# Natural Language Inference

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June 2, 2025

## **SNLI**

**SNLI** (Stanford Natural Language Inference) is a large-scale dataset for training and evaluating models on *natural language inference* (*NLI*).

### **Dataset Split:**

• Training: 550,152 pairs

• Development: 10,000 pairs

• **Test:** 10,000 pairs

#### Each example includes:

- A premise and a hypothesis
- A label:
  - entailment
  - contradiction
  - neutral
  - -1 (no consensus / unclear)

#### Example:

- Premise: A man is playing a guitar.
- Hypothesis: A man is making music.
- Label: entailment



### What is RoBERTa?

### **RoBERTa Overview**

- Robustly Optimized BERT Approach Facebook Al's enhanced transformer
- Transformer Architecture: Based on Encoder only architecture
- Bidirectional Language Model: Understands context from both directions
- Pre-trained for Fine-tuning: Ready for downstream NLP tasks

#### Why Choose RoBERTa?

- Superior Performance: Consistently outperforms BERT
- Better Generalization: Robust across diverse domains
- Easy Integration: Drop-in BERT replacement
- Optimized Training: More efficient learning process

### RoBERTa Strengths in NLI

- Top SNLI Results: 92.3% 93.1% accuracy (best 2 results)
- Strong Cross-Domain Transfer: SNLI & MNLI >90%
- Pre-trained Models: Ready-to-use NLI variants available

# RoBERTa Architecture

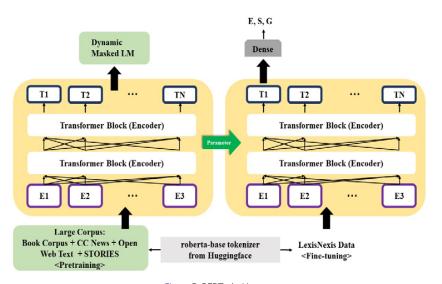


Figure: RoBERTa Architecture

# RoBERTa vs BERT: Key Differences

### **Training Data Improvements**

- 10x More Data: 160GB training corpus vs BERT's 16GB
- Diverse Sources: CommonCrawl, OpenWebText, News articles
- Longer Training: More iterations and larger mini-batches

### **Training Procedure Changes**

- Dynamic Masking: Different tokens masked per epoch vs static masking
- Removed NSP: No Next Sentence Prediction task (focus on MLM only)
- Larger Batches: 8K sequences vs BERT's smaller batches
- Enhanced Vocabulary: 50K BPE tokens vs BERT's 30K

### **Performance Improvements**

- Better Accuracy: Higher scores on GLUE, SQuAD, RACE benchmarks
- More Robust: Better handling of linguistic variations
- Faster Convergence: More efficient training process



## First Architecture

#### Custom NLI Architecture (RoBERTa + Additional Transformer Layers)

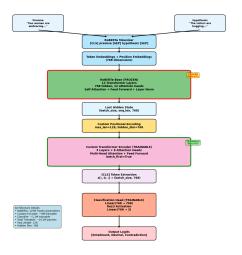
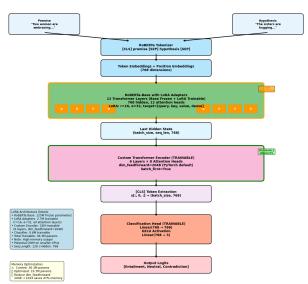


Figure: RoBERTa + 3 TransformerEncoder Architecture

## First Architecture

- Slow training: around 45 min for an epoch !!!
- Smaller number of parameters: around 10.2 M
- Smaller batches: 32 samples/batch
- **Epochs:** Trained only over 5 epochs
- Test accuracy ∼ 82%

#### Lora-Enhanced NLI Architecture (Current Implementation) (Roberta + Lora + 6 Custom Transformer Layers)



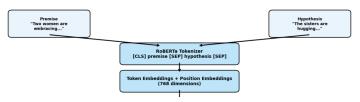


Figure: LoRA-Enhanced RoBERTa for NLI

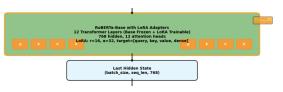


Figure: LoRA-Enhanced RoBERTa for NLI

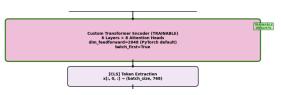


Figure: LoRA-Enhanced RoBERTa for NLI

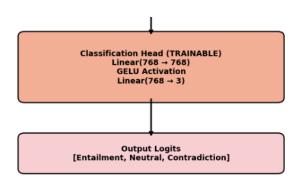


Figure: LoRA-Enhanced RoBERTa for NLI

- Fast training: around  $5\sim 6$  min for an epoch !!!
- LoRA adaptation: Train every W\_q,W\_k,W\_v,W\_d (around 2.7M trainable parameters)
- **Highly optimized:** Trained on A100 with multiple optimization 15 times faster(details later)
- High number of parameters:  $\sim$  36.3 M
- Robust activation function: GELU allows negative values close to 0 to be propagated and is continuous at 0
- Big batches: 512 samples/batch
- **Epochs**: Trained on 15 epochs
- Test accuracy  $\sim 90\%$

# LoRA (Low-Rank Adaptation of Large Language Models)

#### How LoRa works

- Parameter-Efficient Fine-tuning: Adapts pre-trained models with minimal parameters using output = input  $\times$  (W +  $\Delta W$ )
- Low-Rank Decomposition:  $\Delta W = BA$  where  $B \in \mathbb{R}^{d \times r}$ ,  $A \in \mathbb{R}^{r \times k}$
- Mathematical Foundation: Decomposes weight updates into low-rank matrices
- Trainable Parameters: Only A and B matrices, original weights W remain frozen

#### LoRA Configuration Details

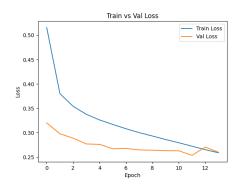
- Rank r=16: Bottleneck dimension, much smaller than original (768×768)
- Scaling Factor =32: Controls adaptation strength:  $\alpha/r \times \Delta W$
- Target Matrices: Query, Key, Value, Dense projections in attention layers
- Dropout: Applied to LoRA layers for regularization during training

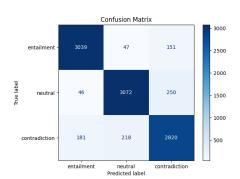
#### **Key Advantages**

- Storage Efficient: Small adapter files (few MB vs full model GB)
- Task Modularity: Switch between different task-specific adapters
- Reduced Overfitting: Fewer parameters prevent memorization
- Hardware Friendly: Enables fine-tuning on consumer GPUs



# Results





#### torch.compile() Optimization

- TorchDynamo JIT: Bytecode interception captures Python execution, extracts FX graphs for TorchInductor backend compilation
- Operator Fusion & Scheduling: Fuses ElementWise+MatMul+Activation chains, applies loop tiling and memory coalescing optimizations
- Graph Specialization: compiled\_model = torch.compile(model) triggers lazy compilation with shape/dtype specialization
- Autograd Integration: Preserves gradient computation through FX graph transformations and backward pass optimization

#### Mode: "max-autotune-no-cudagraphs"

- Triton Autotuning: Exhaustive kernel parameter search (block\_size, num\_warps, num\_stages) for optimal SM utilization
- Shape Polymorphism: Avoids CUDA graph static constraints, supports dynamic seq\_len without recompilation overhead
- Memory Allocator Bypass: Uses PyTorch memory pool instead of CUDA graph capture, prevents memory fragmentation issues
- Attention Kernel Optimization: Flash Attention v2 integration with optimal tile sizes for transformer workloads (1.2x-1.8x speedup)
- LoRA Pattern Recognition: Detects low-rank decomposition patterns, fuses frozen\_weight + (B @ A) operations in single kernel

#### **Mixed Precision Training**

- BFloat16 Autocast: torch.amp.autocast(device\_type='cuda', dtype=torch.bfloat16) for modern GPU training
- TensorFloat-32 (TF32): torch.backends.cuda.matmul.allow\_tf32 = True enables accelerated matrix multiplications on Ampere GPUs
- cuDNN TF32: torch.backends.cudnn.allow\_tf32 = True accelerates convolution and normalization operations
- Flash Attention: torch.backends.cuda.enable\_flash\_sdp(True) enables memory-efficient attention computation
- Gradient Scaler: scaler = GradScaler() prevents gradient underflow in mixed precision training
- $\bullet \ \ \text{Memory Efficiency:} \ 50\% \ \ \text{memory reduction with} \ 1.5\text{-}2x \ \text{speedup on transformer workloads}$

#### Hardware Acceleration Details

- TF32 Benefits: 19-bit precision (vs FP32's 23-bit) with 8x throughput improvement on A100/H100
- ullet Flash Attention Optimization: O(N) memory complexity vs O(N $^2$ ) for standard attention, ideal for long sequences
- Automatic Precision: BF16 forward pass, FP32 gradient accumulation with dynamic loss scaling
- LoRA Acceleration: TF32 matrix multiplications particularly benefit low-rank decomposition operations

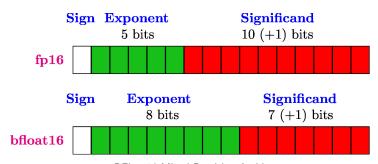


Figure: BFloat16 Mixed Precision Architecture

#### Hardware Comparison: A100 vs L4

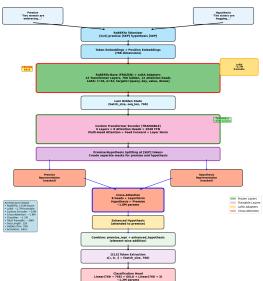
- Compute Capability: A100: 108 SMs, 40GB/80GB HBM2e vs L4: 58 SMs, 24GB GDDR6
- Memory Bandwidth: A100: 1935 GB/s HBM2e vs L4: 300 GB/s GDDR6 (6.5x difference)
- Tensor Core Performance: A100: 312 TFLOPS BF16 vs L4: 121 TFLOPS BF16 (2.6x difference)
- TF32 Acceleration: A100: 156 TFLOPS vs L4: 60 TFLOPS for matrix operations
- Power Consumption: A100: 400W TDP vs L4: 72W TDP (5.5x more efficient per watt)

#### **Training Performance Implications**

- Batch Size: A100 supports larger batches (40-80GB) vs L4 limited to smaller batches (24GB)
- LoRA Training: L4 sufficient for LoRA (2.7M parameters) but slower than A100 for full models
- Memory Efficiency: L4 requires aggressive optimization (BF16, gradient checkpointing, cache cleanup)
- Flash Attention: More critical on L4 due to memory constraints, provides larger relative speedup
- Cost Efficiency: L4 offers better price/performance for parameter-efficient fine-tuning workflows

# Attempt

#### LoRA + Cross-Attention NLI Architecture (RoBERTa + LoRA + 6 Transformer Layers + Cross-Attention)



# Attempt

### **Key Architectural Changes**

- Cross-Attention Module: Added dedicated 8-head cross-attention for premise-hypothesis interaction ( 1.8M params)
- Explicit Separation: Premise and hypothesis representations split after joint encoding instead of single [CLS] token
- Enhanced Fusion: Element-wise combination of premise + cross-attended hypothesis vs direct [CLS] classification
- Interpretable Reasoning: Attention weights reveal premise-hypothesis alignment patterns for better NLI understanding

#### Unsolved issue

• Stagnant Loss: Kept around 1.1 ( log(3)~1.1 from Cross-Entropy)

#### torch.compile() Related Errors

- Graph Recording Error: "input tensor deallocate during graph recording that did not occur during replay"
- Solution: Use mode="max-autotune-no-cudagraphs" to avoid CUDA graph memory issues
- TorchDynamo Compilation: Extensive bytecode transformation logs during first compilation pass
- Mitigation: Expected behavior compilation happens once, then caches optimized version

#### Tensor Dimension Mismatches

- Size Error: "Expected size 16384 but got size 16" in tensor concatenation operations
- Root Cause: Batch size or sequence length inconsistencies between model components
- ullet Solution: Verify tensor shapes at each layer: RoBERTa output o Custom Transformer o Cross-Attention
- Debug Strategy: Add shape logging: print(f"Tensor shape: {tensor.shape}") at critical points

#### **CUDA & Memory Errors**

- Device-Side Assert: CUDA kernel errors with device-side assertion triggers
- Solution: Compile with TORCH\_USE\_CUDA\_DSA=1 for better debugging information
- Model Initialization: RobertaModel weights not properly initialized from checkpoint
- ullet Fix: Ensure proper model loading sequence: base model o LoRA adapters o custom layers

#### Prevention Best Practices

- Gradual Compilation: Test without torch.compile() first, then add optimization
- Memory Management: Regular torch.cuda.empty\_cache() calls during training
- Error Handling: Wrap training loops in try-except for graceful error recovery

### References



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