

# Consensus By Synchronization of Alternative Models

Greg Duane  
MANU

-with contributions from

Ljupco Kocarev

Frank Selten

Wim Wiegerinck

Lasko Basnarkov

Leonie van den Berge

Paul Hiemstra

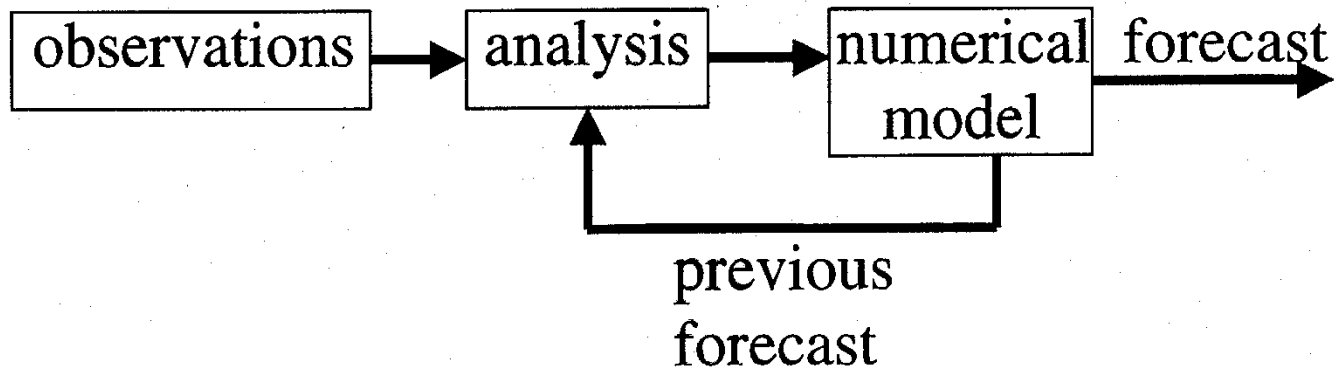
Supported by:

DOE Grant# DE-SC0005238

and

ERC Grant# 266722

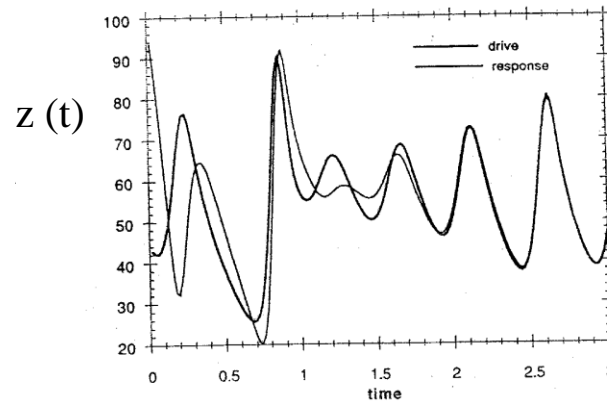
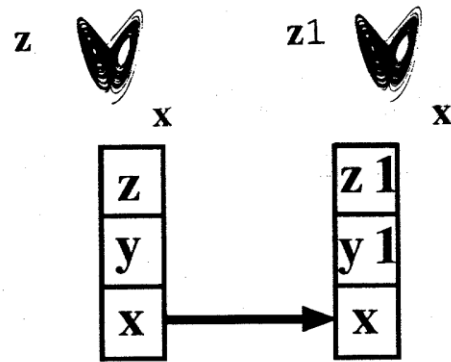
# DATA ASSIMILATION



- the model is a semi-autonomous dynamical system influenced by observations

# SUPPOSE THE WORLD IS A LORENZ SYSTEM AND ONLY $x$ IS OBSERVED

- two coupled chaotic systems can fall into synchronized motion along their strange attractors when linked through only one variable

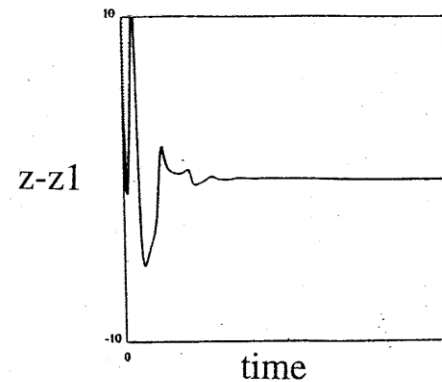


$$x' = \sigma(y-x)$$

$$y' = \rho x - y - xz \quad y_1' = \rho x - y_1 - x(z_1)$$

$$z' = -\beta z + xy \quad z_1' = -\beta(z_1) + x(y_1)$$

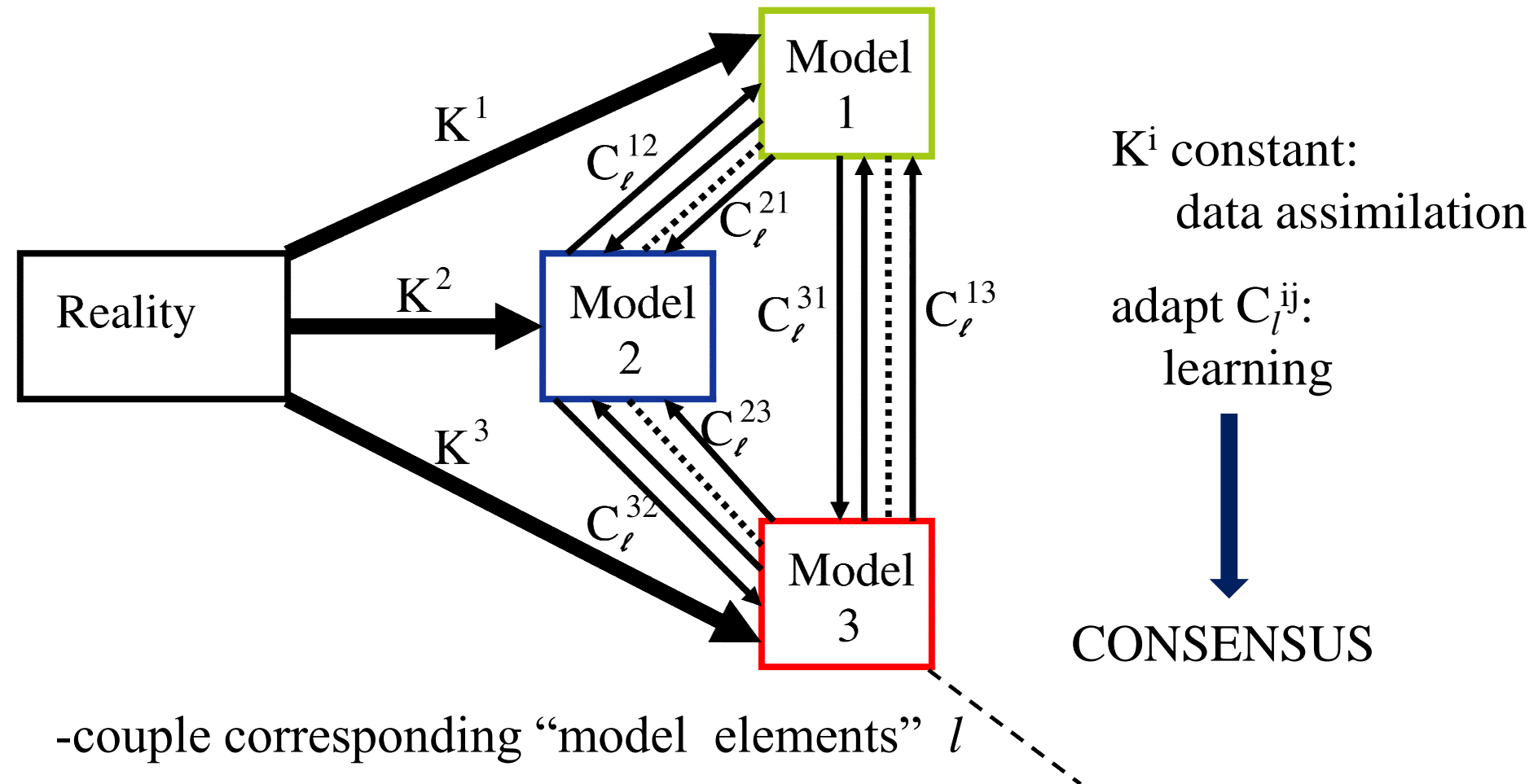
(also works for  $y$ -coupling, but not for  $z$ -coupling)



(Pecora and Carroll '90)

- SYNCHRONIZATION  $\longrightarrow$  DATA ASSIMILATION

LET A COLLECTION OF MODELS  
ASSIMILATE DATA FROM  
(SYNCHRONIZE WITH) ONE ANOTHER;  
ADAPT THE COUPLING COEFFICIENTS



# SUMMARY

- Problem: IPCC-class climate models give widely divergent predictions in regard to:

- a) magnitude of long-term climate change
- b) detailed regional predictions
- c) short-term climate change

Can we do better than averaging model outputs?

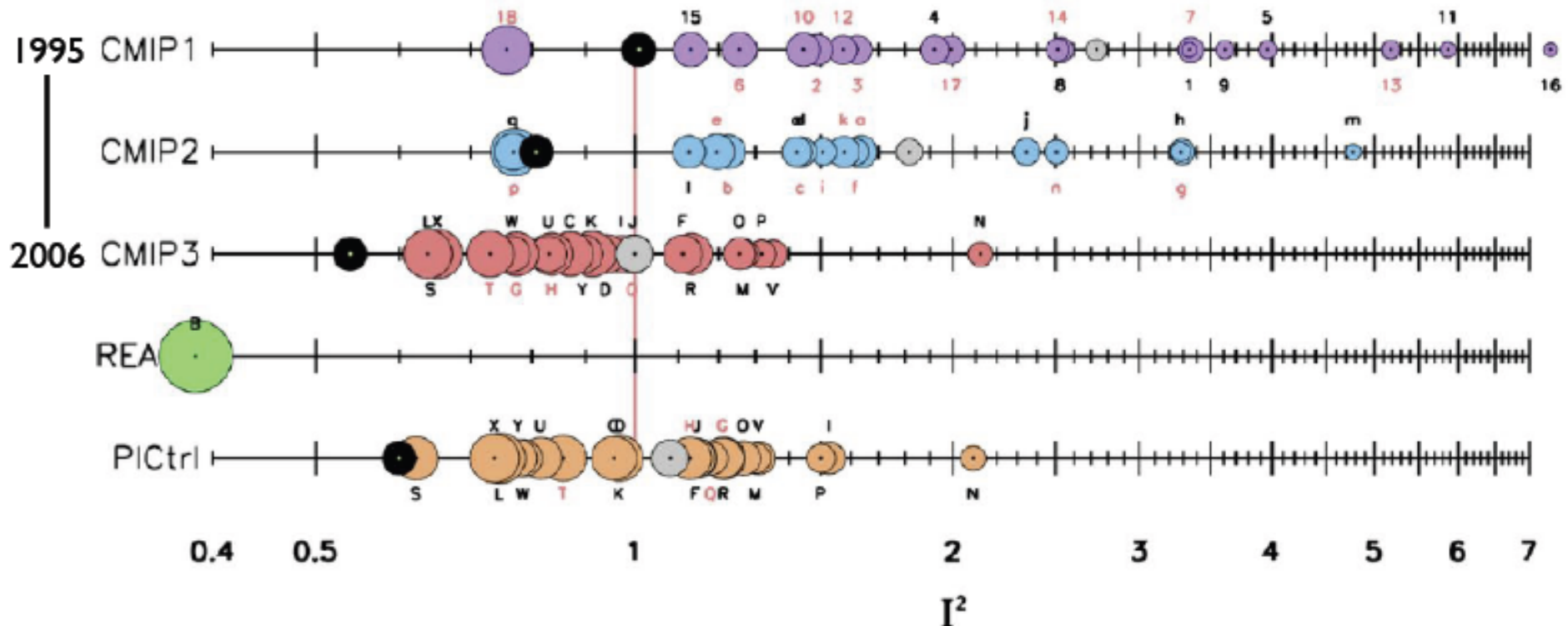
- Potential Solution: Take the synchronization view of data assimilation, and allow models to form a consensus (synchronize) by assimilating data from one another.
  - Sync extends the “nudging” approach to assimilation.
  - Parameters can be nudged as well as states *without ensembles*.
  - Choose the adaptable parameters to be connection coefficients linking corresponding variables in different models; adapt them using historical data.

# Coupled Model Intercomparison Project

Reichler, T., and J. Kim (2008): How Well do Coupled Models Simulate Today's Climate? *Bull. Amer. Meteor. Soc.*, **89**, 303-311.

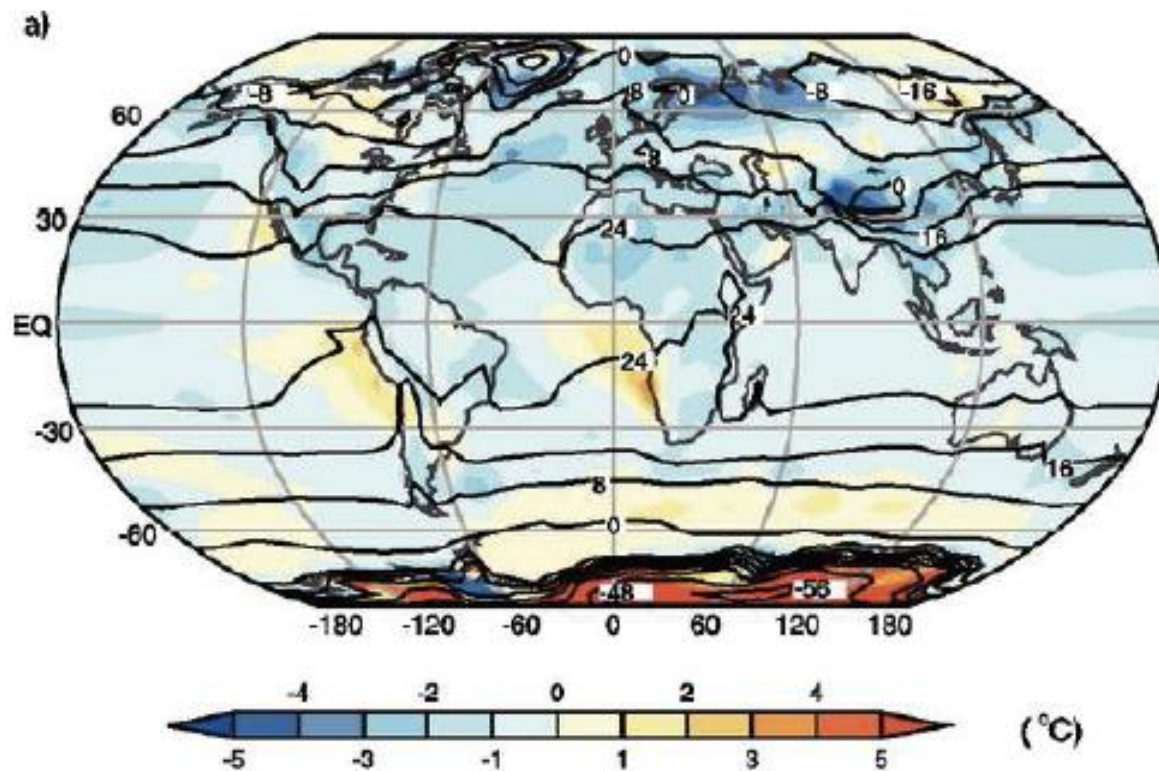
## Performance metric

Based on mean squared errors in time mean global temperatures, winds, precipitation, ....



● = index value based on multi model mean fields: outperforms individual models: why ?

# Error in annual mean surface air temperatures multi model mean over all CMIP3 simulations

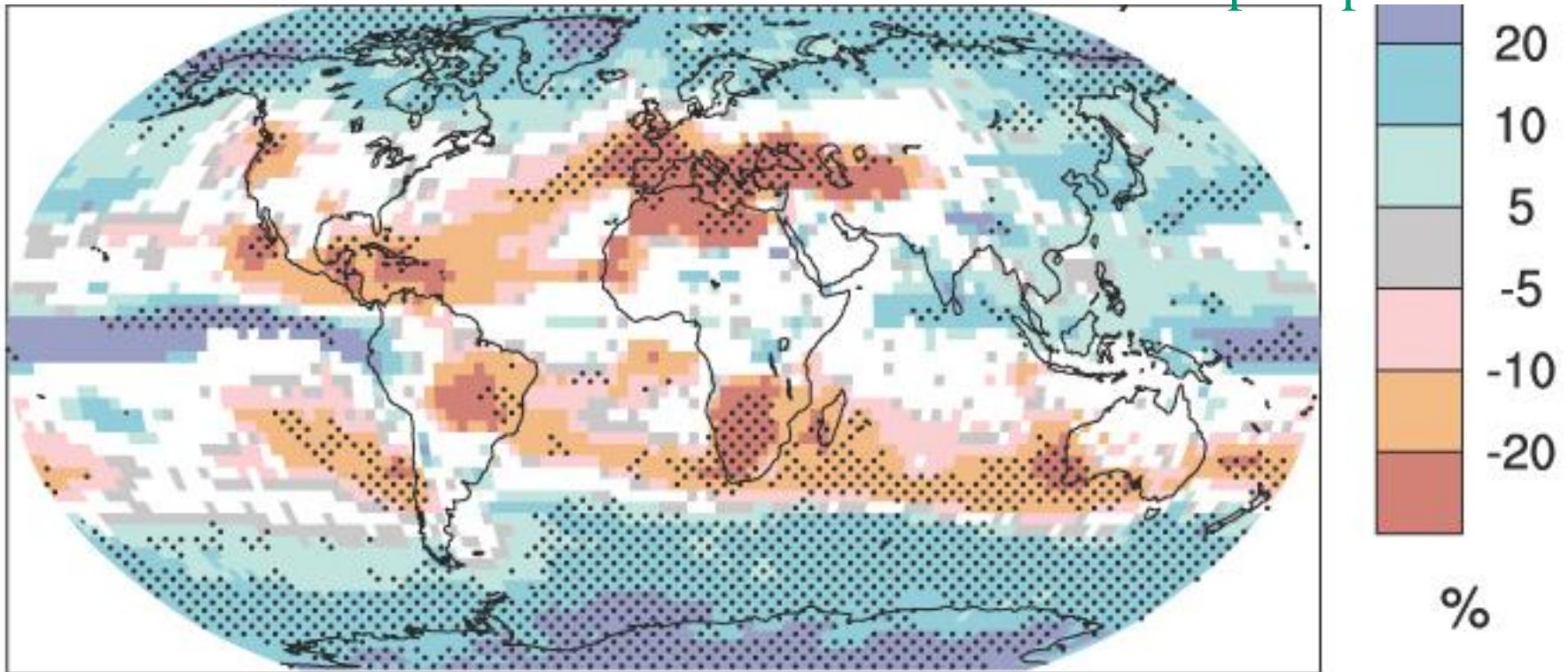


IPCC 2007



# EXAMPLE: DIVERGENT MODEL PROJECTIONS OF REGIONAL PRECIPITATION CHANGE

increased or decreased  
precipitation



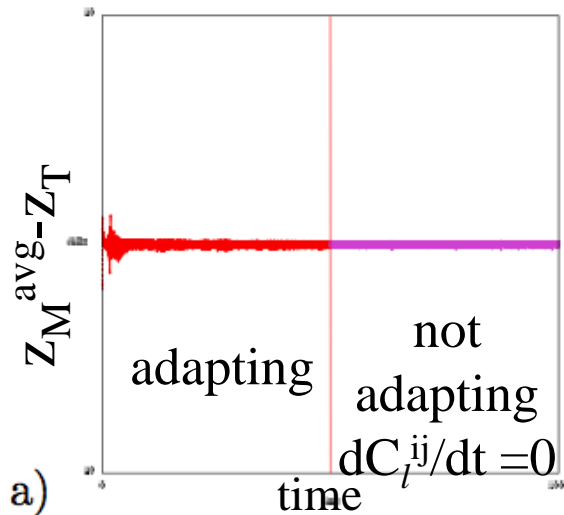
White areas: less than 2/3 of models agree on the sign of precipitation change

Stippled areas: more than 90% of models agree on the sign

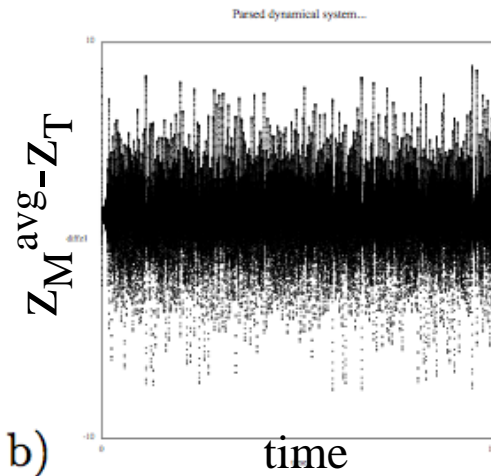


# Test Case: Fusing 3 Lorenz Systems With Different Parameters

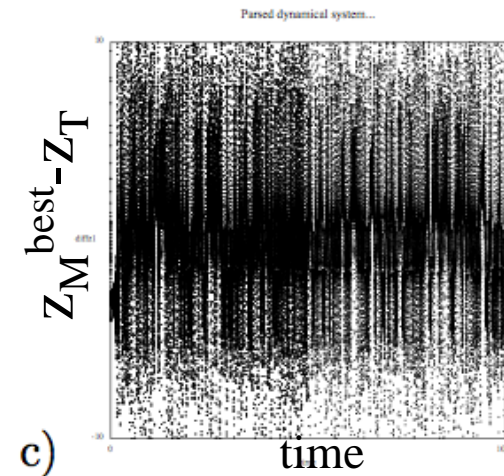
Fused Models



Average Output  
of Models (Unfused)



z from Model  
With Best z Eqn



$$\begin{aligned}\dot{x} &= \sigma(y - z) \\ \dot{y} &= \rho x - y - xz \\ \dot{z} &= -\beta z + xy \\ \dot{x}_i &= \sigma_i(y_i - z_i) + \sum_{j \neq i} C_{ij}^x(x_j - x_i) + K_x(x - x_i) \\ \dot{y}_i &= \rho x_i - y_i - x_i z_i + \mu_i + \sum_{j \neq i} C_{ij}^y(y_j - y_i) + K_y(y - y_i) \\ \dot{z}_i &= -\beta_i z_i + x_i y_i + \sum_{j \neq i} C_{ij}^z(z_j - z_i) + K_z(z - z_i)\end{aligned}$$

$$dC_x^{ij}/dt = a(x_j - x_i)(x - \frac{1}{3}\sum x_k)$$

$$i = 1, 2, 3$$

$$dC_y^{ij}/dt = \dots\dots\dots$$

$$dC_z^{ij}/dt = \dots\dots\dots$$

- Model fusion is superior to any weighted averaging of outputs

# Supermodeling Relies on 3-Way Synchronization of Truth and Alternative Models

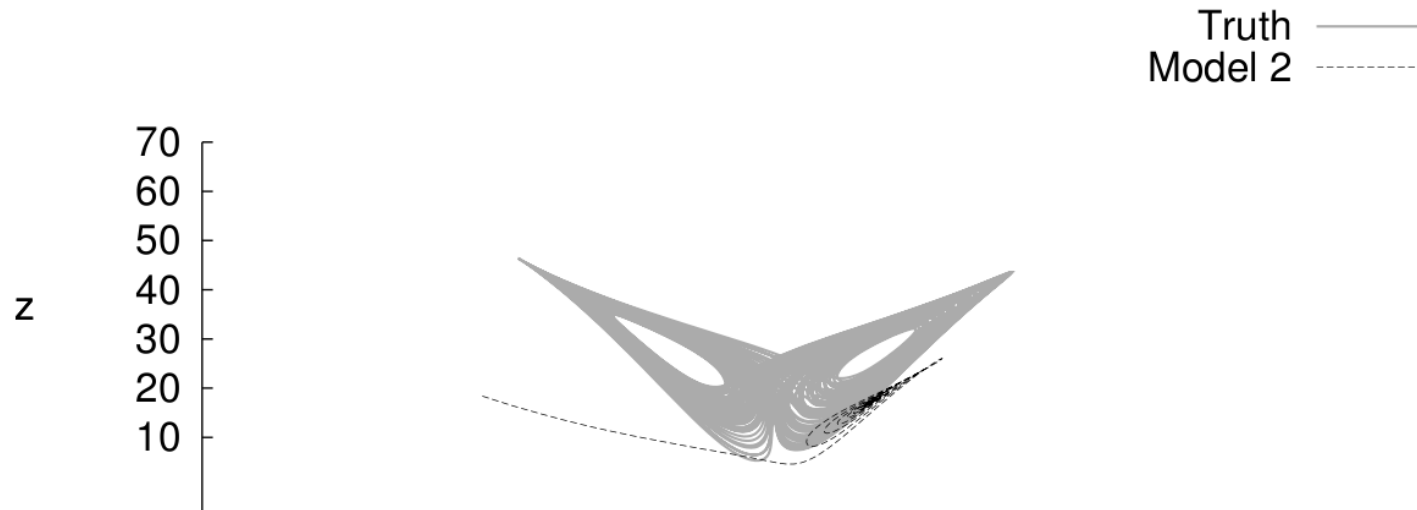
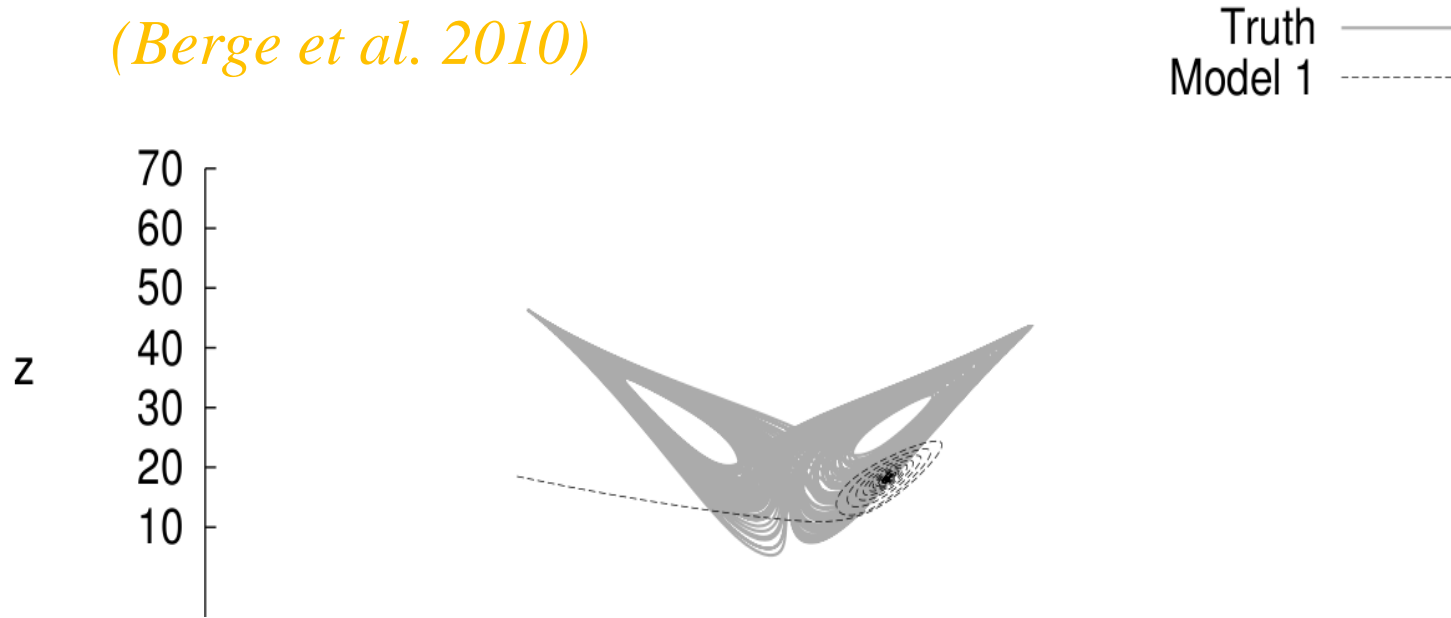
Hebbian learning: “cells that fire together wire together”

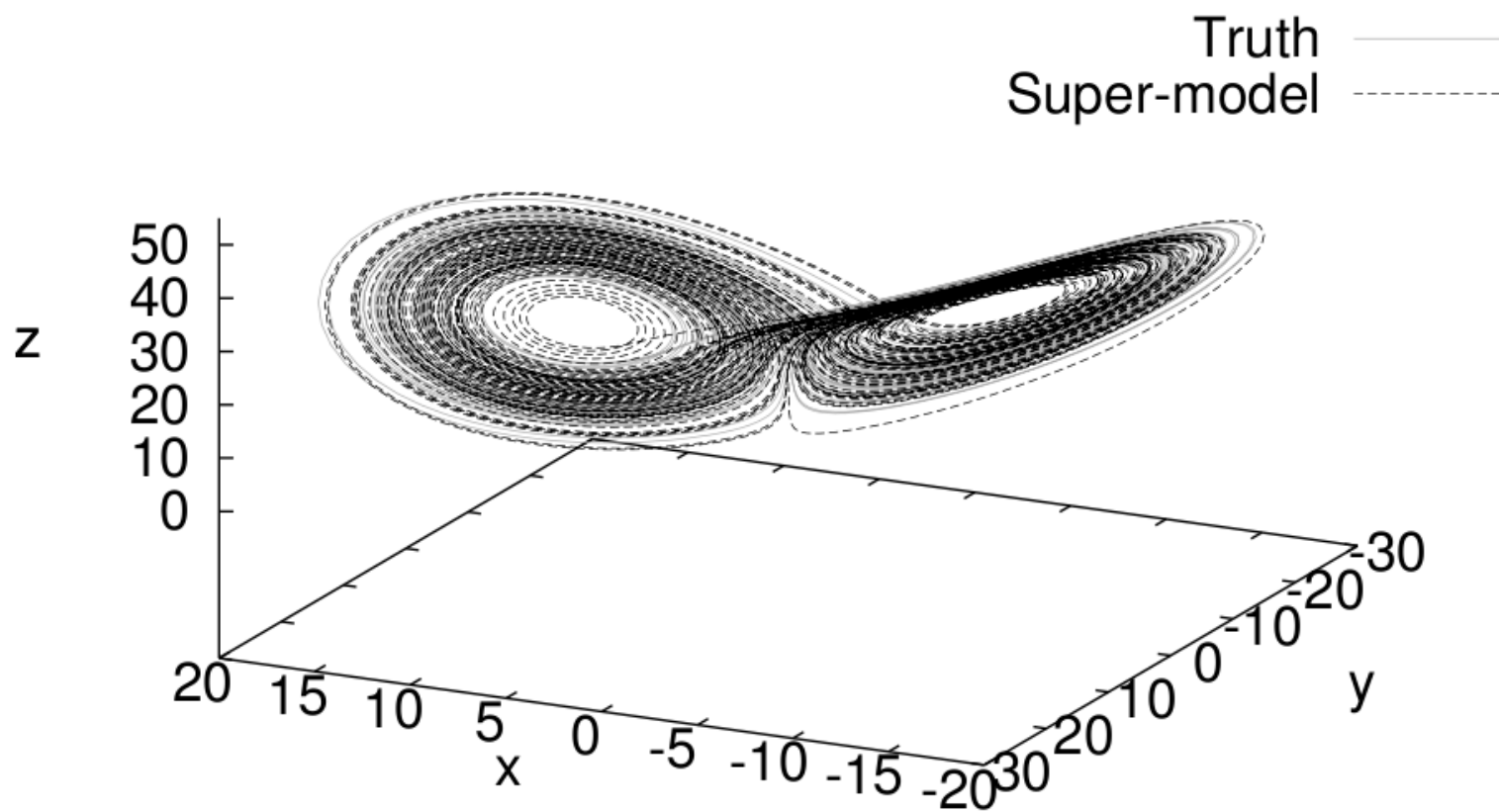
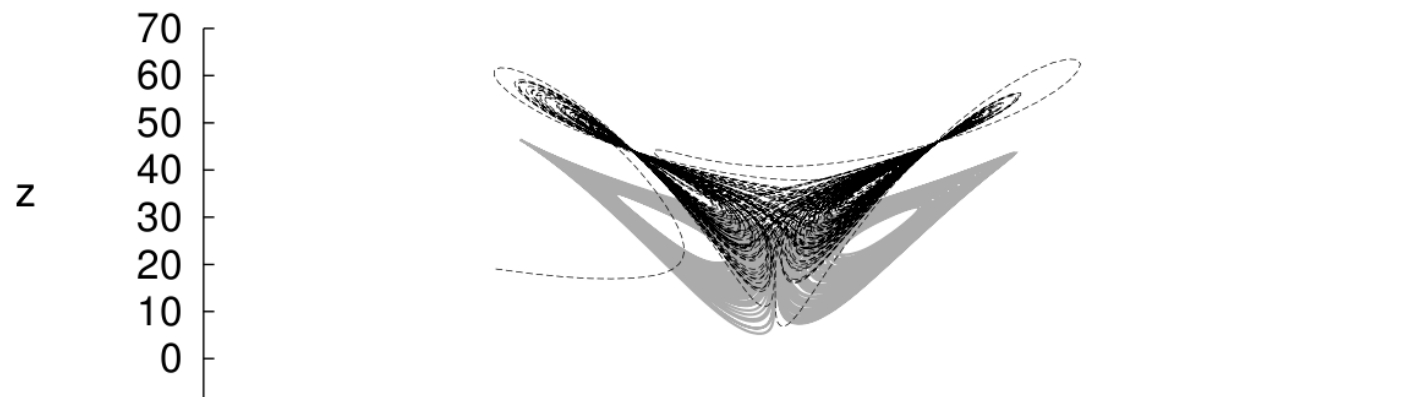


Supermodel learning: model elements “wire” together in such a way that they “fire” in synchrony with reality

# .....OR CAN USE STANDARD MACHINE LEARNING METHODS TO ADAPT INTER-MODEL CONNECTIONS

*(Berge et al. 2010)*



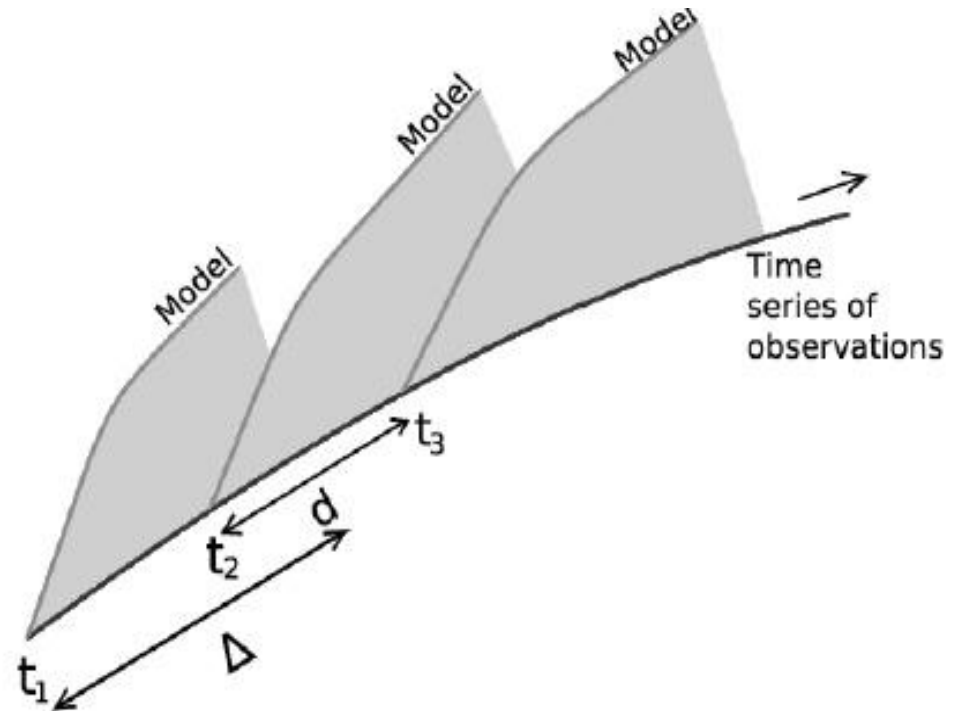


# Learning Algorithm

$$x_s = \frac{1}{3}(x_1 + x_2 + x_3)$$

$$y_s = \frac{1}{3}(y_1 + y_2 + y_3)$$

$$z_s = \frac{1}{3}(z_1 + z_2 + z_3)$$



**Minimize Cost function:**

$$F(C) = \frac{1}{K\Delta} \sum_{i=1}^K \int_{t_i}^{t_i+\Delta} |x_s(C, t) - x_o(t)|^2 \gamma^t dt$$

The cost function is normalized by  $\frac{1}{K\Delta}$ , so that it represents the time averaged mean squared error. The factor  $\gamma^t$  with  $0 < \gamma \leq 1$  is introduced to give stronger weight to the errors close to the initial condition

# Supermodeling Works With Multi-time-scale Models

Lorenz '84 coupled to ocean box model:

$$x' = -(y^2) - (z^2) - a x + a (F_0 + F_1 T) \quad f = \omega T - \xi S$$

$$y' = x y - b x z - y + G_0 + G_1 (T_{av} - T)$$

$$z' = b x y + x z - z$$

$$T' = k_a (\gamma x - T) - |f| T - k_w T$$

$$S' = \delta_0 + \delta_1 (y^2 + z^2) - |f| S - k_w S$$

$X_{\text{supermodel}} - X_{\text{truth}}$



In “weather-prediction mode” ocean strongly nudged to truth so as to obtain an atmospheric supermodel. Ocean supermodel can be trained on longer time scales.

$T_{\text{supermodel}} - T_{\text{truth}}$

# What if all models err in the same way?

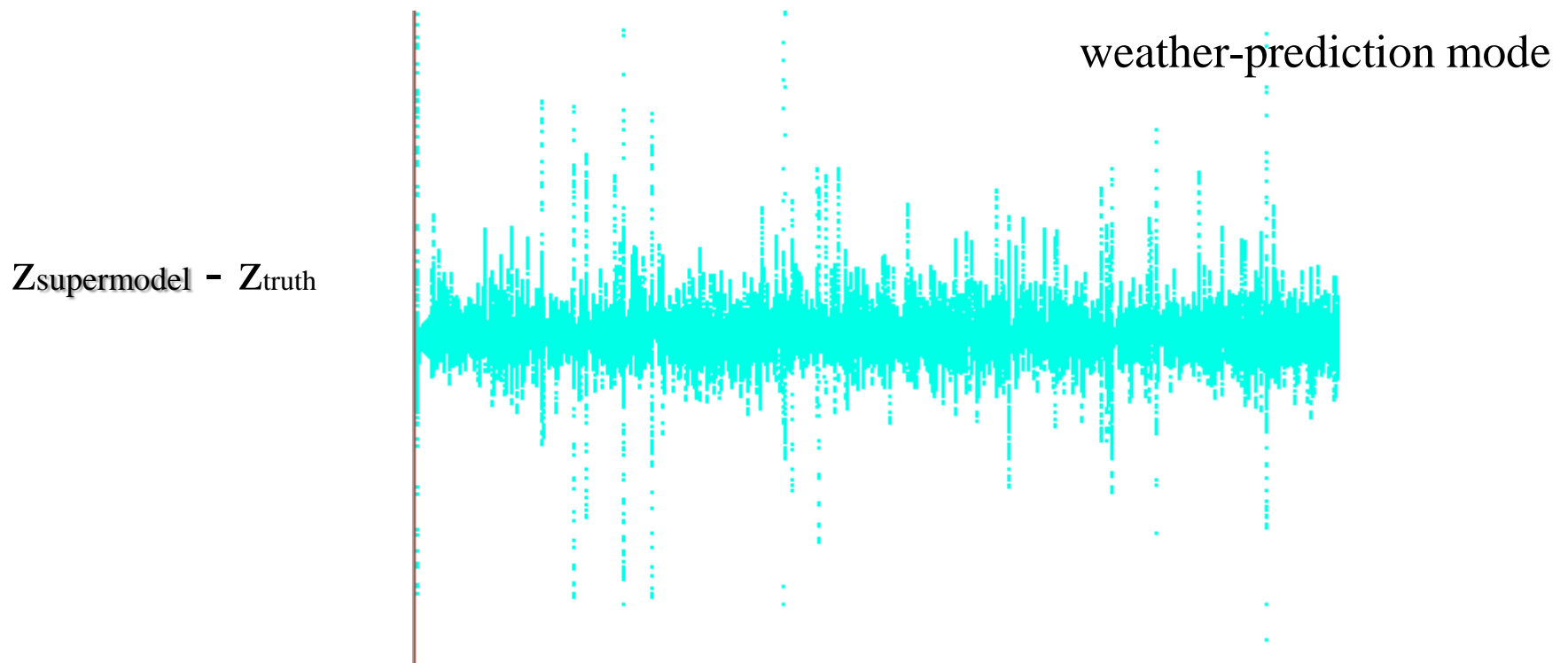
- Analogous to group of experts who make the same mistake, but to different degrees
- Use the advice of the expert who is consistently “least wrong” and extrapolate to values outside the range of the group
- A very risky procedure!



# What if all models are biased in same direction?

Lorenz supermodel with  $\sigma_{\text{truth}} < \sigma_1, \sigma_2, \sigma_3$

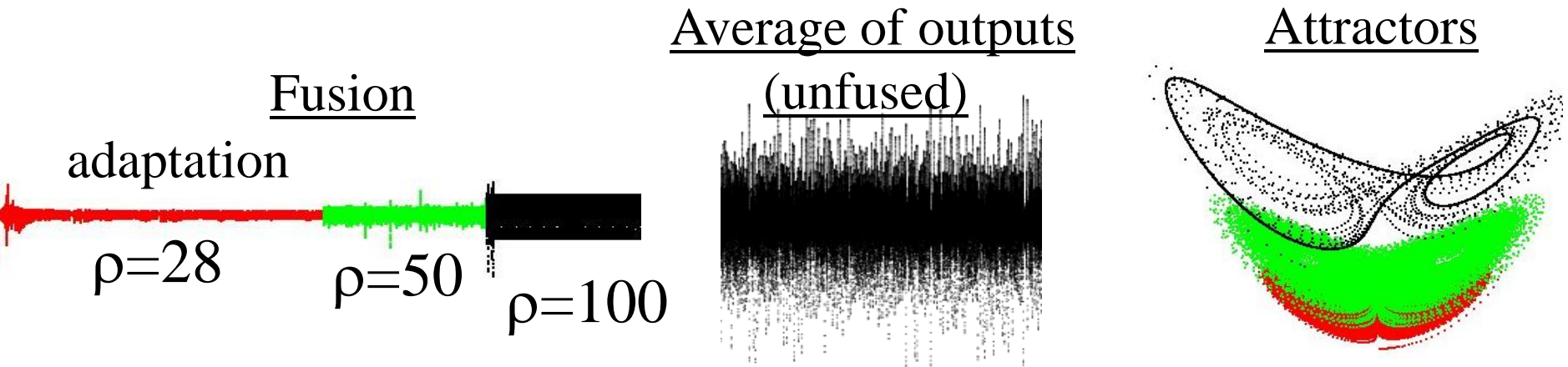
$\Rightarrow$  Some connections become negative



Not as effective as positive connections, but better than averaging.

# What if parameters shift between training and testing?

Train with Lorenz  $\rho=28$  and then reset  $\rho$  in “reality” and in 3 “models”

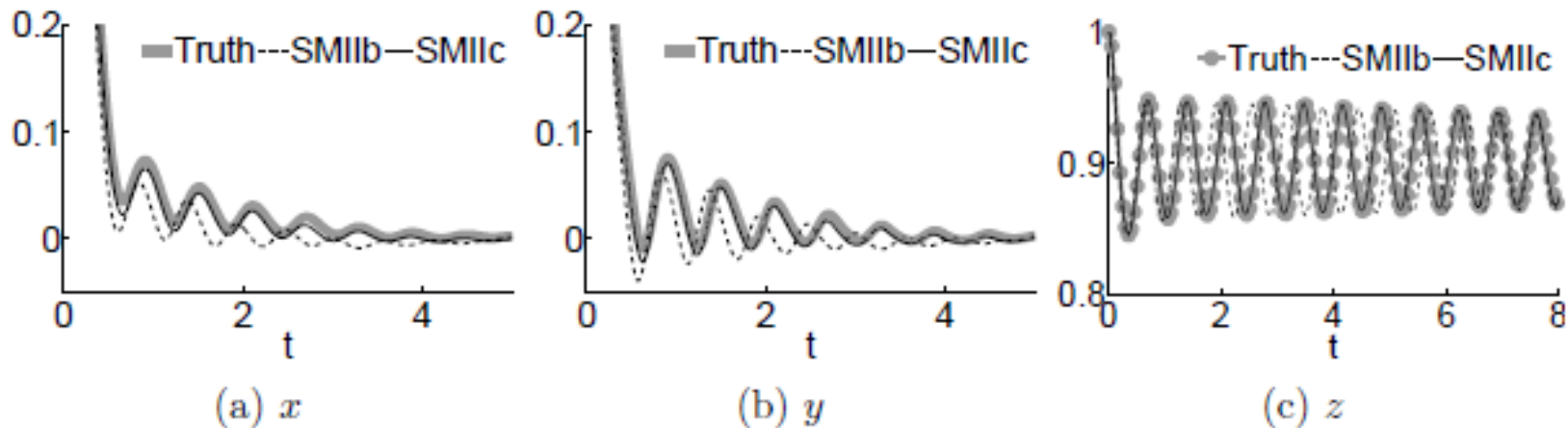


-fusion still better than averaging even when training and test systems differ by a large number of dynamical bifurcations

What if the connection scheme obtained by cost-minimization is only locally optimal?

- stochastic learning methods can help optimize supermodel

Autocorrelations for Truth and Two Supermodels



SMIIb is formed using a deterministic learning method

SMIIc is formed using a stochastic learning method

# Extension to PDE's: What is the required spatial density of inter-model coupling?

Synchronization of two 1D Kuramoto-Sivishinsky systems:

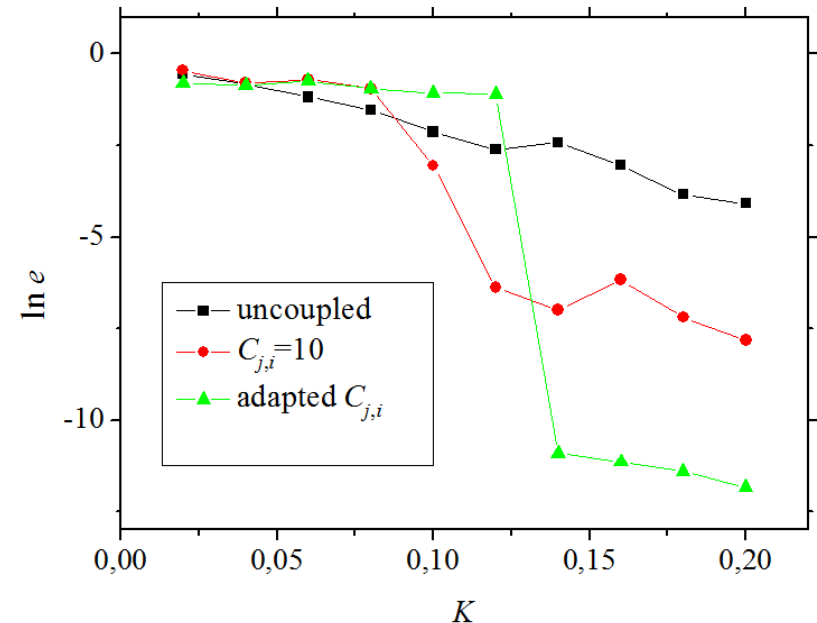
$$u_t = -u_{xxxx} - \alpha_u u_{xxx} - u_{xx} - 2uu_x$$

$$v_t = -v_{xxxx} - \alpha_v v_{xxx} - v_{xx} - 2vv_x + K[u(x) - v(x)]f(x)$$

$f(x)$  non-vanishing only at discrete points

Can form supermodel from 3 KS's:

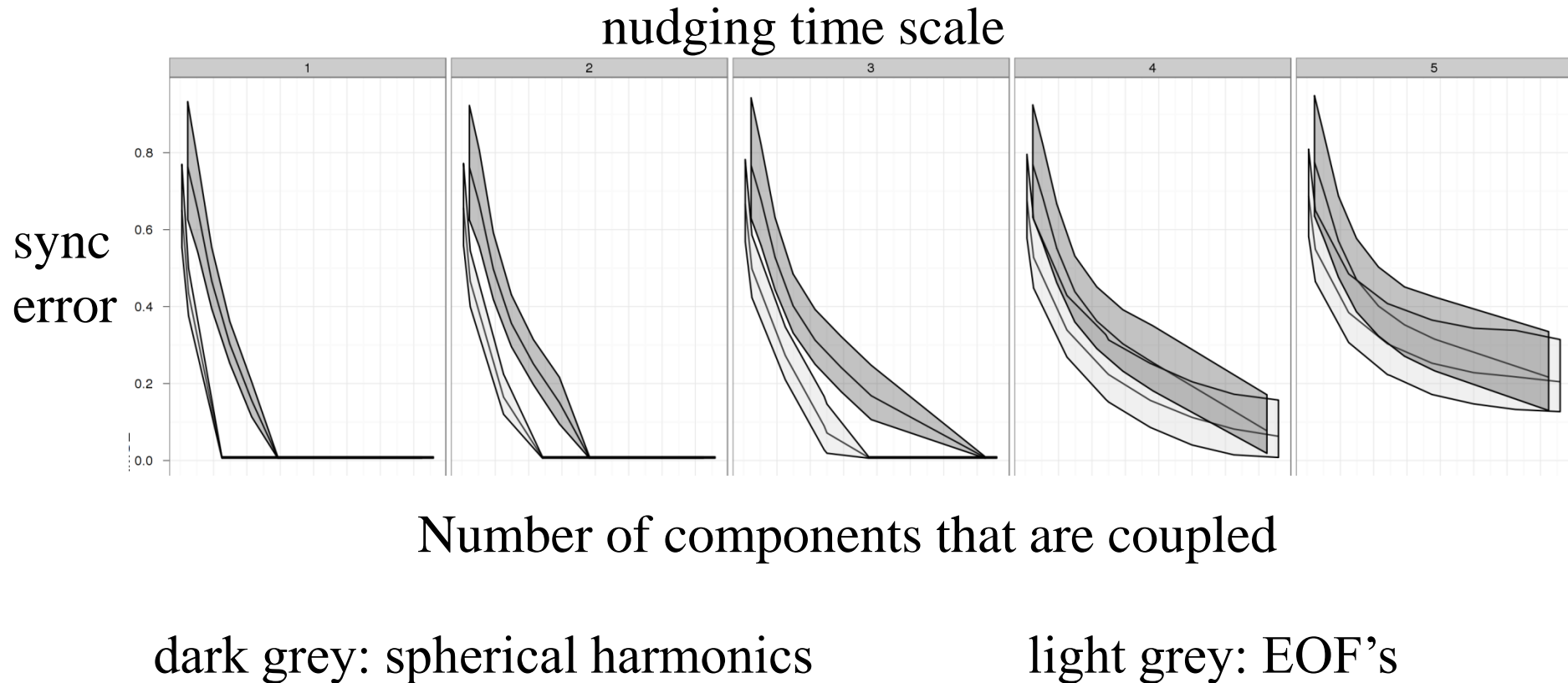
Maximum coupling distance is  
length scale of coherent structures:



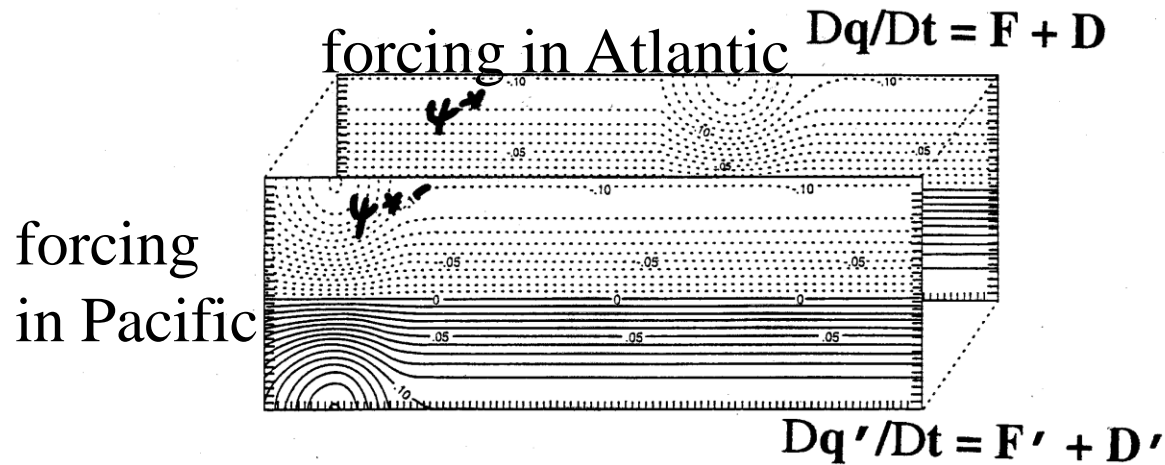
# What variables should be coupled?

Consider 3-layer QG model on sphere with realistic topography and a forcing chosen to reproduce the observed winter mean state.

Compare coupling in a basis of spherical harmonics to a basis of EOF's:



# Proposed Adaptive Fusion of Two QG Channel Models



$$F = f_o(q - q^*) + c J(\psi, q - q')$$

$$F' = f_o(q' - q^{*'}) + c J(\psi', q' - q)$$

$$c = 1/2 \Downarrow$$

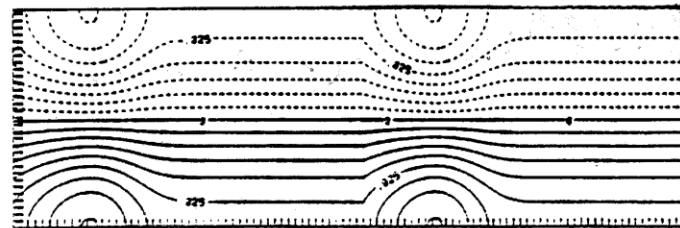
$$D/Dt (q + q')/2 = (F_o + F_o')/2 + (D + D')/2$$

(k-dependence suppressed)

$$F_o = f_o(q - q^*)$$

$$F_o' = f_o(q' - q^{*'})$$

- If the parallel channels synchronize, their common solution also solves the single-channel model with the average forcing



$$\frac{\Psi^* + \Psi^{*'}}{2}$$

To find  $c$  adaptively:

$$dc/dt = \int d^2x J(\psi, q' - q)(q - q_{obs}) + \int d^2x J(\psi', q - q')(q' - q_{obs})$$



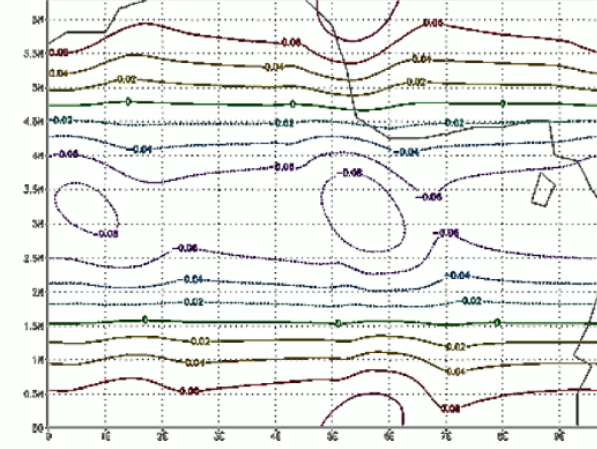
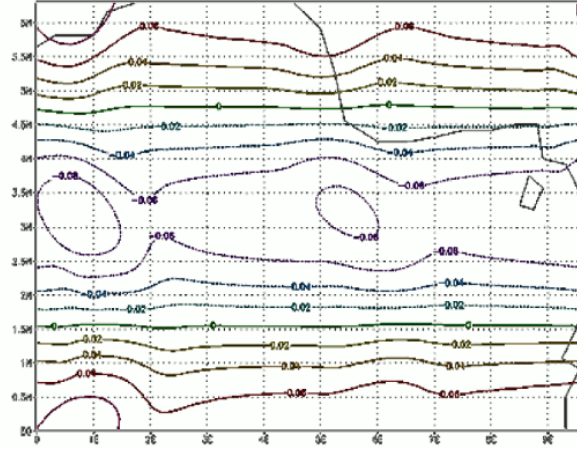
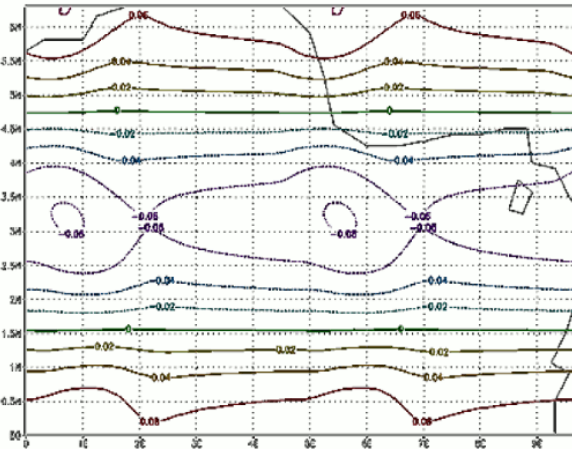
# Models Synchronize With Each Other and With “Truth”

“truth”

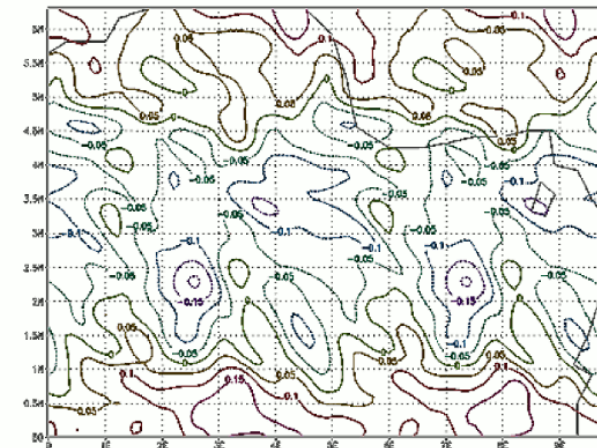
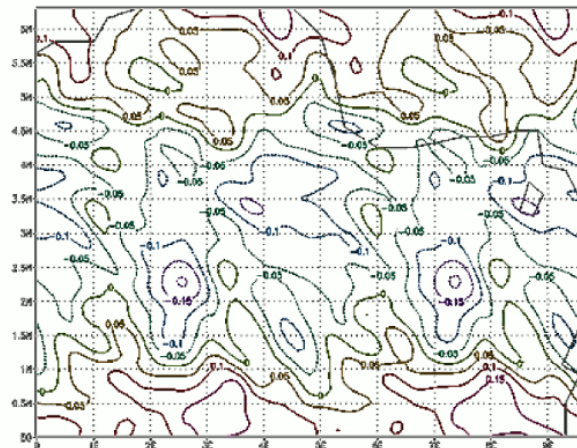
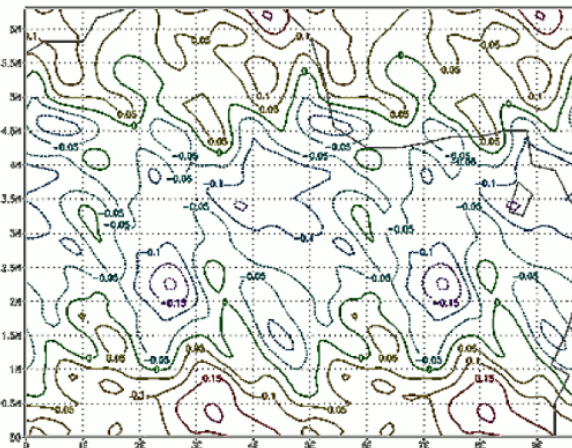
model with Atlantic forcing

model with Pacific forcing

n = 1000:

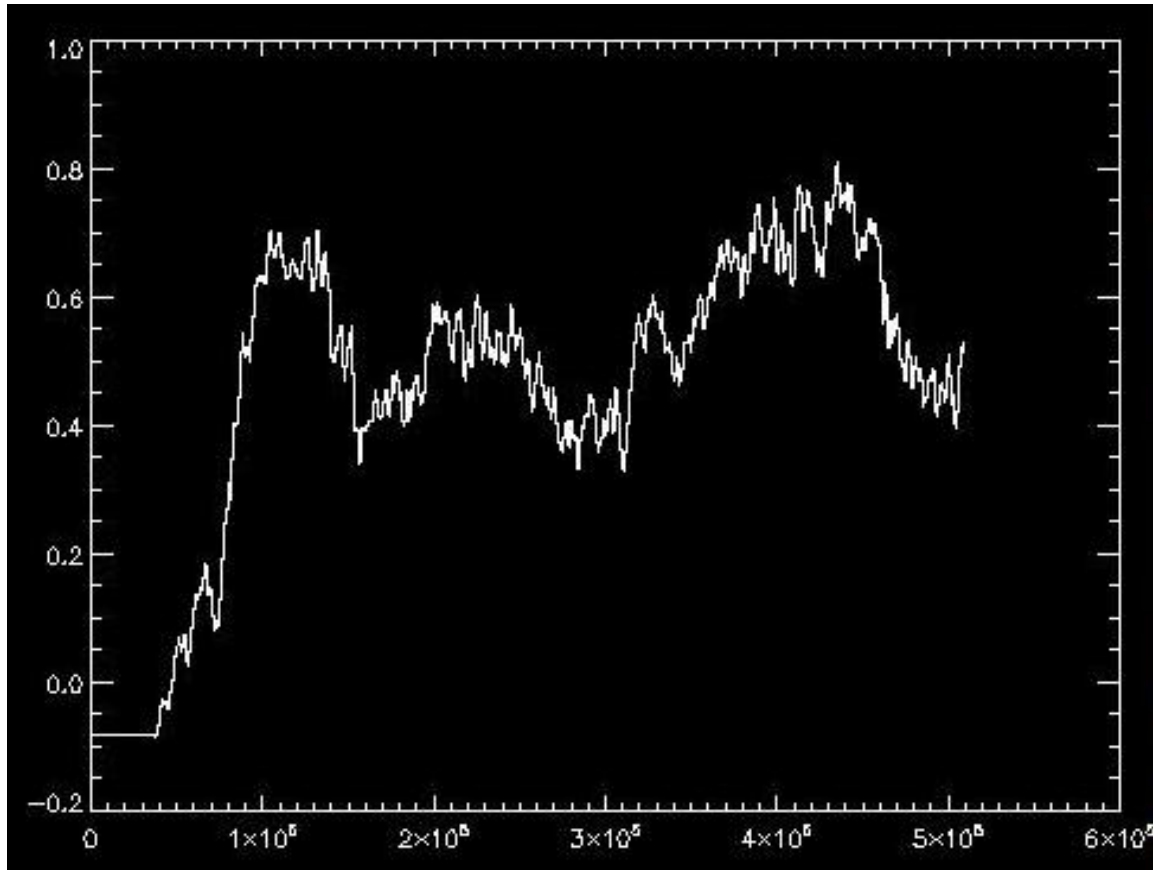


n = 30000:



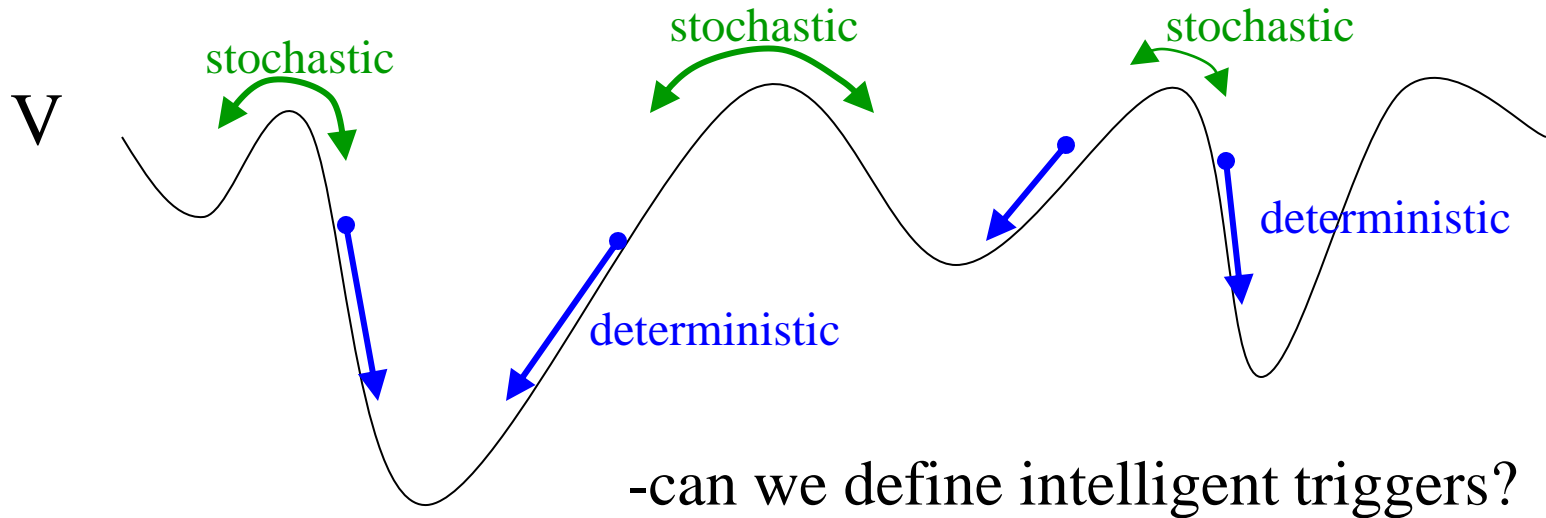


.....As the Adaptation Procedure Estimates the Intermodel Connection Coefficient  $c \rightarrow 1/2$



# Limits of Supermodeling

- reliance on stochasticity to escape local optima



- Can we do better than negative coefficients when individual models err in similar ways?
- How can we restrict the number of separately trained connections ?

⇒ Need expert-system-like generalization of supermodeling