

Matrix Calculus

Anton Andreytsev

Let $X \in \mathbb{R}^d, Y \in \mathbb{R}^q$ be some normed linear spaces and let $f : X \rightarrow Y$
 $f(X + \Delta X) = f(X) + Df(X)[\Delta X] + \bar{o}(\|\Delta X\|), \quad \|\Delta X\| \rightarrow 0$
 $Df(X)[\Delta X]$ – the Fréchet derivative

From the definition above it follows, that

$$Df(X)[\Delta X] = \lim_{t \rightarrow +0} \frac{f(X + t \cdot \Delta X) - f(X)}{t}$$

In particular case, when $X \in \mathbb{R}^n, Y \in \mathbb{R}$ (so $f : \mathbb{R}^n \rightarrow \mathbb{R} \Rightarrow Df(X)[\Delta X] = \nabla f(X)^T \Delta X$

Generalisations:

$$\begin{aligned} x \in \mathbb{R} &\Rightarrow Df(x)[\Delta x] = \nabla f(x) \cdot \Delta x, \quad \nabla f(x) \in \mathbb{R} \\ x \in \mathbb{R}^n &\Rightarrow Df(x)[\Delta x] = \nabla f(x)^T \Delta x, \quad \nabla f(x) \in \mathbb{R}^n \\ x \in \mathbb{R}^{m \times n} &\Rightarrow Df(x)[\Delta x] = \text{Tr}(\nabla f(x)^T \Delta x), \quad \nabla f(x) \in \mathbb{R}^{m \times n} \end{aligned}$$

Example 1: $f : \mathbb{R}^n \rightarrow \mathbb{R}, \quad f(x) = a^T x$

$$f(x + \Delta x) = a^T(x + \Delta x) = \underbrace{a^T x}_{f(x)} + \underbrace{a^T \Delta x}_{Df(x)[\Delta x]} + \underbrace{0}_{\bar{o}(\|\Delta x\|)}$$

$$Df(x)[\Delta x] = \underbrace{a^T}_{\nabla f(x)^T} \Delta x \Rightarrow \boxed{\nabla(a^T x) = a}$$

Example 2: $f : \mathbb{R}^n \rightarrow \mathbb{R}, \quad f(x) = x^T A x$

$$f(x + \Delta x) = (x + \Delta x)^T A (x + \Delta x) = \underbrace{x^T A x}_{f(x)} + \underbrace{\Delta x^T A x + x^T A \Delta x}_{Df(x)[\Delta x]} + \underbrace{\Delta x^T A \Delta x}_{\bar{o}(\|\Delta x\|)}$$

$$Df(x)[\Delta x] = \underbrace{\Delta x^T A x}_{()=()^T, \text{const}} + x^T A \Delta x = x^T A^T \Delta x + x^T A \Delta x = x^T (A + A^T) \Delta x =$$

$$\underbrace{((A + A^T)x)^T}_{\nabla f(x)} \Delta x$$

$$\boxed{\nabla(x^T A x) = (A + A^T)x}$$

Application: The problem of fitting weights of a linear regression can be formalised as follows:

$$\|X\beta - y\|_2^2 \rightarrow \min_{\beta}$$

The necessary condition of extremum is gradient equals zero: $\nabla_{\beta} \|X\beta - y\|_2^2 = 0$

$$\|a\|_2^2 = a^T a, \text{ so } \nabla (X\beta - y)^T (X\beta - y) = 0$$

$$\nabla \left(\beta^T X^T X \beta \underbrace{- \beta^T X^T y - y^T X \beta}_{-2y^T X \beta} + y^T y \right) = \left(\underbrace{X^T X + X^T X}_{2X^T X} \right) \beta - 2X^T y = 0$$

$$X^T X \beta = X^T y \Rightarrow \boxed{\beta = (X^T X)^{-1} X^T y}$$

In case of l_2 -regularisation:

$$\|X\beta - y\|_2^2 + \lambda \|\beta\|_2^2 \rightarrow \min_{\beta}$$

$\nabla = 2X^T X \beta - 2y^T X \beta + \lambda (I + I^T) \beta = 0$ where I - is identity matrix

$$(X^T X + \lambda I) \beta = X^T y \Rightarrow \boxed{\beta = (X^T X + \lambda I)^{-1} X^T y}$$

Example 3: $f : \mathbb{R}^n \rightarrow \mathbb{R}, \quad f(x) = e^{x^T x}$

$$Df(x)[\Delta x] = e^{x^T x} \cdot x^T (I + I^T) \Delta x = \underbrace{2 \cdot x^T \cdot e^{x^T x}}_{\nabla^T} \Delta x$$

$$\nabla (e^{x^T x}) = 2e^{x^T x} x$$

Example 4: $f : \mathbb{R}^n \rightarrow \mathbb{R}, \quad f(x) = x^T e^{xx^T} x, \quad \nabla f(x) = ?$

First consider $e^A = I + \frac{1}{1!}A + \frac{1}{2!}A^2 + \dots$ - this is by definition.

$$\begin{aligned} \text{So } x^T e^{xx^T} x &= x^T \sum_{i=0}^{+\infty} \frac{(xx^T)^i}{i!} x = \sum_{i=0}^{+\infty} \frac{x^T (xx^T)^i x}{i!} = \sum_{i=0}^{+\infty} \frac{\overbrace{x^T (x \ x^T)(xx^T) \dots (xx^T)x}^{i+1\text{-times}}}{i!} = \\ &= \sum_{i=0}^{+\infty} \frac{(x^T x)^{i+1}}{i!} = x^T x \sum_{i=0}^{+\infty} \frac{(x^T x)^i}{i!} = x^T x \exp(x^T x) \end{aligned}$$

Then take into account, that when $f : \mathbb{R}^n \rightarrow \mathbb{R}$ the usual differentiation rules

hold: $\nabla(u \cdot v) = \nabla u \cdot v + u \cdot \nabla v$, and $\nabla\left(\frac{u}{v}\right) = \frac{\nabla u \cdot v - u \cdot \nabla v}{v^2}$

$$\begin{aligned} \nabla(x^T x \exp(x^T x)) &= \nabla(x^T x) \cdot \exp(x^T x) + x^T x \cdot \nabla(\exp(x^T x)) = \\ 2 \cdot x \cdot \exp(x^T x) + x^T x \cdot 2 \exp(x^T x) x &= 2 \exp(x^T x) (1 + x^T x) x \end{aligned}$$

$$\boxed{\nabla(x^T \exp(x x^T) x) = 2 \exp(x^T x) (1 + x^T x) x}$$

Example 5: $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = \text{Det}(2I + x x^T)$

We will need here some properties of matrix differentiation:

$$\boxed{1} \quad h(x) = g(f(x)), \quad f: \mathbb{X} \rightarrow \mathbb{Y}, \quad g: \mathbb{Y} \rightarrow \mathbb{Z} \Rightarrow h: \mathbb{X} \rightarrow \mathbb{Z}$$

$$Dh(x)[\Delta x] = Dg(\underbrace{f(x)}_y) [\underbrace{Df(x)[\Delta x]}_{\Delta y}]$$

$$\boxed{2} \quad D(\text{Tr}(X))[\Delta X] = \text{Tr}(\Delta X)$$

$$\text{So } D(\text{Det}(2I + x x^T))[\Delta x] = \begin{cases} D(\text{Det}(Y))[\Delta Y] & (1) \\ D(2I + x x^T)[\Delta x] & (2) \end{cases}$$

$$(2) : \quad (x + \Delta x)(x^T + \Delta x^T) = x x^T + \underbrace{\Delta x x^T + x \Delta x^T}_{D(x x^T)[\Delta x]} + \Delta x \Delta x^T \Rightarrow$$

$$D(2I + x x^T)[\Delta x] = x \Delta x^T + x^T \Delta x$$

$$(1) \quad D(\text{Det}(Y))[\Delta Y] = \text{Det}(Y) \text{Tr}(Y^{-1} \Delta Y) =$$

$$\text{Det}(2I + x x^T) \text{Tr}(\underbrace{(2I + x x^T)^{-1}}_{A=A^T} [x \Delta x^T + x^T \Delta x]) =$$

$$\text{Det}(2I + x x^T) [\text{Tr}(A x \Delta x^T) + \text{Tr}(A \Delta x x^T)] =$$

$$\begin{aligned} &\{ \text{we could rearrange the order inside trace and transpose, because } A = A^T \\ &= \underbrace{(2I + x x^T)}_{\text{constant}} [2 \text{Tr}(x^T A \Delta x)] = \text{Tr}(2 \text{Det}(2I + x x^T) x^T A \Delta x) = \text{Tr}(\nabla f(x)^T \Delta x) \end{aligned}$$

$$\boxed{\nabla f(x) = 2 \text{Det}(2I + x x^T) (2I + x x^T) x}$$

Example 6: $f: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(x) = \log \text{Det}(x)$, $\nabla f(x) = ?$

$$Df(x)[\Delta x] = \lim_{t \rightarrow +0} \frac{f(x+t \cdot \Delta x) - f(x)}{t}$$

$$D(\log \text{Det}(x))[\Delta x] = \begin{cases} D \log Y[\Delta Y] & (1) \\ \Delta Y = D \text{Det}(X)[\Delta X] & (2) \end{cases}$$

$$(1) \quad D \log Y[\Delta Y] = Y^{-1} \cdot \Delta Y = \text{Det}(X)^{-1} \cdot \text{Det}(X) \cdot \text{Tr}(X^{-1} \Delta X) = \text{Tr}(X^{-1} \cdot \Delta X)$$

$$\begin{aligned}
(2) \quad DDet(X)[\Delta X] &= \lim_{t \rightarrow +0} \frac{Det(X+t \cdot \Delta X) - Det(X)}{t} = \\
\lim_{t \rightarrow +0} \frac{Det(X \cdot [I+t \cdot X^{-1} \cdot \Delta X]) - Det(X)}{t} &= \lim_{t \rightarrow +0} \frac{Det(X) \cdot [Det(I+t \cdot X^{-1} \cdot \Delta X) - 1]}{t} = \\
\lim_{t \rightarrow +0} \frac{Det(X) \cdot [\exp(\log(Det(I+t \cdot X^{-1} \cdot \Delta X))) - 1]}{t} &= \lim_{t \rightarrow +0} \frac{Det(X) \cdot \log(Det(I+t \cdot X^{-1} \cdot \Delta X))}{t} = \\
\{\text{for small } \epsilon \text{ holds : } Det(I + \epsilon \cdot A) \approx 1 + \epsilon \cdot Tr(A) + \bar{o}(\epsilon)\} &= \\
\lim_{t \rightarrow +0} \frac{Det(X) \cdot \log(1+t \cdot Tr(X^{-1} \Delta X))}{t} &= \lim_{t \rightarrow +0} \frac{Det(X) \cdot t \cdot Tr(X^{-1} \Delta X)}{t} = \boxed{Det(X) \cdot Tr(X^{-1} \Delta X)} \\
D(\log Det(X))[\Delta X] &= Tr(X^{-1} \Delta X) = Tr(\nabla f(X)^T \Delta X) \Rightarrow \\
\boxed{\nabla(\log Det(X)) = X^{-T}}
\end{aligned}$$

P.S: $\boxed{\nabla_X \log Det(X^{-1}) = -\nabla_X \log Det(X) = -X^{-T}}$

Example 7: $f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}, \quad f(X) = a^T X a$

$$f(X + \Delta X) = \underbrace{a^T X a}_{f(X)} + \underbrace{a^T \Delta X a}_{Df(X)[\Delta X]}$$

$$Df(X)[\Delta X] = Tr(a^T \Delta X a) = Tr(a a^T \Delta X) = Tr(\nabla f(X)^T \Delta X)$$

$$\boxed{\nabla_X(a^T X a) = a a^T}$$

Application: Let's consider the problem of finding the maximum likelihood estimations for the multidimensional Normal distribution: $x_i \sim \mathcal{N}(\mu, \Sigma)$

$$p(x | \mu, \Sigma) = \frac{1}{\sqrt{Det(2\pi\Sigma)}} \exp(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu))$$

The Likelihood function will look like that: $L(\mu, \Sigma) = \prod_{i=1}^n \frac{1}{\sqrt{Det(2\pi\Sigma)}} \exp(-\frac{1}{2}(x_i - \mu)^T \Sigma^{-1}(x_i - \mu)) = Det(2\pi\Sigma)^{-\frac{n}{2}} \exp(-\frac{1}{2} \sum_{i=1}^n (x_i - \mu)^T \Sigma^{-1}(x_i - \mu)) \rightarrow \max_{\mu, \Sigma}$

$$\log L = -\frac{n^2}{2} \log Det(2\pi) - \frac{n}{2} \log Det(\Sigma) - \frac{1}{2} \sum_{i=1}^n (x_i - \mu)^T \Sigma^{-1}(x_i - \mu) \rightarrow \max_{\mu, \Sigma}$$

$$\nabla_{\mu} \log L = -\frac{1}{2} \sum_{i=1}^n 2 \Sigma^{-1}(x_i - \mu) = 0 \Rightarrow \boxed{\hat{\mu} = \frac{1}{n} \sum_{i=1}^n x_i}$$

$$\begin{aligned}
\nabla_{\Sigma} \log L &= \{\text{for convenience let } \Lambda = \Sigma^{-1}\} = \\
\nabla_{\Lambda} \left(-\frac{n}{2} \log Det \Lambda^{-1} - \frac{1}{2} \sum_{i=1}^n (x_i - \mu)^T \Lambda (x_i - \mu) \right) &= \frac{n}{2} \underbrace{\Lambda^{-T}}_{\Lambda^{-1}} - \frac{1}{2} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T
\end{aligned}$$

$$\mu)^T = 0 \Rightarrow \hat{\Lambda}^{-1} = \boxed{\hat{\Sigma} = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T}$$

Application: Find the maximum of a function $f(X) = \text{Det}(X)^{-1} \exp(-\frac{1}{2} \text{Tr}(X^{-1} \cdot A))$

Necessary condition - $\nabla_X f(X) = 0$:

First let's consider, that the $\text{argmax}_X f(X) = \text{argmax}_X \log f(X)$

$$\log f(X) = -\log \text{Det}(X) - \frac{1}{2} \text{Tr}(X^{-1} A)$$

$$D \text{Tr}(-\frac{1}{2} X^{-1} A) = \text{Tr}(\frac{1}{2} X^{-1} \Delta X X^{-1} A) = \text{Tr}(\frac{1}{2} X^{-1} A X^{-1} \Delta X) \Rightarrow \nabla_X = \frac{1}{2} X^{-T} A^{-T} X^{-T}$$

$$\nabla_X f(X) = -X^{-T} + \frac{1}{2} X^{-T} A^{-T} X^{-T} = -X^{-T} (I - \frac{1}{2} A^{-T} X^{-T}) = 0$$

$$A^{-T} X^{-T} = 2I \Rightarrow X^T A^T = \frac{1}{2} I \Rightarrow \boxed{X^* = \frac{1}{2} A^{-1}}$$

Example 8: $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = \|x\|_2^3$, $\nabla f(x) = ?$

$$f(x) = (x^T x)^{3/2} \Rightarrow \nabla f(x) = \frac{3}{2} (x^T x)^{1/2} 2x = 3(x^T x)^{1/2} x$$

Example 9: $f: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}^{n \times n}$, $f(X) = X^{-1}$, $Df(X)[\Delta X] = ?$

$$\begin{aligned} D(X^{-1})[\Delta X] &= \lim_{t \rightarrow +0} \frac{(X+t \cdot \Delta X)^{-1} - X^{-1}}{t} = \lim_{t \rightarrow +0} \frac{(X \cdot [I + X^{-1} \cdot t \cdot \Delta X])^{-1} - X^{-1}}{t} = \\ \{(AB)^{-1} &= B^{-1} A^{-1}\} = \lim_{t \rightarrow +0} \frac{(I + X^{-1} \cdot t \cdot \Delta X)^{-1} X^{-1} - X^{-1}}{t} = \\ \lim_{t \rightarrow +0} \frac{[(I + X^{-1} \cdot t \cdot \Delta X)^{-1} - I] \cdot X^{-1}}{t} &= \{(I + \epsilon \cdot A)^b - I \approx \epsilon \cdot b \cdot A\} = \lim_{t \rightarrow +0} \frac{-X^{-1} t \Delta X X^{-1}}{t} = \\ &= -X^{-1} \Delta X X^{-1} \end{aligned}$$

$$\boxed{D(X^{-1})[\Delta X] = -X^{-1} \Delta X X^{-1}}$$

Example 10: $f: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = \text{Tr}(X)$, $\nabla f(X) = ?$

$$\begin{aligned} D(\text{Tr}(X))[\Delta X] &= \lim_{t \rightarrow +0} \frac{\text{Tr}(X+t \cdot \Delta X) - \text{Tr}(X)}{t} = \lim_{t \rightarrow +0} \frac{\text{Tr}(X+t \cdot \Delta X - X)}{t} = \\ \lim_{t \rightarrow +0} \frac{t \cdot \text{Tr}(\Delta X)}{t} &= \text{Tr}(I \cdot \Delta X) = \text{Tr}(\nabla f(X)^T \Delta X) \Rightarrow \boxed{\nabla_X \text{Tr}(X) = I} \end{aligned}$$

Example 11: $f: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = \text{Tr}(AX^{-1}B)$, $\nabla f(X) = ?$

$$DTr(AX^{-1}B)[\Delta X] = \begin{cases} DTr(Y)[\Delta Y] = Tr(\Delta Y) \\ D(AX^{-1}B)[\Delta X], \end{cases} \quad (1)$$

$$(1) \quad D(AX^{-1}B)[\Delta X] = \begin{cases} D(AZB)[\Delta Z], \\ \Delta Z = D(X^{-1})[\Delta X] = -X^{-1}\Delta XX^{-1} \end{cases} \quad (2)$$

$$f(Z + \Delta Z) = \underbrace{AZB}_{f(Z)} + \underbrace{A\Delta ZB}_{Df(Z)[\Delta Z]}$$

$$\text{So } DTr(AX^{-1}B)[\Delta X] = Tr(-AX^{-1}\Delta XX^{-1}B) = Tr(\underbrace{-X^{-1}BAX^{-1}}_{\nabla f(X)^T} \Delta X)$$

$$\nabla_X f(X) = (-X^{-1}BAX^{-1})^T = -X^{-T}A^T B^T X^{-T}$$

Example 12 : $f : \mathbb{R}^n \rightarrow \mathbb{R}^{n \times n}$, $f(x) = xx^T$, $Df(x)[\Delta x] = ?$

$$f(x + \Delta x) = (x + \Delta x)(x + \Delta x)^T = \underbrace{xx^T}_{f(x)} + \underbrace{x\Delta x^T + \Delta x x^T}_{Df(x)[\Delta x]} + \underbrace{\Delta x \Delta x^T}_{o(\|\Delta x\|)}$$

$$Df(x)[\Delta x] = x\Delta x^T + (\underbrace{x\Delta x^T}_{\text{symmetric}})^T = 2x\Delta x^T$$

Example 13: $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = \frac{x^T A x}{x^T x}$, $\nabla f(x) = ?$

$$\begin{aligned} \nabla f(x) &= \nabla \left(\frac{g(x)}{h(x)} \right) = \frac{\nabla g(x) \cdot h(x) - g(x) \cdot \nabla h(x)}{h^2(x)} = \frac{(A + A^T)x \cdot x^T x - 2x^T A x \cdot x}{(x^T x)^2} = \\ &= \frac{(A + A^T)x^T x - 2x^T A x \cdot I}{(x^T x)^2} \cdot x \end{aligned}$$

Example 14: $f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = Det(AXB)$, $\nabla f(X) = ?$

$$D(Det(AXB))[\Delta X] = \begin{cases} DDet(Y)[\Delta Y] = Det(Y)Tr(Y^{-1}\Delta Y) \\ \Delta Y = D(AXB)[\Delta X] = A\Delta XB \end{cases}$$

$$Df(X)[\Delta X] = \underbrace{Det(AXB)Tr((AXB)^{-1}A\Delta XB)}_{const} =$$

$$\begin{aligned} Det(AXB)Tr(B^{-1}X^{-1}A^{-1}A\Delta XB) &= Tr(Det(AXB)X^{-1}\Delta X) = \\ Tr(\nabla f(X)^T \Delta X) & \end{aligned}$$

$$\nabla_X Det(AXB) = Det(AXB)X^{-T}$$

Example 15: $f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = Tr(AX^{-1})Tr(XB)$, $\nabla f(X) = ?$

Let's apply the property of matrix differentiation:

$h(x) = g(x) \cdot f(x)$, $f : \mathbb{X} \rightarrow \mathbb{Y}$, $g : \mathbb{X} \rightarrow \mathbb{R}$, then:

$$Dh(x)[\Delta x] = Dg(x)[\Delta x] \cdot f(x) + g(x) \cdot Df(x)[\Delta x]$$

$$D \left(Tr(AX^{-1})Tr(XB) \right) [\Delta X] = Tr(XB) \cdot \underbrace{DTr(AX^{-1})[\Delta X]}_{(1)} + Tr(AX^{-1}) \cdot \underbrace{DTr(XB)[\Delta X]}_{(2)}$$

$$(1) \quad DTr(AX^{-1})[\Delta X] = \begin{cases} DTr(Z)[\Delta Z] = Tr(\Delta Z) \\ \Delta Z = D(AY)[\Delta Y] = A\Delta Y \\ \Delta Y = D(X^{-1})[\Delta X] = -X^{-1}\Delta XX^{-1} \end{cases}$$

$$DTr(AX^{-1})[\Delta X] = Tr(-AX^{-1}\Delta XX^{-1})$$

$$(2) \quad DTr(XB) = Tr(\Delta XB), \text{ so}$$

$$Df(X)[\Delta X] = \underbrace{Tr(XB)}_{const} \cdot Tr(-AX^{-1}\Delta XX^{-1}) + \underbrace{Tr(AX^{-1})}_{const} \cdot Tr(\Delta XB) = Tr(-Tr(XB)X^{-1}AX^{-1}\Delta X + Tr(AX^{-1}B\Delta X)) = Tr([-Tr(XB)X^{-1}AX^{-1} + Tr(AX^{-1})B] \cdot \Delta X) = Tr(\nabla f(X)^T \Delta X)$$

$$\nabla f(X) = Tr(AX^{-1})B - Tr(XB)X^{-1}AX^{-1}$$

Example 16: $f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = Det(\exp(X))$, $\nabla f(X) = ?$

$$DDet(\exp(X))[\Delta X] = \begin{cases} DDet(Y)[\Delta Y] = Det(Y)Tr(Y^{-1}\Delta Y) \\ \Delta Y = D\exp(X)[\Delta X] = \exp(X)\Delta X - \text{prove it !} \end{cases}$$

$$DDet(\exp(X))[\Delta X] = Det(\exp(X))Tr(\exp(X)^{-1}\exp(X)\Delta X) = Tr(Det(\exp(X))\Delta X) = Tr(\nabla f(X)^T \Delta X)$$

$$\boxed{\nabla_X (Det(\exp(X))) = Det(\exp(X)) \cdot I}$$

Example 17: $f : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}$, $f(X) = \frac{1}{2}\|X - A\|_F^2$, $\nabla f(X) = ?$

$$\boxed{\|A\|_F^2 = \sum_{i,j} a_{ij}^2 = Tr(A^T A)}, \text{ so } f(X) = \frac{1}{2}Tr((X - A)^T(X - A)) = \frac{1}{2}Tr(X^T X - X^T A - A^T X + A^T A)$$

$$Df(X)[\Delta X] = \frac{1}{2}Tr(X^T \Delta X + \Delta X^T X - \Delta X^T A - A^T \Delta X) = Tr(X^T \Delta X) + Tr(-A^T \Delta X) = Tr((X^T - A^T) \cdot \Delta X) = Tr(\nabla f(X)^T \Delta X)$$

$$\nabla f(X) = X - A$$

Example 18: $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = \text{Tr}(Axx^T)$, $\nabla f(x) = ?$

$$\begin{aligned} Df(x)[\Delta x] &= \text{Tr}(D(Axx^T)[\Delta x]) = \text{Tr}(Ax\Delta x^T + A\Delta xx^T) = \\ &= \text{Tr}([x\Delta x^T]^T A^T) + \text{Tr}(x^T A\Delta x) = \text{Tr}(x^T A^T \Delta x + x^T A\Delta x) = \text{Tr}(\nabla f(x)^T \Delta x) \end{aligned}$$

$$\nabla f(x) = x^T (A + A^T)$$

Example 19: $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = \frac{1}{2}\|xx^T - A\|_F^2$, $\nabla f(x) = ?$

$$f(x) = \frac{1}{2}\text{Tr}((xx^T - A)^T(xx^T - A)) = \frac{1}{2}\text{Tr}(xx^T xx^T - xx^T A - Axx^T - A^T A)$$

$$Df(x)[\Delta x] = \frac{1}{2}\text{Tr}(4x^T xx^T \Delta x - x^T A\Delta x - x^T A^T \Delta x)$$

$$\begin{aligned} \nabla f(x) &= [2x^T xx^T - \frac{1}{2}x^T(A + A^T)]^T = [x^T(2xx^T - \frac{1}{2}A - \frac{1}{2}A^T)]^T = \\ &= (2xx^T - \frac{1}{2}(A + A^T))x \end{aligned}$$

Example 20: $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = \frac{1}{2}(x^T x + (a^T x)^2)$, $\nabla f(x) = ?$

$$\nabla f(x) = x + a^T x a$$

Example 21: $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = x^T \vec{\log}(x)$, $\nabla f(x) = ?$, where $\vec{\log}(x) = (\log x_1, \dots, \log x_n)$

$$f(x) = x^T \log(x) = \sum_{i=1}^n x_i \cdot \log(x_i), \quad \nabla f(x) = \left(\frac{\partial f(x_1)}{\partial x_1}, \dots, \frac{\partial f(x_n)}{\partial x_n} \right)$$

$$\frac{\partial f(x_i)}{\partial x_i} = \log(x_i) + 1 \Rightarrow \nabla f(x) = \log(x) + \vec{1}$$

Example 22: $f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = \text{Det}(A + X^{-1})$, $\nabla f(X) = ?$

$$DDet(A + X^{-1})[\Delta X] = \begin{cases} DDet(Y)[\Delta Y] = Det(Y)Tr(Y^{-1}\Delta Y) \\ \Delta Y = D(A + X^{-1})[\Delta X] = -X^{-1}\Delta X X^{-1} \end{cases}$$

$$\begin{aligned} Df(X)[\Delta X] &= Det(A + X^{-1})Tr(-(A + X^{-1})^{-1}X^{-1}\Delta X X^{-1}) = \\ &= Tr(-Det(A + X^{-1})X^{-1}(A + X^{-1})^{-1}X^{-1}\Delta X) = Tr(\nabla f(X)^T \Delta X) \end{aligned}$$

$$\nabla f(X) = -Det(A + X^{-1})X^{-T}(A + X^{-1})^{-T}X^{-T}$$

Example 23: (The problem of constructing surrogate eigenvector)

The problem comes from the fact, that the linear system $Ax = b$ can equivalently be rewritten as $f(x) = \frac{1}{2}x^T Ax - b^T x \rightarrow \min_x$, where equivalence means that the solution of both problems would be the same.

$f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = \frac{1}{2}x^T (A - \lambda \cdot I) x \rightarrow \min_x$, where λ is an eigenvalue of A , $A = A^T > 0$

$$f(x) \rightarrow \min_x \Rightarrow \nabla_x f(x) = 0$$

$\nabla f(x) = (A - \lambda \cdot I)x = 0$, from this follows, that a minimiser of this function is an eigenvector of a matrix A , corresponding to an eigenvalue λ , but if we can't find an eigenvector, we can use this gradient to find it iteratively and numerically:

Initialisation: x_0 – some random vector,

$$x_{k+1} = x_k - \alpha_k \cdot \nabla f(x_k) = ((1 + \alpha_k \cdot \lambda) \cdot I - \alpha_k \cdot A) x_k = \{\text{if } \alpha_k \text{ is constant, then } \} = ((1 + \alpha \cdot \lambda) \cdot I - \alpha \cdot A)^{k+1} \cdot x_0$$

Application: (Logistic Regression fitting)

$$f : \mathbb{R}^n \rightarrow \mathbb{R}, \quad f(x) = -\sum_{i=1}^n \log(\sigma(w^T x_i y_i)) \rightarrow \min_w, \text{ where } \sigma(z) = \frac{1}{1+\exp(-z)}, \quad x_i, w \in \mathbb{R}^n, \quad y_i \in \mathbb{R}$$

$$\sigma(z)'_z = \frac{\exp(-z)}{(1+\exp(-z))^2} = \frac{1}{(1+\exp(z))^2} = \sigma^2(-z)$$

$$\nabla_x f(x) = -\sum_{i=1}^n \frac{\sigma^2(-w^T x_i y_i)}{\sigma(w^T x_i y_i)} y_i x_i$$

Example 24 Find minimum of a function $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = \frac{x^T A x}{x^T B x}$, where $A \geq 0, B \geq 0$

Necessary condition $\nabla f(x) = 0$

$$\nabla f(x) = \frac{(A+A^T)x \cdot x^T B x - x^T A x \cdot (B+B^T)x}{(x^T B x)^2}$$

Example 25: $f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = a^T X^{-1} a$, $\nabla f(X) = ?$

$$D(a^T X^{-1} a) [\Delta X] = \text{Tr}(a a^T D X^{-1} [\Delta X]) = \text{Tr}(-a a^T X^{-1} \Delta X X^{-1}) = \text{Tr}(-X^{-1} a a^T X^{-1} \Delta X) = \text{Tr}(\nabla f(X)^T \Delta X) \Rightarrow \nabla f(X) = -X^{-T} a a^T X^{-T}$$

Example 26: $f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = \text{Det}(X^2)$, $\nabla f(X) = ?$

There are 2 ways of dealing with it, let's compare these ways:

$$\begin{aligned} 1) \quad & \text{Det}(X^2) = \text{Det}(X)^2 \Rightarrow D\text{Det}(X)^2[\Delta X] = \\ & \left\{ \begin{aligned} DY^2[\Delta Y] &= Y\Delta Y + \Delta Y Y \quad (1) \\ \Delta Y &= D\text{Det}(X)[\Delta X] = \text{Det}(X)\text{Tr}(X^{-1}\Delta X) \end{aligned} \right. \\ & (1) \quad Df(X)[\Delta X] = 2\text{Det}(X) \cdot \text{Det}(X)\text{Tr}(X^{-1}\Delta X) \Rightarrow \nabla f(X) = \\ & 2\text{Det}(X)^2 X^{-T} \end{aligned}$$

$$2) \text{Det}(X^2), \quad D\text{Det}(X^2)[\Delta X] = \left\{ \begin{aligned} D\text{Det}(Y)[\Delta Y] &= \text{Det}(Y)\text{Tr}(Y^{-1}\Delta Y) \\ \Delta Y &= D(X^2)[\Delta X] = X\Delta X + \Delta X X \end{aligned} \right.$$

$Df(X)[\Delta X] = \text{Det}(X^2)\text{Tr}(2X^{-1}\Delta X) = 2\text{Det}(X)^2\text{Tr}(X^{-1}\Delta X)$, which is indeed the same result as in the first way

Example 27: $f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = \text{Tr}(AX^{-1})$, $\nabla f(X) = ?$

$$Df(X)[\Delta X] = \left\{ \begin{aligned} D\text{Tr}(AY)[\Delta Y] &= \text{Tr}(A\Delta Y) \\ \Delta Y &= D(X^{-1})[\Delta X] = -X^{-1}\Delta X X^{-1} \end{aligned} \right.$$

$$D\text{Tr}(AX)[\Delta X] = \text{Tr}(-AX^{-1}\Delta X X^{-1}) = \text{Tr}(-X^{-1}AX^{-1}\Delta X)$$

$$\nabla f(X) = -X^{-T}A^{-T}X^{-T}$$

Application: Kernel Linear Regression Problem

$$Q(a) = \frac{1}{2}\|\Phi\Phi^T a - y\|_2^2 + \frac{\lambda}{2}a^T\Phi\Phi^T a \rightarrow \min_a, \quad K = \Phi\Phi^T = K^T > 0$$

$$\nabla_a Q = (\Phi\Phi^T)^2 a - \Phi\Phi^T y + \lambda\Phi\Phi^T a = 0 \mid \cdot K^{-1} \Rightarrow Ka - y + \lambda a = 0$$

$$(K + \lambda I)a = y \Rightarrow \boxed{a^* = (K + \lambda I)^{-1}y}$$

Example 28: $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(X) = \log \text{Det}(X) + \text{Tr}(X^{-1}A) \rightarrow \min_X$

$$D \log \text{Det}(X)[\Delta X] = \text{Tr}(X^{-1}\Delta X) \Rightarrow \nabla \log \text{Det}(X) = X^{-T}$$

$$\begin{aligned} D\text{Tr}(X^{-1}A)[\Delta X] &= \text{Tr}(-X^{-1}\Delta X X^{-1}A) = \text{Tr}(-X^{-1}AX^{-1}\Delta X) \Rightarrow \\ \nabla \text{Tr}(X^{-1}A) &= -X^{-T}A^T X^{-T} \end{aligned}$$

$$\nabla f(X) = X^{-T} - X^{-T} A^T X^{-T} = 0 \Rightarrow X^{-T} (I - A^T X^{-T}) = 0$$

$$X^{-1} A = I \Rightarrow X = A$$

Application: Robust linear regression

$$\sum_{i=1}^n w_i (< x_i, \beta > - y_i)^2 = (X\beta - y)^T W (X\beta - y)$$

$$Q(\beta) = (X\beta - y)^T W (X\beta - y) \rightarrow \min_{\beta}$$

$$Q(\beta) = \beta^T X^T W X \beta - 2y^T W X \beta + y^T W y$$

$$\nabla_{\beta} Q = 2X^T W X \beta - 2X^T W y = 0$$

$$\boxed{\beta^* = (X^T W X)^{-1} X^T W y} \quad \text{where } W \text{ is a weight matrix}$$

Application: Available GLS estimator

Problem: $y = X\beta + \epsilon$, $\epsilon \sim \mathcal{N}(0, \Omega) \rightarrow \text{Efficient } \beta^{GLS} = ?$

$$\epsilon = y - X\beta \sim \mathcal{N}(0, \Omega)$$

$$p(\epsilon) = \frac{1}{\sqrt{\text{Det}(2\pi\Omega)}} \exp\{-\frac{1}{2}(y - X\beta)^T \Omega^{-1}(y - X\beta)\}$$

Let's find the ML estimator of Ω :

$$L(\Omega) = \prod_{i=1}^l \frac{1}{\sqrt{\text{Det}(2\pi\Omega)}} \exp\{-\frac{1}{2}(y - X\beta)_i^T \Omega^{-1}(y - X\beta)_i\} = \left(\frac{1}{\sqrt{\text{Det}(2\pi\Omega)}} \right)^l.$$

$$\exp\{-\frac{1}{2} \sum_{i=1}^l (y - X\beta)_i^T \Omega^{-1}(y - X\beta)_i\} \rightarrow \max_{\Omega}$$

$$\log L(\Omega) = -\frac{l \cdot n}{2} \log 2\pi - \frac{l}{2} \log \text{Det}(\Omega) - \frac{1}{2} \sum_{i=1}^l (y - X\beta)_i^T \Omega^{-1}(y - X\beta)_i \rightarrow \max_{i=1}^l$$

$$\{\Lambda = \Omega^{-1}\} \rightarrow \nabla_{\Lambda} \log L(\Lambda) = -\frac{l}{2} \underbrace{\Lambda^{-T}}_{\Lambda^{-1}} - \frac{1}{2} \sum_{i=1}^l (y - X\beta)_i (y - X\beta)_i^T = 0$$

$$\Lambda^{-1} = \frac{1}{l} \sum_{i=1}^l (y - X\beta)_i (y - X\beta)_i^T \Rightarrow \boxed{\hat{\Omega} = \frac{1}{l} \sum_{i=1}^l (y - X\beta)_i (y - X\beta)_i^T}$$

$$\beta^{GLS} = \left(X^T \hat{\Omega}^{-1} X \right)^{-1} X^T \hat{\Omega}^{-1} y$$

Application: Consider the linear model $y = X\beta + \epsilon$, $\epsilon \sim \mathcal{N}(0, \sigma^2 \cdot I)$. Let's call the $MSE(\hat{\beta}) = \mathbb{E} \left(\hat{\beta} - \beta \right) \left(\hat{\beta} - \beta \right)^T$. Compute the $MSE(\hat{\beta})$, where $\hat{\beta} = Ay$

$$\hat{\beta} - \beta = AX\beta + A\epsilon - \beta = (AX - I)\beta + A\epsilon$$

$$\mathbb{E} \left(A\epsilon\epsilon^T A^T \right) = A \underbrace{\mathbb{E}(\epsilon\epsilon^T)}_{\sigma^2 \cdot I} A^T = \sigma^2 AA^T$$

$$\begin{aligned} MSE(\hat{\beta}) &= \mathbb{E} \left[((AX - I)\beta + A\epsilon) (\beta^T (AX - I)^T + \epsilon^T A^T) \right] = \\ & (AX - I)\beta\beta^T (AX - I)^T + \mathbb{E} (A\epsilon\epsilon^T A^T) = \boxed{(AX - I)\beta\beta^T (AX - I)^T + \sigma^2 AA^T} \end{aligned}$$

Consider the problem of minimizing $tr(MSE(\hat{\beta}))$, find the optimal matrix A:

$$f(A) = tr((AX - I)\beta\beta^T (AX - I)^T + \sigma^2 AA^T) \rightarrow \min_A$$

$$f(A) = tr (AX\beta\beta^T X^T A^T - 2AX\beta\beta^T + \beta\beta^T + \sigma^2 AA^T)$$

$$\begin{aligned} tr D(ABA^T) [\Delta A] &= tr (\Delta ABA^T + AB\Delta A^T) = \\ tr (BA^T \Delta A + \Delta AB^T A^T) &= tr (BA^T \Delta A + B^T A^T \Delta A) = \\ tr ((B + B^T)A^T \Delta A) &\Rightarrow \boxed{\nabla_A tr(ABA^T) = A(B + B^T)} \end{aligned}$$

$$tr D(AB) [\Delta A] = tr(\Delta AB) \Rightarrow \boxed{\nabla_A tr(AB) = B^T}$$

$$tr D(AA^T) [\Delta A] = tr(A\Delta A^T + \Delta AA^T) = tr(2A^T \Delta A) \Rightarrow \boxed{\nabla_A tr(AA^T) = 2A}$$

$$\nabla_A f(A) = 2AX\beta\beta^T X^T - 2\beta\beta^T X^T + 2\sigma^2 A = 0$$

$$A(X\beta\beta^T X^T + \sigma^2 I) = \beta\beta^T X^T$$

$$\boxed{A^* = \beta\beta^T X^T (X\beta\beta^T X^T + \sigma^2 I)^{-1}}$$

Example 29: Prove, that $f(x) = a^T x + x^T A x \geq -\frac{1}{4} a^T A a$, where $A = A^T > 0$

$$\nabla_x (a^T x + x^T A x) = a + 2Ax = 0 \Rightarrow x^* = -\frac{1}{2} A^{-1} a$$

$$\text{So } f(x^*) = -\frac{1}{2} a^T A^{-1} a = \frac{1}{4} a^T A^{-1} A A^{-1} a = -\frac{1}{4} a^T A^{-1} a$$

$$x^* \text{ is a minimum, because: } \nabla_{x^2}^2 f(x) = 2A > 0$$

Example 30: $f(X) = \text{tr}(AX^{-1})$, $\nabla_X f(X) = ?$

$$\begin{aligned}
Df(X)[\Delta X] &= \lim_{t \rightarrow +0} \frac{\text{tr}(A[X+t\Delta X]^{-1}) - \text{tr}(AX^{-1})}{t} = \lim_{t \rightarrow +0} \frac{\text{tr}(A[(X+t\Delta X)^{-1} - X^{-1}])}{t} = \\
&= \lim_{t \rightarrow +0} \frac{\text{tr}(A[(I+tX^{-1}\Delta X)^{-1}X^{-1} - X^{-1}])}{t} = \lim_{t \rightarrow +0} \frac{\text{tr}(A[(I+tX^{-1}\Delta X)^{-1} - I]X^{-1})}{t} = \\
&= \lim_{t \rightarrow +0} \frac{\text{tr}(A(-tX^{-1}\Delta X)X^{-1})}{t} = -\text{tr}(AX^{-1}\Delta XX^{-1}) = -\text{tr}(X^{-1}AX^{-1}\Delta X) \Rightarrow \\
&\boxed{\nabla_X f(X) = -X^T A^T X^{-T}}
\end{aligned}$$

Example 31: $f(X) = a^T X X^T a$, $\nabla_X f(X) = ?$

$$\begin{aligned}
\underbrace{f(X + \Delta X)}_{Df(X)[\Delta X]} &= a^T(X + \Delta X) \cdot (X^T + \Delta X^T)a = a^T X X^T a + \\
&+ a^T \Delta X X^T a + a^T X \Delta X^T a + o(\|\Delta X\|) \\
\text{So } Df(X)[\Delta X] &= a^T(X \Delta X^T + \Delta X X^T)a = \text{tr}(a^T \Delta X X^T a) + \\
&\text{tr}(a a^T X \Delta X^T) = \text{tr}(a^T \Delta X X^T a) + \text{tr}(\Delta X X^T a a^T) = 2\text{tr}(a^T \Delta X X^T a) = \\
&2\text{tr}(X^T a a^T \Delta X) \Rightarrow \boxed{\nabla_X f(X) = 2a a^T X}
\end{aligned}$$

Higher order derivatives

When $f : \mathbb{R}^n \rightarrow \mathbb{R} \Rightarrow \boxed{D^2 f(x)[\Delta x_1, \Delta x_2] = \Delta x_1^T H(x) \Delta x_2}$, where $H(x)$ – *Hessian*

$$D^k f(x)[\Delta x_1, \dots, \Delta x_k] = \frac{\partial^k}{\partial t_1 \partial t_2 \dots \partial t_k} \Big|_{t_1 = \dots = t_k = 0} f(x + t_1 \cdot \Delta x_1 + \dots + t_k \cdot \Delta x_k)$$

Example 1: $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = x^T A x$, $D^2 f(x)[\Delta x_1, \Delta x_2] = ?$, $H(x) = ?$

$$Df(x)[\Delta x_1] = 2x^T A \Delta x_1$$

$$\begin{aligned} D^2 f(x)[\Delta x_1, \Delta x_2] &= \lim_{t \rightarrow +0} \frac{Df(x+t \cdot \Delta x_2)[\Delta x_1] - Df(x)[\Delta x_1]}{t} = \\ \lim_{t \rightarrow +0} \frac{2(x^T + t \cdot \Delta x_2^T) A \Delta x_1 - 2x^T A \Delta x_1}{t} &= \boxed{2 \Delta x_2^T A \Delta x_1} \Rightarrow \boxed{H(x) = 2A} \end{aligned}$$

Example 2: $f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$, $f(X) = \log \text{Det}(X)$, $D^2 f(X)[\Delta X_1, \Delta X_2] = ?$

$$Df(X)[\Delta X_1] = \text{Tr}(X^{-1} \Delta X_1)$$

$$\begin{aligned} D^2 f(X)[\Delta X_1, \Delta X_2] &= \lim_{t \rightarrow +0} \frac{Df(X+t \cdot \Delta X_2)[\Delta X_1] - Df(X)[\Delta X_1]}{t} = \\ \lim_{t \rightarrow +0} \frac{\text{Tr}((X+t \cdot \Delta X_2)^{-1}[\Delta X_1]) - \text{Tr}(X^{-1}[\Delta X_1])}{t} &= \lim_{t \rightarrow +0} \frac{\text{Tr}([(X+t \cdot \Delta X_2)^{-1} - X^{-1}][\Delta X_1])}{t} = \\ \lim_{t \rightarrow +0} \frac{\text{Tr}([X(I+t \cdot X^{-1} \Delta X_2)]^{-1} - X^{-1})[\Delta X_1])}{t} &= \lim_{t \rightarrow +0} \frac{\text{Tr}([(I+t \cdot X^{-1} \Delta X_2)^{-1} - I]X^{-1} \Delta X_1)}{t} = \\ \lim_{t \rightarrow +0} \frac{\text{Tr}(-t \cdot X^{-1} \Delta X_2 X^{-1} \Delta X_1)}{t} &= \text{Tr}(-\Delta X_1 X^{-1} \Delta X_2 X^{-1}) \end{aligned}$$

Example 3: $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(\beta) = \|X\beta - y\|_2^2$, $H(\beta) = ?$

$$Df(\beta)[\Delta \beta_1] = (2X^T X \beta - 2X^T y)^T [\Delta \beta_1]$$

$$\begin{aligned} D^2 f(\beta)[\Delta \beta_1, \Delta \beta_2] &= \lim_{t \rightarrow +0} \frac{[2(\beta^T + t \cdot \Delta \beta_2^T) X^T X - 2y^T X - 2\beta^T X^T X + 2y^T X][\Delta \beta_1]}{t} = \\ \Delta \beta_2^T 2X^T X \Delta \beta_1 &= \beta_1^T 2X^T X \Delta \beta_2 \Rightarrow \boxed{H(\beta) = 2X^T X} \end{aligned}$$

Which we could have attained easier: $\nabla_\beta \nabla_\beta f(\beta) = \nabla_\beta (2X^T X \beta) = 2X^T X$

Constraint optimisation

Example 1:
$$\begin{cases} \|x\|_2^2 \rightarrow \min_x \\ \text{s.t. } Ax \leq b \end{cases}$$

$$L = x^T x + \lambda^T (Ax - b)$$

K.K.T conditions:

$$\begin{cases} \nabla_x L = 2x + A^T \lambda = 0 \\ Ax - b \leq 0 \\ \lambda^T (Ax - b) = 0 \\ \lambda \geq 0 \end{cases} \Rightarrow \begin{cases} \lambda^T (-\frac{1}{2} A A^T \lambda - b) = 0 \Rightarrow \lambda^* = -2(AA^T)^{-1}b \\ x^* = -\frac{1}{2} A^T \lambda \end{cases}$$

$$\boxed{x^* = A^T (A A^T)^{-1} b}$$

Application: OLS under constraints:

$$\begin{cases} \|X\beta - y\|_2^2 \rightarrow \min_{\beta} \\ \text{s.t. } C\beta = d \end{cases}$$

$$L = \beta^T X^T X \beta - 2y^T X \beta + y^T y + \mu^T (C\beta - d)$$

K.K.T. conditions:

$$\begin{cases} \nabla_{\beta} L = 2X^T X \beta - 2X^T y + C^T \mu = 0 \\ C\beta - d = 0 \end{cases} \Rightarrow \begin{cases} \beta = (X^T X)^{-1} (X^T y - \frac{1}{2} C^T \mu) \\ C\beta = d \end{cases}$$

$$C\beta = d \Rightarrow C(X^T X)^{-1} X^T y - \frac{1}{2} C(X^T X)^{-1} C^T \mu = d$$

$$\frac{1}{2} C(X^T X)^{-1} C^T \mu = C(X^T X)^{-1} X^T y - d, \quad \mu = 2 \cdot (C(X^T X)^{-1} C^T)^{-1} (C(X^T X)^{-1} X^T y - d)$$

$$\boxed{\beta^* = \underbrace{(X^T X)^{-1} X^T y}_{\beta_{\text{ols}}} - (X^T X)^{-1} C^T (C(X^T X)^{-1} C^T)^{-1} \left(C \underbrace{(X^T X)^{-1} X^T y}_{\beta_{\text{ols}}} - d \right)}$$

Let's derive $V(\beta^*)$:

$$\begin{aligned} V(\beta^*) &= \sigma^2 (X^T X)^{-1} - \sigma^2 \cdot (X^T X)^{-1} C^T (C(X^T X)^{-1} C^T)^{-1} C (X^T X)^{-1} \\ &\cdot ((X^T X)^{-1} C^T (C(X^T X)^{-1} C^T)^{-1} C)^T = \sigma^2 (X^T X)^{-1} - \sigma^2 \cdot \end{aligned}$$

$$\begin{aligned}
& (X^T X)^{-1} C^T (C(X^T X)^{-1} C^T)^{-1} C(X^T X)^{-1} C^T (C(X^T X)^{-1} C^T)^{-1} C(X^T X)^{-1} = \\
& \sigma^2(X^T X)^{-1} - \sigma^2(X^T X)^{-1} (C(X^T X)^{-1} C^T)^{-1} C(X^T X)^{-1} = \\
& \boxed{V(\beta^*) = \sigma^2(X^T X)^{-1} \left(I - (C(X^T X)^{-1} C^T)^{-1} C(X^T X)^{-1} \right)}
\end{aligned}$$

When C is invertable this could be reduced to:

$$\begin{aligned}
& \sigma^2(X^T X)^{-1} \left(I - (C(X^T X)^{-1} C^T)^{-1} C(X^T X)^{-1} C^T C^{-T} \right) = \\
& \boxed{V(\beta^*) = \sigma^2(X^T X)^{-1} (I - C^{-T})}
\end{aligned}$$

Example 2: $\begin{cases} a^T x \rightarrow \min_x \\ \text{s.t. } x^T A x \leq 1 \end{cases}$, where $A = A^T > 0$

$$L = a^T x + \lambda(x^T A x - 1)$$

K.K.T. conditions:

$$\begin{cases} \nabla_x L = a + 2\lambda A x = 0 \\ x^T A x - 1 \leq 0 \\ \lambda(x^T A x - 1) = 0 \\ \lambda \geq 0 \end{cases} \Rightarrow \begin{cases} x^* = -\frac{1}{2\lambda} A^{-1} a \\ \lambda((-\frac{1}{2\lambda} A^{-1} a)^T A (-\frac{1}{2\lambda} A^{-1} a) - 1) = 0 \end{cases} \quad (1)$$

$$(1) \frac{1}{4\lambda} a^T A^{-1} a - \lambda = 0 \mid \cdot \lambda \Rightarrow \lambda^* = \pm \frac{1}{2} \sqrt{a^T A^{-1} a}, \quad \lambda \geq 0 \Rightarrow \lambda^* = \frac{1}{2} \sqrt{a^T A^{-1} a}$$

$$\boxed{x^* = -\frac{A^{-1} a}{\sqrt{a^T A^{-1} a}}}$$

Example 3: $\begin{cases} x^T Q x \rightarrow \min_x \\ \text{s.t. } \|Ax - b\|_2^2 \leq 1 \end{cases}$, where $Q = Q^T > 0, A = A^T > 0$

$$\begin{aligned}
L &= x^T Q x + \lambda((Ax - b)^T (Ax - b) - 1) = x^T Q x + \\
& \lambda(x^T A^T A x - 2b^T A x + b^T b - 1)
\end{aligned}$$

K.K.T. conditions:

$$\begin{cases} \nabla_x L = 2Qx + 2\lambda A^T A x - 2\lambda A^T b = 0 \\ \lambda \geq 0 \\ \lambda(x^T A^T A x - 2b^T A x + b^T b - 1) = 0 \\ \|Ax - b\|_2^2 \leq 1 \end{cases} \Rightarrow$$

$$\begin{cases} \boxed{x^* = \lambda(Q + \lambda A^T A)^{-1} A^T b} \\ \lambda \geq 0 \\ \lambda(x^T A^T A x - 2b^T A x + b^T b - 1) = 0 \\ \|Ax - b\|_2^2 \leq 1 \end{cases}$$

λ^* one can find from the dual function, which will look a bit complex here

Application: (2-rank update)

$$\begin{cases} \|B - B_k\|_F^2 \rightarrow \min_B \\ \text{s.t. } Bs_k = y_k \end{cases}$$

$$L = \text{Tr}(B^T B) + \mu^T (Bs_k - y_k)$$

K.K.T. conditions:

$$\begin{cases} \nabla_B L = 2B + \mu s_k^T = 0 \\ Bs_k = y_k \end{cases} \Rightarrow B = -\frac{1}{2}\mu s_k^T$$

$$\text{Dual function } q(\mu) = \text{Tr}\left(\frac{1}{4}s_k \mu^T \mu s_k^T\right) - \frac{1}{2}\mu^T \mu s_k^T s_k - \mu^T y_k \rightarrow \min_{\mu}$$

$$\nabla_{\mu} q(\mu) = \frac{1}{2}s_k^T s_k \mu - s_k^T s_k \mu - y_k = 0, \quad \mu^* = \frac{-2y_k}{s_k^T s_k}$$

$$\text{So } \boxed{B^* = \frac{y_k s_k^T}{s_k^T s_k}}$$

Example 4:

$$\begin{cases} \frac{1}{2}x^T A x + b^T x + c \rightarrow \min_x \\ \text{s.t. } x^T x \leq 1 \end{cases} \text{ where } A = A^T > 0$$

$$L = \frac{1}{2}x^T A x + b^T x + c + \lambda(x^T x - 1)$$

K.K.T. conditions:

$$\begin{cases} \nabla_x L = Ax + b + \lambda x = 0 \\ x^T x - 1 \leq 0 \\ \lambda(x^T x - 1) = 0 \\ \lambda \geq 0 \end{cases} \Rightarrow \begin{cases} \lambda b^T (A + \lambda \cdot I)^{-T} (A + \lambda \cdot I)^{-1} b - \lambda = 0, \end{cases} \quad \boxed{x^* = -(A + I \cdot \lambda)^{-1} b} \quad (*)$$

$$(*) \lambda(b^T (A + \lambda \cdot I)^{-2} b - 1) = 0 \Rightarrow \lambda^* = \max\{0, \text{solution of } (*)\}$$

Example 5: (Projection on the radius 1 Ball)

$$\begin{cases} \frac{1}{2}\|x - v\|_2^2 \rightarrow \min_x \\ \text{s.t. } x^T x \leq 1 \end{cases}$$

$$L = \frac{1}{2}(x^T x - 2v^T x + v^T v) + \lambda(x^T x - 1)$$

K.K.T. conditions:

$$\begin{cases} \nabla_x L = x - v + 2\lambda x = 0 \\ \lambda \geq 0 \\ \lambda(x^T x - 1) = 0 \\ x^T x - 1 \leq 0 \end{cases} \Rightarrow \begin{cases} x^* = \frac{v}{1+2\lambda} \\ \lambda \left(\frac{v^T v}{(1+2\lambda)^2} - 1 \right) = 0 \end{cases} \quad (\star)$$

$$(\star) 1 + 2\lambda = \sqrt{v^T v} = \|v\|_2$$

So $x^* = \frac{v}{\|v\|_2}$, which is quite intuitive

Application: (Hard margin SVM)

$$\begin{cases} \frac{1}{2} \|w\|_2^2 \rightarrow \min_w \\ y_i (x_i^T w - b) \geq 1 \end{cases}$$

$$L = \frac{1}{2} w^T w - \sum_{i=1}^n \lambda_i (y_i (x_i^T w - b) - 1)$$

K.K.T. conditions:

$$\begin{cases} \nabla_w L = w - \sum_{i=1}^n \lambda_i y_i x_i = 0 \\ \nabla_b L = \sum_{i=1}^n \lambda_i y_i = 0 \\ \lambda_i \geq 0, \forall i = 1, \dots, n \\ \lambda_i (y_i (x_i^T w - b) - 1) = 0, \forall i = 1, \dots, n \end{cases}$$

$$w^* = \sum_{i=1}^n \lambda_i y_i x_i$$

Application: Consider the multiple regression model $y = X \cdot \beta + \epsilon$, where $\epsilon \sim \mathcal{N}(0, \sigma^2 I)$, let's propose a linear estimator of the form $\hat{\beta} = L \cdot y$. Find the unbiased estimator $\hat{\beta}$, for which $Tr(Var(\hat{\beta})) \rightarrow \min_{\beta}$

$$\begin{cases} Tr(Var(Ly)) \rightarrow \min_L \\ \mathbb{E}(\hat{\beta}) = \beta \end{cases}$$

$$\begin{aligned} \mathcal{L} &= Tr(Var(L(X\beta + \epsilon))) + \mu^T (\mathbb{E}(\hat{\beta}) - \beta) = Tr(Var(L\epsilon)) + \\ &\mu^T (LX\beta - \beta) = Tr(\sigma^2 LL^T) + \mu^T (LX\beta - \beta) \end{aligned}$$

$$DTr(LL^T)[\Delta L] = Tr(L\Delta L^T + L^T \Delta L) = Tr(\nabla f(L)^T \Delta L) \Rightarrow \nabla_L = 2L$$

$$D\mu^T LX\beta[\Delta L] = \mu^T \Delta LX\beta = Tr(X\beta \mu^T \Delta L) \Rightarrow \nabla_L = \mu(X\beta)^T = \mu\beta^T X^T$$

$$\text{K.K.T. conditions: } \begin{cases} \nabla_L \mathcal{L} = 2\sigma^2 L + \mu\beta^T X^T = 0 \\ LX\beta = \beta \end{cases} \Rightarrow$$

$$\begin{cases} L^* = -\frac{\mu}{2\sigma^2} \beta^T X^T \\ -\frac{\mu}{2\sigma^2} \beta^T X^T X \beta = \beta \end{cases} \quad (\star)$$

$$(\star) \quad -2\sigma^2 \mu \beta^T X^T X = I \Rightarrow \mu \beta^T = -2\sigma^2 (X^T X)^{-1} \Rightarrow L^* = (X^T X)^{-1} X^T$$

$$\boxed{\hat{\beta} = (X^T X)^{-1} X^T y}$$

P.S: The same problem, but for $\epsilon \sim \mathcal{N}(0, \Sigma)$

$$\begin{cases} \text{Tr}(\text{Var}(Ly)) \rightarrow \min_L \\ \mathbb{E}(Ly) = \beta \end{cases}$$

$$\mathcal{L} = \text{Tr}(\text{Var}(LX\beta + L\epsilon)) + \mu^T (LX\beta - \beta) = \text{Tr}(L\Sigma L^T) + \mu^T (LX\beta - \beta)$$

$$\nabla_L (\text{Tr}(L\Sigma L^T)) = 2L\Sigma^T = 2L\Sigma$$

$$D\text{Tr}(L\Sigma L^T)[\Delta L] = \text{Tr}(L\Sigma \Delta L^T + \Delta L \Sigma L^T) = \text{Tr}(2\Sigma L^T \Delta L) = \text{Tr}(\nabla f(L)^T \Delta L)$$

K.K.T. conditions:

$$\begin{cases} \nabla_L \mathcal{L} = 2L\Sigma + \mu \beta^T X^T = 0 \\ LX\beta = \beta \end{cases} \Rightarrow \begin{cases} L^* = -2\mu \beta^T X^T \Sigma^{-1} \\ -2\mu \beta^T X^T \Sigma^{-1} X \beta = \beta \end{cases} \quad (\star)$$

$$(\star) \quad -2\mu \beta^T X^T \Sigma^{-1} X = I \Rightarrow \mu \beta^T = -\frac{1}{2} (X^T \Sigma^{-1} X)^{-1}$$

$$L^* = (X^T \Sigma^{-1} X)^{-1} X^T \Sigma^{-1}$$

$$\boxed{\hat{\beta} = (X^T \Sigma^{-1} X)^{-1} X^T \Sigma^{-1} y}$$

Application (Principle Component Analysis)

Finding the 1st component:

$$\begin{cases} \|Xa\|_2^2 \rightarrow \max_a \\ \text{s.t. } \|a\|_2^2 = 1 \end{cases}$$

$$L = a^T X^T X a + \mu (a^T a - 1)$$

$$\text{K.K.T. conditions: } \begin{cases} \nabla_a L = 2X^T X a + 2\mu a = 0 \\ a^T a = 1 \end{cases} \quad (1)$$

From the (1) it follows that, $X^T X a = -\mu a \Rightarrow a$ is an eigenvector of $X^T X$. Let's call the corresponding eigenvalue λ , then the problem $\|Xa\|_2^2 \rightarrow \max_a$ would

take the form: $a^T X^T X a = a^T \lambda a = \lambda \cdot a^T a = \lambda \underbrace{\|a\|_2^2}_1 \rightarrow \max \Rightarrow \lambda = \text{maximum}$
eigenvalue of $X^T X$, so the answer would be $a =$ the eigenvector, corresponding
to the maximum eigenvalue of matrix $X^T X$

Finding the k^{th} principal component:

$$\begin{cases} \|X a_k\|_2^2 \rightarrow \max \\ & a_k \\ < a_k, a_i > = 0, \forall i \neq k \\ \|a_k\|_2^2 = 1 \end{cases}$$

$$L = a^T X^T X a + \mu (a^T a - 1) + \sum_{i=1}^{k-1} \gamma_i a_k^T a_i$$

$$\nabla_{a_k} L = 2X^T X a_k + 2\mu a_k + \sum_{i=1}^{k-1} \gamma_i a_i = 0 \Big| \cdot a_k^T \Rightarrow 2a_k^T X^T X a_k + 2\mu a_k^T +$$

$$\underbrace{\sum_{i=1}^{k-1} \gamma_i a_k^T a_i}_0 = 0 \Rightarrow a_k \text{ is an eigenvector of } X^T X, \text{ corresponding to the next biggest eigenvalue.}$$

Application: Consider the model $y = X\beta + \epsilon$, where $\epsilon \sim \mathcal{N}(0, \sigma^2 I)$. Find efficient unbiased quadratic estimator of σ^2

Quadratic estimator takes the form: $\hat{\sigma}^2 = y^T A y$, so the problem can be formalised as follows:

$$\begin{cases} \text{Var}(y^T A y) \rightarrow \min \\ \mathbb{E}(y^T A y) = \sigma^2 \end{cases}$$

$$\begin{aligned} \mathbb{E}(y^T A y) &= \mathbb{E}((X\beta + \epsilon)^T A (X\beta + \epsilon)) = \beta^T X^T A X \beta + \mathbb{E}(\epsilon^T A \epsilon) = \\ \beta^T X^T A X \beta + \sigma^2 \text{tr}(A) &= \sigma^2 \Rightarrow \begin{cases} X^T A X = (0) \\ \text{tr}(A) = 1 \end{cases} \end{aligned}$$

$$\left\{ \mathbb{E}(\epsilon^T A \epsilon) = \mathbb{E}(\text{tr}(\epsilon^T A \epsilon)) = \mathbb{E}(\text{tr}(A \epsilon \epsilon^T)) = \text{tr}(A \underbrace{\mathbb{E}(\epsilon \epsilon^T)}_{\sigma^2 I}) = \sigma^2 \text{tr}(A) \right\}$$

$$\begin{aligned} \text{Var}(y^T A y) &= \text{Var}(\beta^T X^T A X \beta + \underbrace{2\beta^T X^T A \epsilon}_{\text{A would be symm}} + \epsilon^T A \epsilon) = 4\sigma^2 \beta^T X^T A^2 X \beta + \\ &2\sigma^4 \text{tr}(A^2) \end{aligned}$$

$$L = 4\sigma^2\beta^T X^T A^2 X\beta + 2\sigma^4 \text{tr}(A^2) + \text{tr}(\Lambda \cdot X^T A X) + \mu \cdot (\text{tr}(A) - 1)$$

$$\begin{aligned} DL[\Delta A] &= 4\sigma^2\beta^T X^T (\Delta A A + A \Delta A) X\beta + 2\sigma^4 \text{tr}(\Delta A A + A \Delta A) + \\ &\text{tr}(\Lambda X^T \Delta A X) + \mu \text{tr}(\Delta A) = \text{tr}([8\sigma^2 X\beta\beta^T X^T A + 4\sigma^4 A + X\Lambda X^T + \mu I]\Delta A) = \\ &\text{tr}(\nabla_A L^T \Delta A) \end{aligned}$$

$$\nabla_A L = 8\sigma^2 A X\beta\beta^T X^T + 4\sigma^4 A + X\Lambda^T X^T + \mu I$$

K.K.T conditions:

$$\begin{cases} \nabla_A L = 0 \\ X^T A X = (0) \\ \text{tr}(A) = 1 \end{cases} \Rightarrow \begin{cases} 4\sigma^2 A (2X\beta\beta^T X^T + \sigma^2 I) = (X\Lambda^T X^T + \mu I) \end{cases}$$

Example 6: Find the extremum of a function $f(x) = \frac{x^T A x}{x^T B x}$, where A and B > 0 are symmetric matrices

We can reduce this problem to the constrained optimisation problem:

$$\begin{cases} x^T A x \rightarrow \text{extr}_x \\ \text{s.t. } x^T B x = 1 \end{cases}$$

$$L = x^T A x + \mu (x^T B x - 1)$$

As $B > 0$ $B = B^{1/2} \cdot B^{1/2}$, let's denote $B^{1/2} \cdot x = y$, so the problem will transform to:

$$\begin{cases} y^T B^{1/2} A B^{1/2} y \rightarrow \text{extr}_y \\ y^T y = 1 \end{cases}$$

$$L = y^T B^{1/2} A B^{1/2} y + \mu (y^T y - 1)$$

K.K.T conditions:

$$\begin{cases} \nabla_y L = 2B^{1/2} A B^{1/2} y + 2\mu y = 0 \\ y^T y = 1 \end{cases} \Rightarrow y^* \text{ eigenvec of } B^{1/2} A B^{1/2} \text{ with } \lambda$$

So the our function takes the form: $\lambda y^T y \rightarrow \text{extr}_y \Rightarrow \lambda \rightarrow \text{extr}$

The minimum of a function is attained in $y_1 : B^{1/2} A B^{1/2} y = \lambda_{\min} y$, and the maximum is attained in $y : B^{1/2} A B^{1/2} y = \lambda_{\max} y$

Example 7:

$$\begin{cases} \text{tr}(A^T A) - 2\text{tr}(A) \rightarrow \min_A \\ \text{s.t. } AX = 0 \end{cases}$$

$$L = \text{tr}(A^T A) - 2\text{tr}(A) + \text{tr}(\Lambda^T AX) = \text{tr}(A^T A - 2A + \Lambda^T AX)$$

K.K.T. conditions:

$$\begin{cases} \nabla_A L = 2A - 2I + \Lambda X^T = 0 \\ AX = 0 \end{cases} \Rightarrow A^* = I - \frac{1}{2}\Lambda X^T$$

$$\text{Dual problem: } q(\Lambda) = \text{tr}[(I - \frac{1}{2}\Lambda X^T)^T(I - \frac{1}{2}\Lambda X^T)] - 2\text{tr}(I - \frac{1}{2}\Lambda X^T) + \text{tr}(\Lambda^T X - \frac{1}{2}\Lambda^T \Lambda X^T X) = \text{tr}[-I + X^T \Lambda - \frac{1}{4}\Lambda X \Lambda^T \Lambda X^T] \rightarrow \max_{\Lambda}$$

$$\nabla_{\Lambda} q = X - \frac{1}{2}\Lambda X^T X = 0, \Rightarrow \Lambda^* = 2X(X^T X)^{-1}$$

$$\boxed{A^* = I - X(X^T X)^{-1}X^T}$$

Example 8: $f(x) = \frac{(a^T x)^2}{x^T B x} \rightarrow \max_x, B > 0$

This could be represented as a constrained optimisation problem:

$$\begin{cases} a^T x \rightarrow \max_x \\ \text{s.t. } x^T B x = 1 \end{cases}$$

$$L = a^T x + \lambda (x^T B x - 1)$$

K.K.T. conditions:

$$\begin{cases} \nabla_x L = a + 2\lambda \cdot Bx = 0 \\ x^T B x = 1 \end{cases} \Rightarrow \begin{cases} x^* = -\frac{1}{2\lambda} B^{-1} a \\ \frac{1}{4\lambda^2} a^T B^{-1} B B^{-1} a = 1 \end{cases}$$

$$\text{Dual function: } q(\lambda) = -\frac{1}{2\lambda} a^T B^{-1} a + \lambda \left(\frac{1}{4\lambda^2} a^T B^{-1} a - 1 \right) = -\frac{1}{4\lambda} a^T B^{-1} a - \lambda \rightarrow \max_{\lambda}$$

$$q'_{\lambda} = \frac{1}{4\lambda^2} a^T B^{-1} a - 1 = 0 \Rightarrow \lambda^* = \frac{\sqrt{a^T B^{-1} a}}{2}$$

$$x^* = \frac{B^{-1} a}{\sqrt{a^T B^{-1} a}} \Rightarrow f(x^*) = \frac{a^T B^{-1} a}{\frac{a^T B^{-1} B B^{-1} a}{a^T B^{-1} a}} = \boxed{a^T B^{-1} a}$$

Example 9: Prove that $f(y) = \frac{y^T A y}{(y^T x)^2} \geq (x^T A^{-1} x)^{-1}$

$f(y) \rightarrow \min_y$ is equal to:

$$\begin{cases} y^T A y \rightarrow \min_y \\ \text{s.t. } y^T x = 1 \end{cases}$$

$$L = y^T A y + \lambda(x^T y - 1)$$

K.K.T. conditions:

$$\begin{cases} \nabla_y L = 2Ay + \lambda x = 0 \\ x^T y = 1 \end{cases} \Rightarrow \begin{cases} y^* = -\frac{\lambda}{2} A^{-1} x \\ -\frac{\lambda}{2} x^T A^{-1} x = 1 \end{cases}$$

$$\lambda^* = -\frac{2}{x^T A^{-1} x} \Rightarrow \boxed{y^* = \frac{A^{-1} x}{x^T A^{-1} x}}$$

$$\text{So } f(y^*) = \frac{\frac{x^T A^{-1} x}{(x^T A^{-1} x)(x^T A^{-1} x)}}{\left(\frac{x^T A^{-1} x}{x^T A^{-1} x}\right)^2} = (x^T A^{-1} x)^{-1}$$

Example 10: Let A be an $m \times n$ matrix of rank r . Let $\delta_1, \dots, \delta_r$ be the singular values of A (that is the square roots of the non-zero eigenvalues of AA^T) and let $\delta = \delta_1 + \dots + \delta_r$. Prove, that $-\delta \leq \text{tr}(AX) \leq \delta$ for every $n \times m$ matrix X satisfying $X^T X = I_m$

Constrained extremum problem:

$$\begin{cases} \text{tr}(AX) \rightarrow \text{extr}_X \\ \text{s.t. } X^T X = I_m \end{cases}$$

$$L = \text{tr}(AX) + \text{tr}(\Lambda^T X^T X - \Lambda^T)$$

Since the matrix $X^T X$ is symmetric $\Rightarrow \Lambda$ should also be symmetric, so:

K.K.T. conditions:

$$\begin{cases} \nabla_X L = A^T + 2X\Lambda = 0 \\ X^T X = I_m \end{cases} \Rightarrow \begin{cases} X^* = -\frac{1}{2} A^T \Lambda^{-1} \\ \frac{1}{4} \Lambda^{-1} A A^T \Lambda^{-1} = I_m (*) \end{cases}$$

$$(*) \Lambda^2 = \frac{1}{4} A A^T \Rightarrow \boxed{\Lambda^* = \pm \frac{1}{2} \sqrt{A A^T}}$$

$$\boxed{X^* = \pm A^T (A A^T)^{-\frac{1}{2}}}$$

To sum up:

$$\text{tr}(AX^*) = \text{tr}(A A^T (A A^T)^{-\frac{1}{2}}) = \text{tr}(\sqrt{A A^T}) \text{ which results the proof}$$

Example 11:

$$\begin{cases} \|y - \theta\|_2^2 \rightarrow \min_{\theta} \\ \text{s.t. } A\theta = 0 \end{cases}, \quad A = A^T \geq 0$$

$$L = y^T y - 2y^T \theta + \theta^T \theta - \lambda^T A\theta$$

K.K.T. conditions:

$$\begin{cases} \nabla_{\theta} L = -2y + 2\theta - A^T \lambda = 0 \\ A\theta = 0 \end{cases} \Rightarrow \begin{cases} \theta^* = y + \frac{1}{2} A^T \lambda \\ Ay + \frac{1}{2} A A^T \lambda = 0(*) \end{cases}$$

$$(*) \lambda^* = -2(AA^T)^{-1} Ay \Rightarrow \theta^* = y - A^T (AA^T)^{-1} Ay = (I - A^T (AA^T)^{-1} A) y$$

$$\boxed{\theta^* = (I - A^T (AA^T)^{-1} A) y}$$

Example : $\begin{cases} x^T A x \rightarrow \min_x \\ \text{s.t. } \|x\|_2^2 \leq 1 \end{cases}, \text{ where } A = A^T > 0$

$$L = x^T A x + \lambda(x^T x - 1)$$

K.K.T conditions:

$$\begin{cases} \nabla_x L = 2Ax + 2\lambda x = 0 \\ x^T x \leq 1 \\ \lambda(x^T x - 1) = 0 \\ \lambda \geq 0 \end{cases} \Rightarrow Ax = -\lambda x, \text{ so } x \text{ should be the eigenvector of}$$

matrix A for example with eigenvalue γ , then the dual function:

Other

Example 1: Find $\mathbb{E}(x^T x)$, where $x \sim \mathcal{N}(\mu, \Sigma)$

$$\mathbb{E}x = \mu, \quad \mathbb{E}(x - \mu)(x - \mu)^T = \Sigma$$

$$\mathbb{E}(x - \mu)(x - \mu)^T = \mathbb{E}xx^T - 2\mu^T \mathbb{E}x + \mathbb{E}\mu^T \mu = \mathbb{E}xx^T - 2\mu\mu^T + \mu\mu^T = \mathbb{E}xx^T - \mu\mu^T = \Sigma \Rightarrow \mathbb{E}xx^T = \Sigma + \mu\mu^T$$

$$\mathbb{E}x^T x = \text{tr}(\mathbb{E}x^T x) = \mathbb{E}(\text{tr}(x^T x)) = \mathbb{E}(\text{tr}(xx^T)) = \text{tr}(\mathbb{E}xx^T) = \text{tr}(\Sigma + \mu\mu^T) = \text{tr}\Sigma + \mu^T \mu$$

$$\boxed{\mathbb{E}x^T x = \text{tr}\Sigma + \mu^T \mu}$$

Here we used the fact, that $\text{tr}(aa^T) = a^T a$

Example 2 Find the ML estimator for the Σ parameter of Wishart distribution.

$$\text{Wishart distribution: } M \in \mathbb{R}^{P \times P} \quad p(M|\Sigma, m) = \frac{1}{2^{\frac{mP}{2}} \pi^{\frac{P(P-1)}{4}} \prod_{p=1}^P \Gamma[\frac{1}{2}(m+1-p)]} \cdot \det(\Sigma)^{-\frac{m}{2}} \cdot \det(M)^{\frac{m-P-1}{2}} \cdot \exp[-\frac{1}{2}\text{tr}(\Sigma^{-1}M)]$$

$\underbrace{\hspace{10em}}_{\text{const of } \Sigma}$

$$L(\Sigma) = \prod_{i=1}^n \text{Const} \cdot \det(\Sigma)^{-\frac{m}{2}} \cdot \det(M_i)^{\frac{m-P-1}{2}} \cdot \exp[-\frac{1}{2}\text{tr}(\Sigma^{-1}M_i)] \rightarrow \max_{\Sigma}$$

$$\log L(\Sigma) = -\frac{mn}{2} \log \det(\Sigma) + \frac{m-P-1}{2} \sum_{i=1}^n \log \det(M_i) - \frac{1}{2} \sum_{i=1}^n \text{tr}(\Sigma^{-1}M_i) \rightarrow \max_{\Sigma}$$

$$\Lambda = \Sigma^{-1} \rightarrow \log L(\Lambda) = \frac{mn}{2} \log \det(\Lambda) + \dots - \frac{1}{2} \sum_{i=1}^n \text{tr}(\Lambda M_i)$$

$$\nabla_{\Lambda} \log L = \frac{mn}{2} \Lambda^{-1} - \frac{1}{2} \sum_{i=1}^n M_i^T = 0$$

$$mn\Sigma = \sum_{i=1}^n M_i^T \Rightarrow \boxed{\hat{\Sigma} = \frac{1}{mn} \sum_{i=1}^n M_i^T}$$

Application: R^2 representation

$$R^2 = \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y})^2}{\sum_{i=1}^n (y_i - \bar{y})^2} = 1 - \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{\sum_{i=1}^n (y_i - \bar{y})^2}, \text{ let's consider, that we're working with the}$$

standartised data: $\bar{y} = 0, \sigma_y = 1 \Rightarrow \sum_{i=1}^n (y_i - \bar{y})^2 = \sum_{i=1}^n y_i^2 = \sigma_y^2 = 1$, so

$$R^2 = 1 - e^T e = 1 - (X\beta - y)^T (X\beta - y) = 1 - \beta^T X^T X \beta + 2y^T X \beta - \underbrace{y^T y}_{\sigma_y^2=1} =$$

$$2y^T X \beta - \beta^T X^T X \beta = \{\beta^{\text{ols}} = (X^T X)^{-1} X^T y\} = 2y^T X (X^T X)^{-1} X^T y -$$

$$y^T X (X^T X)^{-1} X^T X (X^T X)^{-1} X^T y = y^T X (X^T X)^{-1} X^T y = \{V(\beta^{\text{ols}}) =$$

$$\sigma_\epsilon^2 (X^T X)^{-1} = \Sigma_\beta\} = \frac{1}{\sigma_\epsilon^2} y^T X \underbrace{\Sigma_\beta}_{\text{Grammian matrix}} X^T y$$

Let's recall, that in the ortonormal basis $\{e\}$ the scale product of 2 vectors \vec{a} and \vec{b} , could be represented as: $\langle a, b \rangle_e = a^T b$.

If the basis $\{f\}$ is not an ortonormal one, it would be represented as:

$$\langle a, b \rangle_f = a^T \Gamma b, \text{ where } \Gamma = \begin{pmatrix} \langle f_1, f_1 \rangle & \dots & \langle f_1, f_n \rangle \\ \vdots & \ddots & \vdots \\ \langle f_n, f_1 \rangle & \dots & \langle f_n, f_n \rangle \end{pmatrix} - \text{Grammian}$$

matrix of the basis vectors.

So $R^2 = \frac{1}{\sigma_\epsilon^2} (X^T y)^T \Sigma_\beta (X^T y) = \frac{1}{\sigma_\epsilon^2} \|X^T y\|_\beta^2$ could be interpreted as a squared norm of a $X^T y$ vector in the space of parameters β : $\mathcal{L} = L\{\beta_1, \dots, \beta_k\}$

Example R^2 representation

$$R^2 = 1 - \frac{ESS}{TSS} = 1 - \frac{e^T e}{(y - \bar{y})^T (y - \bar{y})}$$

$$e^T e = (y - X\beta)^T (y - X\beta) = (y - X(X^T X)^{-1} X^T y)^T (y - X(X^T X)^{-1} X^T y) =$$

$$y^T \underbrace{(I - X(X^T X)^{-1} X^T)^2}_{\text{idempotent}} y = y^T (I - X(X^T X)^{-1} X^T) y$$

$$R^2 = 1 - \frac{y^T (I - X(X^T X)^{-1} X^T) y}{y^T y - 2\bar{y}^T y + n \cdot (\bar{y})^2} = \frac{y^T (X(X^T X)^{-1} X^T) y - 2\bar{y}^T y + n \cdot (\bar{y})^2}{y^T y - 2\bar{y}^T y + n \cdot (\bar{y})^2} =$$

$$1 - \frac{(y + \bar{y} \cdot \vec{1})^T (I - X(X^T X)^{-1} X^T) (y + \bar{y} \cdot \vec{1})}{y^T y}$$

Example: $x \sim \mathcal{N}(\mu, \Omega)$, find $\mathbb{V}(x^T A x)$, $A = A^T$

Theorem: if $y \sim \mathcal{N}(\mu, \Sigma) \Rightarrow M_y(t) = \exp\{t^T \mu + \frac{1}{2} t^T \Sigma t\}$, where $M_y(t)$ - is a moment generating function.

$$\textbf{Proof: } M_y(t) = \frac{1}{\sqrt{\text{Det}(2\pi\Sigma)}} \int_{-\infty}^{+\infty} \dots \int_{-\infty}^{+\infty} \exp\{t^T y - \frac{1}{2} (y - \mu)^T \Sigma^{-1} (y - \mu)\} dy = \frac{1}{\sqrt{\text{Det}(2\pi\Sigma)}} \int_{-\infty}^{+\infty} \dots \int_{-\infty}^{+\infty} \exp\{t^T \mu + \frac{1}{2} t^T \Sigma t -$$

$$\frac{1}{2}(y - \mu - \Sigma t)^T \Sigma^{-1} (y - \mu - \Sigma t) dy = \exp\{t^T \mu + \frac{1}{2} t^T \Sigma t\} \cdot$$

$$\underbrace{\frac{1}{\sqrt{\text{Det}(2\pi\Sigma)}} \int_{-\infty}^{+\infty} \cdots \int_{-\infty}^{+\infty} \exp\{-\frac{1}{2} (y - (\mu + \Sigma t))^T \Sigma^{-1} (y - (\mu + \Sigma t))\} dy}_{1} =$$

$\exp\{t^T \mu + \frac{1}{2} t^T \Sigma t\}$

Equivalent actions will lead to:

$M_{x^T A x}(t) = |I - 2tA\Sigma|^{-1/2} \exp\{-\frac{1}{2} \mu^T [I - (I - 2tA\Sigma)^{-1}] \Sigma^{-1} \mu\}$

Other way:

$$\text{Var}(x^T A x) = \text{cov}(x^T A x, x^T B x), \text{ where } B = A$$

$$\text{cov}(x^T A x, x^T B x) = \mathbb{E}(x^T A x x^T B x) - \mathbb{E}(x^T A x) \cdot \mathbb{E}(x^T B x)$$

$$\mathbb{E}(x^T A x) = \text{tr}(A \mathbb{E} x x^T) = \text{tr}(A \cdot (\Sigma + \mu \mu^T))$$

.

Example: $\log \text{Det}(A) = \text{tr}(\log A)$

Proof: $\text{tr}(A) = \sum_{j=1}^d \lambda_j, \quad \text{Det}(A) = \prod_{j=1}^d \lambda_j, \quad \lambda_j - j\text{-th eigenvalue of matrix } A$

$$\log \text{Det}(A) = \log \left(\prod_{j=1}^d \lambda_j \right) = \sum_{j=1}^d \log \lambda_j = \{\log x = x - \frac{1}{2}x^2 + \frac{1}{3}x^3 + \dots\} =$$

$$\sum_{j=1}^d \sum_{k=1}^{+\infty} (-1)^{k-1} \cdot \frac{1}{k} \cdot \lambda_j^k$$

$$\text{tr}(\log A) = \text{tr} \left(\sum_{k=1}^{+\infty} (-1)^{k-1} \cdot \frac{1}{k} \cdot A^k \right) = \sum_{k=1}^{+\infty} (-1)^{k-1} \cdot \frac{1}{k} \cdot \text{tr}(A^k) =$$

$$\sum_{k=1}^{+\infty} (-1)^{k-1} \cdot \frac{1}{k} \cdot \sum_{j=1}^d \lambda_j^k = \sum_{j=1}^d \sum_{k=1}^{+\infty} (-1)^{k-1} \cdot \frac{1}{k} \cdot \lambda_j^k$$

Example: $\text{Det}(e^A) = e^{\text{tr}(A)}, \quad A = A^T$

Proof: $\text{Det}(e^A) = \text{Det} \left(T \cdot \begin{pmatrix} e^{\lambda_1} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdot & e^{\lambda_d} \end{pmatrix} \cdot T^{-1} \right) = \text{Det}(T) \cdot \text{Det}(T^{-1}) \cdot$

$$\prod_{j=1}^d e^{\lambda_j} = e^{\sum_{j=1}^d \lambda_j} = e^{\text{tr}(A)}$$

Example: Find Eigvals(xx^T), where $x = (x_1, \dots, x_n)$

Let's look at the 4x4 case and find some patterns:

$$xx^T = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \cdot (x_1 \ \dots \ x_n) = \begin{pmatrix} x_1^2 & x_1x_2 & x_1x_3 & x_1x_4 \\ x_1x_2 & x_2^2 & x_2x_3 & x_2x_4 \\ x_1x_3 & x_2x_3 & x_3^2 & x_3x_4 \\ x_1x_4 & x_2x_4 & x_3x_4 & x_4^2 \end{pmatrix} \rightarrow$$

$$\text{Gauss transformations} \rightarrow \begin{pmatrix} x_1^2 & x_1x_2 & x_1x_3 & x_1x_4 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \Rightarrow \text{this shows us,}$$

that xx^T has $\lambda = 0$, whose geometry multiplicity is $n-1$. The left eigenvalue can be guessed from the 2x2 case and it is $\lambda = \sum_{i=1}^n x_i^2$

$$\text{So Eigvals}(xx^T) = \begin{cases} 0, & AM = n - 1 \\ \sum_{i=1}^n x_i^2, & AM = 1 \end{cases}$$

Theorem

if $P = P^T$ and $P^2 = P \Rightarrow P \geq 0$

Proof: $x^T Px = x^T P^2 x = x^T \underbrace{P}_{P^T} Px = (Px)^T (Px) = \|Px\|_2^2 \geq 0 \Rightarrow$

$$x^T Px \geq 0$$