Homework no. 6

Given (n+1) distinct points, x_0, x_1, \ldots, x_n $(x_i \in \mathbf{R} \ \forall i, x_i \neq x_j, i \neq j)$ and the (n+1) values of an unknown function f at these points, $y_0 = f(x_0)$, $y_1 = f(x_1), \ldots, y_n = f(x_n)$:

approximate the value of function f in \bar{x} , $f(\bar{x})$, for a given \bar{x} , a value which is not in the above table, $\bar{x} \neq x_i$, $i = 0, \ldots, n$ using:

- polynomial approximation computed with the least squares method. For computing the value of least squares polynomial in \bar{x} , use Horner's algorithm; display $P_m(\bar{x})$, $|P_m(\bar{x}) f(\bar{x})|$ and $\sum_{i=0}^n |P_m(x_i) y_i|$. For m introduce values smaller than 6.
- using the quadratic spline function of class C^1 . In this case, consider also known about function f, the value of the first derivative in x_0 , $d_a = f'(x_0 = a)$. Display $S_f(\bar{x})$ şi $|S_f(\bar{x}) f(\bar{x})|$.

For solving the linear systems involved in solving the above interpolation problems use the library employed in **Homework 2**.

Generate the interpolation nodes $\{x_i, i = 0, ..., n\}$ in the following way: $x_0 \not \equiv x_n$ are introduced from the keyboard or from a file such that $x_0 < x_n$, and x_i are randomly generated such that $x_i \in (x_0, x_n)$ and $x_{i-1} < x_i$; the values $\{y_i, i = 0, ..., n\}$ are computed using a function f declared in your program (examples of how to choose the nodes x_0, x_n and the function f(x) are at the end of this document), $y_i = f(x_i), i = 0, ..., n$;

Bonus (10 pt): Draw the graphs of function f and of the approximative computed functions P_m and T_n .

Least Squares Interpolation

Let $a = x_0 < x_1 < \cdots < x_n = b$. Given $\bar{x} \in [a, b]$ approximate $f(\bar{x})$ knowing that the n + 1 values y_i of function f in the interpolation nodes.

One computes a polynomial of degree m:

$$P_m(x) = P_m(x; a_0, a_1, \dots, a_m) = a_m x^m + a_{m-1} x^{m-1} + \dots + a_1 x + a_0 = \sum_{k=0}^m a_k x^k$$

the coefficients $\{a_i; i = \overline{0, m}\}$ being the solution to the optimization problem:

$$\min \left\{ \sum_{r=0}^{n} \left| P_m(x_r; a_0, a_1, \dots, a_m) - y_r \right|^2 ; \ a_0, a_1, \dots, a_m \in \mathbb{R} \right\}$$

Solving this problem leads to solving the linear system:

$$Ba = f$$

$$B = (b_{ij})_{i,j=0,\dots,m} \in \mathbb{R}^{(m+1)\times(m+1)} \quad f = (f_i)_{i=0,\dots,m} \in \mathbb{R}^{m+1}$$

$$\sum_{j=0}^{m} \left(\sum_{k=0}^{n} x_k^{i+j}\right) a_j = \sum_{k=0}^{n} y_k x_k^i \quad , \quad i = 0,\dots,m$$

This linear system can be solved with the same numerical library that was used for *Homework 2*.

The value of function f in \bar{x} is approximated by the value of the polynomial P_m in \bar{x} :

$$f(\bar{x}) \approx P_m(\bar{x}; a_0, a_1, \dots, a_m)$$

For computing the value of polynomial $P_m(\bar{x})$ use Horner's method described below.

Horner's method for computing P(v)

Let P be a polynomial of degree p:

$$P(x) = c_0 x^p + c_1 x^{p-1} + \dots + c_{p-1} x + c_p , \quad (c_0 \neq 0)$$

We can write polynomial P also as:

$$P(x) = ((\cdots((c_0x + c_1)x + c_2)x + c_3)x + \cdots)x + c_{p-1})x + c_p$$

Taking into account this grouping of the coefficients, one obtains an efficient way to compute the value of polynomial P in any point $v \in \mathbf{R}$, this procedure is knowns as Horner's method:

In the above sequence:

$$P(v) := d_p$$

the rest of the computed elements of the sequence d_i , i = 1, ..., p - 1, are the coefficients of the quotient polynomial Q, obtained in the division:

$$P(x) = (x - v)Q(x) + r,$$

$$Q(x) = d_0x^{p-1} + d_1x^{p-2} + \cdots + d_{p-2}x + d_{p-1},$$

$$r = d_p = P(v).$$

Computing P(v) (d_p) with formula (1) can be performed using only one real variable $d \in \mathbf{R}$ instead of using a vector $d \in \mathbf{R}^p$.

Quadratic spline functions of class C^1

Let $a = x_0 < x_1 < \cdots < x_n = b$. Given $\bar{x} \in [a, b]$, approximate the value of $f(\bar{x})$ knowing beside the n + 1 pairs $(x_i, y_i = f(x_i))$ the value d_a of the first derivative of function f in a:

$$f'(a) = d_a.$$

One looks for a function S_f of class C^1 on [a, b] such that:

$$S_f(x) = a_i x^2 + b_i x^2 + c_i$$
, for $x \in [x_i, x_{i+1}]$, $i = \overline{0, n-1}$
 $S_f(x_i) = y_i$, $i = \overline{0, n}$, $S'_f(a) = d_a(d_a = f'(a))$

The function S_f that satisfies the above stated properties has the following form:

$$S_f(x) = \frac{(A_{i+1} - A_i)}{2h_i} (x - x_i)^2 + A_i(x - x_i) + y_i \quad , \text{ for } x \in [x_i, x_{i+1}], \ i = \overline{0, n-1}$$

where

$$h_i = x_{i+1} - x_i$$
 , $i = 0, ..., n-1$
 $A_{i+1} = -A_i + \frac{2(y_{i+1} - y_i)}{h_i}$, $i = 0, ..., n-1$
 $A_0 = d_a$

The value of function f in \bar{x} , $f(\bar{x})$, is approximated by the value $S_f(\bar{x})$ (\bar{x} must be a value in the interval [a,b]). One searches an index i_0 such that $\bar{x} \in [x_{i_0}, x_{i_0+1}]$. We have:

$$f(\bar{x}) \approx S_f(\bar{x}) = \frac{(A_{i_0+1} - A_{i_0})}{2h_{i_0}} (x - x_{i_0})^2 + A_{i_0}(x - x_{i_0}) + y_{i_0}.$$

Input data - examples

$$x_0 = a = 1$$
 , $x_n = b = 5$, $f(x) = x^2 - 12x + 30$
 $x_0 = a = 0$, $x_n = b = 1.5$, $f(x) = \sin(x) - \cos(x)$
 $x_0 = a = 0$, $x_n = b = 2$, $f(x) = 2x^3 - 3x + 15$