(Z_{1})^{t}Z_{1}} = \sum_{i=1}^{q} \frac{\left(\frac{1}{n}(Z_{1})^{t}z_{i1}\right)^{2}}{\frac{1}{n^{2}}(z_{i1})^{t}z_{i1}} = \sum_{i=1}^{q} \frac{\left((Z_{1})^{t}z_{i1}\right)^{2}}{\left(Z_{i1}\right)^{t}z_{i1}} = \sum_{i=1}^{q} \frac{\left((Z_{1})^{t}z_{i1}\right)^{2}}{\left(Z_{i1}\right)^{t}z_{i1}}$$

#### **Generalized Canonical Analysis (gCCA)**

• Replacing  $z_{i1}$  with  $P_i \cdot Z_1$ , we obtain:

$$\sum_{i=1}^{q} R^{2}(Z_{1}, z_{i1}) = \sum_{i=1}^{q} \frac{\left( (Z_{1})^{t} P_{i} Z_{1} \right)^{2}}{\left( Z_{1} \right)^{t} \left( P_{i} \right)^{t} P_{i} Z_{1}} = \sum_{i=1}^{q} \left( Z_{1} \right)^{t} P_{i} Z_{1} = \left( Z_{1} \right)^{t} \left( \sum_{i=1}^{q} P_{i} \right) Z_{1},$$

because 
$$(P_i)^t P_i = P_i^2 = P_i$$
.

• Therefore, the optimum problems becomes:

$$\begin{cases} Maxim(Z_1)^t \left(\sum_{i=1}^q P_i\right) Z_1 \\ (Z_1)^t Z_1 = 1 \end{cases}$$

## **Generalized Canonical Analysis (gCCA)**

• The solution of this problem (see PCA) implies that the variable  $Z_1$ ,

is the eigenvector of the matrix 
$$\sum_{i=1}^{q} P_i$$

corresponding to the greatest eigenvalue, while the canonical variables of the sets,  $z_{i1}$ , are determined using the relation:

$$z_{i1} = P_i \cdot Z_1$$
.

• At the k phase there is to be determined the auxiliary variable  $Z_k$  and the canonical variables  $z_{ik}$  (i = 1, q) such that:

$$\sum_{i=1}^{q} R^2(Z_k, z_{ik})$$

to be maximal.

## **Generalized Canonical Analysis (gCCA)**

• Under the following conditions:

$$1) \left( Z_{k} \right)^{t} Z_{k} = 1 ,$$

2) 
$$(Z_k)^t Z_j = 0$$
,  $j = \overline{1, k-1}$ 

• The variable  $Z_k$  is the eigenvector of matrix  $\sum_{i=1}^{n} P_i$ ,

corresponding to the eigenvalue of rank k, while the canonical variables of the sets are:  $z_{ik} = P_i Z_k$ .

## **Generalized Canonical Analysis (gCCA)**

• The orthogonal projection on space  $W_i$  is determined using the following relation:

$$P_i = X_i (X_i^t X_i)^{-1} X_i^t$$
,  $i=1, q$  (see the CCA).

• If the sum of the projection matrices is developed then:

$$\sum_{i=1}^{q} P_{i} = \sum_{i=1}^{q} X_{i} \cdot (X_{i}^{t} X_{i})^{-1} X_{i}^{t} = X \cdot D_{XX}^{-1} X^{t},$$

where  $D_{XX}$  is a block-diagonal matrix of the following format:

$$egin{bmatrix} V_{11} & 0 & ... & 0 \ 0 & V_{22} & ... & 0 \ ... & ... & 0 \ 0 & 0 & ... & V_{qq} \ \end{bmatrix}$$
 ,

## **Generalized Canonical Analysis (gCCA)**

with 
$$V_{jj} = X_j^t X_j$$

The matrix  $X \cdot D_{XX}^{-1} X^t$  has *n* rows and *n* columns.

- The number non-zero eigenvalue of the matrix  $X \cdot D_{XX}^{-1} X^t$ , and the number of implicit steps (phases) of the algorithm is m, the total number of the initial (causal) variables.
- An auxiliary variable  $Z_k$  is eigenvector of the matrix

$$X \cdot D_{XX}^{-1} X^t$$

if:

$$X \cdot D_{XX}^{-1} X^t Z_k = \alpha_k Z_k \tag{1}$$

#### **Generalized Canonical Analysis (gCCA)**

• Since  $Z_k$  is a linear combination of causal variables, it can be written as:

$$Z_k = X \cdot b_k$$
,

where  $b_k$  is the vector of the linear combination, or *the factor*.

• Replacing  $Z_k$  in relation (1) it is obtained:

$$X \cdot D_{XX}^{-1} X^{\dagger} X \cdot b_k = \alpha_k X \cdot b_k \tag{2}$$

• Multiplying relation (2) at the left with the matrix  $(X^t X)^{-1} X^t$  it is obtained:

$$(X^{t}X)^{-1}X^{t}X \cdot D_{XX}^{-1}X^{t}X \cdot b_{k} = \alpha_{k}(X^{t}X)^{-1}X^{t}X \cdot b_{k}$$

## **Generalized Canonical Analysis (gCCA)**

- Therefore:  $D_{XX}^{-1} X^t X \cdot b_k = \alpha_k b_k$ .
- Hence the factors  $b_k$  are obtained as eigenvectors of the matrix  $D_{XX}^{-1} X^t X$
- The eigenvalues of the matrix  $D_{XX}^{-1} X^t X$  coincide with the m non-zero eigenvalues of the matrix  $X \cdot D_{XX}^{-1} X^t$ .
- The eigenvalues represent the sum of the determination (correlation) coefficients between the auxiliary variables  $Z_k$  and the canonical variables of the sets:

$$\alpha_k = \sum_{j=1}^q R(Z_k, z_{jk})^2, \quad k = \overline{1, m}.$$